

From Axioms to Rules:
The Factory of Modal Proof Systems



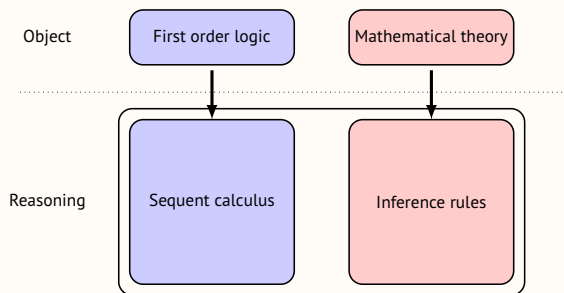
8. Lecture
Synthetic rules in labelled sequents



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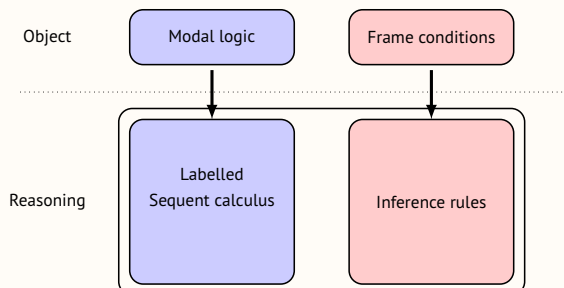
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Remember?



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What if...



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The standard translation

Modal language \Rightarrow **FO language** with:
 - a binary predicate R
 - a unary predicate a for each atom a

$$\begin{aligned} ST_x(a) &= a(x) \\ ST_x(A \wedge B) &= ST_x(A) \wedge ST_x(B) \\ ST_x(\Box A) &= \forall y(R(x, y) \supset ST_y(A)) \\ ST_x(\Diamond A) &= \exists y(R(x, y) \wedge ST_y(A)) \end{aligned}$$

where x is a free variable.

Equivalence

For any modal formula A , any model \mathcal{M} and any world w

$$\mathcal{M}, w \Vdash A \quad \text{iff} \quad \mathcal{M} \models [x/w]ST_x(A)$$

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Delays

Delay operators ∂^+/∂^- force a formula to be **positive** / **negative**.

$$\begin{aligned} \frac{\Gamma \vdash B \Downarrow \Delta}{\Gamma \vdash \partial^+ B \Downarrow \Delta} \partial_R^+ & \quad \frac{\Gamma \Uparrow \Theta, B \vdash \Omega \Uparrow \Delta}{\Gamma \Uparrow \Theta, \partial^+ B \vdash \Omega \Uparrow \Delta} \partial_L^+ \\ \frac{\Gamma \Uparrow \Theta \vdash B, \Omega \Uparrow \Delta}{\Gamma \Uparrow \Theta \vdash \partial^- B, \Omega \Uparrow \Delta} \partial_R^- & \quad \frac{\Gamma \Downarrow B \vdash \Delta}{\Gamma \Downarrow \partial^- B \vdash \Delta} \partial_L^- \end{aligned}$$

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Polarised translation

We define a **translation for labelled sequents**

$$\begin{aligned} [\mathcal{G}_1, \Gamma \vdash \mathcal{G}_2, \Delta] &= [\mathcal{G}_1, \Gamma]_l \vdash [\mathcal{G}_2, \Delta]_r \\ [x : a]_l = [x : a]_r &= a(x) \\ [xRy]_l = [xRy]_r &= R(x, y) \\ [x : A \wedge B]_l &= \partial^+ [x : A]_l \bar{\wedge} \partial^+ [x : B]_l \\ [x : A \wedge B]_r &= \partial^+ ([x : A]_r \bar{\wedge} [x : B]_r) \\ [x : \Box A]_l &= \forall y(R(x, y) \supset \partial^+ [y : A]_l) \\ [x : \Box A]_r &= \partial^+ \forall y(R(x, y) \supset [y : A]_r) \\ [x : \Diamond A]_l &= \partial^- \exists y(R(x, y) \bar{\wedge} [y : A]_l) \\ [x : \Diamond A]_r &= \exists y(R(x, y) \bar{\wedge} \partial^- [y : A]_r) \end{aligned}$$

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Labelled rules are synthesised!

An **inference rule** in the labelled modal proof system corresponds to a **synthetic rule** in the focused proof system LKF.

$$\square \frac{xRy, \mathcal{G}, \Gamma \vdash \Delta, y : A}{\mathcal{G}, \Gamma \vdash \Delta, x : \Box A}$$

$$\begin{array}{l} S_R \frac{\mathcal{G}, \Gamma' \uparrow \vdash \uparrow \Delta', \partial^+[\Box A]_x, \partial^+[A]_y}{\mathcal{G}, \Gamma', R(x, y) \uparrow \vdash \partial^+[A]_y \uparrow \Delta', \partial^+[\Box A]_x} \\ S_L \frac{\mathcal{G}, \Gamma' \uparrow R(x, y) \vdash \partial^+[A]_y \uparrow \Delta', \partial^+[\Box A]_x}{\mathcal{G}, \Gamma' \uparrow \vdash \uparrow \Delta', \partial^+[\Box A]_x} \\ \supset_R \frac{\mathcal{G}, \Gamma' \uparrow \vdash R(x, y) \supset \partial^+[A]_y \uparrow \Delta', \partial^+[\Box A]_x}{\mathcal{G}, \Gamma' \uparrow \vdash \forall y(R(x, y) \supset \partial^+[A]_y) \uparrow \Delta', \partial^+[\Box A]_x} \\ \forall_R \frac{\mathcal{G}, \Gamma' \uparrow \vdash \forall y(R(x, y) \supset \partial^+[A]_y) \uparrow \Delta', \partial^+[\Box A]_x}{\mathcal{G}, \Gamma' \uparrow \vdash \forall y(R(x, y) \supset \partial^+[A]_y) \downarrow \Delta', \partial^+[\Box A]_x} \\ R_R \frac{\mathcal{G}, \Gamma' \uparrow \vdash \forall y(R(x, y) \supset \partial^+[A]_y) \downarrow \Delta', \partial^+[\Box A]_x}{\mathcal{G}, \Gamma' \uparrow \vdash \partial^+ \forall y(R(x, y) \supset \partial^+[A]_y) \downarrow \Delta', \partial^+[\Box A]_x} \\ \partial_R^+ \frac{\mathcal{G}, \Gamma' \uparrow \vdash \partial^+ \forall y(R(x, y) \supset \partial^+[A]_y) \downarrow \Delta', \partial^+[\Box A]_x}{\mathcal{G}, \Gamma' \uparrow \vdash \uparrow \Delta', \partial^+[\Box A]_x} \end{array}$$

Note: in this case, the polarity assigned to $R(x, y)$ does not matter, it can always be stored.

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Alternative synthetic rules

$R(x, y)$ **positive:**

$$\frac{y : A, xRy, \Gamma \vdash \Delta}{x : \Box A, xRy, \Gamma \vdash \Delta} \square_{L1} \quad \frac{xRy, \Gamma \vdash \Delta, y : A}{xRy, \Gamma \vdash \Delta, x : \Diamond A} \diamond_{R1}$$

$R(x, y)$ **negative:**

$$\frac{\Gamma \vdash \Delta, xRy \quad y : A, \Gamma \vdash \Delta}{x : \Box A, \Gamma \vdash \Delta} \square_{L2} \quad \frac{\Gamma \vdash \Delta, xRy \quad \Gamma \vdash \Delta, y : A}{\Gamma \vdash \Delta, x : \Diamond A} \diamond_{R2}$$

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Pre-existing extensions

Horn clauses as bipoles.

$$\forall \bar{z}(P_1 \wedge \dots \wedge P_m \supset Q)$$

$$\forall \bar{z}(P_1^\pm \wedge \dots \wedge P_m^\pm \supset Q^\pm)$$

$$\forall \bar{z}(P_1^+ \wedge \dots \wedge P_m^+ \supset Q^+)$$

$$\forall \bar{z}(P_1^- \wedge \dots \wedge P_m^- \supset Q^-)$$

$$\frac{Q, \Gamma \vdash C}{P_1, \dots, P_m, \Gamma \vdash C} (H1)$$

$$\frac{\Gamma \vdash P_1, \dots, \Gamma \vdash P_m}{\Gamma \vdash Q} (H2)$$

Geometric axioms as bipoles.

$$\forall \bar{z}(P_1 \wedge \dots \wedge P_m \supset \exists \bar{x}_1(\wedge Q_1) \vee \dots \vee \exists \bar{x}_n(\wedge Q_n))$$

$$\forall \bar{z}(P_1^\pm \wedge \dots \wedge P_m^\pm \supset \exists \bar{x}_1(\wedge Q_1^\pm) \vee \dots \vee \exists \bar{x}_n(\wedge Q_n^\pm))$$

$$\forall \bar{z}(P_1^+ \wedge \dots \wedge P_m^+ \supset \exists \bar{x}_1(\wedge Q_1^+) \vee \dots \vee \exists \bar{x}_n(\wedge Q_n^+))$$

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$$\frac{\bar{Q}_1, \Gamma \vdash C \quad \dots \quad \bar{Q}_n, \Gamma \vdash C}{P_1, \dots, P_m, \Gamma \vdash C} (G)$$

In the modal cube

Axiom	Rule scheme 1	Rule scheme 2
t	$\frac{R(x, x), \Gamma \vdash \Delta}{\Gamma \vdash \Delta} t_1$	$\frac{}{\Gamma \vdash \Delta, R(x, x)} t_2$
4	$\frac{R(x, z), \Gamma \vdash \Delta}{R(x, y), R(y, z), \Gamma \vdash \Delta} 4_1$	$\frac{\Gamma \vdash \Delta, R(x, y) \quad \Gamma \vdash \Delta, R(y, z)}{\Gamma \vdash \Delta, R(x, z)} 4_2$
5	$\frac{R(y, z), \Gamma \vdash \Delta}{R(x, y), R(x, z), \Gamma \vdash \Delta} 5_1$	$\frac{\Gamma \vdash \Delta, R(x, y) \quad \Gamma \vdash \Delta, R(x, z)}{\Gamma \vdash \Delta, R(y, z)} 5_2$
b	$\frac{R(y, x), \Gamma \vdash \Delta}{R(x, y), \Gamma \vdash \Delta} b_1$	$\frac{\Gamma \vdash \Delta, R(x, y)}{\Gamma \vdash \Delta, R(y, x)} b_2$