

LIX, ÉCOLE POLYTECHNIQUE



Software Modelling and Architecture: Exercises

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Contents

1	Introduction	7
1.1	Structure of this book	7
2	UML exercises	9
2.1	Use case diagrams	9
2.1.1	Simplified ATM machine	9
2.1.2	Vending machine	9
2.2	Sequence diagrams	10
2.2.1	The norm of a vector	10
2.2.2	Displaying graphical objects	11
2.2.3	Vending machine	12
2.3	Class diagrams	13
2.3.1	Complex number class	13
2.3.2	Singly linked list	19
2.3.3	Doubly linked list	20
2.3.4	Binary tree	20
2.3.5	n -ary tree	20
2.3.6	Vending machine	21
3	Modelling	23
3.1	The vending machine revisited	23
3.1.1	Solution	23
3.2	Mistakes in modelling a tree	23
3.2.1	Solution	27
4	Mathematical programming exercises	29

4.1	Museum guards	29
4.1.1	Solution	30
4.2	Mixed production	32
4.2.1	Solution	32
4.3	Checksum	34
4.3.1	Solution	36
4.4	Network Design	39
4.4.1	Solution	40
4.5	Error correcting codes	43
4.5.1	Solution	43
4.6	Selection of software components	44
4.6.1	Solution	44
5	Log analysis architecture	47
5.1	Definitions	47
5.2	Software goals	47
5.3	Requirements	48
5.3.1	User interaction	48
5.3.2	Log file reading	48
5.3.3	Computation and statistics	48
5.4	The software architecture	48
5.4.1	Summary	49
5.4.2	Details	51
6	A search engine for projects	57
6.1	The setting	57
6.2	Initial offer	58
6.2.1	Kick-off meeting	58
6.2.2	Brainstorming meeting	59
6.2.3	Formalization of a commercial offer	61
6.3	System planning	63
6.3.1	Understanding T-Sale's database structure	63
6.3.2	Brainstorming: Ideas proposal	65

6.3.3	Functional architecture	66
6.3.4	Technical architecture	74

Chapter 1

Introduction

This exercise book is meant to go with the course INF561 given at École Polytechnique by Prof. D. Krob. The current course edition is 1st semester 2007/2008. It contains a series of exercises in software modelling and architecture.

1.1 Structure of this book

Software modelling and software architecture are concepts needed when planning complex software systems. The book will focus on exercises to be carried out by means of the UML language, some notions of optimization, and a good deal of common sense. One becomes a good software architect by experience.

Chapter 2 focuses on simple UML exercises. It is split in Sections 2.1 (use case diagrams), 2.2 (sequence diagrams) and 2.3 (class diagrams). Chapter 3 groups various modelling exercises, only some of which involve UML. Chapters 5 and 6 are large scale exercises that should give meaningful examples on various modelling techniques in practice (these sometimes employ UML-like diagrams, but are not based on UML). Since some of the large scale exercises use mathematical programming techniques, there is a small collection of exercises on mathematical programming in Chapter 4.

Chapter 2

UML exercises

This chapter proposes small to medium scale exercises on UML. Some of them are by the author, whilst others have been taken from books (credits are made explicit in each exercise: where no explicit citation is given, the exercise is to be considered the author's work).

2.1 Use case diagrams

In this section we give some examples of use case diagrams for various situations.

2.1.1 Simplified ATM machine

Propose a use case diagram for an ATM machine for withdrawing cash. Make the use case simple yet informative; only include the major features.

2.1.1.1 Solution

The use case diagram is given in Fig. 2.1 (taken from [7], Fig. 16.5).

2.1.2 Vending machine

Propose a use case diagram for a vending machine that sells beverages and snacks. Make use of inclusion and extension associations, mark multiplicities and remember that a vending machine may need technical assistance from time to time.

2.1.2.1 Solution

The use case diagram is given in Fig. 2.2. We remark that the “+” character in front of multiplicities should not be there and that the {xor} constraint should be marked by a dashed segment rather than a box (the `umbrello` UML modeller that comes with the KDE linux desktop has some bugs and limitations).

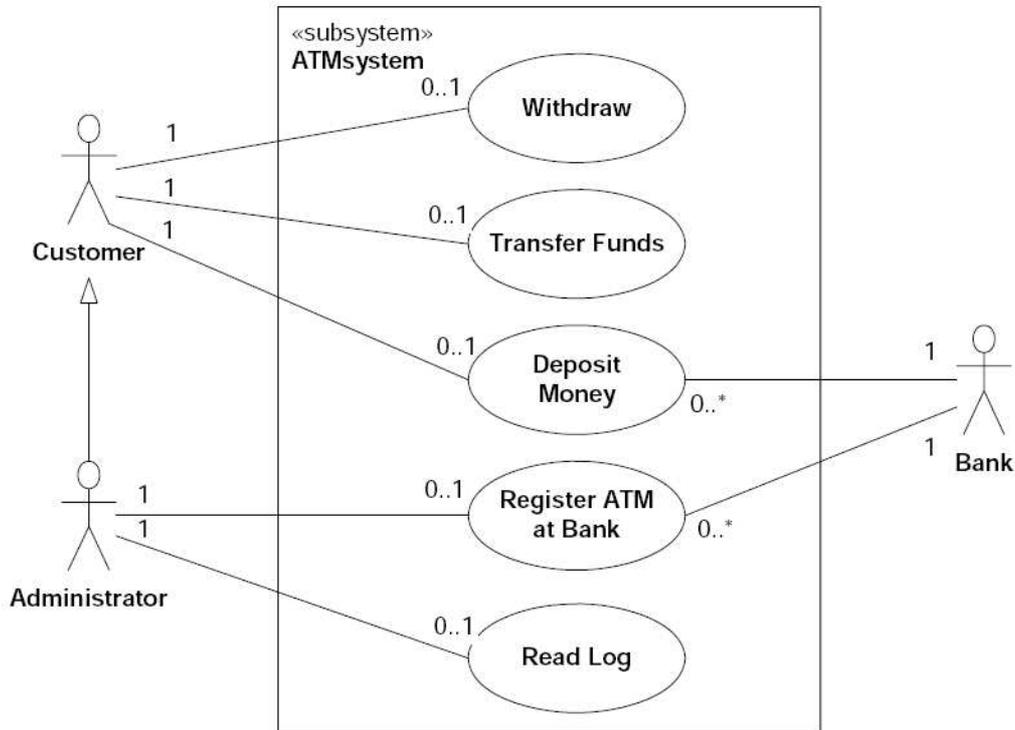


Figure 2.1: The simplified use case diagram of an ATM.

2.2 Sequence diagrams

In this section we shall present some easy examples of sequence diagrams.

2.2.1 The norm of a vector

Consider the following algorithm for computing the norm of a vector.

```

Class Array {
    ...
    public:

    // return the index-th component of the array
    double get(int index);
    ...
};

double norm(const Array& myArray) {
    double theNorm = 0;
    for(int index = 0; index < myArray.size() - 1; index++) {
        theNorm = theNorm + myArray.get(index);
    }
    theNorm = sqrt(theNorm);
    return theNorm;
}

```

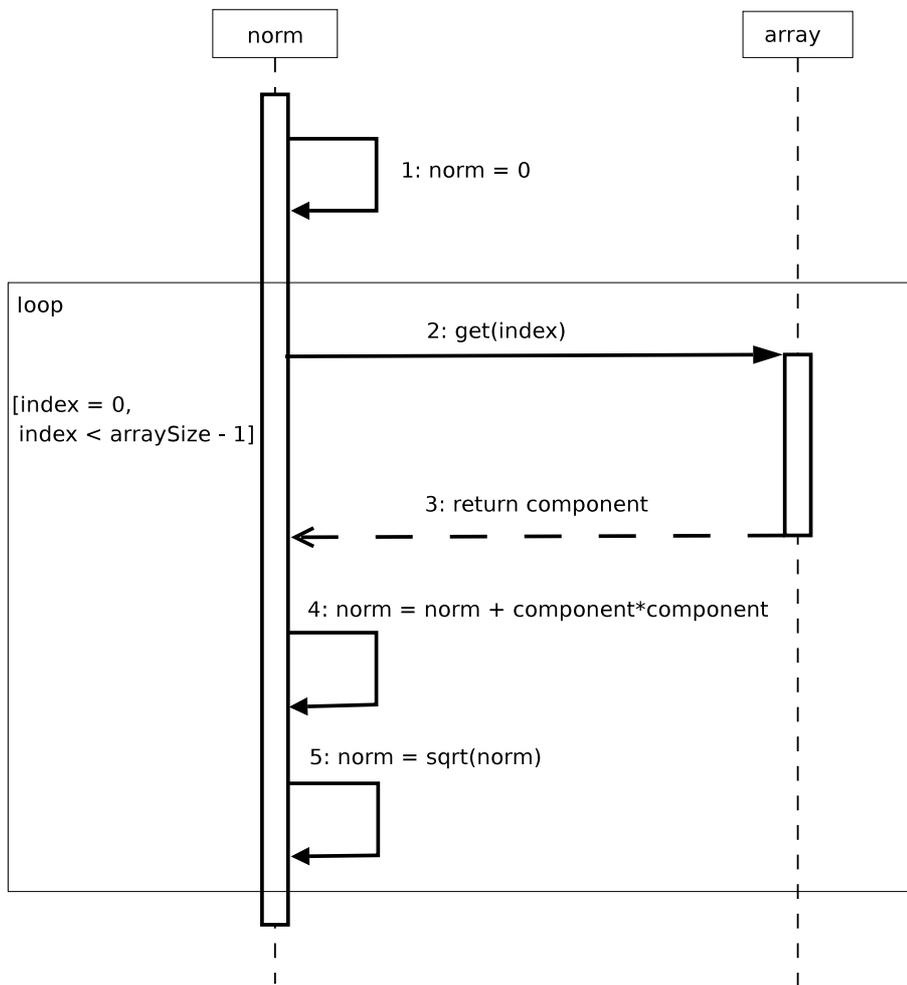



Figure 2.3: The sequence diagram describing the computation of the norm of a vector.

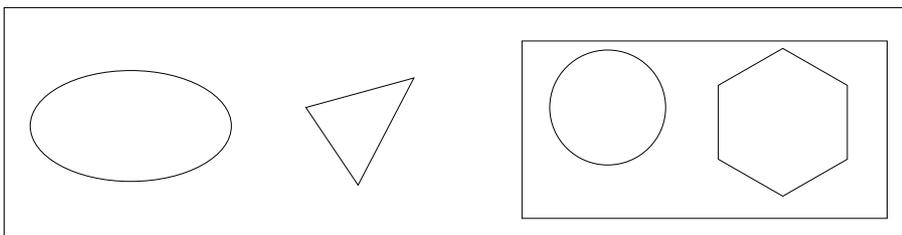


Figure 2.4: The sequence diagram describing the computation of the norm of a vector.

2.2.3 Vending machine

Draw a sequence diagram for the vending machine of Sect. 2.1.2.

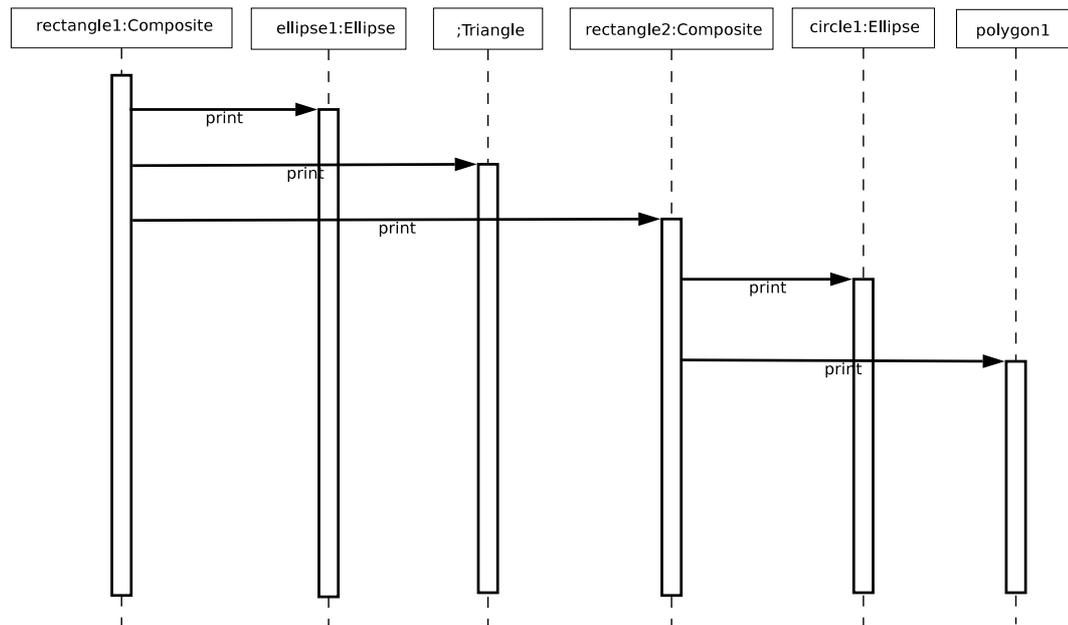


Figure 2.5: The sequence diagram describing the printing of the drawing in Fig. 2.4.

2.2.3.1 Solution

The sequence diagram in Fig. 2.6 describes the required behaviour.

2.3 Class diagrams

In this section we present some elementary exercises on class diagrams.

2.3.1 Complex number class

Draw a class diagram for the single class `Complex`. A `Complex` object has a private real and an imaginary part (of type `double`), and can perform addition, subtraction, multiplication and division by another complex number.

2.3.1.1 Solution

The class diagram for the `Complex` class is given in Fig. 2.7.

Most UML modellers can be used to automatically generate C++ (or Java) code from the class diagram. This results in “class skeleton” files (a header file `Complex.h` and a corresponding implementation file `Complex.cpp`). Both are given below.

```

/*****
                                Complex.h.h - Copyright liberti
  
```

```

Here you can write a license for your code, some comments or any other
information you want to have in your generated code. To to this simply
  
```

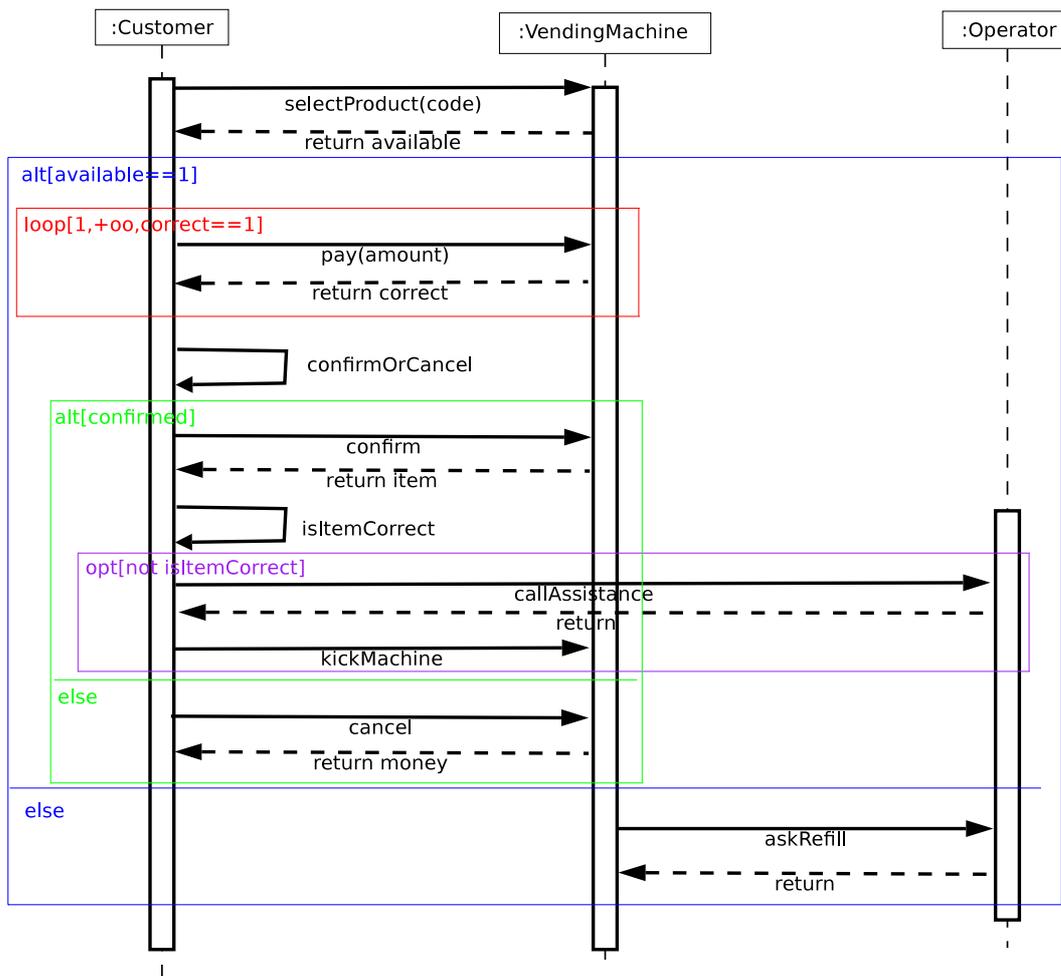


Figure 2.6: The sequence diagram for the vending machine of Sect. 2.1.2.

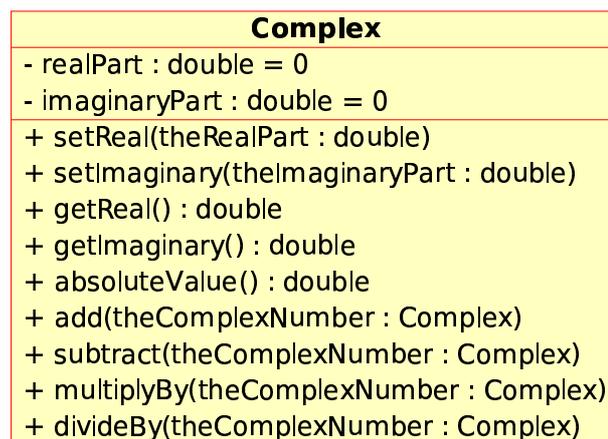


Figure 2.7: The class diagram for a complex number.

configure the "headings" directory in uml to point to a directory where you have your heading files.

or you can just replace the contents of this file with your own.
If you want to do this, this file is located at

/usr/share/apps/umbrello/headings/heading.h

-->Code Generators searches for heading files based on the file extension
i.e. it will look for a file name ending in ".h" to include in C++ header
files, and for a file name ending in ".java" to include in all generated
java code.
If you name the file "heading.<extension>", Code Generator will always
choose this file even if there are other files with the same extension in the
directory. If you name the file something else, it must be the only one with that
extension in the directory to guarantee that Code Generator will choose it.

you can use variables in your heading files which are replaced at generation
time. possible variables are : author, date, time, filename and filepath.
just write %variable_name%

This file was generated on %date% at %time%

*****/

```
#ifndef COMPLEX_H
#define COMPLEX_H

#include <string>

/**
 * class Complex
 */

class Complex
{
public:

    // Constructors/Destructors
    //

    /**
     * Empty Constructor
     */
    Complex ( );

    /**
     * Empty Destructor
     */
    virtual ~Complex ( );

    // Static public attributes
    //

    // public attributes
    //

    // public attribute accessor methods
    //

    // public attribute accessor methods
    //

    /**
     * @param theRealPart
     */
    void setReal (double theRealPart );

    /**
     * @param theImaginaryPart
     */
    void setImaginary (double theImaginaryPart );

    /**
     * @return double
     */

```

```
double getReal ( );

/**
 * @return double
 */
double getImaginary ( );

/**
 * @return double
 */
double absoluteValue ( );

/**
 * @param theComplexNumber
 */
void add (Complex theComplexNumber );

/**
 * @param theComplexNumber
 */
void subtract (Complex theComplexNumber );

/**
 * @param theComplexNumber
 */
void multiplyBy (Complex theComplexNumber );

/**
 * @param theComplexNumber
 */
void divideBy (Complex theComplexNumber );

protected:

    // Static protected attributes
    //

    // protected attributes
    //

public:

    // protected attribute accessor methods
    //

protected:

public:

    // protected attribute accessor methods
    //

protected:

private:

    // Static private attributes
    //

    // private attributes
    //

    double m_realPart;
    double m_imaginaryPart;
public:

    // private attribute accessor methods
    //

private:
```

```

public:

    // private attribute accessor methods
    //

    /**
     * Set the value of m_realPart
     * @param new_var the new value of m_realPart
     */
    void setRealPart ( double new_var );

    /**
     * Get the value of m_realPart
     * @return the value of m_realPart
     */
    double getRealPart ( );

    /**
     * Set the value of m_imaginaryPart
     * @param new_var the new value of m_imaginaryPart
     */
    void setImaginaryPart ( double new_var );

    /**
     * Get the value of m_imaginaryPart
     * @return the value of m_imaginaryPart
     */
    double getImaginaryPart ( );

private:

    void initAttributes ( ) ;

};

#endif // COMPLEX_H

/*****
Complex.h.cpp - Copyright liberti

Here you can write a license for your code, some comments or any other
information you want to have in your generated code. To to this simply
configure the "headings" directory in uml to point to a directory
where you have your heading files.

or you can just replace the contents of this file with your own.
If you want to do this, this file is located at

/usr/share/apps/umbrello/headings/heading.cpp

-->Code Generators searches for heading files based on the file extension
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If you name the file "heading.<extension>", Code Generator will always
choose this file even if there are other files with the same extension in the
directory. If you name the file something else, it must be the only one with that
extension in the directory to guarantee that Code Generator will choose it.

you can use variables in your heading files which are replaced at generation
time. possible variables are : author, date, time, filename and filepath.
just write %variable_name%

This file was generated on %date% at %time%
*****/

#include "Complex.h"

// Constructors/Destructors
//

Complex::Complex ( ) {
initAttributes();
}

Complex::~Complex ( ) { }

```

```
//  
// Methods  
//  
  
// Accessor methods  
//  
  
// public static attribute accessor methods  
//  
  
// public attribute accessor methods  
//  
  
// protected static attribute accessor methods  
//  
  
// protected attribute accessor methods  
//  
  
// private static attribute accessor methods  
//  
  
// private attribute accessor methods  
//  
  
/**  
 * Set the value of m_realPart  
 * @param new_var the new value of m_realPart  
 */  
void Complex::setRealPart ( double new_var ) {  
    m_realPart = new_var;  
}  
  
/**  
 * Get the value of m_realPart  
 * @return the value of m_realPart  
 */  
double Complex::getRealPart ( ) {  
    return m_realPart;  
}  
  
/**  
 * Set the value of m_imaginaryPart  
 * @param new_var the new value of m_imaginaryPart  
 */  
void Complex::setImaginaryPart ( double new_var ) {  
    m_imaginaryPart = new_var;  
}  
  
/**  
 * Get the value of m_imaginaryPart  
 * @return the value of m_imaginaryPart  
 */  
double Complex::getImaginaryPart ( ) {  
    return m_imaginaryPart;  
}  
  
// Other methods  
//  
  
/**  
 * @param theRealPart  
 */  
void Complex::setReal (double theRealPart ) {  
  
}  
  
/**  
 * @param theImaginaryPart  
 */
```

```
void Complex::setImaginary (double theImaginaryPart ) {  
}  
  
/**  
 * @return double  
 */  
double Complex::getReal ( ) {  
}  
  
/**  
 * @return double  
 */  
double Complex::getImaginary ( ) {  
}  
  
/**  
 * @return double  
 */  
double Complex::absoluteValue ( ) {  
}  
  
/**  
 * @param theComplexNumber  
 */  
void Complex::add (Complex theComplexNumber ) {  
}  
  
/**  
 * @param theComplexNumber  
 */  
void Complex::subtract (Complex theComplexNumber ) {  
}  
  
/**  
 * @param theComplexNumber  
 */  
void Complex::multiplyBy (Complex theComplexNumber ) {  
}  
  
/**  
 * @param theComplexNumber  
 */  
void Complex::divideBy (Complex theComplexNumber ) {  
}  
  
void Complex::initAttributes ( ) {  
    m_realPart = 0;  
    m_imaginaryPart = 0;  
}
```

2.3.2 Singly linked list

Draw a class diagram representing a singly linked list.

2.3.2.1 Solution

The class diagram is given in Fig. 2.8. It consists of a class with a single unidirectional association (`next`) with multiplicity 1, because a node of a singly linked list only has one neighbouring node (the next node).

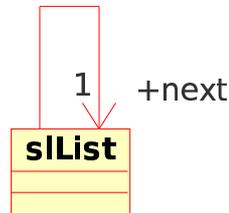


Figure 2.8: The class diagram of a singly linked list.

2.3.3 Doubly linked list

Draw a class diagram representing a doubly linked list.

2.3.3.1 Solution

The class diagram is given in Fig. 2.9. It consists of a class with a single bidirectional association with reference names `previous` and `next` both with multiplicity 1, because a doubly linked list has a previous and a next node.

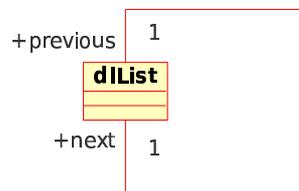


Figure 2.9: The class diagram of a doubly linked list.

2.3.4 Binary tree

Draw a class diagram representing a binary tree.

2.3.4.1 Solution

The class diagram is given in Fig. 2.10. It consists of a class with a single bidirectional association with reference names `child` (with multiplicity 2) and `parent` (with multiplicity 1), because a binary tree has two children and one parent node.

2.3.5 *n*-ary tree

Draw a class diagram representing an *n*-ary tree (a tree with a variable number of children nodes).

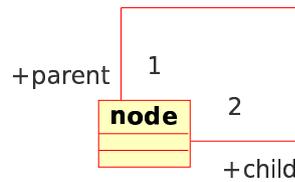
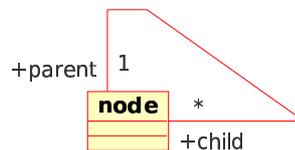


Figure 2.10: The class diagram of a binary tree.

2.3.5.1 Solution

The class diagram is given in Fig. 2.11. It consists of a class with a single bidirectional association with reference names `child` (with multiplicity `*`) and `parent` (with multiplicity `1`), because a binary tree has a variable number of children and one parent node.

Figure 2.11: The class diagram of an n -ary tree.

2.3.6 Vending machine

Draw a class diagram for the vending machine described in Sect. 2.1.2 and 2.2.3.

2.3.6.1 Solution

The class diagram is given in Fig. 2.12.

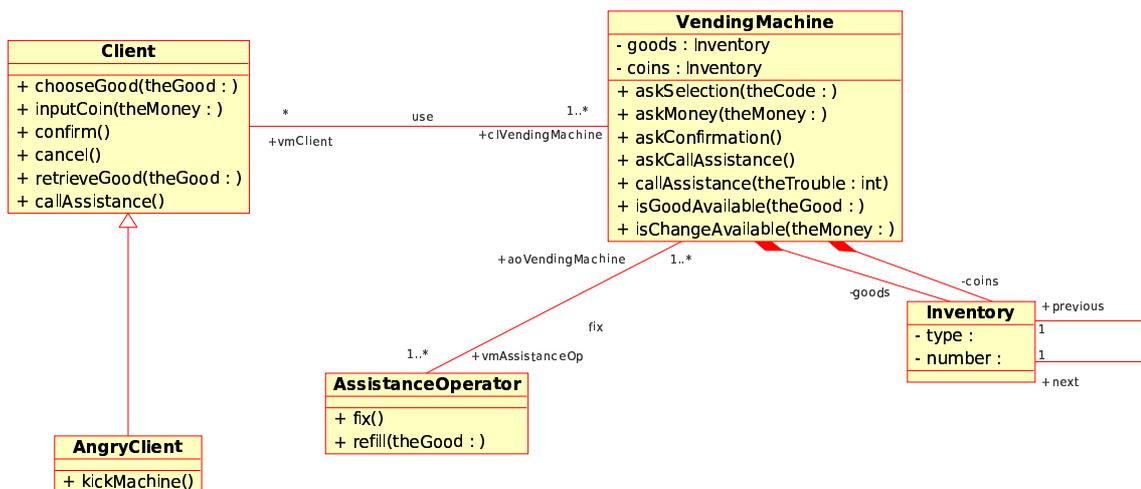


Figure 2.12: The class diagram of a vending machine.

Chapter 3

Modelling

This chapter groups some modelling exercises, only some of which involve UML.

3.1 The vending machine revisited

Consider the vending machine described in Sect. 2.1.2, 2.2.3 and 2.3.6. The proposed use case diagram (Fig. 2.2), sequence diagram (Fig. 2.6) and class diagram (Fig. 2.12) make up for a very poor system modelling indeed. The vending machine is always thought of as a monolithic entity: this makes the external relationships clear but says nothing about how to plan and build one. In particular, the monolithic view is incompatible with the fact that a vending machine is composed of different parts. Given the following list of parts:

1. main controller
2. mechanical robot
3. coin acceptor
4. remote messaging system
5. door

and the fact that 2,3,4,5 can only be interfaced with 1, draw a use case diagram and a sequence diagram to provide an initial blueprint for the inner workings of a vending machine.

3.1.1 Solution

The use case diagram is found in Fig. 3.1. The sequence diagram is found in Fig. 3.2. Notice that they do not provide mechanisms for calling assistance operators on failure of providing change and/or food. How should these diagrams change to cater for these occurrences?

3.2 Mistakes in modelling a tree

Fig. 3.3 describes the class diagram of a tree node, which can be used recursively to build an expression tree.



Figure 3.1: The revised use case diagram of the vending machine.

Generate the header file and implementation code using Umbrello, then add the implementation of the only non-obvious functions (`getNumberOfChildren` and `getChildType`) as follows:

```

int TreeNode::getNumberOfChildren ( ) {
    // number of children
    int nc = 0;
    switch(m_operatorLabel) {
    case 0: // sum
        nc = 2;
        break;
    case 1: // difference
        nc = 2;
        break;
    case 2: // multiplication
        nc = 2;
        break;
    case 3: // division
        nc = 2;
        break;
    case 4: // square
        nc = 1;
        break;
    case 5: // cube
        nc = 1;
        break;
    }
}

```

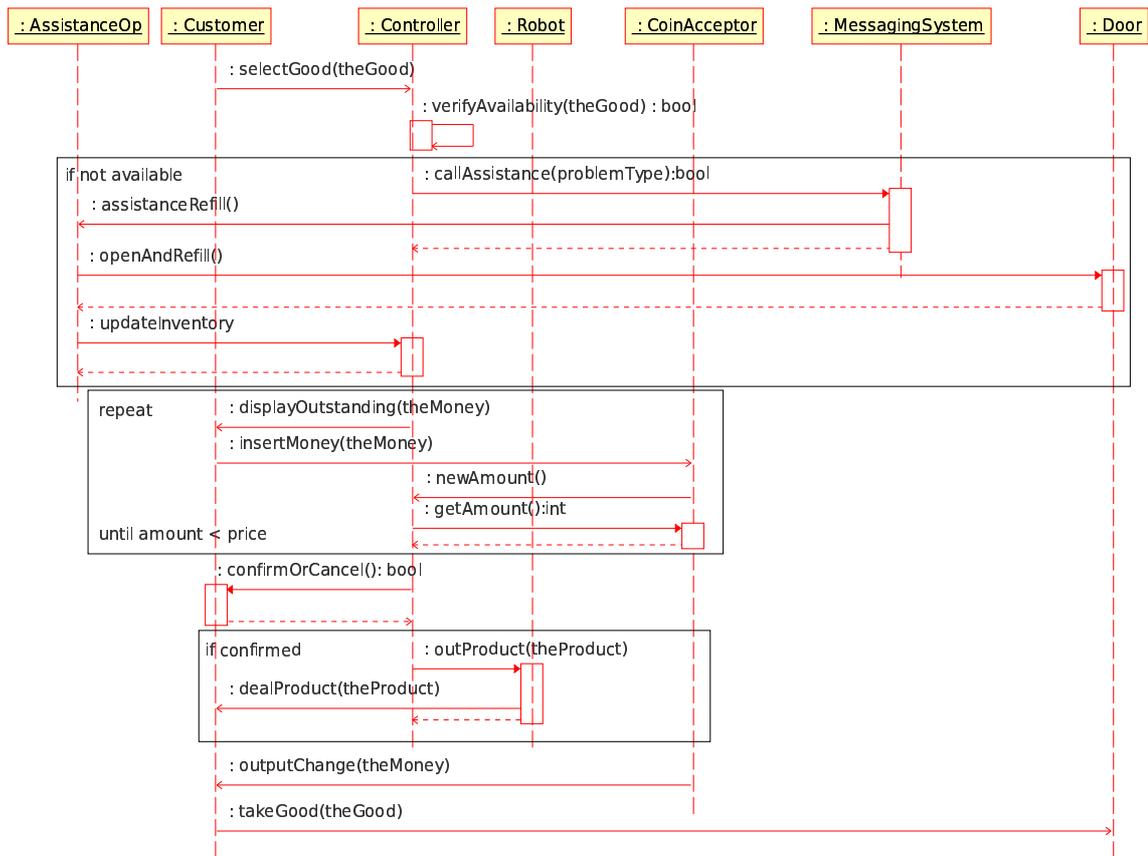
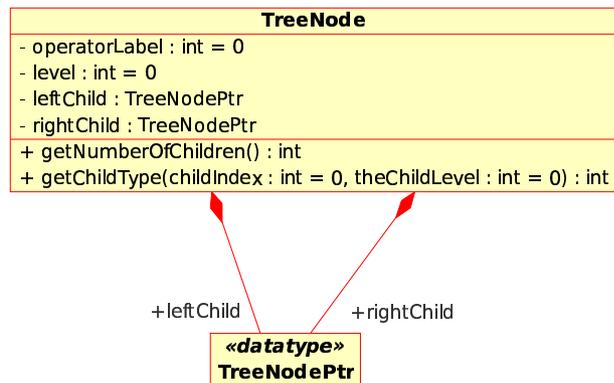


Figure 3.2: The revised sequence diagram of a vending machine.

Figure 3.3: The UML class diagram for the `TreeNode` class.

```

case 6: // sqrt
    nc = 1;
    break;
case 10: // number
    nc = 0;
    break;
default:
    break;
  
```

```

    }
    return nc;
}

int TreeNode::getChildType (int childIndex, int theChildLevel) {
    int ret = -1;
    // increase the level by one unit
    theChildLevel++;
    if (childIndex == 0) {
        // left child
        ret = m_leftChild->getOperatorLabel();
    } else if (childIndex == 1) {
        // right child
        ret = m_rightChild->getOperatorLabel();
    }
    return ret;
}

```

Now consider the following main function in the file `TreeNode_main.cxx`:

```

// TreeNode_main.cxx

#include <iostream>
#include "TreeNode.h"

int main(int argc, char** argv) {

    int ret = 0;

    // expression tree t: number + number^2
    TreeNode t;
    t.setOperatorLabel(0);
    t.setLevel(0);
    t.setLeftChild(new TreeNode);
    t.setRightChild(new TreeNode);
    t.getLeftChild()->setOperatorLabel(10);
    t.getLeftChild()->setLevel(1);
    t.getRightChild()->setOperatorLabel(4);
    t.getRightChild()->setLevel(1);
    t.getRightChild()->setLeftChild(new TreeNode);
    t.getRightChild()->getLeftChild()->setOperatorLabel(10);
    t.getRightChild()->getLeftChild()->setLevel(2);

    // get right child type and level
    int theLevel = 0;
    int theOperatorLabel = -1;
    theOperatorLabel = t.getChildType(1, theLevel);

    // expect theOperatorLabel = 4, theLevel = 1;
    std::cout << theOperatorLabel << ", " << theLevel << std::endl;
    // actual output is 4,0

    return ret;
}

```

Compile the project by typing:

```
c++ -o TreeNode TreeNode_main.cxx TreeNode.cpp
```

and verify whether the output is as expected (4, 1). If not, why? Is this a bug or a modelling error?

We would now like to code in `TreeNode.main.cxx` a new function that accepts a tree node and returns the number of children of the root node of the expression tree. Convince yourself that you cannot do this easily, and explain why. How can you fix this modelling error? Change the UML diagram and the code accordingly.

3.2.1 Solution

The output is 4, 0. The problem is given by the fact that the second argument of `getChildType`, that is, `theLevel`, was not declared as an *inout* (read/write) parameter but as an *in* (read only) parameter instead, so it cannot be changed by the function itself (notice the compiler issues no warning about this occurrence: it is perfectly legal syntactically if not semantically).

The new function cannot be coded in because the model provide no mechanism for going from a given node to its parent node, much less the root node of the tree. The correct UML class diagram is given in Fig. 3.4.

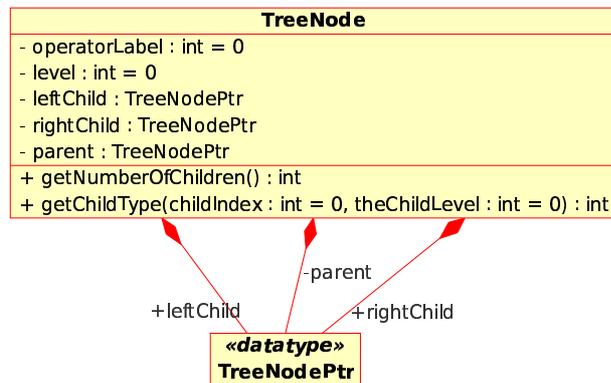


Figure 3.4: The corrected UML class diagram for the `TreeNode` class.

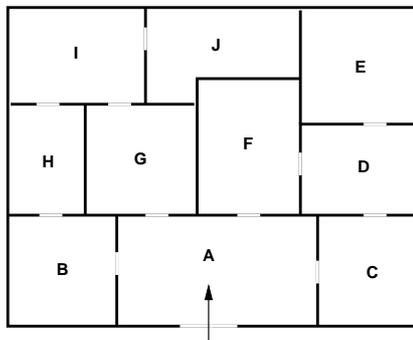
Chapter 4

Mathematical programming exercises

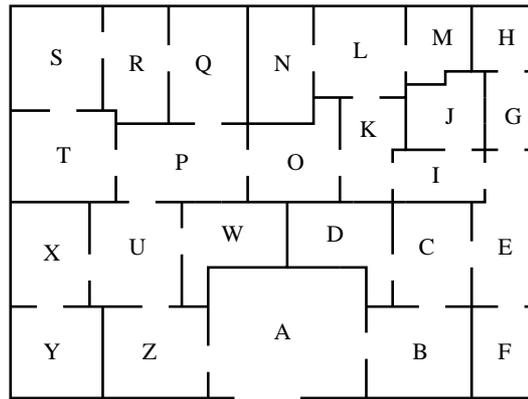
The mathematical programming formulation language is a very powerful tool used to formalize optimization problems by means of parameters, decision variables, objective functions and constraints. Such diverse settings as combinatorial, integer, continuous, linear and nonlinear optimization problems can be defined precisely by their corresponding mathematical programming formulations. Its power is not limited to its expressiveness, but usually allows hassle-free solution of the problem: most general-purpose solution algorithms solve optimization problems cast in their mathematical programming formulation, and the corresponding implementations can usually be hooked into language environments which allow the user to input and solve complex optimization problems easily. This chapter provides an introduction (by way of examples) to a mathematical programming software system, called AMPL (A Mathematical Programming Language) [6] which is interfaced with continuous mixed-integer linear (CPLEX [8]) and nonlinear solvers. See www.ampl.com for details on downloading and installing the student versions of AMPL and CPLEX.

4.1 Museum guards

A museum director must decide how many guards should be employed to control a new wing. Budget cuts have forced him to station guards at each door, guarding two rooms at once. Formulate a mathematical program to minimize the number of guards. Solve the problem on the map below using AMPL.



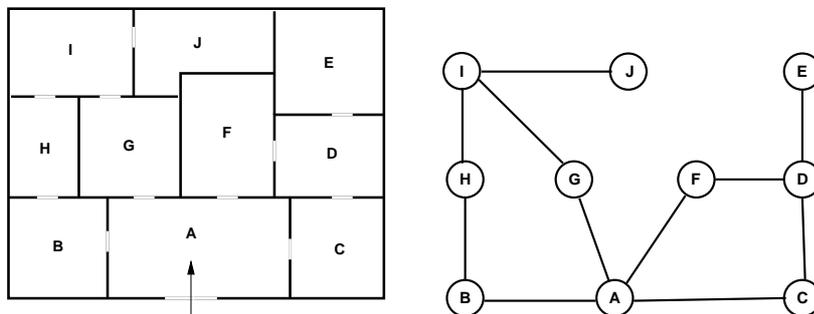
Also solve the problem on the following map.



[P. Belotti, Carnegie Mellon University]

4.1.1 Solution

The problem can be formalized by representing each museum room by a vertex $v \in V$ of an undirected graph $G = (V, E)$. There is an edge between two vertices if there is a door leading from one room to the other; this way, edges represent the possibility of there being a guard on a door. We want to choose the smallest subset $F \subseteq E$ of edges *covering* all vertices, i.e. such that for all $v \in V$ there is $w \in V$ with $\{v, w\} \in F$.



To each $\{i, j\} \in E$ we associated a binary variable x_{ij} is assigned the value 1 if there is a guard on the door represented by edge $\{i, j\}$ and 0 otherwise.

4.1.1.1 Formulation

- *Parameters.* $G = (V, A)$: graph description of the museum topology.
- *Variables.* x_{ij} : 1 if edge $\{i, j\} \in E$ is to be included in F , 0 otherwise.
- *Objective function*

$$\min \sum_{\{i,j\} \in E} x_{ij}$$

- *Constraints.* (Vertex cover): $\sum_{j \in V: \{i,j\} \in E} x_{ij} \geq 1 \quad \forall i \in V$.

4.1.1.2 AMPL model, data, run

```
# museum.mod

param n >= 0, integer;
set V := 1..n;
set E within {V,V};
var x{E} binary;
minimize cost : sum{(i,j) in E} x[i,j];
subject to vertexcover {i in V} :
    sum{j in V : (i,j) in E} x[i,j] + sum{j in V : (j,i) in E} x[j,i] >= 1;

# museum.dat

param n := 10;
set E :=
    1 2
    1 3
    1 6
    1 7
    2 8
    3 4
    4 5
    7 9
    8 9
    9 10 ;

# museum.run

model museum.mod;
data museum.dat;
option solver cplexstudent;
solve;
display cost;
display x;
```

4.1.1.3 CPLEX solution

```
CPLEX 7.1.0: optimal integer solution; objective 6
2 MIP simplex iterations
0 branch-and-bound nodes
cost = 6

x :=
1 2    0
1 3    1
1 6    1
1 7    1
2 8    1
3 4    0
4 5    1
7 9    0
8 9    0
9 10   1
;
```

4.2 Mixed production

A firm is planning the production of 3 products A_1, A_2, A_3 . In a month production can be active for 22 days. In the following tables are given: maximum demands (units=100kg), price (\$/100Kg), production costs (per 100Kg of product), and production quotas (maximum amount of 100kg units of product that would be produced in a day if all production lines were dedicated to the product).

Product	A_1	A_2	A_3
Maximum demand	5300	4500	5400
Selling price	\$124	\$109	\$115
Production cost	\$73.30	\$52.90	\$65.40
Production quota	500	450	550

1. Formulate an AMPL model to determine the production plan to maximize the total income.
2. Change the mathematical program and the AMPL model to cater for a fixed activation cost on the production line, as follows:

Product	A_1	A_2	A_3
Activation cost	\$170000	\$150000	\$100000

3. Change the mathematical program and the AMPL model to cater for both the fixed activation cost and for a minimum production batch:

Product	A_1	A_2	A_3
Minimum batch	20	20	16

[E. Amaldi, Politecnico di Milano]

4.2.1 Solution

4.2.1.1 Formulation

- *Indices:* Let i be an index on the set $\{1, 2, 3\}$.
- *Parameters:*
 - P : number of production days in a month;
 - d_i : maximum market demand for product i ;
 - v_i : selling price for product i ;
 - c_i : production cost for product i ;
 - q_i : maximum production quota for product i ;
 - a_i : activation cost for the plant producing i ;
 - l_i : minimum batch of product i .
- *Variables:*
 - x_i : quantity of product i to produce ($x_i \geq 0$);
 - y_i : activation status of product i (1 if active, 0 otherwise).

- *Objective function:*

$$\max \sum_i ((v_i - c_i)x_i - a_i y_i)$$

- *Constraints:*

1. (demand): for each i , $x_i \leq d_i$;
2. (production): $\sum_i \frac{x_i}{q_i} \leq P$;
3. (activation): for each i , $x_i \leq Pq_i y_i$;
4. (minimum batch): for each i , $x_i \geq l_i y_i$;

4.2.1.2 AMPL model, data, run

```
# mixedproduction.mod

set PRODUCTS;

param days >= 0;
param demand { PRODUCTS } >= 0;
param price { PRODUCTS } >= 0;
param cost { PRODUCTS } >= 0;
param quota { PRODUCTS } >= 0;
param activ_cost { PRODUCTS } >= 0; # activation costs
param min_batch { PRODUCTS } >= 0; # minimum batches

var x { PRODUCTS } >= 0; # quantity of product
var y { PRODUCTS } >= 0, binary; # activation of production lines

maximize revenue: sum {i in PRODUCTS}
((price[i] - cost[i]) * x[i] - activ_cost[i] * y[i]);

subject to requirement {i in PRODUCTS}:
x[i] <= demand[i];

subject to production:
sum {i in PRODUCTS} (x[i] / quota[i]) <= days;

subject to activation {i in PRODUCTS}:
x[i] <= days * quota[i] * y[i];

subject to batches {i in PRODUCTS}:
x[i] >= min_batch[i] * y[i];

# mixedproduction.dat

set PRODUCTS := A1 A2 A3 ;

param days := 22;
param : demand price cost quota activ_cost min_batch :=
A1 5300 124 73.30 500 170000 20
A2 4500 109 52.90 450 150000 20
A3 5400 115 65.40 550 100000 16 ;

# mixedproduction.run
```

```
model mixedproduction.mod;
data mixedproduction.dat;
option solver cplexstudent;
solve;
display x;
display y;
```

4.2.1.3 CPLEX solution

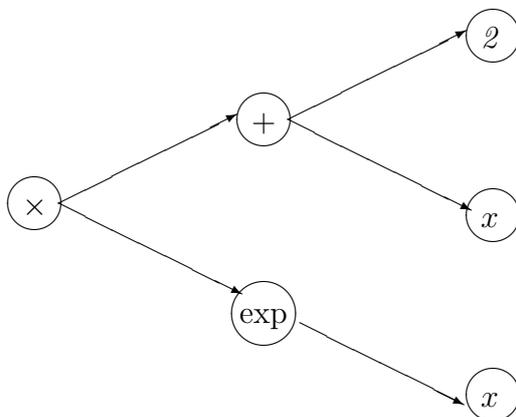
```
.

CPLEX 7.1.0: optimal integer solution; objective 220690
5 MIP simplex iterations
0 branch-and-bound nodes
ampl: display x;
x [*] :=
A1 0
A2 4500
A3 5400
;

ampl: display y;
y [*] :=
A1 0
A2 1
A3 1
;
```

4.3 Checksum

An *expression parser* is a program that reads mathematical expressions (input by the user as strings) and evaluates their values on a set of variable values. This is done by representing the mathematical expression as a directed binary tree. The leaf nodes represent variables or constants; the other nodes represent binary (or unary) operators such as arithmetic (+, -, *, /, power) or transcendental (sin, cos, tan, log, exp) operators. The unary operators are represented by a node with only one arc in its outgoing star, whereas the binary operators have two arcs. The figure below is the binary expression tree for $(x + 2)e^x$.



The expression parser consists of several subroutines.

- `main()`: the program entry point;
- `parse()`: reads the string containing the mathematical expression and transforms it into a binary expression tree;
- `gettoken()`: returns and deletes the next semantic token (variable, constant, operator, brackets) from the mathematical expression string buffer;
- `ungettoken()`: pushes the current semantic token back in the mathematical expression string buffer;
- `readexpr()`: reads the operators with precedence 4 (lowest: +,-);
- `readterm()`: reads the operators with precedence 3 (*, /);
- `readpower()`: reads the operators with precedence 2 (power);
- `readprimitive()`: reads the operators of precedence 1 (functions, expressions in brackets);
- `sum(term a, term b)`: make a tree $+ \begin{matrix} \nearrow a \\ \searrow b \end{matrix}$;
- `difference(term a, term b)`: make a tree $- \begin{matrix} \nearrow a \\ \searrow b \end{matrix}$;
- `product(term a, term b)`: make a tree $* \begin{matrix} \nearrow a \\ \searrow b \end{matrix}$;
- `fraction(term a, term b)`: make a tree $/ \begin{matrix} \nearrow a \\ \searrow b \end{matrix}$;
- `power(term a, term b)`: make a tree $\wedge \begin{matrix} \nearrow a \\ \searrow b \end{matrix}$;
- `minus(term a)`: make a tree $- \rightarrow a$;
- `logarithm(term a)`: make a tree $\log \rightarrow a$;
- `exponential(term a)`: make a tree $\exp \rightarrow a$;
- `sine(term a)`: make a tree $\sin \rightarrow a$;
- `cosine(term a)`: make a tree $\cos \rightarrow a$;
- `tangent(term a)`: make a tree $\tan \rightarrow a$;
- `variable(var x)`: make a leaf node x ;
- `number(double d)`: make a leaf node d ;
- `readdata()`: reads a table of variable values from a file;
- `evaluate()`: computes the value of the binary tree when substituting each variable with the corresponding value;
- `printresult()`: print the results.

For each function we give the list of called functions and the quantity of data to be passed during the call.

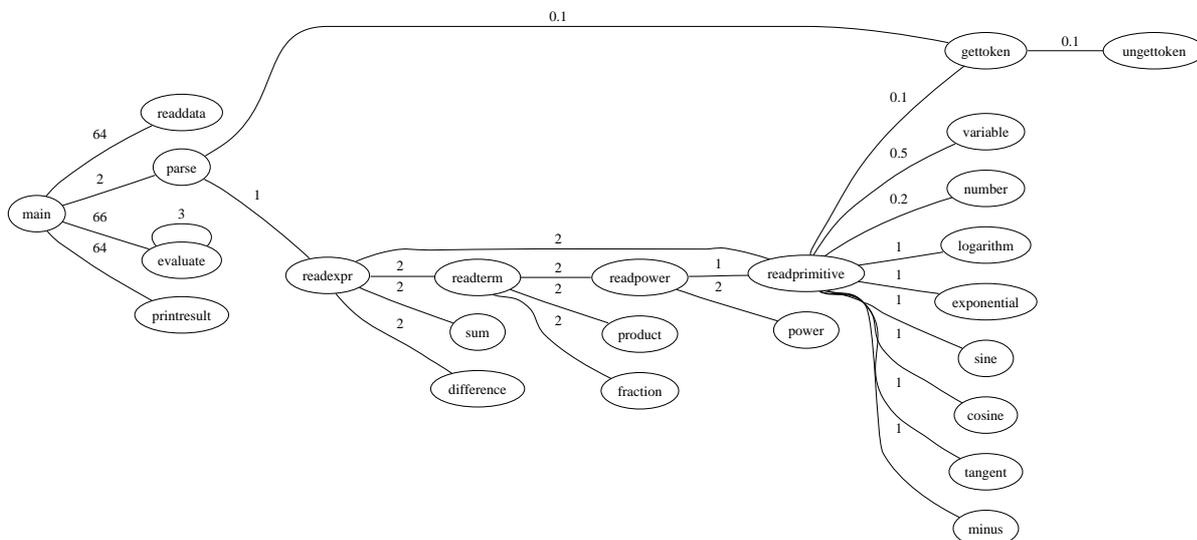
- main: readdata (64KB), parse (2KB), evaluate (66KB), printresult(64KB)
- evaluate: evaluate (3KB)
- parse: gettoken (0.1KB), readexpr (1KB)
- readprimitive: gettoken (0.1KB), variable (0.5KB), number (0.2KB), logarithm (1KB), exponential (1KB), sine (1KB), cosine (1KB), tangent (1KB), minus (1KB), readexpr (2KB)
- readpower: power (2KB), readprimitive (1KB)
- readterm: readpower (2KB), product (2KB), fraction (2KB)
- readexpr: readterm (2KB), sum (2KB), difference (2KB)
- gettoken: ungettoken (0.1KB)

Each function call requires a bidirectional data exchange between the calling and the called function. In order to guarantee data integrity during the function call, we require that a checksum operation be performed on the data exchanged between the pair (calling function, called function). Such pairs are called *checksum pairs*. Since the checksum operation is costly in terms of CPU time, we limit these operations so that no function may be involved in more than one checksum pair. Naturally though, we would like to maximize the total quantity of data undergoing a checksum.

1. Formulate a mathematical program to solve the problem, and solve the given instance with AMPL.
2. Modify the model to ensure that `readprimitive()` and `readexpr()` are a checksum pair. How does the solution change?

4.3.1 Solution

We represent each subroutine with a vertex in an undirected graph $G = (V, E)$. For each $u, v \in V$, $\{u, v\} \in E$ if subroutine u calls subroutine v (or vice versa). Each edge $\{i, j\} \in E$ is weighted by the quantity p_{ij} of data exchanged between the subroutines. We want to choose a subset $L \subseteq E$ such that for each $u \in V$ there is $v \in V$ with $\{u, v\} \in L$ (i.e. L covers V), such that each vertex $v \in V$ is adjacent to exactly 1 edge in L and such that the total weight $p(L) = \sum_{\{i,j\} \in L} p_{ij}$ is maximum. G is shown below.



4.3.1.1 Formulation

- *Parameters:* for each $\{i, j\} \in E$, p_{ij} is the weight on the edge.
- *Variables:* for each $\{i, j\} \in E$, $x_{ij} = 1$ if $\{i, j\} \in L$ and 0 otherwise.
- *Objective function:*

$$\max \sum_{e=\{i,j\} \in E} p_{ij} x_{ij}$$

- *Constraints:*

$$\forall i \in V \quad \sum_{j \in V | \{i,j\} \in E} x_{ij} = 1; \quad (4.1)$$

$$\forall \{i, j\} \in E \quad x_{ij} \in \{0, 1\}. \quad (4.2)$$

4.3.1.2 AMPL model, data, run

```
# checksum.mod

set V;
set E within {V,V};
param p{E};
var x{E} binary;
maximize data : sum{(i,j) in E} p[i,j] * x[i,j];
subject to assignment {i in V} :
    sum{j in V : (i,j) in E} x[i,j] + sum{j in V : (j,i) in E} x[j,i] <= 1;

# checksum.dat

set V := main readdata parse evaluate printresult gettoken readexpr
        readprimitive variable number logarithm exponential sine cosine
        tangent minus power readpower readterm product fraction sum ;
set E :=
main readdata
main parse
main evaluate
main printresult
evaluate evaluate
parse gettoken
parse readexpr
readprimitive gettoken
readprimitive variable
readprimitive number
readprimitive logarithm
readprimitive exponential
readprimitive sine
readprimitive cosine
readprimitive tangent
readprimitive minus
readprimitive readexpr
readpower power
readpower readprimitive
readterm readpower
readterm product
readterm fraction
readexpr readterm
```

```

readexpr  sum  ;

param p :=
main  readdata  64
main  parse     2
main  evaluate  66
main  printresult  64
evaluate  evaluate  3
parse  gettoken  0.1
parse  readexpr  1
readprimitive  gettoken  0.1
readprimitive  variable  0.5
readprimitive  number  0.2
readprimitive  logarithm  1
readprimitive  exponential  1
readprimitive  sine  1
readprimitive  cosine  1
readprimitive  tangent  1
readprimitive  minus  1
readprimitive  readexpr  2
readpower  power  2
readpower  readprimitive  1
readterm  readpower  2
readterm  product  2
readterm  fraction  2
readexpr  readterm  2
readexpr  sum  2 ;

```

```
# checksum.run
```

```

model checksum.mod;
data checksum.dat;
option solver cplexstudent;
solve;
display data;
printf "L = {\n";
for {(i,j) in E : x[i,j] = 1} {
  printf "      (%s,%s)\n", i, j;
}
printf "    }\n";

```

4.3.1.3 CPLEX solution

```

CPLEX 8.1.0: optimal integer solution; objective 73.1
3 MIP simplex iterations
0 branch-and-bound nodes
data = 73.1

```

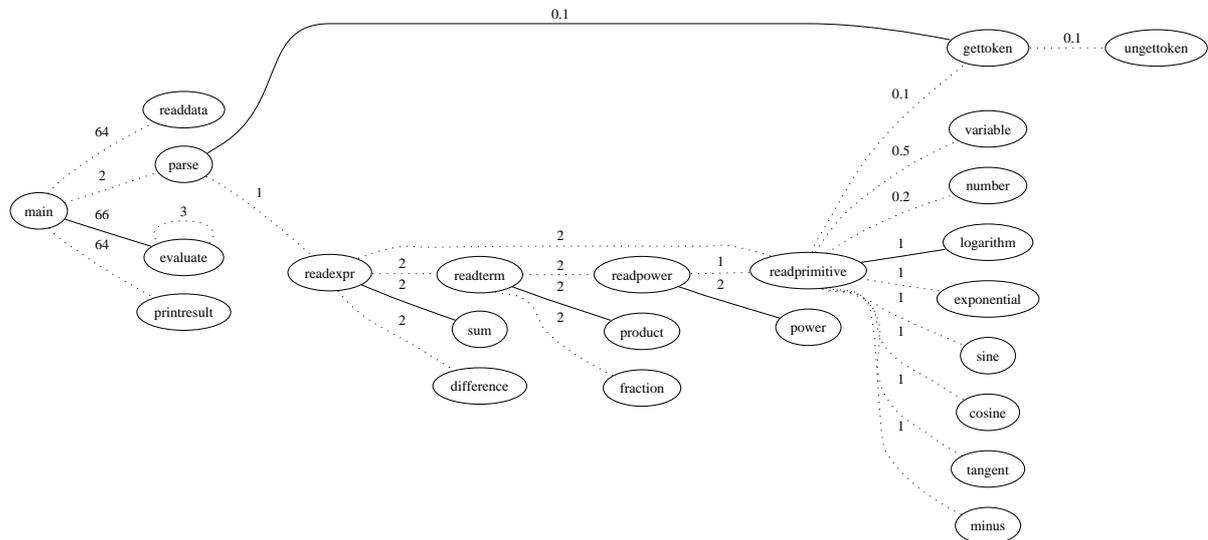
```

L = {
  (main,evaluate)
  (parse,gettoken)
  (readprimitive,cosine)
  (readpower,power)
  (readterm,product)
  (readexpr,sum)
}

```

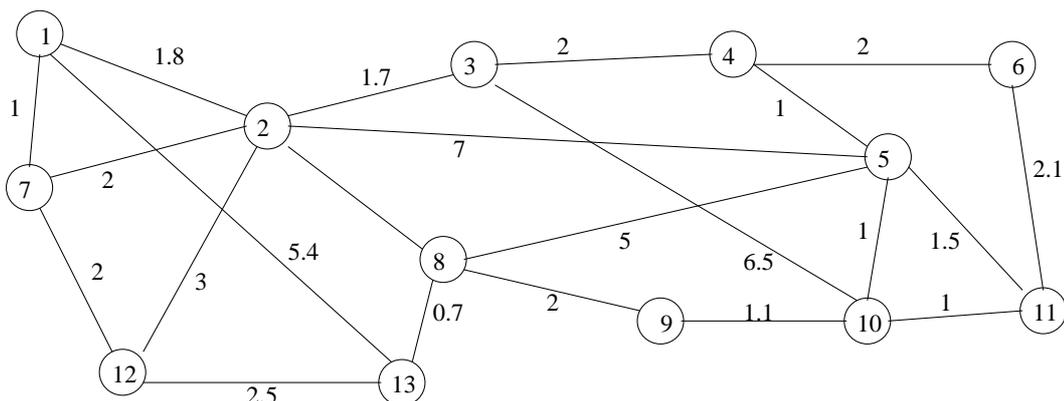
}

The picture below is the solution represented on the graph.



4.4 Network Design

Orange is the unique owner and handler of the telecom network in the figure below.



The costs on the links are proportional to the distances $d(i, j)$ between the nodes, expressed in units of 10km. Because of anti-trust regulations, Orange must delegate to SFR and Bouygtel two subnetworks each having at least two nodes (with Orange handling the third part). Orange therefore needs to design a backbone network to connect the three subnetworks. Transforming an existing link into a backbone link costs $c = 25$ euros/km. Formulate a mathematical program to minimize the cost of implementing a backbone connecting the three subnetworks, and solve it with AMPL. How does the solution change if Orange decides to partition its network in 4 subnetworks instead of 3?

4.4.1 Solution

Let $G = (V, E)$ be the graph of the network. The problem can be formalized as looking for the partition of V in three disjoint subsets V_1, V_2, V_3 such that the sum of the backbone update cost are minimum on the edges having one adjacent vertex in a set of the partition, and the other adjacent vertex in another set of the partition. This problem is often called GRAPH PARTITIONING or MIN- k -CUT problem.

4.4.1.1 Formulation and linearization

- *Indices:* $i, j \in V$ and $h, k \in K = \{1, 2, 3\}$.
- *Parameters:*
 - for each $\{i, j\} \in E$, d_{ij} is the edge weight (distance between i and j);
 - c : backbone updating cost;
 - m : minimum cardinality of the subnetworks.
- *Variables:* for each $i \in V$, $h \in K$, let $x_{ih} = 1$ if vertex i is in V_h , and 0 otherwise.
- *Objective function:*

$$\min \frac{1}{2} \sum_{h \neq k \in K} \sum_{\{i, j\} \in E} cd_{ij}x_{ih}x_{jk}$$

- *Constraints:*

$$\forall i \in V \quad \sum_{k \in K} x_{ik} = 1; \text{ (assignment)} \quad (4.3)$$

$$\forall h \in K \quad \sum_{i \in V} x_{ih} \geq m; \text{ (subnetwork cardinality)}. \quad (4.4)$$

This formulation involves products between binary variables, and can therefore be classified as a Binary Quadratic Program (BQP). Its feasible region is nonconvex (due to the integrality constraints and the quadratic terms), and the continuous relaxation of its feasible region is also nonconvex (due to the quadratic terms). This poses additional problems to the calculation of the lower bound within Branch-and-Bound (BB) type solution algorithms. However, the formulation can be linearized exactly, which means that there exists a Mixed-Integer Linear Programming (MILP) formulation of the problem whose projection in the x -space of the BQP yields exactly the same feasible region. The above program can be reformulated as follows:

1. replace each quadratic product $x_{ih}x_{jk}$ by a continuous *linearization variable* w_{ij}^{hk} constrained by $0 \leq w_{ij}^{hk} \leq 1$;
2. add the following constraints to the formulation:

$$\forall \{i, j\} \in E, h \neq k \in K \quad w_{ij}^{hk} \geq x_{ih} + x_{jk} - 1 \quad (\text{if } x_{ih} = x_{jk} = 1, w_{ij}^{hk} = 1) \quad (4.5)$$

$$\forall \{i, j\} \in E, h \neq k \in K \quad w_{ij}^{hk} \leq x_{ih} \quad (\text{if } x_{ih} = 0, w_{ij}^{hk} = 0) \quad (4.6)$$

$$\forall \{i, j\} \in E, h \neq k \in K \quad w_{ij}^{hk} \leq x_{jk} \quad (\text{if } x_{jk} = 0, w_{ij}^{hk} = 0). \quad (4.7)$$

Constraints (4.5)-(4.7) are a way to express the equation $w_{ij}^{hk} = x_{ih}x_{jk}$ (i.e. the condition vertex i assigned to subnetwork h and vertex j assigned to subnetwork k) without introducing quadratic products in the formulation. The resulting formulation is a MILP whose continuous relaxation is a Linear Programming problem (hence it is convex, which implies that each local optimum is also global — so it can be safely used to compute lower bounds in BB algorithms such as that implemented in CPLEX).

4.4.1.2 AMPL model, data, run

```

# network design
param n >= 0, integer;
param k >= 1, integer;
set V := 1..n;
set K := 1..k;
param c >= 0;
param m >= 0, integer;
param d{V,V} >= 0 default 0;

var x{V,K} binary;
var w{V,V,K,K} >= 0, <= 1;

minimize cost : sum{h in K, l in K, i in V, j in V :
    h != l and i < j and d[i,j] > 0} c*d[i,j]*w[i,j,h,l];
subject to assignment {i in V} : sum{h in K} x[i,h] = 1;
subject to cardinality {h in K} : sum{i in V} x[i,h] >= m;
subject to linearization {h in K, l in K, i in V, j in V :
    h != l and i < j and d[i,j] > 0} :
    w[i,j,h,l] >= x[i,h] + x[j,l] - 1;

# netdes.dat
param n := 13;
param k := 3;
param c := 25;
param m := 2;
param d :=
  1 2 1.8
  1 7 1
  2 3 1.7
  2 5 7
  2 7 2
  2 12 3
  3 4 2
  3 10 6.5
  4 5 1
  4 6 2
  5 8 5
  5 10 1
  5 11 1.5
  6 11 2.1
  7 12 2
  8 9 2
  8 13 0.7
  9 10 1.1
  10 11 1
  12 13 2.5 ;

# netdes.run

model netdes.mod;
data netdes.dat;
for {i in V, j in V : i < j} {
  let d[j,i] := d[i,j];
}
option solver cplexstudent;
solve;

```

```

display cost;
for {h in K} {
  printf "subnetwork %d:", h;
  for {i in V} {
    if (x[i,h] == 1) then {
      printf " %d", i;
    }
  }
  printf "\n";
}

```

4.4.1.3 CPLEX solution

For $k = 3$:

```

CPLEX 8.1.0: optimal integer solution; objective 232.5
1779 MIP simplex iterations
267 branch-and-bound nodes
cost = 232.5

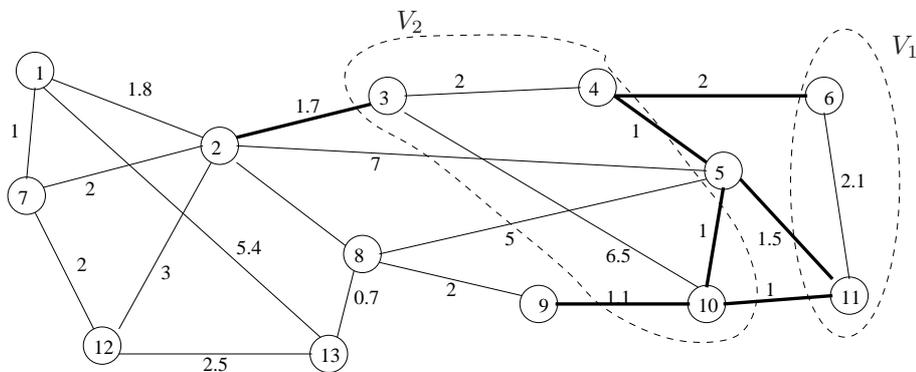
```

```

subnetwork 1: 6 11
subnetwork 2: 3 4 10
subnetwork 3: 1 2 5 7 8 9 12 13

```

The solution is in the picture below.



For $k = 4$:

```

CPLEX 8.1.0: optimal integer solution; objective 332.5
18620 MIP simplex iterations
1403 branch-and-bound nodes
cost = 332.5

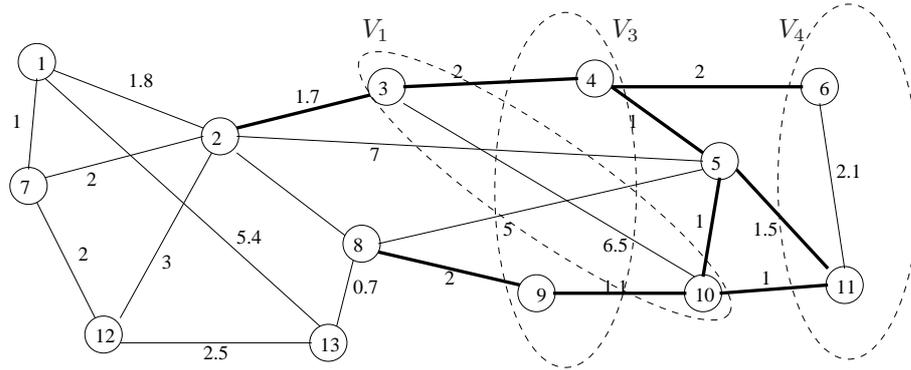
```

```

subnetwork 1: 1 2 5 7 8 12 13
subnetwork 2: 4 9
subnetwork 3: 3 10
subnetwork 4: 6 11

```

The solution is in the picture below.

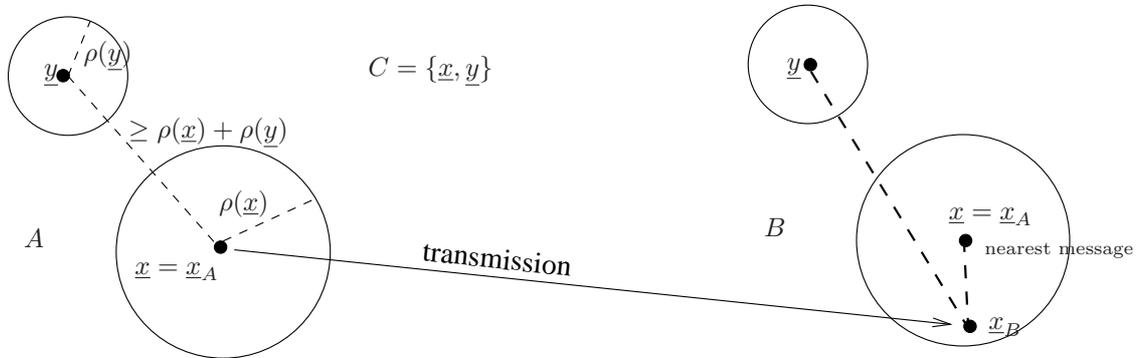


4.5 Error correcting codes

A message sent by A to B is represented by a vector $\underline{z} = (z_1, \dots, z_m) \in \mathbb{R}^m$. An *Error Correcting Code* (ECC) is a finite set C (with $|C| = n$) of messages with an associated function $\rho : C \rightarrow \mathbb{R}$, such that for each pair of distinct messages $\underline{x}, \underline{y} \in C$ the inequality $\|\underline{x} - \underline{y}\| \geq \rho(\underline{x}) + \rho(\underline{y})$ holds. The *correction radius* of code C is given by

$$R_C = \min_{\underline{x} \in C} \rho(\underline{x}),$$

and represents the maximum error that can be corrected by the code. Assume both A and B know the code C and that their communication line is faulty. A message $\underline{x}_A \in C$ sent by A gets to B as $\underline{x}_B \notin C$ because of the faults. Supposing the error in \underline{x}_B is strictly less than R_C , B is able to reconstruct the original message \underline{x}_A looking for the message $\underline{x} \in C$ closest to \underline{x}_B as in the figure below.



Formulate a (nonlinear) mathematical program to build an ECC C of 10 messages in \mathbb{R}^{12} (where all message components are in $[0, 1]$) so that the correction radius is maximized.

4.5.1 Solution

1. *Indices:* $j \leq m, i \leq n$.
2. *Variables:*
 - $\underline{x}^i \in \mathbb{R}^m$: position of i -th message;
 - $\rho_i \in \mathbb{R}_+$: value of ρ on \underline{x}^i
3. *Objective function:*

$$\max \min_{i \leq n} \rho_i$$

4. Constraints:

- (coordinates limits)

$$0 \leq \underline{x}_j^i \leq 1 \quad \forall i \leq n, j \leq m$$

- (distances)

$$\|\underline{x}^i - \underline{x}^k\| \geq \rho_i + \rho_k \quad \forall i, k \leq n$$

The AMPL implementation and solution (to be carried out by the MINOS solver because the model is nonlinear) is left as an exercise.

4.6 Selection of software components

In this example we shall see how a large, complex Mixed-Integer Nonlinear Programming (MINLP) problem (taken from [12]) can be reformulated to a Mixed-Integer Linear Programming (MILP) problem. It can be subsequently modelled and solved in AMPL.

Large software systems consist of a complex architecture of interdependent, modular software components. These may either be built or bought off-the-shelf. The decision of whether to build or buy software components influences the cost, delivery time and reliability of the whole system, and should therefore be taken in an optimal way. Consider a software architecture with n component slots. Let I_i be the set of off-the-shelf components and J_i the set of purpose-built components that can be plugged in the i -th component slot, and assume $I_i \cap J_i = \emptyset$. Let T be the maximum assembly time and R be the minimum reliability level. We want to select a sequence of n off-the-shelf or purpose-built components compatible with the software architecture requirements that minimize the total cost whilst satisfying delivery time and reliability constraints.

4.6.1 Solution

This problem can be modelled as follows.

- *Parameters:*

1. Let $N \in \mathbb{N}$;
2. for all $i \leq n$, s_i is the expected number of invocations;
3. for all $i \leq n, j \in I_i$, c_{ij} is the cost, d_{ij} is the delivery time, and μ_{ij} the probability of failure on demand of the j -th off-the-shelf component for slot i ;
4. for all $i \leq n, j \in J_i$, \bar{c}_{ij} is the cost, t_{ij} is the estimated development time, τ_{ij} the average time required to perform a test case, p_{ij} is the probability that the instance is faulty, and b_{ij} the testability of the j -th purpose-built component for slot i .

- *Variables:*

1. Let $x_{ij} = 1$ if component $j \in I_j \cup J_i$ is chosen for slot $i \leq n$, and 0 otherwise;
2. Let $N_{ij} \in \mathbb{Z}$ be the (non-negative) number of tests to be performed on the purpose-built component $j \in J_i$ for $i \leq n$: we assume $N_{ij} \in \{0, \dots, N\}$.

- *Objective function.* We minimize the total cost, i.e. the cost of the off-the-shelf components c_{ij} and the cost of the purpose-built components $\bar{c}_{ij}(t_{ij} + \tau_{ij}N_{ij})$:

$$\min \sum_{i \leq n} \left(\sum_{j \in I_i} c_{ij} x_{ij} + \sum_{j \in J_i} \bar{c}_{ij} (t_{ij} + \tau_{ij} N_{ij}) x_{ij} \right).$$

- *Constraints:*

1. assignment constraints: each component slot in the architecture must be filled by exactly one software component

$$\forall i \leq n \quad \sum_{j \in I_i \cup J_i} x_{ij} = 1;$$

2. delivery time constraints: the delivery time for an off-the-shelf component is simply d_{ij} , whereas for purpose-built components it is $t_{ij} + \tau_{ij}N_{ij}$

$$\forall i \leq n \quad \sum_{j \in I_i} d_{ij}x_{ij} + \sum_{j \in J_i} (t_{ij} + \tau_{ij}N_{ij})x_{ij} \leq T;$$

3. reliability constraints: the probability of failure on demand of off-the shelf components is μ_{ij} , whereas for purpose-built components it is given by

$$\vartheta_{ij} = \frac{p_{ij}b_{ij}(1-b_{ij})^{(1-b_{ij})N_{ij}}}{(1-p_{ij}) + p_{ij}(1-b_{ij})^{(1-b_{ij})N_{ij}}},$$

so the probability that no failure occurs during the execution of the i -th component is

$$\varphi_i = e^{-s_i \left(\sum_{j \in I_i} \mu_{ij}x_{ij} + \sum_{j \in J_i} \vartheta_{ij}x_{ij} \right)},$$

whence the constraint is

$$\prod_{i \leq n} \varphi_i \geq R;$$

notice we have three classes of reliability constraints involving two sets of added variables ϑ, φ .

This problem is a MINLP with no continuous variables. We shall now apply several reformulations to this problem (call it P).

1. We take the logarithm of both sides of the constraint $\prod_i \varphi_i \geq R$ to obtain:

$$-\sum_{i \leq n} s_i \left(\sum_{j \in I_i} \mu_{ij}x_{ij} + \sum_{j \in J_i} \vartheta_{ij}x_{ij} \right) \geq \log(R).$$

2. We now make use of the fact that N_{ij} is an integer variable for all $i \leq n, j \in J_i$. For $k \in \{0, \dots, N\}$ we add assignment variables ν_{ij}^k so that $\nu_{ij}^k = 1$ if $N_{ij} = k$ and 0 otherwise. Now for all $k \in \{0, \dots, N\}$ we compute the constants $\vartheta^k = \frac{p_{ij}b_{ij}(1-b_{ij})^{(1-b_{ij})k}}{(1-p_{ij}) + p_{ij}(1-b_{ij})^{(1-b_{ij})k}}$, which we add to the problem parameters. We remove the constraints defining ϑ_{ij} in function of N_{ij} . Since the following constraints are valid:

$$\forall i \leq n, j \in J_i \quad \sum_{k \leq N} \nu_{ij}^k = 1 \tag{4.8}$$

$$\forall i \leq n, j \in J_i \quad \sum_{k \leq N} k\nu_{ij}^k = N_{ij} \tag{4.9}$$

$$\forall i \leq n, j \in J_i \quad \sum_{k \leq N} \vartheta^k \nu_{ij}^k = \vartheta_{ij}, \tag{4.10}$$

the second set of constraints are used to replace N_{ij} and the third to replace ϑ_{ij} . The first set is added to the formulation. We obtain:

$$\begin{aligned} \min \sum_{i \leq n} & \left(\sum_{j \in I_i} c_{ij} x_{ij} + \sum_{j \in J_i} \bar{c}_{ij} (t_{ij} + \tau_{ij} \sum_{k \leq N} k \nu_{ij}^k) x_{ij} \right) \\ & \forall i \leq n \quad \sum_{j \in I_i \cup J_i} x_{ij} = 1 \\ \forall i \leq n \quad & \sum_{j \in I_i} d_{ij} x_{ij} + \sum_{j \in J_i} (t_{ij} + \tau_{ij} \sum_{k \leq N} k \nu_{ij}^k) x_{ij} \leq T \\ & \sum_{i \leq n} s_i \left(\sum_{j \in I_i} \mu_{ij} x_{ij} + \sum_{j \in J_i} x_{ij} \sum_{k \leq N} \vartheta_{ij}^k \nu_{ij}^k \right) \geq \log(R) \\ & \forall i \leq n, j \in J_i \quad \sum_{k \leq N} \nu_{ij}^k = 1. \end{aligned}$$

3. We distribute products over sums in the formulation to obtain the binary product sets $\{x_{ij} \nu_{ij}^k \mid k \leq N\}$ for all $i \leq n, j \in J_i$. We replace each binary product $x_{ij} \nu_{ij}^k$ (with indices ranging over all the appropriate ranges) by continuous *linearizing variables* w_{ij}^k defined over $[0, 1]$ and add the following constraints: $w_{ij}^k \leq x_{ij}$, $w_{ij}^k \leq \nu_{ij}^k$, and $w_{ij}^k \geq x_{ij} + \nu_{ij}^k - 1$; these supply a well-known exact linearization for products of binary variables [5]. By repeatedly applying this reformulation to all binary products of binary variables, we get a MILP reformulation Q of P where all the variables are binary.

We remark that the MILP reformulation Q derived above has a considerably higher cardinality than $|P|$. More compact reformulations are applicable in step 3 because of the presence of the assignment constraints [11].

A semantic interpretation of step 3 is as follows. Notice that for $i \leq n, j \in J_i$, if $x_{ij} = 1$, then $x_{ij} = \sum_k \nu_{ij}^k$ (because only one value k will be selected), and if $x_{ij} = 0$, then $x_{ij} = \sum_k \nu_{ij}^k$ (because no value k will be selected). This means that

$$\forall i \leq n, j \in J_i \quad x_{ij} = \sum_{k \leq N} \nu_{ij}^k \quad (4.11)$$

is a valid problem constraint. We use it to replace x_{ij} everywhere in the formulation where it appears with $j \in I_i$, obtaining a opt-reformulation with x_{ij} for $j \in I_i$ and quadratic terms $\nu_{ij}^k \nu_{lp}^h$. Now, because of (4.8), these are zero when $(i, j) \neq (l, p)$ or $k \neq h$ and are equal to ν_{ij}^k when $(i, j) = (l, p)$ and $k = h$, so they can be linearized exactly by replacing them by either 0 or ν_{ij}^k according to their indices. What this really means is that the reformulation Q , obtained through a series of automatic reformulation steps, is a semantically different formulation defined in terms of the following decision variables: $\forall i \leq n, j \in I_i$, $x_{ij} = 1$ if $j \in I_i$ is assigned to i and 0 otherwise; and $\forall i \leq n, j \in J_i, k \leq N$, $\nu_{ij}^k = 1$ if $j \in J_i$ is assigned to i and there are k tests to be performed, and 0 otherwise.

The AMPL implementation of the reformulation and consequent CPLEX solution is left as an exercise.

Chapter 5

Log analysis architecture

Some firms currently handle project management in an innovative way, letting teams interact freely with each other whilst trying to induce different teams and people to converge towards the ultimate project goal. In this “liberal” framework, a continual assessment of team activity is paramount. This can be obtained by performing an analysis of the amount of read and write access of each team to the various project documents. Read and write document access is stored in the log files of the web server managing the project database. Such firms therefore require a software package which reads the webserver log files and displays the relevant statistical analyses in visual form on a web interface.

Propose a detailed software architecture consistent with the definitions, goals and requirements listed in Sections 5.1, 5.2, 5.3.

5.1 Definitions

An *actor* is a person taking part in a project. A *tribe* is a group of actors. A *document* is an electronic document uploaded to a central database via a web interface. Documents are grouped according to their semantical value according to a pre-defined map which varies from project to project. There are therefore various *semantical zones* (or simply *zones*) in each project: a zone can be seen as a semantically related group of documents.

A *visual map* of document accesses concerning a set of tribes T and a set of zones Z is a bipartite graph $B_T^Z = (T, Z, E)$ with edges weighted by a function $w : E \rightarrow \mathbb{N}$ where an edge $e = \{t, z\}$ exists if the tribe t has accessed documents in the zone z , and $w(e)$ is the number of accesses. There may be different visual maps for read or write accesses, and a union of the two is also envisaged.

A *timespan* is a time interval $\bar{\tau} = [s, e]$ where s is the starting time and e is the ending time. Visual maps clearly depend on a given timespan, and may therefore be denoted as $B_T^Z(\bar{\tau})$. For each edge $e \in E$ we can draw the coordinate *time graph* of $w(e)$ changing in function of time (denoted as $w_e(\tau)$ in this case).

5.2 Software goals

The log scanning software overall user goals are:

1. given a tribe t and a timespan $\bar{\tau}$, display a per-tribe visual map $B_{\{t\}}^Z(\bar{\tau})$;

2. given a zone z and a timespan $\bar{\tau}$, display a per-zone visual map $B_T^{\{z\}}(\bar{\tau})$;
3. given a timespan $\bar{\tau}$, display a global visual map $B_T^Z(\bar{\tau})$;
4. given a timespan $\bar{\tau}$ and an edge $e = \{t, z\}$ in $B_T^Z(\bar{\tau})$, display a time graph of $w(e)$.

The per-tribe and per-zone visual maps can be extended to the per-tribe-pair, per-tribe-triplet, per-zone-pair, per-zone-triplet cases.

5.3 Requirements

The technical requirements of the software can be subdivided into three main groups: (a) user interaction, (b) log file reading, (c) computation and statistics.

5.3.1 User interaction

All user interaction (input and output) occurs via a web interface. This will:

1. configure the desired visual map (or time graph) according to user specification (input action);
2. delegate the necessary computation to an external agent (a log database server) and obtain the results (process action);
3. present the visual map or time graph in a suitable graphical format (output action).

5.3.2 Log file reading

Log file data will be gathered at pre-definite time intervals by a daemon, parsed according to the log file format, and stored in a database. The daemon will:

1. find the latest entries added the log files since last access (input action);
2. parse them according to the log file format (process action);
3. write them to suitable database tables (output action).

5.3.3 Computation and statistics

Actually counting the relevant numbers and types of accesses will be carried out by a database engine. This will receive a query, perform it, and output the desired results.

5.4 The software architecture

According to the above requirements, the overall software architecture is based on three main modules:

1. *user interface*;
2. *log reading daemon*;

3. *log database server*;

plus an optional added *project interface* module to configure project-specific data into the log analysis database. The overall software architecture is depicted in Fig. 5.1.

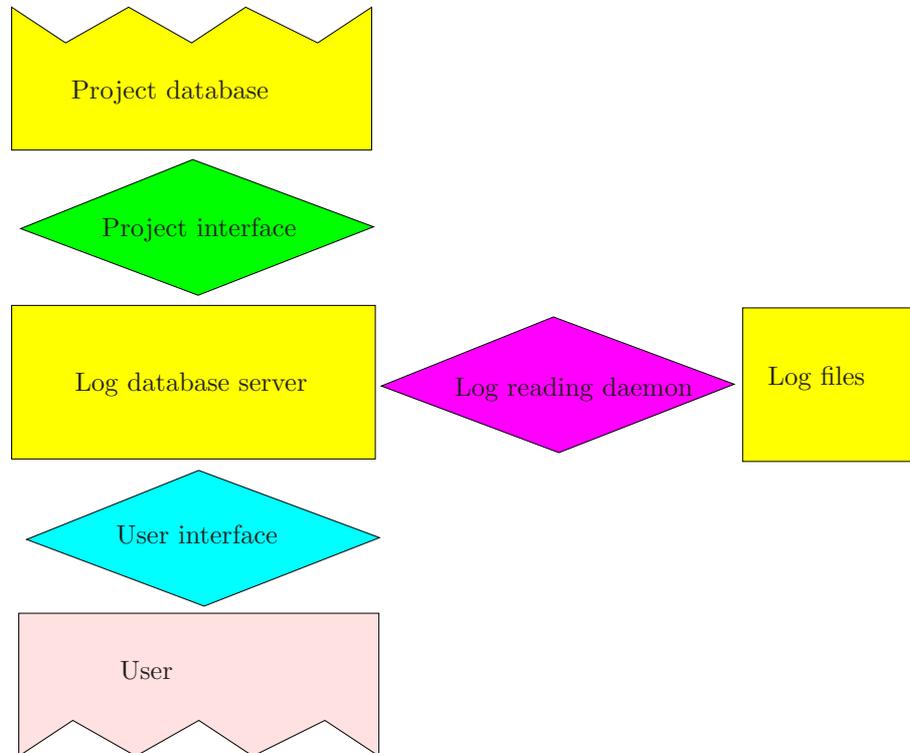


Figure 5.1: The overall software architecture.

Project-specific data are: (a) a set of tribes (possibly with hierarchical/functional relationships expressed via a set of edges in the graph induced by the tribes); (b) a set of zones (possibly with semantic relationships expressed via a set of edges in the graph induced by the zones); (c) a document-to-zone map (here we refer to the documents listed in the project webserver log files); (d) an IP-to-tribe map (where IP is the IP address requesting documents from the project webserver log files).

5.4.1 Summary

5.4.1.1 User interface

This is the most complex module. It needs to perform the following actions (in the given order):

1. configure its runtime parameters: project name, DB server information access, XSL specification for statistics visualization output;
2. get project-specific (list of tribes, list of zones) information from the log database server
3. ask the user the desired type of statistic (per-tribe, per-zone, global, time-graph);
4. ask the user the necessary input data (timespan, tribe(s), zone(s), tribe-zone pair), presenting lists of tribes, zones and pairs to choose from;

5. form the database query according according to user specification;
6. perform the database query;
7. gather output statistics;
8. form an XML representation of the statistics visualization
9. produce an output (HTML, other publishing formats).

Should any action fail in the events sequence, the correct error recovering procedure is simply to abort the sequence, display an error, and return to Step 2.

5.4.1.2 Log reading daemon

The log reading daemon simply waits in the background and every so often reads the tail of the log files, parses it, and records the data in the log database server. It needs to perform the following actions (in the given order):

1. configure its runtime parameters: project name, DB server information access, log file format specification, uniform resource identifiers (URIs) of log files, update information file name;
2. read log file sizes when last accessed from the update information file;

then, for each log file listed:

3. get tail of log file;
4. parse records according to log file format, to extract: (i) requesting IP address, (ii) requested document URL, (iii) access date/time, (iv) success/failure, (v) access type (read/write);
5. store those data to the log database server.

Care must be taken to read a whole number of records in Step 3, as the “tail” of a file is defined on the amount of bytes last read. This depends on the operating system, so it cannot be enforced a priori. One possible way around is to count the bytes used during data parsing, and add those bytes the file size stored in the update information file.

Should any action fail in the events sequence, the correct error recovering procedure is to abort the daemon and notify a system administrator immediately.

5.4.1.3 Log database server

The log database server is going to perform the necessary computation on the (stored) relevant information. It needs to store the following information:

1. project-specific information:
 - tribes table: tribe name, associated IP address pool
 - zones table: zone name, associated directory name in web site map
 - actors/tribes incidence information (optional)
 - documents/zones incidence information (optional)

- hierarchical/functional tribes/actors relationships (optional)
 - semantic zones relationships (optional);
2. log information table:
- requesting IP address
 - tribe name
 - requested document URL
 - zone name
 - access date/time
 - type of access (read/write).

Note that the zone name can be inferred by the directory name of the document URL (contained in the zones table), and the tribe name can be inferred by the IP address according to the tribes table.

5.4.1.4 Project Interface

This module is optional in the sense that a prototype may well work without it. Its main function is to load incidence information of document URLs with zones and IP addresses with tribes on the database server. This can be carried out either as a web interface drawing input from the user or as an executable program configured through a text file. In both cases, this interface should hook into the project-specific database to build the document-to-zone and IP-to-tribe tables.

5.4.2 Details

The user interface and log reading daemon expose a C-like API. API entries are listed in the following format:

Return**Type** **FunctionName** (*in* InputArgument, ..., *out* OutputArgument, ...)

In this document, all functions return an integer error status (this can be changed to using exceptions where applicable). The `TimeSpan` type is simply a pair of date/time records (starting and ending times).

5.4.2.1 User interface

The user interface is going to be coded in PHP. It is going to make use of several primitive PHP API subsets: text file handling, abstract DB connection and query, XML/XSL, vector image creation.

- **ErrorStatus ReadConfiguration** (*in* String FileName, *out* DBConnectionData theDB, *out* String XSLVisualSpecFileName)
It opens a text configuration file named `FileName`; reads the following information: name of the project, DB server name, DB user name, DB password, DB database name, XSL visual specification file name; finally, it closes the configuration file.
- **ErrorStatus GetTribesList** (*out* List TribesList)
Queries the DB engine to obtain the zones list.
- **ErrorStatus GetZonesList** (*out* List ZonesList)
Queries the DB engine to obtain the zones list.

- **ErrorStatus GetUserSpecifications** (*out* int StatisticsType, *out* String[3] SelectedTribes, *out* String[3] SelectedZones, *out* TimeSpan theTimeSpan, *out* int AccessType)
Gets the user specifications for the desired statistics from a web form. The StatisticsType will denote per-tribe, per-zone, global or time-graph. If per-tribe is selected, SelectedTribes contains up to three names of meaningful tribes. If per-zone is selected, SelectedZones contains up to three names of meaningful zones. If time-graph is selected, SelectedTribes[0] and SelectedZones[0] will contain the relevant tribe-zone pair. In all cases, AccessType will denote read access, write access or both.
- **ErrorStatus GetByTribeStatistics** (*in* String[3] SelectedTribes, *in* TimeSpan theTimeSpan, *in* AccessType, *in* DBConnectionData theDB, *out* Map<<Tribe,Zone>,double> Statistics)
Forms the SQL query to count how many accesses occurred during the specified timespan from the selected tribes to each zone; performs the query; organizes the data in the specified output map.
- **ErrorStatus GetByZoneStatistics** (*in* String[3] SelectedZones, *in* TimeSpan theTimeSpan, *in* AccessType, *in* DBConnectionData theDB, *out* Map<<Tribe,Zone>,double> Statistics)
Forms the SQL query to count how many accesses occurred during the specified timespan from each tribe to the selected zones; performs the query; organizes the data in the specified output map.
- **ErrorStatus GetGlobalStatistics** (*in* TimeSpan theTimeSpan, *in* AccessType, *in* DBConnectionData theDB, *out* Map<<Tribe,Zone>,double> Statistics)
Forms the SQL query to count how many accesses occurred during the specified timespan from each tribe to each zone; performs the query; organizes the data in the specified output map.
- **ErrorStatus GetTimeGraphStatistics** (*in* String Tribe, *in* String Zone, *in* TimeSpan theTimeSpan, *in* AccessType, *in* DBConnectionData theDB, *out* Map<DateTime,double> Statistics)
Forms the SQL query to track the access of Tribe towards Zone versus time; performs the query; organizes the data in the specified output map.
- **ErrorStatus PublishIncidenceStatistics** (*in* Map<<Tribe,Zone>,double> Statistics, *in* String XSLVisualSpecFileName, *out* TextBuffer XMLStatistics)
Transforms the incidence Statistics map into XML format; uses the PHP PNG vector graphics API subset to produce a JPEG image of the desired graph (in full colours); reads the specified XSL visual specification file to produce an HTML output (which also displays the GIF/JPEG image directly on the screen).
- **ErrorStatus PublishTimeGraphStatistics** (*in* Map<DateTime,double> Statistics, *in* String XSLVisualSpecFileName, *out* TextBuffer XMLStatistics)
Transforms the time-graph Statistics map into XML format; uses the PHP PNG vector graphics API subset to produce a PNG image of the desired graph (in full colours); transforms this to GIF or JPEG format; reads the specified XSL visual specification file to produce an HTML output (which also displays the GIF/JPEG image directly on the screen).

Note to implementors: some of the above functions are extensive pieces of coding. They should be implemented by breaking them up into smaller (protected) functions.

The transition state diagram for the user interface is given in Fig. 5.2. The class diagram is given in Fig. 5.3. Note to implementors: this class diagram is intended to give a semantic grouping of the required data and methods. PHP is not necessarily best used in object-oriented mode. Should the choice fall on a procedural PHP development, the class diagram should just be used for clarification and as general guidance.

5.4.2.2 Log reading daemon

The log file daemon is going to be coded in Java and will use the following primitive JAVA API subsets: process/timer handling, text file handling, abstract DB connection and query, and possibly an advanced

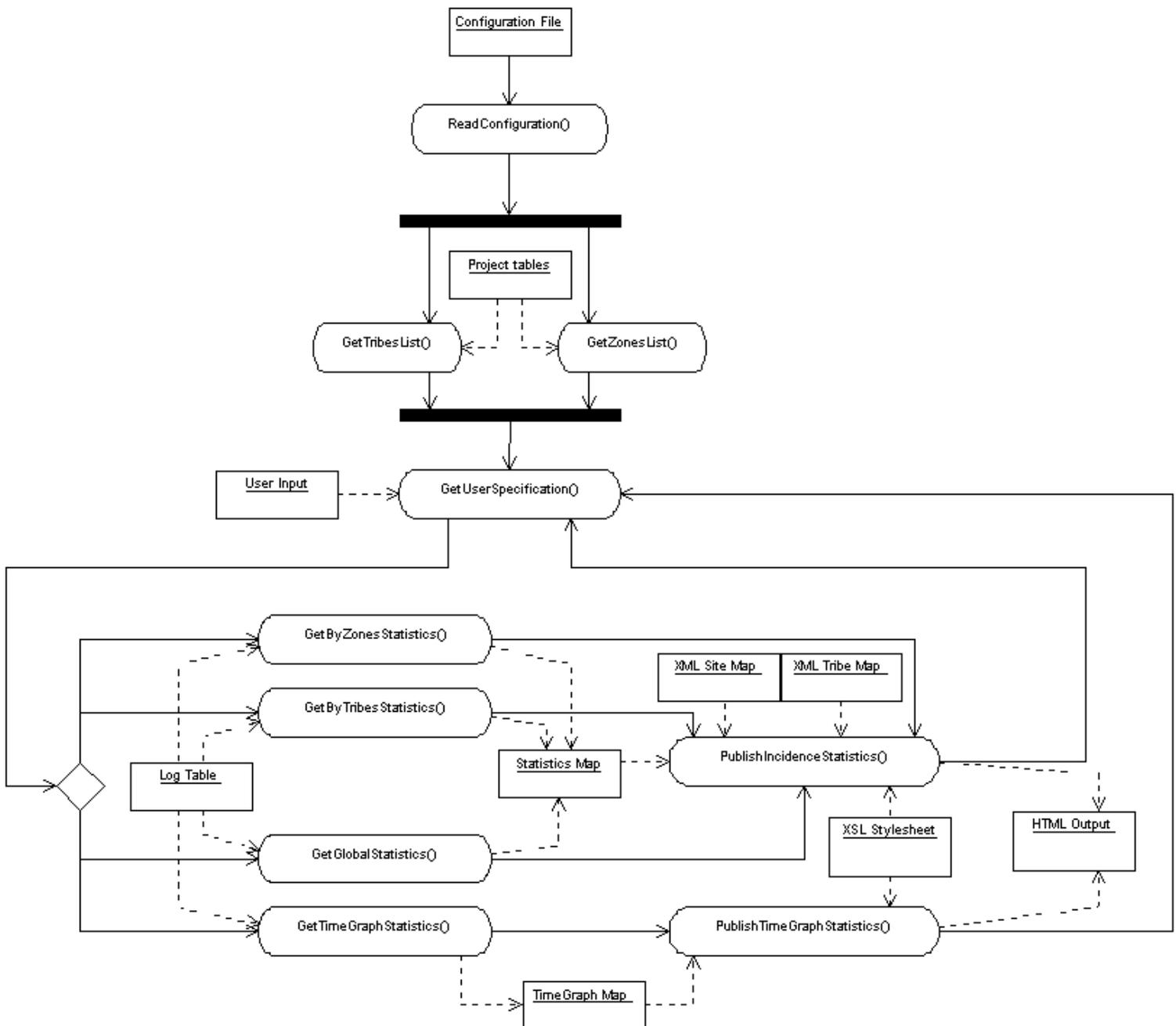


Figure 5.2: The transition state diagram for the user interface.

(s)FTP API to retrieve log file tails.

- **ErrorStatus ReadConfiguration** (*in* String FileName, *out* DBConnectionData theDB, *out* int LogFileFormat, *out* String[] LogURI, *out* String UpdateInfoFileName)
Opens a text configuration file named FileName; reads the following information: name of the project, DB server name, DB user name, DB password, DB database name, log file format, uni-

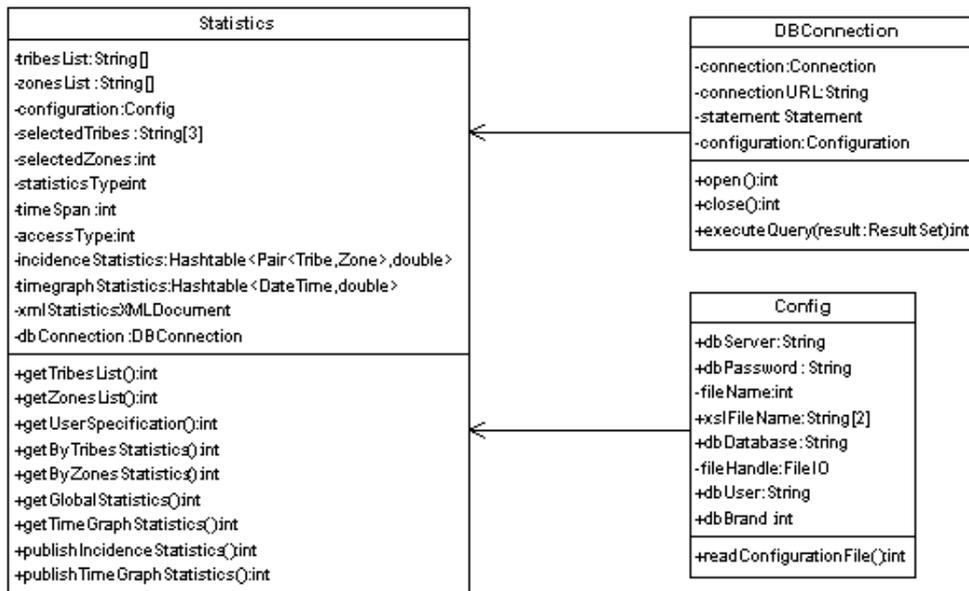


Figure 5.3: The class diagram for the user interface.

form resource identifiers (URIs) of log files, update information file name; finally, it closes the configuration file.

- **ErrorStatus ReadUpdateInfo** (*in* String UpdateInfoFileName, *in* String[] LogURI, *out* long[] LogSize)
Opens the update information file; reads a “file read up to size” for each given log file URI; closes the file.
- **ErrorStatus SaveUpdateInfo** (*in* String UpdateInfoFileName, *in* String[] LogURI, *in* long[] LogSize)
Writes a new update information file with the current log sizes; closes the file.
- **ErrorStatus ReadLogFileTail** (*in* String LogURI, *in* long LogSize, *out* TextBuffer theTail)
Uses a network or filesystem transfer method to retrieve the last (filesize(LogURI) – LogSize) bytes of the log file LogURI.
- **ErrorStatus ParseLogData** (*in* TextBuffer theTail, *in* int LogSize, *in* int LogFileFormat, *out* DBTable UpdatedLogData, *out* UpdatedLogSize)
Calls a lower-level parsing driver according to LogFileFormat; this driver must parse theTail, identify the relevant fields and organize them into a memory representation of a DB table UpdatedLogData; furthermore, it must return the exact number of bytes used during the parsing, add them to the LogSize and put the result into UpdatedLogSize. The format of the DB table is as in Section 5.4.1.3, Step 2 (the tribe and zone name fields are left blank).
- **ErrorStatus SaveLogData** (*in* DBTable UpdatedLogData, *in* DBConnectionData theDB)
Connects to the log database server; finds the tribe corresponding to each IP address in the DB table; finds the zone corresponding to each document URL in the DB table; completes the table; saves the latest log data in the log database server, adding them to the relevant table.

Notes to implementors. (a) Some of the above functions are extensive pieces of coding. They should be implemented by breaking them up into smaller (protected) functions. (b) The main function of this

program should take a number of seconds s as argument, and configure and start a timer calling the log reading procedure every s seconds.

The transition state diagram for the log reading daemon is given in Fig. 5.4, and the class diagram in Fig. 5.5.

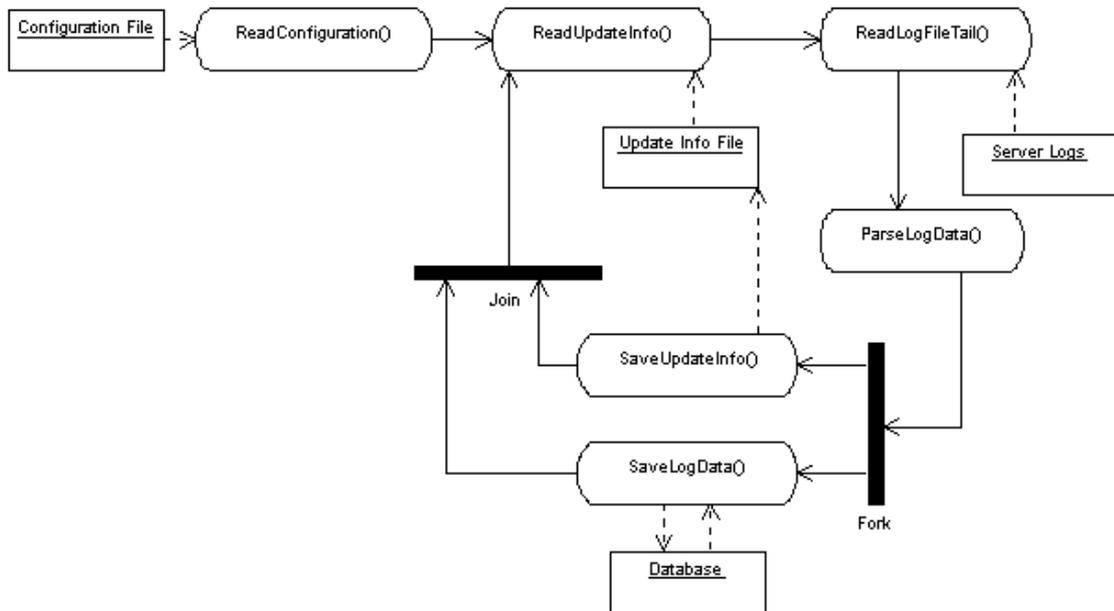


Figure 5.4: The transition state diagram for the log reading daemon.

5.4.2.3 Log database server

The database server of choice is MySQL (www.mysql.com), but this can be changed as desired with any other internet-enabled DB engine accepting SQL queries and exporting data through the normal standardized APIs.

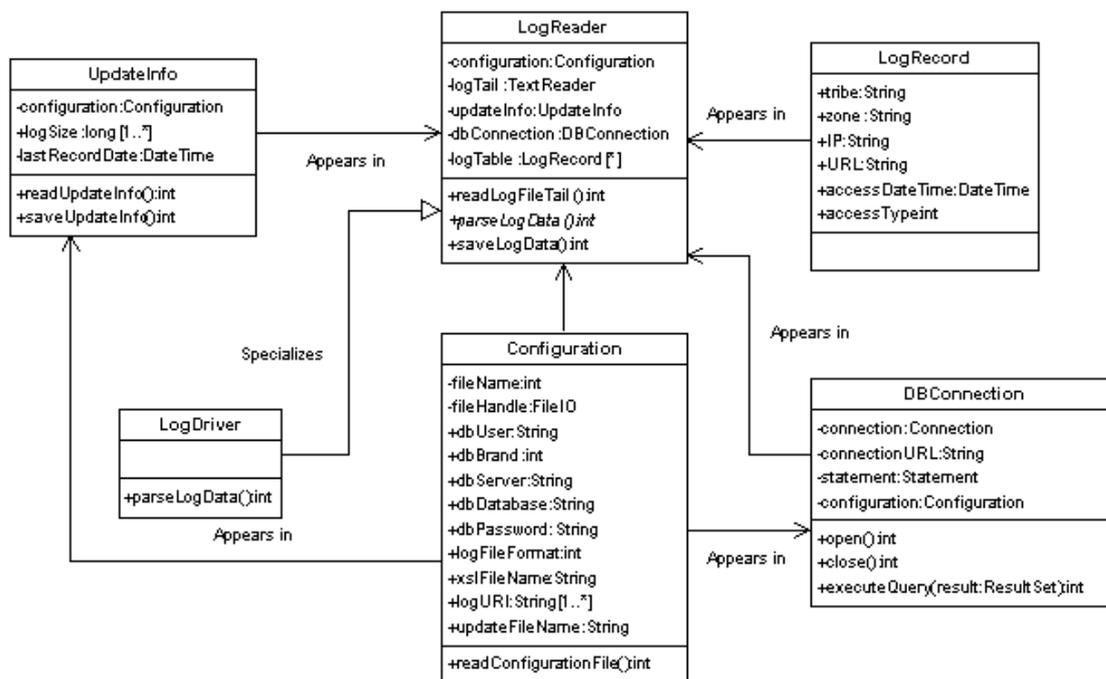


Figure 5.5: The class diagram for the log reading daemon.

Chapter 6

A search engine for projects

This large-scale example comes from an actual industrial need. An industry manager once mentioned to me how nice it would be to have a search engine for projects, and how easy their work would be if they were able to come up with relevant past data “at a glance” whenever a decision on a new project has to be taken. Although this example does not use UML (although it does use some diagrams inspired to UML), it employs some novel, partially automatic graph reformulation techniques for manipulating the software architecture graph. This example also shows how optimization techniques and mathematical programming are useful tools in software architecture.

6.1 The setting

T-Sale is a large multinational firm which is often employed by national governments and other large institutions to provide very large-scale services. They will secure contracts by responding to the prospective customers’ public tenders with commercial offers that have to be competitive. The upper management of *T-Sale* noticed some inefficiencies in the way these commercial offers are put together, in that very often the risk analysis are incorrect. They decided that they could improve the situation by trying to use stored information about past projects. More precisely, *T-Sale* keeps a detailed project database which allows one to see how an initial commercial offer became the true service that was eventually sold to the customer. The management hope that the preliminary customer requirements contained in the public tender may be successfully matched with the stored initial requirements to draw some meaningful inference on how the project actually turned out in the past.

T-Sale wants to enter into a contract with a smaller firm, called *VirtualClass*, to provide the following service, which was expressed in very vague terms from one senior vice-president of *T-Sale* to *VirtualClass*’ sales department.

We want a sort of “Google” for starting projects. We want to find all past projects which were similar at the initial stage and we want to know how they developed; this should give us some idea of future development of the current project.

VirtualClass must estimate the cost and time required to complete this task, and make *T-Sale* a competitive offer. Should *T-Sale* accept the offer, *VirtualClass* will then have to actually plan and implement the system. Note:

1. The commercial offer needs to be drawn quickly. The associated risks should be assessed. It should be as close as possible to the delivered product.

2. In general, the software engineering team should follow the “V” development process (left branch) for planning the system, as shown in Fig. 6.1. We shall limit the discussion to the leftmost branch of the “V” process.

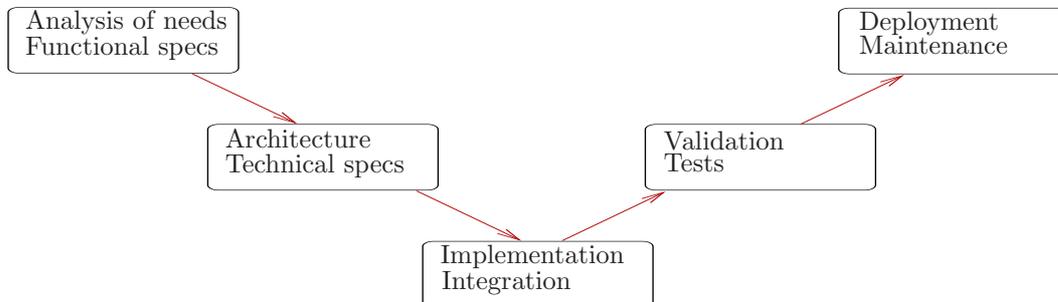


Figure 6.1: The “V” development process.

6.2 Initial offer

6.2.1 Kick-off meeting

Aims of the meeting:

1. Formalize the customer requirements as much as possible
 - (a) What is the deliverable, i.e. what is actually sold to the customer?
 - (b) What is the first coarse “common-sense” system breakdown?
2. What data is needed from T-Sale’s databases?

6.2.1.1 Meeting output

1. Given some meaningful key-words or other well-defined indicators in the description of a new project, we want to classify it by some quantitative indices and look in a project database for all projects which were sufficiently similar at the initial stage and proceeded to completion with a uniform degree of success; we should then display a list of such projects so that the user can immediately glance at all important information concerning risk-assessment.
 - (a) The deliverable is a software module that must be plugged in the existing T-Sale back-office network; it should have query access to some of the T-Sale databases and should be usable through a web interface.
 - (b) At a first analysis, we shall need:
 - I/O user interface through a web browser;
 - a way to find meaningful indicators in the given project;
 - a system to query the databases for those indicators and return information about initial, intermediate and final cost, time and resources estimates.
2. We shall need T-Sales’ data concerning:
 - project descriptions;

- project schedules;
- project costs;
- teams involved;
- people involved;
- other resources involved.

T-Sale's answer, as often happens, is rather vague.

Dear VirtualClass Team,

We are sorry to have to tell you that the structure of our databases is classified information, and we will only be able to give it to you at a later stage when and if we choose to employ your services. We can however describe the main features of what we think is useful to your job. We have an HR database detailing the usual information (salary, rank, . . .) abilities and skills. We have a technical database with project information (nature and cost of project, teams, people, schedule and associated changes). We naturally have a commercial database detailing customers and payments. Unfortunately the database which details hardware resources and costs may not be accessed as it contains some information classified at national level.

Best regards,

A. Smith

6.2.2 Brainstorming meeting

Aims of the meeting:

1. propose ideas for a system plan with sufficient details for a rough cost estimate;
2. collect these ideas in a formal document;
3. decide on a sexy project name.

6.2.2.1 Meeting output

Main idea. Collect all data from past projects and cluster data according to different indicators (i.e. technological area to which the project belongs, type of architecture topology, expertise needed, total projected cost, total actual cost, risk. . .) to get an idea of what it means for projects to be similar. Classify indicators according to whether they can be known at an early (i.e. technological area) or late stage in the project (e.g. total actual cost). Compare clusterings: if roughly same number of clusters and each cluster has roughly the same cardinality, we can infer that the two indicators are probably correlated. Assess correlations between all early/late indicator pairs. Classify new project according to early indicators, look at correlated late indicators and output the projects in the corresponding clusters (see Fig. 6.2).

1. User will input project indicators known at early stage
2. **Functionality:** an input web form (user interface)
3. Which among these “early indicators” are quantitative, which qualitative?
4. What sort of clustering of the project space do they lead to?
5. According to what other indicators (“late indicators”) can project be clustered?

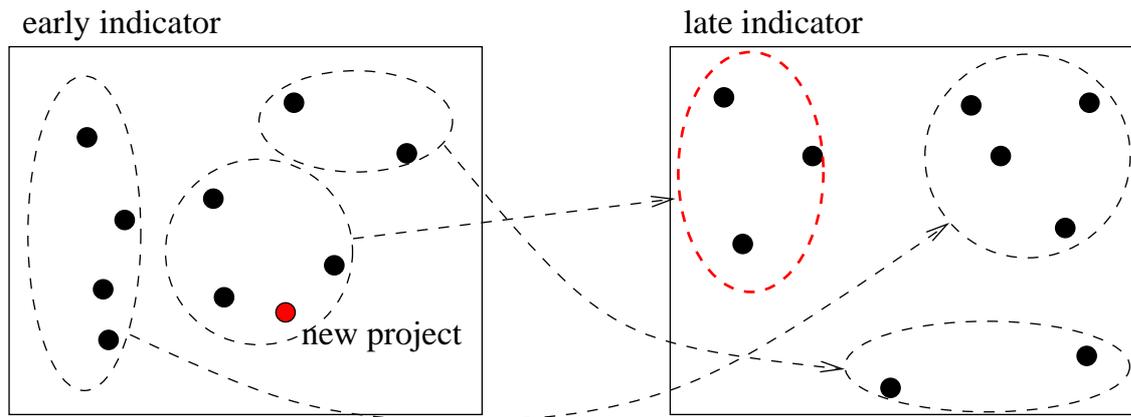
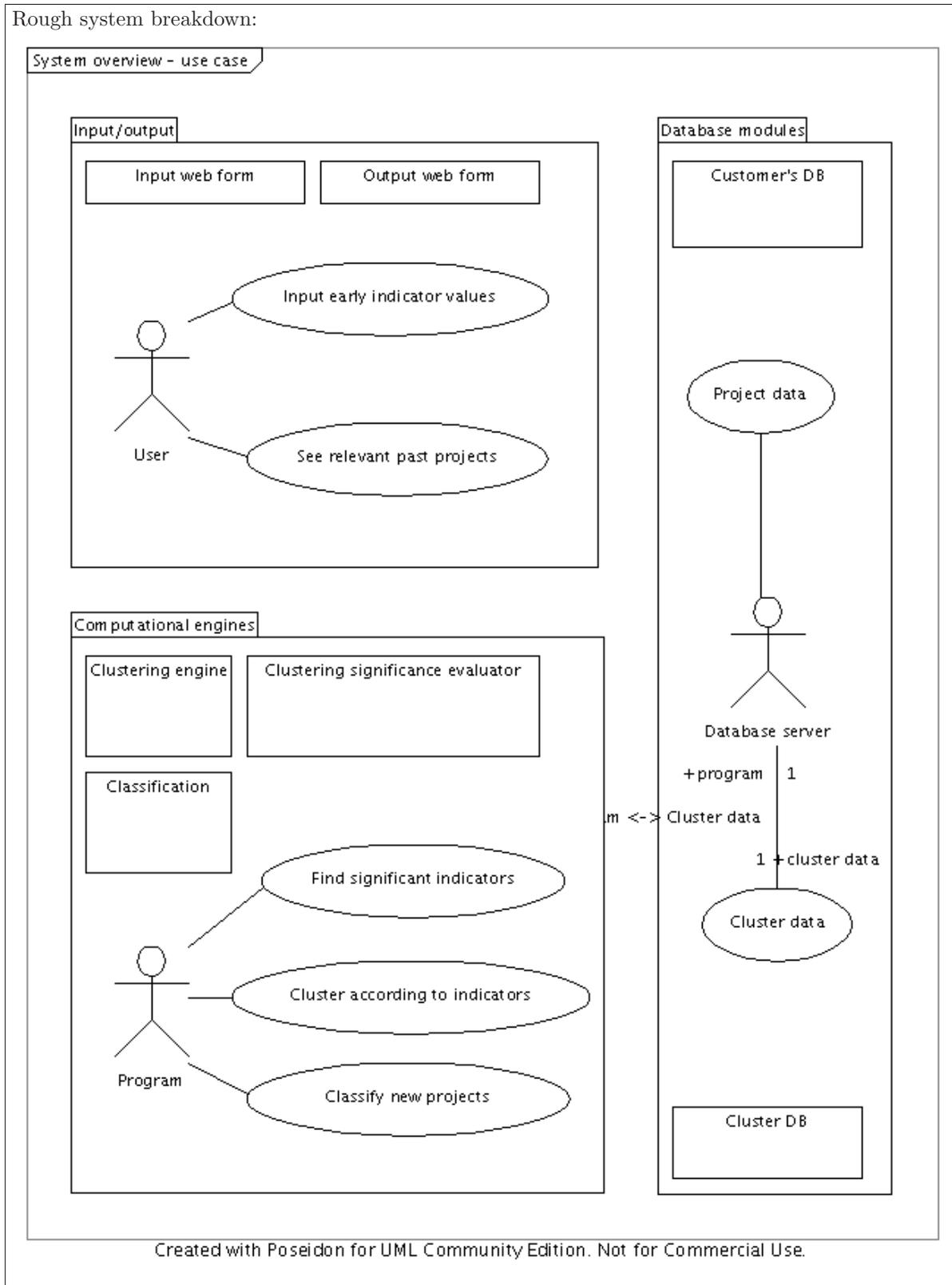


Figure 6.2: Main idea for the Proogle project.

6. **Functionality:** cluster projects according to a given quantitative/qualitative indicator (computational engine)
7. **Functionality:** access the customer database (database module)
8. How do we assess the quality of a clustering?
9. How “clear-cut” is a clustering?
10. **Functionality:** clustering significance evaluator (computational engine)
11. How are the early/late clusterings used later on?
12. **Functionality:** record a clustering (database module)
13. New projects must be classified according to early indicators: how do we use the information given by the clusterings obtained with late indicators? More in general, how do we pick a set of significant late clustering (which give the useful risk assessment information) given an early clustering?
14. **Functionality:** clustering compatibility evaluator (computational engine)
15. Literature review on clustering
16. How do we classify a new project according to the stored clusterings?
17. **Functionality:** query clusterings for
18. How do we present the output to the user?
19. **Functionality:** output form (user interface)
20. Name: how about “proogle” (the “project google”?)

6.2.3.1 Meeting output



Risks:

1. Failure to obtain necessary data/clearance from T-Sale — catastrophic, low probability
2. Not enough specific in-house clustering expertise — serious, high probability
3. Results not as useful as expected — low, medium probability

Address risks:

1. Insert clause in contract
2. Plan training
3. Insert clause in contract

6.3 System planning

We shall now suppose that T-Sale accepted VirtualClass' offer and is now engaged in a contract. The next step is to actually plan the system. The contract clearly states that T-Sale is under obligation to provide T-Sale with database details, which are shown in Fig. 6.3.

6.3.1 Understanding T-Sale's database structure

Aims of the meeting: analysis and documentation of T-Sales' database structure. Note that the project's *condition* contains information about whether the project was a success or a failure, and other overall properties. Make sure every software engineer understands the database structure by answering the following questions:

1. How do we find the main occupation of an employee?
2. How do we find the expertises of an employee?
3. How do we find the condition of a project?
4. How do we find how many times a project was changed?
5. How do we find whether a project was paid for on time or late?
6. How do we find whether a customer usually pays on time or late?
7. How do we verify that the cost of all phases in a project sums up to the total project cost?
8. How do we evaluate the cost in function of time during the project's lifetime?
9. How do we discriminate between the phase cost due to human resources and the cost due to other reasons?
10. How do we find the expertises (with their levels) that were necessary in a given project?
11. How do we find out the abilities and skills (with their levels) that were necessary in a given project?
12. How do we find out which teams were most successful?
13. How do we find out the most dangerous personal incompatibilities?

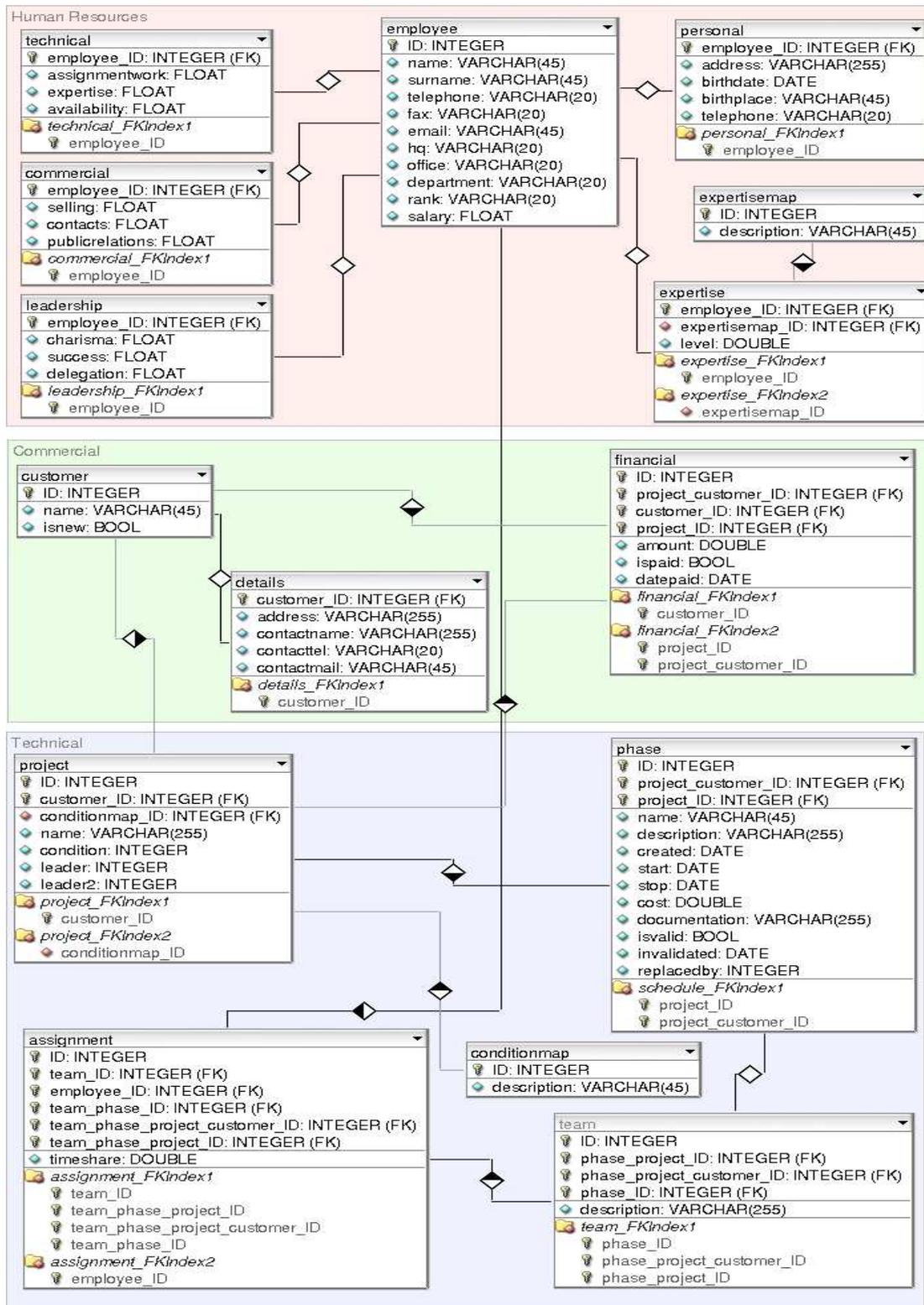


Figure 6.3: T-Sales' database structure.

6.3.1.1 Meeting output

1. The table among `technical`, `commercial`, `leadership` which contains the employee's ID gives its main occupation.
2. We consult the `expertise` table. For a description of the expertise, we consult `expertisemap`.
3. We simply look at the `condition` field of the `project` table, whose description is in `conditionmap`.
4. We scan the `phase` table for a given project and count the times the `isvalid` field contains 'true'.
5. We find the last phase of the project looking at the `phase` table and we compare the `stop` field with the `datepaid` field of the `financial` table.
6. We scan the `financial` table for a given customer, and find whether the completion date (`stop` field) of the last phase in the project (table `phase`, accessed through `project`) corresponds with the `datepaid` field of the `financial` table.
7. We sum the costs of all the non-invalidated phases in the project and compare it to the total project cost (`amount` field in `financial` table).
8. The function changes every time a phase is invalidated or created. The cost is the cumulative cost of all the phases which are valid at any given time.
9. Since we only know the costs due to human resources, we must find the salaries of all the people involved in the project and scale them by the percentage of their time they devoted to the project. In other words, we must sum the scaled salaries over all phases of the project, over all teams involved in the phase, and over all people associated to the team.
10. We find the people involved in the project through phases and teams, and we compute their expertise level vector.
11. Similar to the above.
12. We match the teams involved in a project with indicators such as the project's condition and the number of invalidated phases (the fewer, the better).
13. We find the subsets of people from a team which occur most often in the most unsuccessful projects.

6.3.2 Brainstorming: Ideas proposal

The commercial offer quotes: "Given some meaningful key-words or other well-defined indicators in the description of a new project, we want to classify it by some quantitative indices [...]". Such concepts as "meaningful key-words or other well-defined indicators" and "quantitative indices" are not well-defined, and therefore pose the most difficult problem to be solved in order to arrive at a software architecture. In order to solve the problem, a brainstorming meeting is called.

Aim of the meeting:

1. find a set of well-defined new project indicators which are suitable for searching similar terms in the T-Sale database;
2. find a set of quantitative indices to be computed using the T-Sale database information, which should shed light on the future life cycle of the new project;
3. document all ideas spawned during the meeting in a formal document.

6.3.2.1 Meeting output

Here is one possible approach to solving these problems:

1. find all project indicators which are known at the initial stage (details of first phase, customer history, personal compatibilities in teams);
2. propose a sizable number of quantitative indices that can be associated to a project (initial projected cost, cost curve, required skill levels, total human resources cost, number of teams, number of people, total cost, ...);
3. cluster all projects with similar degree of success (i.e. look at the `condition` field and at the number of invalidated phases) and produce a partition of the set of projects such that all projects in a partition subset have the same degree of success;
4. the most meaningful quantitative indices in the proposed set are those having the least variance in each partition subset;
5. finding the variance of the project indicators in the partition subsets will give an idea of the indicator reliability.

6.3.3 Functional architecture

Propose a functional architecture for the software. This should include the main software components and their interconnections, as well as a break-down of the architecture into sub-parts so that development teams can be formed and assigned to each project part. Since system-wide faults arise from badly interacting teams, it is naturally wise to minimize the amount of team interaction needed.

6.3.3.1 Solution

The only available point of departure for this analysis is the sketched architecture design contained in our commercial offer, which at this point should be used and expanded into a detailed and fully implementable software architecture. The following components are apparent:

1. **Input web form** (IWF): user inputs early indicator values concerning a new project
2. **Output web form** (OWF): user sees similar projects with relevant indicator values
3. **Clustering engine** (CE): given a set of objects and their pairwise distances, perform a clustering minimizing the inter-cluster distances
4. **Clustering significance evaluator** (CSE): Given a clustering, does it match well to another given clustering?
5. **Classification** (CLS): given an indicator for a given type of clustering, find the cluster it belongs to in the given and all similar clusterings
6. **Customer's DB**: split in *Commercial* (CDB), *Human resources* (HRDB), *Technical* (TDB) data repositories
7. **Clustering DB** (CLDB): repository for existing clusterings.

Fig. 6.4 shows a mixture of state, architecture and deployment diagram based on this modularization. Vertices are either logic anchors (black), actions (yellow), important data (green) and databases (blue). Arcs denote logic flow (black) or data flow (blue).

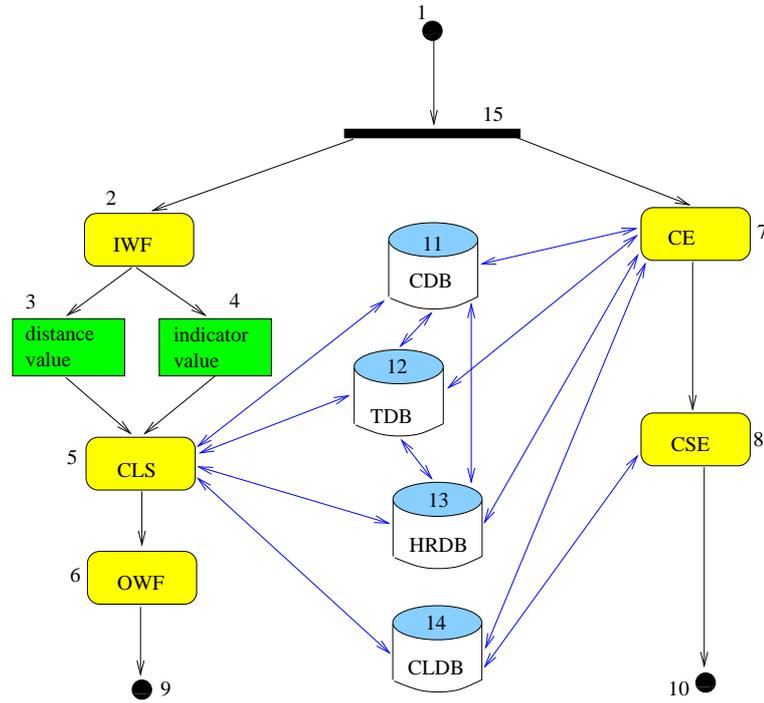


Figure 6.4: Initial diagram.

6.3.3.1.1 Interfacing An *interface* is a module whose only purpose is that of passing data between other module. Interfaces are useful to standardize function calls or message passing protocols. Functional/technical architectures may become entangled and “modularized” after prototype implementations have exhibited previously unsuspected module connection needs, resulting in architecture graph diagrams having many arcs/edges (connections) and relatively few nodes (modules). The *interfacing operator* is an automatic graph reformulation that adds interface modules in order to reduce the total number of connections.

Consider a digraph $G = (V, A)$ representing the existing architecture. We aim to construct a digraph $G' = (V', A')$ with fewer arcs but same transitive closure (i.e. same connection topology) by introducing interface modules. In our formalism, we represent the inter-modular connection/relation type as a colour on the corresponding arc.

Given an arc colouring $\mu : A \rightarrow \mathbb{N}$ of G and a connected subgraph $H = (U, F)$ of G' such that $\mu(e) = \mu(f)$ for all $e, f \in F$, G' is defined as G with the subgraph H replaced by a subgraph $H' = (U', F')$ where $U' = U \cup \{\iota\}$; $(u, \iota), (\iota, v) \in F'$ if and only if $(u, v) \in F$. The aim of this reformulation is to simplify a set of interconnections of the same type. In the extreme case where H is a complete subgraph, the reformulation replaces it with a complete star around ι , which reduces the number of interconnections by a factor $|U|$. Naturally, in order for this reformulation to be worthwhile, we require $|F'| < |F|$. As $|F'|$ is bounded above by $2|U|$, it is interesting to study the problem of finding a (not necessarily induced) subgraph $H = (U, F)$ of G whose arcs have the same colour and such that $|F| - |U|$ is maximum. Let $\{1, \dots, K\}$ be the set of arc colours in G . For all $v \in V_{i-1}$ consider binary variables $x_v = 1$ if $v \in U$ and 0 otherwise. For any colour $k \leq K$, the problem of finding the “densest” proper uniformly coloured

subgraph $H_k = (U, F)$ of G can be formulated as follows.

$$\max_{x,y} \sum_{(u,v) \in A_{i-1}} x_u x_v - \sum_{v \in V_{i-1}} x_v \quad (6.1)$$

$$\forall (u,v) \in A_{i-1} \quad x_u x_v \leq \min(\max(0, \mu_{uv} - k + 1), \max(0, k - \mu_{uv} + 1)) \quad (6.2)$$

$$x \in \{0, 1\}^{|V_{i-1}|}. \quad (6.3)$$

The interfacing operator is implemented by algorithmically providing a solution to (6.1)-(6.3). We apply the interfacing operator to this graph on the blue arc color (data flow arcs, coded by the label 2 in the AMPL data file). The AMPL model file is as follows.

```
# interface.mod
# AMPL model for interface creation

# graph
param n >= 1, integer;
set V := 1..n;
set E within {V,V};

# edge weights
param c{E};

# edge inclusions
param I{E};

# vertex colours
param lambda{V};

# arc colours
param kmax default 10;
param k <= kmax, >= 0, integer, default 1;
param mu{E} >= 0, integer, <= kmax;

# variables
var x{V} binary;
var y{(u,v) in E} >= 0, <= min(max(0, mu[u,v]-k+1), max(0,k-mu[u,v]+1));

# model
maximize densesubgraph : sum{(u,v) in E} I[u,v] * c[u,v] * y[u,v] -
    sum{v in V} x[v];

# linearization constraints
subject to lin1 {(u,v) in E} : y[u,v] <= x[u];
subject to lin2 {(u,v) in E} : y[u,v] <= x[v];
subject to lin3 {(u,v) in E} : y[u,v] >= x[u] + x[v] - 1;
```

The AMPL data file is as follows.

```
# activity1.dat
# AMPL dat file from UML activity diagram 1

param n := 15;
param : E : c I mu :=
    1 15 1 1 1
    2 15 1 1 1
    2 3 1 1 1
    2 4 1 1 1
    3 5 1 1 1
    4 5 1 1 1
    5 6 1 1 1
    5 11 1 1 2
    5 12 1 1 2
    5 13 1 1 2
    5 14 1 1 2
    6 9 1 1 1
    7 8 1 1 1
    7 11 1 1 2
    7 12 1 1 2
    7 13 1 1 2
    7 14 1 1 2
    7 15 1 1 1
```

```

      8 10 1 1 1
      8 14 1 1 2
      11 12 1 1 2
      11 13 1 1 2
      12 13 1 1 2
;

param lambda :=
1 1
2 2
3 3
4 3
5 2
6 2
7 2
8 2
9 1
10 1
11 4
12 4
13 4
14 4
15 1 ;

```

The AMPL run file is as follows.

```

# file interface.run
model interface.mod;
data activity1.dat;
let k := 2; # choose the colour
option solver cplexstudent;
solve;
display y;
display x;

```

We solve the problem by issuing the command `cat interface.run | ampl`. We find the interface subgraph $H = (U, F)$ where $U = \{5, 7, 11, 12, 13, 14\}$ and $F = \{\text{all blue arcs}\}$. We add a new vertex 16 representing the interface, remove the arcs F and add the (bidirected) arcs $F' = \{\{u, 16\} \mid u \in U\}$. Since 16 is a database interface, we assign it the database vertex colour (blue). The diagram evolves into Fig. 6.5.

6.3.3.1.2 Synthesis Modules in a software architecture need to be clustered for at least two good reasons: (a) to give an idea of the different independent (or nearly independent) “streams” in the architecture; (b) to be able to assign separate sets of modules to separate teams.

One of the most common ways to bootstrap a software architecture design process is to construct the initial graph G_0 by means of a brainstorming session: this will almost always give rise to a very “tangled” architecture. Modules will roughly correspond to the requirements list, and will be heavily interconnected. Clustering these modules in an arbitrary way according to their perceived semantics may give rise to clusters whose degree of inter-dependency is not minimal, which will greatly complicate team interactions and possibly impair the whole development process.

In its most basic form, the clustering procedure acts on a weighted, undirected graph $G = (V, E, c)$ (where $w : E \rightarrow \mathbb{R}$) and outputs an assignment of vertices in V to a set of clusters such that the weights of inter-cluster edges is minimized. Such a problem is known in the combinatorial optimization literature as the GRAPH PARTITIONING PROBLEM (GPP) [1, 9, 4, 2].

Its formulation in terms of mathematical programming is as follows: given the weighted undirected graph G and an integer $K \leq |V|$, the problem consists of finding a partition of k subsets (clusters) of V minimizing the total weight of edges $\{u, v\}$ where u, v belong to different clusters. To each vertex $v \in V$ and for each cluster $k \leq K$, we associate a binary variable x_{vk} which is 1 if vertex v is in cluster h and 0

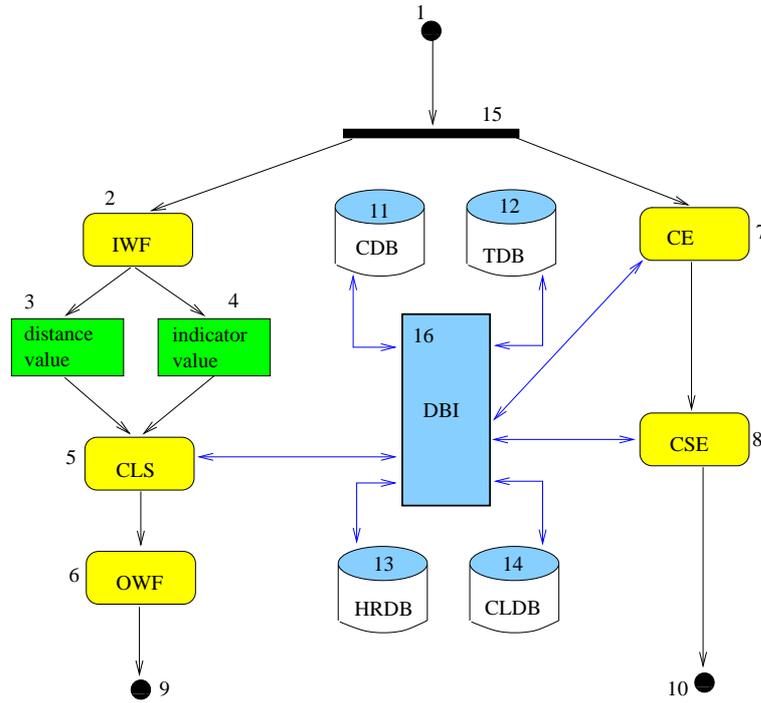


Figure 6.5: Diagram after interfacing.

otherwise. We formulate the problem as follows:

$$\min_x \frac{1}{2} \sum_{k \neq l \leq K} \sum_{\{u,v\} \in E} c_{uv} x_{uk} x_{vl} \quad (6.4)$$

$$\forall v \in V \quad \sum_{k \leq K} x_{vk} = 1 \quad (6.5)$$

$$\forall k \leq K \quad \sum_{v \in V} x_{vk} \geq 1 \quad (6.6)$$

$$\forall v \in V, k \leq K \quad x_{vk} \in \{0, 1\}. \quad (6.7)$$

This model relies on binary variables and includes many (nonconvex) quadratic terms. Various ways to linearize the formulation have been suggested [3, 10]. The objective function (6.4) tends to minimize the total weight of edges with adjacent vertices in different clusters. Constraints (6.5) make sure that each vertex is assigned to exactly one cluster. Constraints (6.6) excludes the trivial solution (all the vertices in one cluster) and ensures each cluster exists. Further conditions, such as the clusters not exceeding a “balanced” cardinality, may also be imposed:

$$\forall k \leq K \quad \sum_{v \in V} x_{vk} \leq \left\lceil \frac{|V|}{2} \right\rceil. \quad (6.8)$$

A useful variant of the problem asks for all adjacent vertices with like colours to be clustered together. The vertex colours are defined by an integer-valued function $\lambda : V \rightarrow \mathbb{N}$ (we denote $\lambda(u)$ by λ_u). For all $u, v \in V$ (with $u \neq v$) we introduce binary parameters $\gamma_{uv} = 1$ if u, v have different colours. We must then add the following constraints:

$$\forall u \neq v \in V, k \neq l \leq K \quad x_{uk} x_{vl} \leq \gamma_{uv}. \quad (6.9)$$

Should these constraints be too restrictive and make it too difficult for the solution algorithm to actually find a solution, we may want to relax them somewhat. We can do this by removing (6.9) and adding the term $\sum_{u \neq v \in V} \sum_{k \neq l \leq K} |x_{uk}x_{vl} - \gamma_{uv}|$ to the objective function (6.4).

Another useful variant allows the optimization process to determine the number of clusters actually used. For all $k \leq K$ we introduce binary variables $z_k = 1$ if cluster k is non-empty and 0 otherwise. We change constraints (6.6) to

$$\forall k \leq K \quad \sum_{v \in V} x_{vk} \geq z_k, \quad (6.10)$$

to ensure that a cluster that does not exist need not have any vertices assigned to it, and then we add the term $\sum_{k \leq K} z_k$ to the objective function to be minimized, thus ensuring that the maximum number of clusters should be empty.

Once the set of clusters \mathcal{K} have been identified, the current graph G may be replaced by a graph $G' = (V', A')$ where V' is the set of clusters \mathcal{K} and $(u, v) \in A'$ if there are $w \in u, z \in v$ (recall u, v are subsets of V) such that $(w, z) \in A$. The *synthesis operator* performs such a reformulation to the architecture diagram.

We now apply the synthesis operator to the architecture, in order to identify some clusters with a small number of interconnections. Such clusters may help break down the architecture in logically disconnected parts; as system-wide faults usually emerge from inter-team lack of communication, assigning such parts to different teams will minimize the chances of ending up with system-wide faults.

The AMPL model is as follows.

```
# flexcolour_clustering.mod
# flexible coloured clustering (colours on vertices) - AMPL model

# graph
param n >= 1, integer;
set V := 1..n;
set E within {V,V};

# edge weights
param c{E};

# edge inclusions
param I{E};

# vertex colours
param lambda{V};
param gamma{u in V, v in V : u != v} :=
  if (lambda[u] = lambda[v]) then 0 else 1;

# arc colours
param mu{E};

# max number of clusters
param kmax default n;
set K := 1..kmax;

# original problem variables
var x{V,K} binary;

# linearization variables
var w{V,K,V,K} >= 0, <= 1;

# cluster existence variables
var z{K} binary;

# model
minimize intercluster :
  sum{k in K, l in K, (u,v) in E : k != l} I[u,v] * c[u,v] * w[u,k,v,l] +
  sum{k in K} z[k];

subject to assignment {v in V} : sum{k in K} x[v,k] = 1;

# use (ceil(card{V}/kmax)+1) as RHS for balanced multi-cluster cardinality
subject to cardinality {k in K} : sum{v in V} x[v,k] <= ceil(card{V}/2);
```

```

subject to existence {k in K} : sum{v in V} x[v,k] >= z[k];

subject to difffcolours {u in V, v in V, k in K, l in K : u != v and k != l} :
  w[u,k,v,l] <= gamma[u,v];

### linearization constraints
subject to lin1 {u in V, v in V, h in K, k in K : (u,v) in E or (v,u) in E} :
  w[u,h,v,k] <= x[u,h];
subject to lin2 {u in V, v in V, h in K, k in K : (u,v) in E or (v,u) in E} :
  w[u,h,v,k] <= x[v,k];
subject to lin3 {u in V, v in V, h in K, k in K : (u,v) in E or (v,u) in E} :
  w[u,h,v,k] >= x[u,h] + x[v,k] - 1;

```

The AMPL data file is as follows.

```

# activity2.dat
# AMPL dat file from UML activity diagram 2

param n := 16;
param : E : c I mu:=
  1 15 1 1 1
  2 15 1 1 1
  2 3 1 1 1
  2 4 1 1 1
  3 5 1 1 1
  4 5 1 1 1
  5 6 1 1 1
  5 16 1 1 2
  6 9 1 1 1
  7 8 1 1 1
  7 16 1 1 2
  8 10 1 1 1
  8 16 1 1 2
  11 16 1 1 2
  12 16 1 1 2
  13 16 1 1 2
  14 16 1 1 2
;

param lambda :=
  1 1
  2 2
  3 3
  4 3
  5 2
  6 2
  7 2
  8 2
  9 1
  10 1
  11 4
  12 4
  13 4
  14 4
  15 1
  16 4 ;

```

The AMPL run file is as follows.

```

# file flexcolour_clustering.run
model flexcolour_clustering.mod;
data activity1.dat;
let kmax := 4; # maximum number of clusters
option solver cplexstudent;
solve;
display y;
display x;

```

We solve the problem by issuing the command `cat flexcolour_clustering.run | ampl`. We ask for at most 4 clusters (`let kmax := 4;`). We obtain two clusters: $C_1 = \{1, 2, 3, 4, 5, 6, 9, 15\}$ and $C_2 = \{7, 8, 10, 11, 12, 13, 14, 16\}$. The diagram is now as in Fig. 6.6.

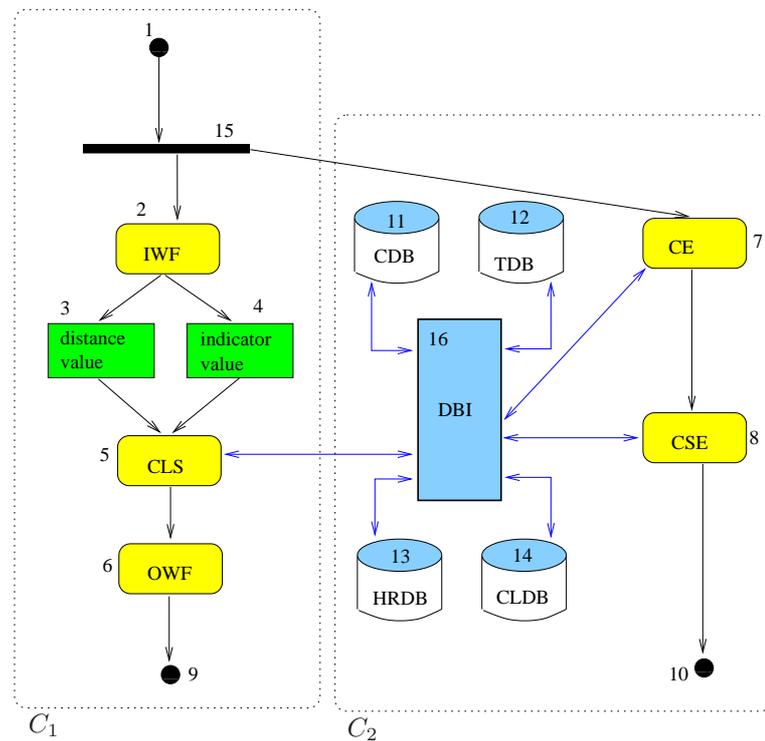


Figure 6.6: Diagram after clustering.

The architecture is composed of two main subsystems C_1, C_2 , corresponding to two activity processes $IWF \rightarrow CLS \rightarrow OWF$ (performed by the user) and $CE \leftrightarrow CSE \leftrightarrow DBI$ (performed by the program) that we may call respectively the *foreground* and *background* processes. The foreground subsystem consists of three main components (input, classifier and output); the background subsystem consists of a database sub-subsystem (with an interface and four databases) and two main components (clustering engine and clustering significance evaluator). Very high-level specifications may now be given as follows:

1. IWF: input indicator(s) and clustering distance(s) from the user
2. CLS: classify new project according to given indicator(s) and distance(s) using a database of existing clusterings with cluster-matching information
3. OWF: output set of existing projects close to the new project w.r.t. given indicator(s)
4. CE: given a set of indicator values and an associated distance metric, cluster the values; pass the clustering to the DB interface for storage
5. CSE: given two clusterings, match them and verify their compatibility; pass the matching information to the DB interface for storage
6. DBI: interface to customer and clustering DBs.

The two processes (corresponding to C_1, C_2) are linked by arcs (15, 7) (a logical flow arc) and (5, 16) (a data flow arc). The logical path choices (1, 15, 2) and (1, 15, 7) identify the foreground and background processes respectively. If we consider two separate starting points for the two processes we can eliminate vertex 15 and all its adjacent arcs (including (15, 7)). We then introduce a starting vertex (labelled 15, since the old vertex 15 was reformulated out of the graph) for the background process (see Fig. 6.7). The data flow arc (5, 16) is crucial to the process interplay and cannot be eliminated. It actually gives

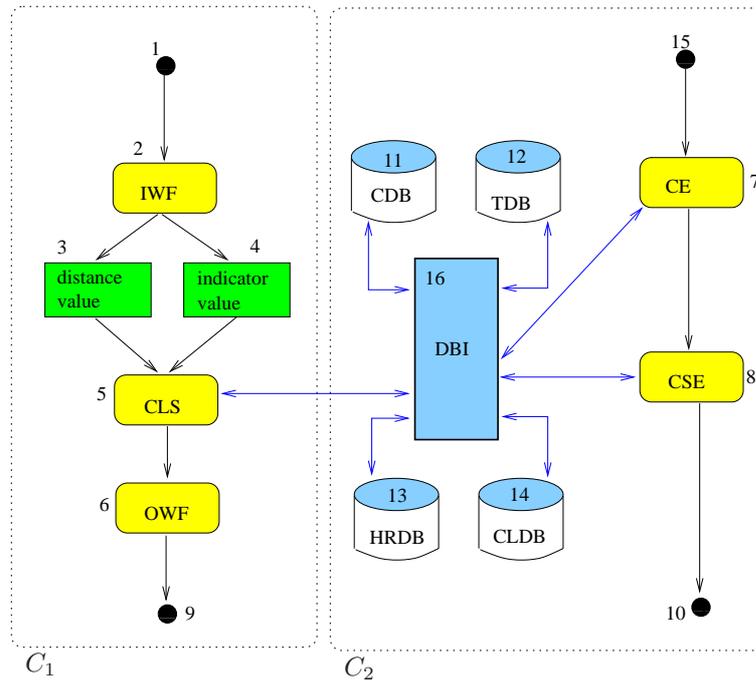


Figure 6.7: Final diagram: separating the processes.

the extent and the type of interconnection between the processes. It also suggests where the two teams developing the different process will need to interact, namely in the design of the database interface (DBI, vertex 16): more precisely, the background process team will need to explain to the other team what data is made available by the interface, and the foreground process team will need to require the appropriate data exchange formats and protocols.

The precise breakdown of each component into classes and methods is part of the technical architecture.

6.3.4 Technical architecture

Propose a technical architecture detailing the inner working of each system component, as well as the system as a whole. This should include a class diagram and component APIs (application programming interfaces).

6.3.4.1 Solution

In order to build a class diagram and the APIs, we need to know how input data are transformed into the output data, and exactly which data is passed from one component to another. As the background process is in some way a server to the foreground one, we shall model the latter first (top-down approach).

Informally, the data flow for the foreground process is as follows:

input $\xrightarrow{\text{IWF}}$ (early indicator, indicator value, distance value) $\xrightarrow{\text{CLDB}}$
 \rightarrow (corresponding early clustering, cluster) $\xrightarrow{\text{CLS}}$
 \rightarrow (matching late clustering(s), cluster(s)) $\xrightarrow{\text{OWF}}$
 \rightarrow **output** projects in identified cluster(s).

In order for the foreground process data flow to make any sense, the CLDB database must contain all the clusterings relative to the given early indicator value and distance, and the CLS component must be able to match early and late clusterings (and to draw the appropriate “close” clusters from the matched clusterings). The background process must therefore supply the necessary information. Recall that the foreground process is ran by each user, and so should be as fast as possible. It is therefore necessary to delegate most of the computational work to the background process: all data transformation should draw from information that was pre-computed by the background process. In particular, finding a matching late clustering should be as simple as looking up a pre-computed boolean value in an array; in turn, this means that the background process must pre-compute all possible matching information and store it in the CLDB database.

Informally, the data flow for the background process is as follows:

start \rightarrow all possible pairs ((early indicator, distance), (late indicator, distance)) $\xrightarrow{\text{CE}}$
 \rightarrow (clustering) $\xrightarrow{\text{DBI}}$
 \rightarrow **store** (clustering) $\xrightarrow{\text{CSE}}$
 \rightarrow (do clustering match?, list of matching clusters) $\xrightarrow{\text{DBI}}$
 \rightarrow **store** (matching info) \rightarrow **stop**.

To make the data flow descriptions more formal, we must make clear what we mean precisely by such concepts as indicator, distance, cluster, clustering, clustering comparison.

6.3.4.1.1 Indicators An *indicator* is a non-negative real-valued function $v : P \rightarrow \mathbb{R}_+$ defined on the set of projects P . Given an indicator v , we let:

$$\bar{v} = \max_{p \in P} v(p)$$

$$\underline{v} = \min_{p \in P} v(p).$$

Early indicators are indicators whose value can be defined before the project is started; *late* indicators may only be defined after the project ends. Consider early indicators v_i^E for $i \leq m$ and late indicators v_j^L for $j \leq n$. For each early indicator $i \leq m$ we also consider finite sets of distances¹ D_i^E with (and likewise for late indicators).

6.3.4.1.2 Clusterings Given an indicator v on P and a distance value $d \in \mathbb{R}_+$, a *clustering* γ_{vd} of P is a set of $K_{vd} = |\gamma_{vd}|$ subsets γ_{vdk} of P , where $k \leq K_{vd}$ and

$$K_{vd} = \left\lceil \frac{\bar{v}_i - \underline{v}_i}{d} \right\rceil,$$

such that:

¹By *distance* we mean here a generic measure of similarity, without implying the triangular inequality.

- (a) $\forall p \in P \exists k \leq K_{vd} (p \in \gamma_{vdk})$ (covering condition).
 (b) $\forall k \leq K_{vd} \forall p \in \gamma_{vdk} (\underline{v}_i + kd \leq v(p) \leq \underline{v}_i + (k+1)d)$ (cluster extent).

Notice we define clusterings so that γ_{vd} is unique for each choice of v, d and can be computed in $O(|P|)$. This is not the only possible such definitions. Other definitions allow for non-uniqueness and for higher computational complexity orders.

Each subset γ_{vdk} of a clustering is called a *cluster*; because of (b), we can assign to each cluster γ_{vdk} an interval $I_{vdk} = [\underline{v}_i + kd, \underline{v}_i + (k+1)d]$. Let γ_{id}^E be the clustering of P corresponding to the early indicator v_i^E and distance $d \in D_i^E$, with $K_{id} = |\gamma_{id}^E|$; let γ_{idk}^E be the k -th cluster of γ_{id}^E for $k \leq K_{id}$ (and likewise for late indicators). Fig. 6.8 shows an example of a clustering where $P = \{1, \dots, 10\}$, $\underline{v} = 0$, $\bar{v} = 3$, $d = 1$.

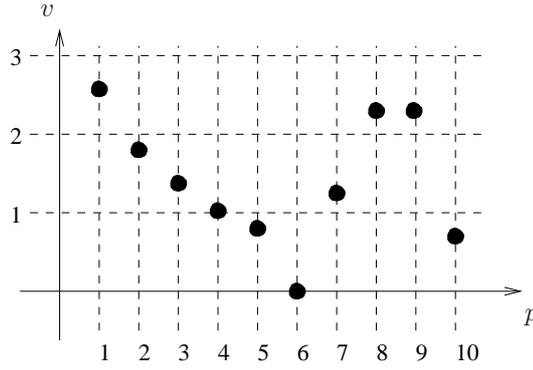


Figure 6.8: Clustering example. We obtain three clusters $\gamma_{vd1} = \{4, 5, 6, 10\}$ with $I_{vd1} = [0, 1]$, $\gamma_{vd2} = \{2, 3, 4, 7\}$ with $I_{vd2} = [1, 2]$ and $\gamma_{vd3} = \{1, 8, 9\}$ with $I_{vd3} = [2, 3]$.

6.3.4.1.3 Clustering comparison Our software relies on our ability to successfully compare early and late clusterings and say if they match or not. Given two indicators u, v and distances d, δ with relative clusterings γ_{ud} and $\gamma_{v\delta}$, we first scale the indicator values and distances so that they are comparable. This can be easily done by scaling the two clustering intervals I_{ud} and $I_{v\delta}$ to the interval $[0, 1]$: for all $p \in P$ let

$$\begin{aligned}\tilde{u}(p) &= \frac{u(p) - \underline{u}(p)}{\bar{u}(p) - \underline{u}(p)} \\ \tilde{v}(p) &= \frac{v(p) - \underline{v}(p)}{\bar{v}(p) - \underline{v}(p)} \\ \tilde{d} &= \frac{d - \underline{u}(p)}{\bar{u}(p) - \underline{u}(p)} \\ \tilde{\delta} &= \frac{\delta - \underline{v}(p)}{\bar{v}(p) - \underline{v}(p)}.\end{aligned}$$

We define the dissimilarity between the two clusterings $\gamma_{ud}, \gamma_{v\delta}$ as:

$$\Delta(\gamma_{ud}, \gamma_{v\delta}) = (\tilde{d} - \tilde{\delta})^2 + \sum_{p \in P} (\tilde{u}(p) - \tilde{v}(p))^2.$$

Notice this definition does not actually consider the clustering itself, but just the indicator and the distance: this occurs because of the way our clusterings are defined. More precisely, this occurs because the cluster each $p \in P$ belongs to is determined by p alone and not by the other elements of P .

Given an overall tolerance $\varepsilon > 0$, an early indicator clustering γ_{id}^E (where $i \leq m$ and $d \in D_i^E$) *matches* a late indicator clustering $\gamma_{j\delta}^L$ (where $j \leq n$ and $\delta \in D_j^L$) if either one of the two conditions below is satisfied:

1. $\Delta(\gamma_{id}^E, \gamma_{j\delta}^L) \leq \varepsilon$;
2. $\Delta(\gamma_{id}^E, \gamma_{j\delta}^L) = \min_{h \leq n, b \in D_h^L} \Delta(\gamma_{id}^E, \gamma_{hb}^L)$;

we denote the matching by $M(\gamma_{id}^E, \gamma_{j\delta}^L) = 1$ and a mismatch by $M(\gamma_{id}^E, \gamma_{j\delta}^L) = 0$. If two matching clusterings satisfy the first condition, it is a close match. The second condition is a ‘‘catch-all’’ condition which ensures that we can match each early indicator clustering to at least one late indicator clustering.

Given two matching clusterings $\gamma_{ud}, \gamma_{v\delta}$, we must now find indices $h \leq K_{ud}$ and $k \leq K_{v\delta}$ such that γ_{udh} and $\gamma_{v\delta k}$ are ‘‘as close as possible’’. We extend the dissimilarity definition Δ to clusters as follows:

$$\Delta(\gamma_{udh}, \gamma_{v\delta k}) = (\tilde{d} - \tilde{\delta})^2 + \sum_{p \in \gamma_{udh} \cap \gamma_{v\delta k}} (\tilde{u}(p) - \tilde{v}(p))^2 + |\gamma_{udh} \Delta \gamma_{v\delta k}|,$$

where $A \Delta B = (A \cup B) \setminus (A \cap B)$ is the symmetric difference of two sets A, B . This definition is justified by the fact that the difference in normalized indicator value for a project p in $\gamma_{udh} \Delta \gamma_{v\delta k}$ is simply the diameter of the corresponding normalized interval $[0, 1]$, namely 1, and that $1^2 = 1$. With this extended definition, we can compute $\Delta(\gamma_{udh}, \gamma_{v\delta k})$ for each possible pair (h, k) and determine a pair of closest clusters. We denote the set of clusters $\gamma_{v\delta k}$ in $\gamma_{v\delta}$ closest to a given cluster γ_{udh} by $\Gamma(\gamma_{udh}, \gamma_{v\delta})$.

6.3.4.1.4 The foreground process The data transformation model of the foreground process is as follows: we are given a new project π ; we select an early indicator v_i^E , compute $w = v_i^E(\pi)$, select a meaningful distance $d \in D_i^E$, find the corresponding clustering γ_{id}^E and the cluster γ_{idk}^E such that $w \in I_{idk}$. We then find a late indicator clustering $\gamma_{j\delta}^L$ (where $j \leq n$ and $\delta \in D_j^L$) such that $M(\gamma_{id}^E, \gamma_{j\delta}^L) = 1$, and the corresponding closest clusters $\gamma_{j\delta h}^L \in \Gamma(\gamma_{idk}^E, \gamma_{j\delta}^L)$. The formal data flow description of the foreground process is:

$$\begin{aligned} \text{input} & \xrightarrow{\text{IWF}} (\pi, v_i^E, d) \xrightarrow{\text{CLDB}} (\gamma_{id}^E, \gamma_{idk}^E : v_i^E(\pi) \in I_{idk}) \xrightarrow{\text{CLS}} \\ & \rightarrow O = \{(j, \delta, h) \mid M(\gamma_{id}^E, \gamma_{j\delta}^L) = 1 \wedge \gamma_{j\delta h}^L \in \Gamma(\gamma_{idk}^E, \gamma_{j\delta}^L)\} \xrightarrow{\text{OWF}} \\ & \rightarrow \forall (j, \delta, h) \in O \text{ output projects in } \gamma_{j\delta h}^L \end{aligned}$$

The required data structures are:

- project (p , class): contains project attributes as defined in the T-Sale DB;
- cluster (list of projects);
- clustering (γ : list of clusters);
- indicator (v , class): contains
 - methods to retrieve the indicator value given a project
 - list of clustering distances D (floating point numbers)
 - extremal values \bar{v}, \underline{v} (floating point numbers)
 - list of clusterings γ_{vd} for this indicator, relative to all distances $d \in D$
 - methods to scale the indicator values and distances in D to the interval $[0, 1]$
- foreground process (class): contains
 - list of early indicators ($v_i^E \mid i \leq m$);
 - list of late indicators ($v_j^L \mid j \leq n$);
 - matching information (M , array of booleans indexed on $i \leq m, d \in D_i^E, j \leq n, \delta \in D_j^L$);
 - matching cluster information (Γ , maps clusters γ_{idk} for varying $k \leq K_{id}$ to list of matching clusters ($\gamma_{j\delta h}$) for varying $h \in \{1, \dots, K_{j\delta}\}$).

6.3.4.1.5 The background process The data transformation model of the background process is as follows: given an early indicator v_i^E ($i \leq m$), a distance $d \in D_i^E$, a late indicator v_j^L ($j \leq n$) and a distance $\delta \in D_j^L$:

- if γ_{id}^E is present in the CLDB database retrieve it, else compute it and store it;
- if $\gamma_{j\delta}^L$ is present in the CLDB database retrieve it, else compute it and store it.

Determine $M(\gamma_{id}^E, \gamma_{j\delta}^L)$ and store it in the CLDB database; if $M(\gamma_{id}^E, \gamma_{j\delta}^L) = 1$, for each $k \in K_{id}$ compute the set $\Gamma(\gamma_{idk}^E, \gamma_{j\delta}^L)$ and store it in the CLDB database. The formal data flow description of the background process is:

```

start  →   $\{(v_i^E, d), (v_j^L, \delta) \mid i \leq m \wedge d \in D_i^E \wedge j \leq n \wedge \delta \in D_j^L\} \xrightarrow{\text{CE}}$ 
          →   $\mathcal{C} = \{(\gamma_{id}^E, \gamma_{j\delta}^L) \mid i \leq m \wedge d \in D_i^E \wedge j \leq n \wedge \delta \in D_j^L\} \xrightarrow{\text{DBI}}$ 
          →  store  $\mathcal{C} \xrightarrow{\text{CSE}}$ 
          →   $\mathcal{M} = ((M(c) \mid c \in \mathcal{C}), (\Gamma(\gamma_{idk}^E, \gamma_{j\delta}^L) \mid (\gamma_{id}^E, \gamma_{j\delta}^L) \in \mathcal{C}, k \in K_{id})) \xrightarrow{\text{DBI}}$ 
          →  store  $\mathcal{M} \rightarrow$  stop.

```

The required data structures are all those listed in Section 6.3.4.1.4 aside from the foreground process class, plus a background process class containing:

- list of early indicators ($v_i^E \mid i \leq m$)
- list of late indicators ($v_j^L \mid j \leq n$)
- matching information (M , array of booleans indexed on $i \leq m, d \in D_i^E, j \leq n, \delta \in D_j^L$)
- matching cluster information (Γ , maps clusters γ_{idk} for varying $k \leq K_{id}$ to list of matching clusters $(\gamma_{j\delta h})$ for varying $h \in \{1, \dots, K_{j\delta}\}$)
- methods for computing Δ applied to clusterings
- methods for computing intersections of clusters
- methods for computing symmetric differences of clusters
- methods for computing Δ applied to clusters.

6.3.4.1.6 Class structure The class structure is detailed in Fig. 6.9.

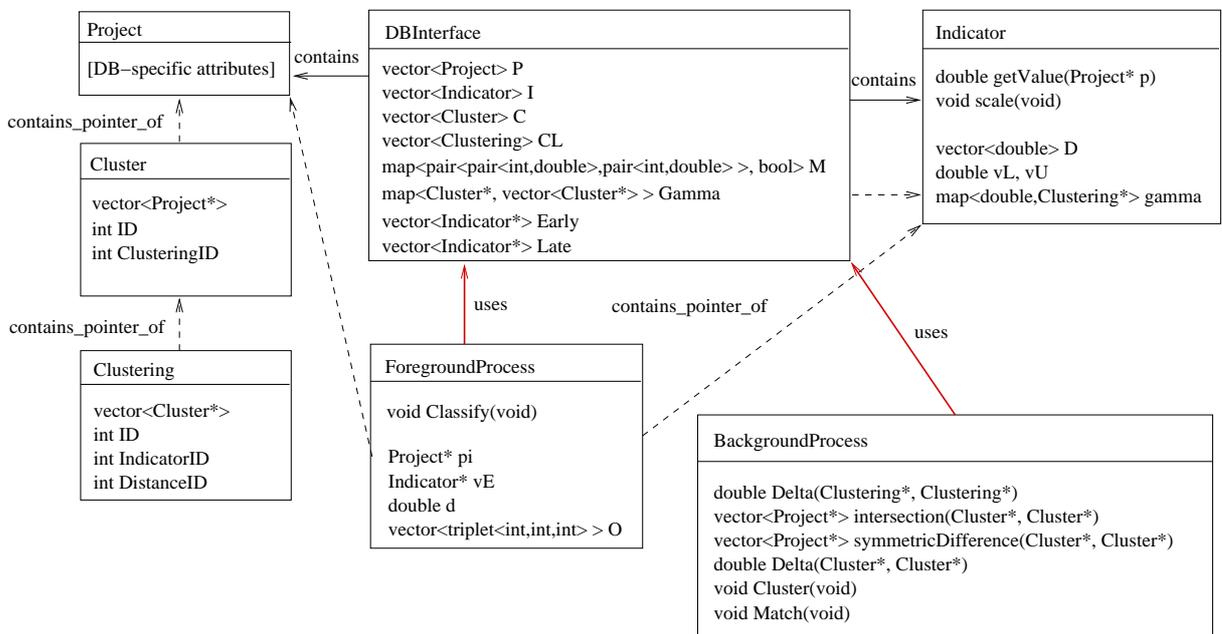


Figure 6.9: The class diagram of the fore- and background processes.

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