

Online k -MLE for mixture modelling with exponential families

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We are interested in building a system (a model) which evolves when new data is available:

$$x_1, x_2, \dots, x_N, \dots$$

- The time needed for processing a new observation must be constant w.r.t the number of observations.
- The memory required by the system is bounded.
- Denote π the unknown distribution of X



- 1 Online learning exponential families
- 2 Online learning of mixture of exponential families
 - Introduction, EM, k -MLE
 - Recursive EM, Online EM
 - Stochastic approximations of k -MLE
 - Experiments
- 3 Conclusions



Reminder : (Regular) Exponential Family

Firstly, π will be approximated by a member of a (regular) exponential family (EF):

$$E_F = \{f(x; \theta) = \exp \{ \langle s(x), \theta \rangle + k(x) - F(\theta) \mid \theta \in \Theta \}$$

Terminology:

λ source parameters.

θ natural parameters.

η expectation parameters.

$s(x)$ sufficient statistic.

$k(x)$ auxiliary carrier measure.

$F(\theta)$ the log-normalizer:
differentiable, strictly
convex

$\Theta = \{ \theta \in \mathbb{R}^D \mid F(\theta) < \infty \}$
is an open convex set

Almost all common distributions are EF members but uniform, Cauchy distributions.



Reminder : Maximum Likelihood Estimate (MLE)

- Maximum Likelihood Estimate for general p.d.f:

$$\hat{\theta}^{(N)} = \operatorname{argmax}_{\theta} \prod_{i=1}^N f(x_i; \theta) = \operatorname{argmin}_{\theta} -\frac{1}{N} \sum_{i=1}^N \log f(x_i; \theta)$$

assuming a sample $\chi = \{x_1, x_2, \dots, x_N\}$ of i.i.d observations.

- Maximum Likelihood Estimate for an EF:

$$\hat{\theta}^{(N)} = \operatorname{argmin}_{\theta} \left(-\left\langle \frac{1}{N} \sum_i s(x_i), \theta \right\rangle - \operatorname{cst}(\chi) + F(\theta) \right)$$

which is exactly solved in H , the space of expectation parameters:

$$\hat{\eta}^{(N)} = \nabla F(\hat{\theta}^{(N)}) = \frac{1}{N} \sum_i s(x_i) \quad \equiv \quad \hat{\theta}^{(N)} = (\nabla F)^{-1} \left(\frac{1}{N} \sum_i s(x_i) \right)$$



- A recursive formulation is easily obtained

Algorithm 1: Exact Online MLE for EF

Input: a sequence \mathcal{S} of observations

Input: Functions s and $(\nabla F)^{-1}$ for some EF

Output: a sequence of MLE for all observations seen before

$\hat{\eta}^{(0)} = 0; \quad N = 1;$

for $x_N \in \mathcal{S}$ **do**

$\hat{\eta}^{(N)} = \hat{\eta}^{(N-1)} + N^{-1}(s(x_N) - \hat{\eta}^{(N-1)});$

yield $\hat{\eta}^{(N)}$ or **yield** $(\nabla F)^{-1}(\hat{\eta}^{(N)});$

$N = N + 1;$

Analytical expressions of $(\nabla F)^{-1}$ exist for most EF (but not all)



Case of Multivariate normal distribution (MVN)

- Probability density function of MVN:

$$\mathcal{N}(x; \mu, \Sigma) = (2\pi)^{-\frac{d}{2}} |\Sigma|^{-\frac{1}{2}} \exp^{-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)}$$

- One possible decomposition:

$$\begin{aligned} \mathcal{N}(x; \theta_1, \theta_2) = \exp\{ & \langle \theta_1, x \rangle + \langle \theta_2, -xx^T \rangle_F \\ & - \frac{1}{4} \text{tr} \theta_1 \theta_2^{-1} \theta_1 - \frac{d}{2} \log(\pi) + \frac{1}{2} \log |\theta_2| \} \end{aligned}$$

$$\implies \begin{cases} s(x) = (x, -xx^T) \\ (\nabla F)^{-1}(\eta_1, \eta_2) = ((-\eta_1 \eta_1^T - \eta_2)^{-1} \eta_1, \frac{1}{2}(-\eta_1 \eta_1^T - \eta_2)^{-1}) \end{cases}$$



See details in the paper.



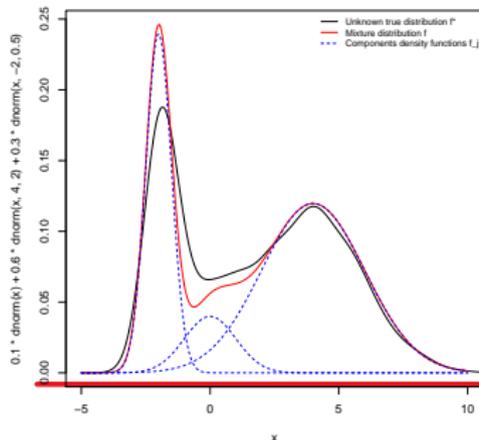
Finite (parametric) mixture models

- Now, π will be approximated by a finite (parametric) mixture $f(\cdot; \theta)$ indexed by θ :

$$\pi(x) \approx f(x; \theta) = \sum_{j=1}^K w_j f_j(x; \theta_j), \quad 0 \leq w_j \leq 1, \quad \sum_{j=1}^K w_j = 1$$

where w_j are the mixing proportions, f_j are the component distributions.

- When all f_j 's are EFs, it is called a Mixture of EFs (MEF).





Incompleteness in mixture models

incomplete
observable

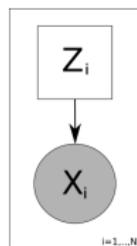
$$\chi = \{x_1, \dots, x_N\}$$

deterministic
←

complete
unobservable

$$\chi_c = \{y_1 = (x_1, z_1), \dots, y_N\}$$

$$Z_i \sim \text{cat}_K(w)$$
$$X_i | Z_i = j \sim f_j(\cdot; \theta_j)$$



For a MEF, the joint density $p(x, z; \theta)$ is an EF:

$$\log p(x, z; \theta) = \sum_{j=1}^K [z = j] \{ \log(w_j) + \langle \theta_j, s_j(x) \rangle + k_j(x) - F_j(\theta_j) \}$$

$$= \sum_{j=1}^K \left\langle \left(\begin{array}{c} [z = j] \\ [z = j] s_j(x) \end{array} \right), \left(\begin{array}{c} \log w_j - F_j(\theta_j) \\ \theta_j \end{array} \right) \right\rangle + k(x, z)$$



The EM algorithm maximizes iteratively $Q(\theta; \hat{\theta}^{(t)}, \chi)$.

Algorithm 2: EM algorithm

Input: $\hat{\theta}^{(0)}$ initial parameters of the model

Input: $\chi^{(N)} = \{x_1, \dots, x_N\}$

Output: A (local) maximizer $\hat{\theta}^{(t^*)}$ of $\log f(\chi; \theta)$

$t \leftarrow 0$;

repeat

 Compute $Q(\theta; \hat{\theta}^{(t)}, \chi) := \mathbb{E}_{\hat{\theta}^{(t)}}[\log p(\chi_c; \theta) | \chi]$; // E-Step

 Choose $\hat{\theta}^{(t+1)} = \operatorname{argmax}_{\theta} Q(\theta; \hat{\theta}^{(t)}, \chi)$; // M-Step

$t \leftarrow t + 1$;

until *Convergence of the complete log-likelihood*;

- For a mixture, the E-Step is always explicit:

$$\hat{z}_{i,j}^{(t)} = \hat{w}_j^{(t)} f(x_i; \hat{\theta}_j^{(t)}) / \sum_{j'} \hat{w}_{j'}^{(t)} f(x_i; \hat{\theta}_{j'}^{(t)})$$

- For a MEF, the M-Step then reduces to:

$$\hat{\theta}^{(t+1)} = \operatorname{argmax}_{\{w_j, \theta_j\}} \sum_{j=1}^K \left\langle \left(\begin{array}{c} \sum_i \hat{z}_{i,j}^{(t)} \\ \sum_i \hat{z}_{i,j}^{(t)} s_j(x_i) \end{array} \right), \left(\begin{array}{c} \log w_j - F_j(\theta_j) \\ \theta_j \end{array} \right) \right\rangle$$

$$\hat{w}_j^{(t+1)} = \sum_{i=1}^N \hat{z}_{i,j}^{(t)} / N$$

$$\hat{\eta}_j^{(t+1)} = \nabla F(\hat{\theta}_j^{(t+1)}) = \frac{\sum_i \hat{z}_{i,j}^{(t)} s_j(x_i)}{\sum_i \hat{z}_{i,j}^{(t)}} \quad (\text{weighted average of SS})$$



k -Maximum Likelihood Estimator (k -MLE) [2]

- The k -MLE introduces a geometric split $\chi = \bigsqcup_{j=1}^K \hat{\chi}_j^{(t)}$ to accelerate EM :

$$\tilde{z}_{i,j}^{(t)} = [\operatorname{argmax}_{j'} w_{j'} f(x_i; \hat{\theta}_{j'}^{(t)}) = j]$$

- Equivalently, it amounts to maximize \mathcal{Q} over partition Z [3]
- For a MEF, the M-Step of the k -MLE then reduces to:

$$\hat{\theta}^{(t+1)} = \operatorname{argmax}_{\{w_j, \theta_j\}} \sum_{j=1}^K \left\langle \left(\sum_{x_i \in \hat{\chi}_j^{(t)}} |\hat{\chi}_j^{(t)}|^{-1} s_j(x_i) \right), \left(\begin{array}{c} \log w_j - F_j(\theta_j) \\ \theta_j \end{array} \right) \right\rangle$$

$$\hat{w}_j^{(t+1)} = |\hat{\chi}_j^{(t)}| / N \quad \hat{\eta}_j^{(t+1)} = \nabla F(\hat{\theta}_j^{(t+1)}) = \frac{\sum_{x_i \in \hat{\chi}_j^{(t)}} s_j(x_i)}{|\hat{\chi}_j^{(t)}|}$$

(*cluster-wise unweighted average of SS*)



- Consider now the online setting

$$x_1, x_2, \dots, x_N, \dots$$

- Denote $\hat{\theta}^{(N)}$ or $\hat{\eta}^{(N)}$ the parameter estimate after dealing N observations
- Denote $\hat{\theta}^{(0)}$ or $\hat{\eta}^{(0)}$ their initial values
- Remark: For a fixed-size dataset χ , one may apply multiple passes (with shuffle) on χ .
- The increase in the likelihood function is no more guaranteed after an iteration.



Two main approaches to online EM-like estimation:

- Stochastic M-Step : Recursive EM (1984) [5]

$$\hat{\theta}^{(N)} = \hat{\theta}^{(N-1)} + \{N I_c(\hat{\theta}^{(N-1)})\}^{-1} \nabla_{\theta} \log f(x_N; \hat{\theta}^{(N-1)})$$

where I_c is the Fisher Information matrix for the complete data:

$$I_c(\hat{\theta}^{(N-1)}) = -\mathbb{E}_{\hat{\theta}_j^{(N-1)}} \left[\frac{\log p(x, z; \theta)}{\partial \theta \partial \theta^T} \right]$$

A justification for this formula comes from the Fisher's Identity:

$$\nabla \log f(x; \theta) = \mathbb{E}_{\theta} [\log p(x, z; \theta) | x]$$

One can recognize a second order Stochastic Gradient Ascent which requires to update and invert I_c after each iteration.

- Stochastic E-Step : Online EM (2009) [7]

$$\hat{Q}^{(N)}(\theta) = \hat{Q}^{(N-1)}(\theta) + \alpha^{(N)} \left(\mathbb{E}_{\hat{\theta}^{(N-1)}} [\log p(x_N, z_N; \theta) | x_N] - \hat{Q}^{(N-1)}(\theta) \right)$$

In case of a MEF, the algorithm works only with the cond. expectation of the sufficient statistics for complete data.

$$\hat{z}_{N,j} = \mathbb{E}_{\theta^{(N-1)}} [z_{N,j} | x_N]$$

$$\begin{pmatrix} \hat{S}_{w_j}^{(N)} \\ \hat{S}_{\theta_j}^{(N)} \end{pmatrix} = \begin{pmatrix} \hat{S}_{w_j}^{(N-1)} \\ \hat{S}_{\theta_j}^{(N-1)} \end{pmatrix} + \alpha^{(N)} \left(\begin{pmatrix} \hat{z}_{N,j} \\ \hat{z}_{N,j} s_j(x_N) \end{pmatrix} - \begin{pmatrix} \hat{S}_{w_j}^{(N-1)} \\ \hat{S}_{\theta_j}^{(N-1)} \end{pmatrix} \right)$$

The *M*-Step is unchanged:

$$\begin{aligned} \hat{w}_j^{(N)} &= \hat{\eta}_{w_j}^{(N)} = \hat{S}_{w_j}^{(N)} \\ \hat{\theta}_j^{(N)} &= (\nabla F_j)^{-1}(\hat{\eta}_{\theta_j}^{(N)} = \hat{S}_{\theta_j}^{(N)} / \hat{S}_{w_j}^{(N)}) \end{aligned}$$



Some properties:

- Initial values $\hat{S}^{(0)}$ may be used for introducing a "prior":

$$\hat{S}_{w_j}^{(0)} = w_j, \hat{S}_{\theta_j}^{(0)} = w_j \eta_j^{(0)}$$

- Parameters constraints are automatically respected
- No matrix to invert !
- Policy for $\alpha^{(N)}$ has to be chosen (see [7])
- Consistent, asymptotically equivalent to the recursive EM !!



In order to keep previous advantages of online EM for an online k -MLE, our only choice concerns the way to affect x_N to a cluster.

Strategy 1 Maximize the likelihood of the complete data
(x_N, z_N)

$$\tilde{z}_{N,j} = [\operatorname{argmax}_{j'} \hat{w}_{j'}^{(N-1)} f(x_N; \hat{\theta}_{j'}^{(N-1)}) = j]$$

Equivalent to Online CEM and similar to Mac-Queen iterative k-Means.



Strategy 2 Maximize the likelihood of the complete data (x_N, z_N) **after** the M-Step:

$$\tilde{z}_{N,j} = [\operatorname{argmax}_{j'} \hat{w}_{j'}^{(N)} f(x_N; \hat{\theta}_{j'}^{(N)}) = j]$$

- Similar to Hartigan's method for k -means.
- Additional cost: pre-compute all possible M-Steps for the Stochastic E -Step.



Strategy 3 Draw $\tilde{z}_{N,j}$ from the categorical distribution

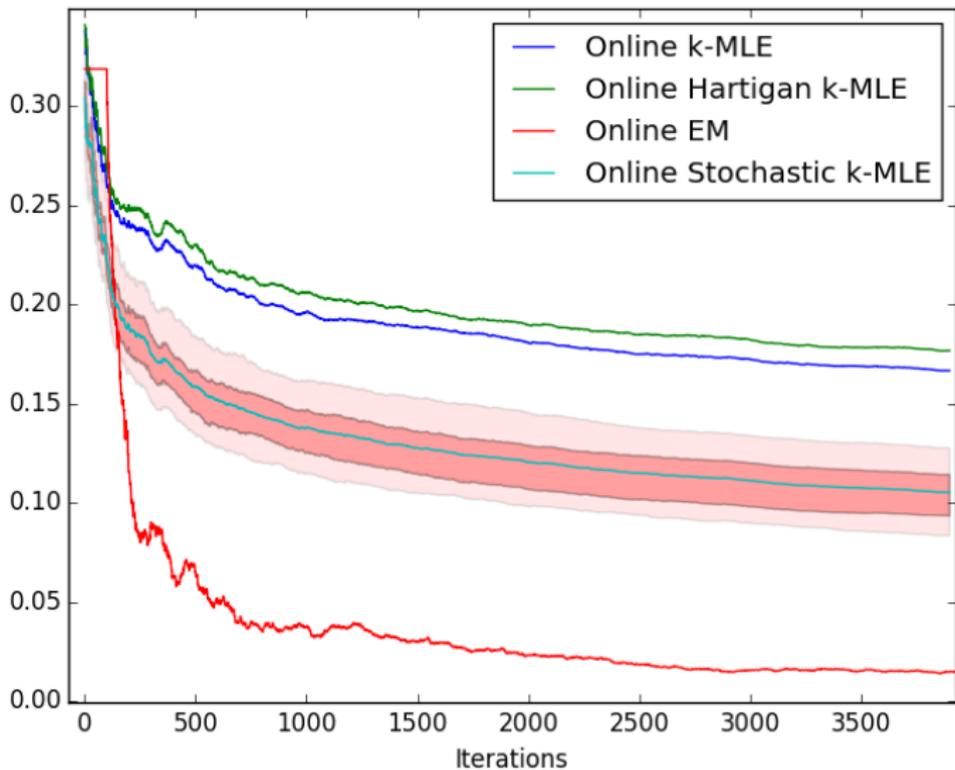
\tilde{z}_N sampled from $Cat_K(\{p_j = \log(\hat{w}_j^{(N-1)} f_j(x_N; \hat{\theta}_j^{(N-1)}))\}_j)$

- Similar to sampling in Stochastic EM [3]
- The motivation is to try to break the inconsistency of k -MLE.

For strategies 1 and 3, the M -Step reduces the update of the parameters for a single component.



- True distribution $\pi = 0.5\mathcal{N}(0, 1) + 0.5\mathcal{N}(\mu_2, \sigma_2^2)$
- Different values for μ_2, σ_2 for more or less overlap between components.
- A small subset of observations has been taken for initialization (k -MLE++ / k -MLE).
- Video illustrating the inconsistency of online k -MLE.





- On consistency:
 - EM, Online EM are consistent
 - k -MLE, online k -MLE (Strategies 1,2) are inconsistent (due to the Bayes error in maximizing the classification likelihood)
 - Online stochastic k -MLE (Strategy 3) : consistency ?
- So, when components overlap, online EM $>$ k -MLE $>$ online k -MLE for parameter learning.
- Need to study how the dimension influences the inconstancy/convergence rate for online k -MLE.
- Convergence rate is lower for online methods (sub-linear convergence of the SGD)
- Time for an update vs sample size:
online k -MLE (1,3) $<$ online EM $<$ online k -MLE (2) \ll k -MLE



online EM appears to be the best compromise !!



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