From Axioms to Rules: The Factory of Modal Proof Systems ATT ATT ATT 3. Lecture First-Order Predicate Logic JAT Sonia Marin and Lutz Straßburger Formulas of First-Order Logic Terms and formulas: $t := x \mid f(t_1, \ldots, t_m)$ $A,B \quad ::= \quad \top \mid \perp \mid p(t_1,\ldots,t_n) \mid A \land B \mid A \lor B \mid A \supset B \mid \neg A \mid \forall x.A \mid \exists x.A$ • x is a first-order variable • f is an m-ary function symbol • *p* is an *n*-ary predicate symbol • $\forall x. A \text{ is read as "for all } x, we have A"$ • $\exists x. A$ is read as "there exists a x, such that A" • \forall and \exists are called *quantifiers*

Free and Bound Variables and Substitution

they *bind* the first-order variable *x*.

Definition: The free and bound variable occurrences in a formula are defined inductively as follows.

- x occurs free in an atomic formula A iff x occurs in A. There are *no bound* variables in any atomic formula.
- x occurs free in $\neg A$ iff x occurs free in A. x occurs bound in $\neg A$ iff x occurs bound in A.
- x occurs free in $A \land B$, $A \lor B$, $A \supset B$ iff x occurs free in A or in B. *x* occurs *bound* in $A \land B$, $A \lor B$, $A \supset B$ iff *x* occurs bound in *A* or in *B*.
- x occurs free in $\forall y. A$ or $\exists y. A$, iff x occurs free in A and x is a different variable symbol from y. *x* occurs *bound* in $\forall y. A$ or $\exists y. A$, iff *x* is *y* or *x* occurs bound in *A*.

Substitution:

where

A[x/t] is the result of replacing all free occurrences of x in A by t.

- In the language od first-order logic, we have
 - a countable set $\mathcal{X} = \{x, y, z, \ldots\}$ of first-order variables.
 - a countable set $\mathcal{F} = \{f, g, \ldots\}$ of *m*-ary function symbols (for each $m \ge 0$), and
 - \bullet a countable set $\mathcal{P} = \{p, q, \ldots\}$ of $n\text{-}\mathrm{ary}$ predicate symbols (for each $n \ge 0$).

- In a formula, a variable may occur free or bound (or both). A variable occurrence is *bound* in a formula if it is quantified. Otherwise it is free.
- Exercise 3.1: What are the free and bound variables in the following formulas: • $\forall x. \forall y. (p(x) \supset q(x, f(x), z))$

• $p(x) \supset \forall x. q(x)$

• Exercise 3.2: Let $A = p(x) \supset \forall x. q(x)$. What is A[x/f(y)] ?

Axioms for First-Order Logic

- Axioms for propositional logic (for \supset, \bot):
 - $A \supset (B \supset A)$
 - $(A \supset (B \supset C)) \supset ((A \supset B) \supset (A \supset C))$
 - $((A \supset \bot) \supset \bot) \supset A$
- Axioms for ∀:
 - $(\forall x. (A \supset B)) \supset (A \supset \forall x. B)$ (provided x is not free in A) - $(\forall x. A) \supset A[x/t]$
- The other connectives are defined via \bot, \supset, \forall :
 - $\neg \neg A \equiv A \supset \bot \qquad \exists x. A \equiv \neg \forall x. (\neg A)$
 - $A \lor B \equiv \neg A \supset B \qquad A \land B \equiv \neg (\neg A \lor \neg B)$
- Inference rules:

$$mp \frac{A \qquad A \supset B}{B} \qquad gen$$

Definition: A formula is *provable* (or *a theorem*) if it is either (a substitution instance of) an axiom, or can be derived via an instance of a rule mp or gen from provable formulas.

Semantics for First-Order Logic

Definition: A *model* \mathcal{M} of first order logic is a non-empty set \mathcal{D} (the *domain* of \mathcal{M}) together with an *interpretation* $[\![\cdot]\!]$:

- for each *m*-ary function symbol *f*:
 a function [[*f*]]: D^m → D
- for each *n*-ary predicate symbol *p*: a function [[*p*]]: *Dⁿ* → {true, false}

Definition: Given a model \mathcal{M} , a *variable assignment* μ is a mapping assigning each variable x to an element $\mu(x) \in \mathcal{D}$.

5/15

6/15

4/15

Semantics for First-Order Logic (cont.)

Given a model \mathcal{M} and a variable assignment μ , we can extend the interpretation $[\![\cdot]\!]$ to all terms:

- $\llbracket x \rrbracket = \mu(x)$
- $\llbracket f(t_1,\ldots,t_m) \rrbracket = \llbracket f \rrbracket (\llbracket t_1 \rrbracket,\ldots,\llbracket t_m \rrbracket)$
- and to all formulas:
 - $\llbracket \bot \rrbracket = false$
 - [[⊤]] = true
 - $[\![p(t_1,\ldots,t_n)]\!] = [\![p]\!]([\![t_1]\!],\ldots,[\![t_n]\!])$
 - [A ∧ B]], [A ∨ B]], [A ⊃ B]], [¬A]] as in truth tables for propositional logic
 - [[∀x. A]] = true iff [[A]] = true for every variable assignment μ' with μ'(y) = μ(y) for all variable symbols y different from x.
 - [[∃x. A]] = true iff there is a variable assignment μ' with μ'(y) = μ(y) for all variable symbols y different from x, such that [[A]] = true.

- As for propositional logic, there are many different Hilbert-style systems for first order logic.
- We picked here one that defines only \forall , to keep the list of axioms short. It can be found, for example, in
 - Chang, C.C. and Keisler, H.J.: "Model Theory". North-Holland, Amsterdam, 1973
- Exercise 3.3: Can you prove $\exists x. \forall y. p(x) \supset p(y)$?
- Exercise 3.4: The formula above is also called the *Drinker's formula*. Can you figure out why?

- The definition of $[\forall x. A]$ captures the idea that $\forall x. A$ is true if every possible choice of a value for x causes A to be true.
- The definition of $[\exists x. A]$ captures the idea that $\exists x. A$ is true if there is a possible choice of a value for x such that A is true.

Soundness and Completeness for First-Order Logic

We write $\mathcal{M}, \mu \vDash A$ iff $\llbracket A \rrbracket =$ true for model \mathcal{M} and assignent μ .

Definition: A formula *A* is *satisfiable* if there is a model \mathcal{M} and a variable assignment μ , such that $\mathcal{M}, \mu \models A$.

Definition: A formula *A* is *valid* iff $\mathcal{M}, \mu \models A$ for all models \mathcal{M} and variable assignments μ .

Theorem: (Soundness) Every formula that is provable is also valid.

Theorem: (Completeness) Every formula that is valid is also provable.

Sequent Calculus for First-Order Logic

• Sequents:

$$A_1,\ldots,A_m\vdash B_1,\ldots,B_n$$

Corresponding Formula:

$$(A_1 \wedge \cdots \wedge A_m) \supset (B_1 \vee \cdots \vee B_n)$$

• if m = 0 then the corresponding formula is

$$B_1 \vee \cdots \vee B_n$$
 or $\top \supset (B_1 \vee \cdots \vee B_n)$

• if n = 0 then the corresponding formula is

$$(A_1 \wedge \cdots \wedge A_m) \supset \bot$$
 or $\overline{A}_1 \vee \ldots \vee \overline{A}_n$

• if m = 0 and n = 0 then the corresponding formula is *falsum*:

 $\top \supset \bot \quad \text{or} \quad \bot$

8/15

9/15

Sequent Calculus for First-Order Logic

• Initial sequents / Axioms:

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$$\perp \underbrace{\qquad}_{\perp \vdash} \qquad \text{id} \underbrace{}_{A \vdash A}$$

Structural rules:

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$$\mathsf{veak}_{\mathsf{L}} \frac{\Gamma \vdash \Theta}{A, \Gamma \vdash \Theta} \qquad \mathsf{weak}_{\mathsf{R}} \frac{\Gamma \vdash \Theta}{\Gamma \vdash \Theta, A}$$

$$\operatorname{con}_{\mathsf{L}} \frac{A, A, \Gamma \vdash \Theta}{A, \Gamma \vdash \Theta} \qquad \operatorname{con}_{\mathsf{R}} \frac{\Gamma \vdash \Theta, A, A}{\Gamma \vdash \Theta, A}$$

$$\operatorname{ch}_{\mathsf{L}} \frac{\Delta, B, A, \Gamma \vdash \Theta}{\Delta, A, B, \Gamma \vdash \Theta} \qquad \operatorname{exch}_{\mathsf{R}} \frac{\Gamma \vdash \Theta, A, B, \Lambda}{\Gamma \vdash \Theta, A, B, \Lambda}$$

• Cut:

$$\vdash \Theta, A \qquad A, \Delta \vdash$$

cut

- **Exercise 3.5:** Show that the formula $\forall x. \forall y. p(x) \land p(y)$ is not valid.
- **Exercise 3.6:** Show that $\forall x. p(x) \lor \neg p(x)$ is valid.
- Exercise 3.7: Is $\forall x. \forall y. p(x) \lor p(y)$ valid?
- Exercise 3.8: What about $\forall x. \forall y. p(x) \lor \neg p(y)$?

For the exercises above work only with the models (don't use Soundness/Completeness).

- Exercise 3.9: Prove soundness.
- Completeness for first-order logic is more involved than for modal logics. It has first been shown by Gödel in his PhD thesis:
 - Kurt Gödel: "Die Vollständigkeit der Axiome des logischen Funktionenkalküls". Monatshefte für Mathematik und Physik 37, 1930, p.349-360

- A sequent is essentially a pair of finite lists of formulas. This is how Gentzen introduced them:
 Gerhard Gentzen: "Untersuchungen über das
 - logische Schließen. I". Mathematische Zeitschrift (39), 1935, p.176–210
- Nowadays authors also often use multisets (the order of the formulas is irrelevant) or sets (also the number of occurrences of a formula is irrelevant).

- We use Capital Greek letters, like $\Gamma,\Delta,\Theta,\Lambda,\ldots$ to denote finite lists of formulas.
- The structural rules are called like this because they work on the structure of the sequent. When multisets are used instead of lists, the *exchange* rules **exch_L** and **exch_R** are not needed. And when sets are used instead, the rules for *weakening* (weak_L and weak_R) and *contraction* (con_L and con_R) are not needed.
- However, lists are used in order to have more control over the structure of proofs.
- The *cut* rule can be seen as generalisation of *modus ponens*. The formula *A* in that rule is also called the *cut formula*.

Sequent Calculus for First-Order Logic

• Logical rules:

$$\begin{array}{c} \vee_{\mathsf{L}} \frac{A, \Gamma \vdash \Theta}{A \lor B, \Gamma \vdash \Theta} & \vee_{\mathsf{R}} \frac{\Gamma \vdash \Theta, A}{\Gamma \vdash \Theta, A \lor B} & \vee_{\mathsf{R}} \frac{\Gamma \vdash \Theta, B}{\Gamma \vdash \Theta, A \lor B} \\ \wedge_{\mathsf{L}} \frac{A, \Gamma \vdash \Theta}{A \land B, \Gamma \vdash \Theta} & \wedge_{\mathsf{L}} \frac{B, \Gamma \vdash \Theta}{A \land B, \Gamma \vdash \Theta} & \wedge_{\mathsf{R}} \frac{\Gamma \vdash \Theta, A}{\Gamma \vdash \Theta, A \land B} \\ \supset_{\mathsf{L}} \frac{\Gamma \vdash \Theta, A}{A \supset B, \Gamma \vdash \Theta} & \sim_{\mathsf{R}} \frac{A, \Gamma \vdash \Theta, B}{\Gamma \vdash \Theta, A \supset B} \\ \neg_{\mathsf{L}} \frac{\Gamma \vdash \Theta, A}{\neg A, \Gamma \vdash \Theta} & \neg_{\mathsf{R}} \frac{A, \Gamma \vdash \Theta}{\Gamma \vdash \Theta, \neg A} \\ \forall_{\mathsf{L}} \frac{A[x/t], \Gamma \vdash \Theta}{\forall x. A, \Gamma \vdash \Theta} & \forall_{\mathsf{R}} \frac{\Gamma \vdash \Theta, A}{\Gamma \vdash \Theta, \forall x. A} \text{ x not free in } \Gamma, \Theta \\ \exists_{\mathsf{L}} \frac{A, \Gamma \vdash \Theta}{\exists x. A, \Gamma \vdash \Theta} \text{ x not free in } \Gamma, \Theta & \exists_{\mathsf{R}} \frac{\Gamma \vdash \Theta, A[x/t]}{\Gamma \vdash \Theta, \exists x. A} \end{array}$$

Soundness and Completeness of the Sequent Calculus

- **Definition:** A formula *A* is *provable* in LK if the sequent ⊢ *A* is derivable with the rules shown in the previous two slides.
- **Definition:** A formula *A* is *cut-free provable* in LK if the sequent ⊢ *A* is derivable without the use of the cut-rule.
- **Theorem:** For every formula *A*, the following are equivalent:
 - 1. *A* is a theorem of first-order logic.
 - 2. A is valid.
 - 3. A is provable in LK.
 - 4. A is cut-free provable in LK.

Cut elimination

- Basic idea: permute instances of cut upwards in the proof until they meet an axiom.
 - commutation cases:

$$\operatorname{cut} \frac{\Gamma' \vdash \Theta', A}{\Gamma \vdash \Theta, A} \xrightarrow{A, \Delta \vdash \Lambda} \quad \rightsquigarrow \quad \operatorname{cut} \frac{\Gamma' \vdash \Theta', A \xrightarrow{A, \Delta \vdash \Lambda}}{\Gamma, \Delta \vdash \Theta, \Lambda}$$

• key cases:

- The side condition that x must not be free in Γ and Θ in the rules \forall_R and \exists_L is important to avoid *variable capturing*. In these two rules, the variable x is called *Eigenvariable*.
- In the rules \forall_L and \exists_R , the term t is arbitrary. It might or might not contain x.
- \bullet Gentzen called this calculus $\mathsf{LK}.$
- Observe that while in Hilbert systems there are many axioms and only a few rules, in the sequent calculus we have only a few (trivial) axioms and many rules. This is what allows us to eventually get more control over the structure of proofs.
- **Exercise 3.10:** Are the following fromulas provable in the sequent calculus?
 - $\forall x. p(x) \lor \neg p(x)$
 - $\forall x. \forall y. p(x) \lor p(y)$
 - $\forall x. \forall y. p(x) \lor \neg p(y)$
 - ∃x. ∀y. p(x) ∨ ¬p(y)
 ∀x. ∃y. p(x) ∨ ¬p(y)
- Exercise 3.11: Prove $1 \Longrightarrow 3$.

10/15

11/15

- Exercise 3.12: Prove $3 \Longrightarrow 2$.
- The implication $3 \Longrightarrow 4$ is Gentzen's contribution, proved in
 - Gerhard Gentzen: "Untersuchungen über das logische Schließen. I". Mathematische Zeitschrift (39), 1935, p.176–210

 $(4 \Longrightarrow 3 \text{ is trivial.})$

- With this theorem, completess is easier to show, as it is shown via contrapositive: ¬4 ⇒ ¬2 is simpler than ¬3 ⇒ ¬2 or ¬1 ⇒ ¬2.
- The implication $3 \implies 4$ is also known as *cut elimination*.

- Exercise 3.13: Write down all key cases.
- Exercise 3.14: What would be the base case?

Cut elimination (cont.)

• cut meets structural rules:

cases for weakening:

$$\operatorname{weak}_{\mathsf{R}} \underbrace{\frac{\Gamma \vdash \Theta}{\Gamma \vdash \Theta, A}}_{\mathsf{Cut}} \underbrace{\begin{array}{c} A, \Delta \vdash \Lambda \\ \overline{\Gamma, \Delta \vdash \Theta, \Lambda} \end{array}}_{\mathsf{R}, \Delta \vdash \Theta, \Lambda} \quad \rightsquigarrow \quad \operatorname{weak}_{\mathsf{R}} \underbrace{\begin{array}{c} \Gamma \vdash \Theta \\ \overline{\Gamma \vdash \Theta, \Lambda} \end{array}}_{\mathsf{Weak}_{\mathsf{L}}} \underbrace{\begin{array}{c} \overline{\Gamma \vdash \Theta, \Lambda} \\ \overline{\Gamma, \Delta \vdash \Theta, \Lambda} \end{array}}_{\mathsf{R}, \Delta \vdash \Theta, \Lambda}$$

• cases for contraction:

$$\operatorname{con}_{\mathsf{R}} \frac{\Gamma \vdash \Theta, A, A}{\operatorname{Cut}} \xrightarrow{\boldsymbol{\Gamma} \vdash \Theta, A, A} A, \Delta \vdash \Lambda}{\Gamma, \Delta \vdash \Theta, \Lambda} \xrightarrow{\quad \leftrightarrow} \operatorname{Cut} \frac{\frac{\Gamma \vdash \Theta, A, A}{\operatorname{Cut}} \xrightarrow{\boldsymbol{A}, \Delta \vdash \Lambda}}{\operatorname{Cut}} \xrightarrow{\begin{array}{c} \Gamma, \Delta \vdash \Theta, A, \Lambda \\ \hline \Gamma, \Delta \vdash \Theta, \Lambda, A \\ \operatorname{Cut} \\ \hline \hline \Gamma, \Delta \vdash \Theta, \Lambda, \Lambda \\ \operatorname{Con}_{\mathsf{R}} \\ \hline \hline \Gamma, \Delta, \Delta \vdash \Theta, \Lambda \\ \operatorname{Con}_{\mathsf{L}} \\ \hline \hline \Gamma, \Delta, \Delta \vdash \Theta, \Lambda \\ \hline \hline \Gamma, \Delta \vdash \Theta, \Lambda \end{array}} \xrightarrow{\quad \leftrightarrow} \operatorname{Cut} \operatorname$$

13/15

Cut elimination (cont.)

• *the super-cut rule:*

$$\mathsf{scut}\,\frac{{\displaystyle \Gamma\vdash\Theta'\quad\Delta'\vdash\Lambda}}{{\displaystyle \Gamma,\Delta\vdash\Theta,\Lambda}}$$

where

- Θ' and Δ' are list of formulas that both contain at least once the cut formula A.
- Θ and Δ are obtained from Θ' and Δ' , respectively, by removing all occurrences of the cut formula *A*.

14/15

- Because of the contraction cases, this naive cut elimination process is not terminating.
- **Exercise 3.15:** To see this, write down the reduction for this case:

$$\operatorname{con}_{\mathsf{R}} \frac{\Gamma \vdash \Theta, A, A}{\Gamma \vdash \Theta, A} \quad \operatorname{con}_{\mathsf{L}} \frac{A, A, \Delta \vdash \Lambda}{A, \Delta \vdash \Lambda}$$
$$\operatorname{cut} \frac{\Gamma, \Delta \vdash \Theta, \Lambda}{\Gamma, \Delta \vdash \Theta, \Lambda}$$

- $\bullet\,$ Note that the cut rule is a special case of the $\mathsf{scut}\,$ rule.
- The scut rule and its variations have many different names in the literature. Gentzen called it *Mischung*. Therefore it is often called *Mix* or *Merge*. Very common is also *multi-cut* because multiple occurrences of the cut formula occur in the premises.
- **Exercise 3.16:** Write down the super-cut reduction cases for the structural rules. What do you observe?
- **Exercise 3.17:** Write down the key cases for super-cut. What do you observe?