

# Compatible programs

Two programs  $P$  and  $Q$  are said to be **compatible** when their initial valuations and their arity maps coincide on the intersection of their domains of definition. In that case we define the **parallel composition**  $P|Q$ .

By extension we define the parallel composition of  $P_1, \dots, P_N$  when the programs are **pairwise compatible**.

Two programs are said to be **syntactically independent** when the set of resources they use are disjoint:

- they have no variables in common,
- they have no semaphores in common, and
- they have no barriers in common.

Syntactically independent programs are compatible.

Syntactical independence can be decided **statically**, it is **compositional**, but it is too **restrictive**.

# Model Independence

Suppose the programs  $P_1, \dots, P_N$  are **conservative**.

The programs  $P_1, \dots, P_N$  are said to be **model independent** when

$$\llbracket P_1 | \dots | P_N \rrbracket = \llbracket P_1 \rrbracket \times \dots \times \llbracket P_N \rrbracket$$

Model independence can be decided **statically**.

# Compatible permutations

Assume we have a partition

$$\{1, \dots, n\} = S_1 \sqcup \dots \sqcup S_N$$

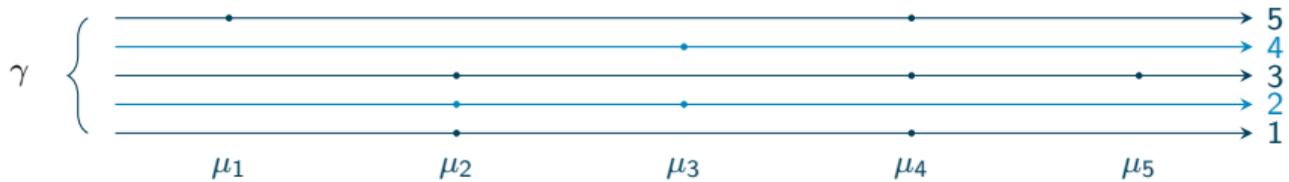
Two multi-instructions  $\mu$  and  $\mu'$  ( $\text{dom}(\mu), \text{dom}(\mu') \subseteq \{1, \dots, n\}$ ) can be **swapped** when

$$\{j \in \{1, \dots, N\} \mid S_j \cap \text{dom}(\mu) \neq \emptyset\} \cap \{j \in \{1, \dots, N\} \mid S_j \cap \text{dom}(\mu') \neq \emptyset\} = \emptyset$$

A permutation  $\pi$  of the set  $\{0, \dots, q-1\}$  is said to be **compatible** with the sequence of multi-instructions  $\mu_0, \dots, \mu_{q-1}$  when it is order preserving on all pairs  $\{k, k'\}$  such that  $\mu_k$  and  $\mu_{k'}$  cannot be swapped.

The permutation  $\pi$  is said to be **compatible** with the directed path  $\gamma$  when it is compatible with its associated sequence of multi-instructions.

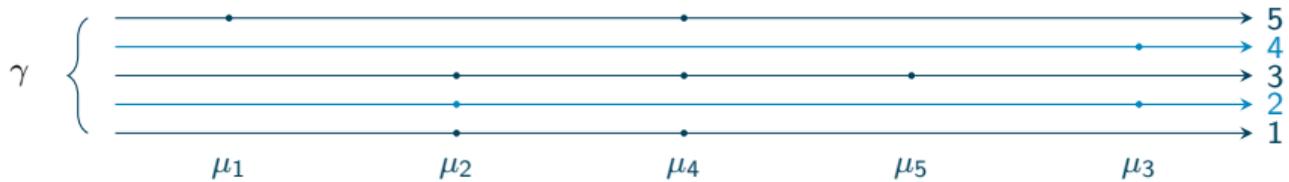
Assume that  $S_1 = \{1, 3, 5\}$  and  $S_2 = \{2, 4\}$ .



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# Observational independence

related to partial order reduction (?)

Suppose that the programs  $P_1, \dots, P_N$  are compatible and that  $P_j$  has  $n_j$  running processes.

The identifiers of the running processes of  $P_1 | \dots | P_N$  are the elements of  $\{1, \dots, n\}$  with

$$n = \sum_{j=1}^N n_j, \quad \text{and for } j \in \{1, \dots, N\} \quad s_j = \sum_{k=1}^j n_k$$

$$S_j = \{ i \in \{1, \dots, n\} \mid s_{j-1} < i \leq s_j \}$$

The programs  $P_1, \dots, P_N$  are said to be **observationally independent** when:

- for all execution traces  $\gamma$
- for all permutations  $\pi$  compatible with the sequence of multi-instructions  $(\mu_0 \cdots \mu_{q-1})$  associated with  $\gamma$ ,

there exists an execution trace  $\gamma'$  whose associated sequence of multi-instructions is  $\pi \cdot (\mu_0 \cdots \mu_{q-1})$ , which has the same action on the system state than  $\gamma$ , that is to say

$$\sigma \cdot (\mu_0 \cdots \mu_{q-1}) = \sigma \cdot (\mu_{\pi^{-1}(0)} \cdots \mu_{\pi^{-1}(q-1)}) .$$

Observational independence cannot be decided **statically**, moreover it is too **loose**.

# Main theorem



# One-dimensional regions

Let  $G$  be a finite graph, the collection  $\mathcal{R}_1 G$  of all finite unions of connected subsets of  $|G|$  forms a Boolean subalgebra of  $\text{Pow}(|G|)$ .

Moreover

$$\mathcal{R}_1 G \cong \text{Pow}(V) \times (\mathcal{R}_1 ]0, 1[)^{\text{card}A}$$

with  $A$  (resp.  $V$ ) being the set of arrows (resp. vertices) of  $G$ , and  $\mathcal{R}_1 ]0, 1[$  being the Boolean algebra of finite unions of subintervals of  $]0, 1[$ .

The elements of  $\mathcal{R}_1 G$  are seen as one-dimensional blocks.

**Proof:** If  $X$  is a connected subset of  $|G|$  then for all arrows  $\alpha \in G$ ,  $X \cap (\{\alpha\} \times ]0, 1[)$  has at most two connected components.

The finiteness condition is not necessary e.g.

$$\dots \rightarrow \cdot \rightarrow \dots$$

Yet some infinite graphs may not enjoy the property e.g. when  $G$  is a graph with a single vertex and infinitely many arrows.

# Higher dimensional blocks

- A **block** of dimension  $n \in \mathbb{N}$ , or  $n$ -**block**, is the product of  $n$  connected subsets of the metric graph  $|G|$ .
- A collection of blocks is called a **block covering** of  $X \subseteq |G|^n$  when the union of its elements is  $X$ .
- The collection of  $n$ -dimensional block coverings is denoted by  $\text{Cov}_n G$ , it is preordered by

$$C \preccurlyeq C' \quad \equiv \quad \forall b \in C \exists b' \in C', b \subseteq b'$$

# Maximal blocks

- A block contained in  $X$  is said to be a block of  $X$ . Such a block is said to be **maximal** when no block of  $X$  strictly contains it.
- The **maximal connected block covering** of  $X \subseteq |G|^n$  is the set of all its maximal connected blocks, it is denoted by  $\alpha_n(X)$ .
- $\alpha_n(X) = \{\emptyset\}$  if and only if  $X = \emptyset$ .

# A Galois connection

We have a Galois connection  $(\gamma_n, \alpha_n)$  between  $\text{Cov}_n G$  and  $\text{Pow}(|G|^n)$  with  $\gamma_n(D) = \bigcup D$  for all  $D \in \text{Cov}_n G$ .

$$\text{Cov}_n G \begin{array}{c} \xrightarrow{\gamma_n} \\ \xleftarrow{\alpha_n} \end{array} \text{Pow}(|G|^n)$$

In particular  $\gamma_n \circ \alpha_n = id$  and  $id \preceq \alpha_n \circ \gamma_n$ . That Galois connection induces an **isomorphism of Boolean algebras** between  $\text{Pow}(|G|^n)$  and the image of  $\alpha_n$  i.e. the collection of maximal connected block coverings.

**Proof:** any *connected* block is contained in a maximal *connected* block (by the Hausdorff maximal principle).

$$\bigcup_i^\uparrow (B_1^{(i)} \times \cdots \times B_n^{(i)}) = \left( \bigcup_i^\uparrow B_1^{(i)} \right) \times \cdots \times \left( \bigcup_i^\uparrow B_n^{(i)} \right)$$

# Isothetic regions

- An **isothetic region** of dimension  $n$  is a subset of  $|G|^n$  that admits a **finite** block covering.
- The **geometric model** of a conservative program is an isothetic region.
- The collection of isothetic regions of dimension  $n$  is denoted by  $\mathcal{R}_n G$ .
- The collection of **finite** block covering of dimension  $n$  is denoted by  $\text{Cov}_{nf} G$ .

# The previous Galois connection

restricted to isothetic regions

Suppose that the graph  $G$  is finite. The collection of  $n$ -dimensional isothetic regions  $\mathcal{R}_n G$  forms a Boolean subalgebra of  $\text{Pow}(|G|^n)$  and the previous Galois connection restricts to a Galois connection between  $\text{Cov}_{nf} G$  and  $\mathcal{R}_n G$ , which induces an isomorphism of Boolean algebras between  $\mathcal{R}_n G$  and the image of  $\alpha_n$  i.e. the collection of finite maximal block coverings.

$$\text{Cov}_{nf} G \begin{array}{c} \xrightarrow{\gamma_n} \\ \xleftarrow{\alpha_n} \end{array} \mathcal{R}_n G$$

A subset  $X \subseteq |G|^n$  is an isothetic region iff the collection of maximal subblocks of  $X$  is finite and covers  $X$ .

# The complement of a block is an isothetic region

If  $X$  is 1-dimensional then its maximal blocks are its connected components.  
The complement of a block  $B = B_1 \times \cdots \times B_n$  can be written as

$$B^c = \bigcup_{k=1}^n |G| \times \cdots \times B_k^c \times \cdots \times |G|$$

Its maximal blocks are found among that of  $B^c$  therefore they have the form

$$D_1 \times \cdots \times D_{k-1} \times C_k \times D_{k+1} \times \cdots \times D_n$$

with  $k \in \{1, \dots, n\}$ ,  $C_k$  ranging through the connected components of  $B_k^c$  and  $D_j$ , for  $j \neq k$ , ranging through the connected components of  $|G|$ .

# Intersection of two isothetic regions

The intersection of the blocks  $B$  and  $B'$  is given by

$$B \cap B' = (B_1 \cap B'_1) \times \cdots \times (B_n \cap B'_n)$$

The maximal blocks of  $B \cap B'$  are therefore of the form

$$C_1 \times \cdots \times C_n$$

with each  $C_k$  ranging through the connected components of  $(B_k \cap B'_k)$ .

It follows from De Morgan's laws that the intersection of two regions is still a region.

Moreover if  $\mathcal{B}$  and  $\mathcal{B}'$  are block coverings of  $X$  and  $X'$  containing all their maximal blocks, then the collection of maximal blocks of  $B \cap B'$  for  $B \in \mathcal{B}$  and  $B' \in \mathcal{B}'$  is a block covering of  $X \cap X'$  containing all its maximal blocks.

## Concluding the proof

If  $\mathcal{F}$  is any finite block covering of  $X$ , then

$$X^c = \bigcap_{B \in \mathcal{F}} B^c$$

- The collection of maximal blocks of  $B^c$  is finite and covers  $B^c$ .
- The maximal blocks of  $X^c$  are obtained as certain finite intersection of the form

$$\bigcap \{M_B \mid B \in \mathcal{F}\}$$

where  $M_B$  is a maximal block of  $B^c$ .

- The maximal blocks of  $X^c$  thus form a finite block covering of  $X^c$ .

## A result from directed topology

For all directed paths  $\gamma$  on  $|G|^n$  and all  $X \in \mathcal{R}_n G$ , the inverse image of  $X$  by  $\gamma$  has **finitely** many connected components.

# Closure, interior, and boundary of an isothetic region

The closure operator preserves finite products, therefore it preserves blocks.

The closure operator preserves finite unions hence it preserves isothetic regions.

The boundary of a set is the intersection of its closure and the closure of its complement, hence it also preserves isothetic regions.

The interior of a set is the difference between its closure and its boundary. It follows that the interior operator also preserves isothetic regions.

# The forward and the backward operators

Let  $A, B$  be subsets of a local pospace  $X$ .

- The **forward** and the **backward** operators are defined as

$$\text{frw}(A, B) = \{\partial^+ \delta \mid \delta \text{ directed path on } X; \partial^+ \delta \in A; \text{im}(\delta) \subseteq A \cup B\}$$

$$\text{bck}(A, B) = \{\partial^- \delta \mid \delta \text{ directed path on } X; \partial^- \delta \in A; \text{im}(\delta) \subseteq A \cup B\}$$

- The **future cone** of  $A$  in  $X$  is  $\text{cone}^f A := \text{frw}(A, X)$  and the **past cone** of  $A$  in  $X$  is  $\text{cone}^p A := \text{bck}(A, X)$ .
- The **future closure** of  $A$  in  $X$  is  $\overline{A}^f := \text{frw}(A, \overline{A})$  and the **past closure** of  $A$  in  $X$  is  $\overline{A}^p := \text{bck}(A, \overline{A})$ .  
The closure  $\overline{A}$  being understood in  $X$ .

**Theorem:** if  $A, B$ , and  $X$  are isothetic regions, then so are  $\text{frw}(A, B)$ ,  $\text{cone}^f A$ ,  $\overline{A}^f$ , and their duals.

# Future/past stable subsets of $X$

let  $A$  be a subset of a local pospace  $X$ .

- $\text{cone}^f \text{cone}^f A = \text{cone}^f A$  and  $\text{cone}^p \text{cone}^p A = \text{cone}^p A$
- $A$  is said to be future (resp. past) stable (in  $X$ ) when  $\text{cone}^f A = A$  (resp.  $\text{cone}^p A = A$ )
- $A$  is future stable iff  $X \setminus A$  is past stable
- The collection of future stable subsets of  $X$  is a complete lattice, the greatest lower (resp. least upper) bound of a family being given by its intersection (resp. union).
- The same holds for past stable subsets.

# Past/future attractors

Let  $A$  be a subset of a local pospace  $X$ .

$$\text{cone}^p A = \{p \in X \text{ from which } A \text{ can be reached}\} = \text{bck}(A, X) = \text{cone}^p A$$

$$\text{escape}^f A = \{p \in X \text{ from which } A \text{ is avoided}\} = \{p \in X \text{ from which } A \text{ cannot be reached}\}$$

$$\text{escape}^f A = (\text{cone}^p A)^c$$

$$\text{att}^p A = \{p \in X \text{ from which } A \text{ cannot be avoided}\}$$

$$\text{att}^p A = \text{escape}^f(\text{escape}^f A)$$

# The deadlock attractor of a conservative program

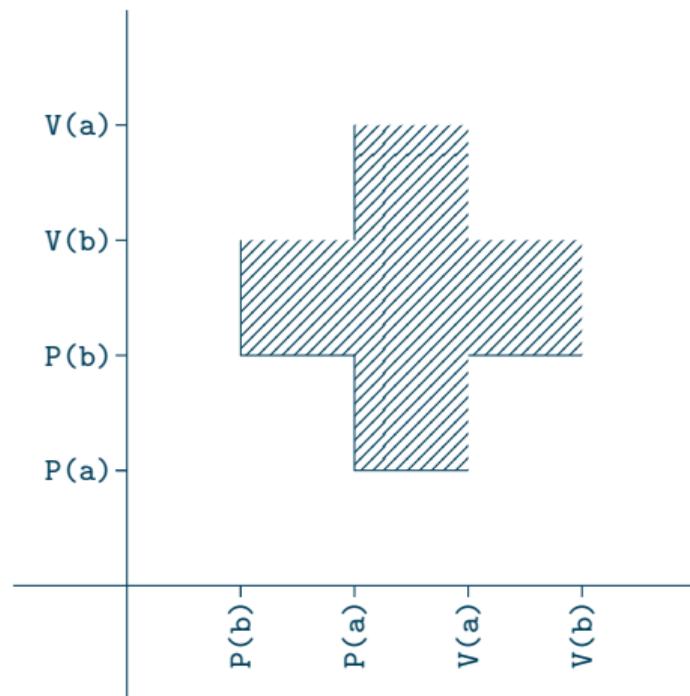
Let  $G_1, \dots, G_n$  be the running processes of a conservative program  $P$ .

Let  $\llbracket P \rrbracket$  be the geometric model of the program.

- The **reachable** space of  $\llbracket P \rrbracket$  is the future cone of the initial point
- A point  $p \in \downarrow G_i$  is said to be **terminal** when  $\llbracket \gamma \rrbracket$  is empty for all directed paths on  $\downarrow G_i$  starting at  $p$ .
- A point  $p \in \llbracket P \rrbracket$  is said to be **terminal** when so are all its projections
- The terminal points form a future stable isothetic region of  $\llbracket P \rrbracket$
- A point  $p \in \llbracket P \rrbracket$  is said to be **deadlock** when its future cone neither contains directed loops (i.e. it is **loop-free**) nor terminal points.
- The deadlock points form a future stable isothetic region of  $\llbracket P \rrbracket$
- The **deadlock attractor** of the program is the past attractor of its deadlock region.

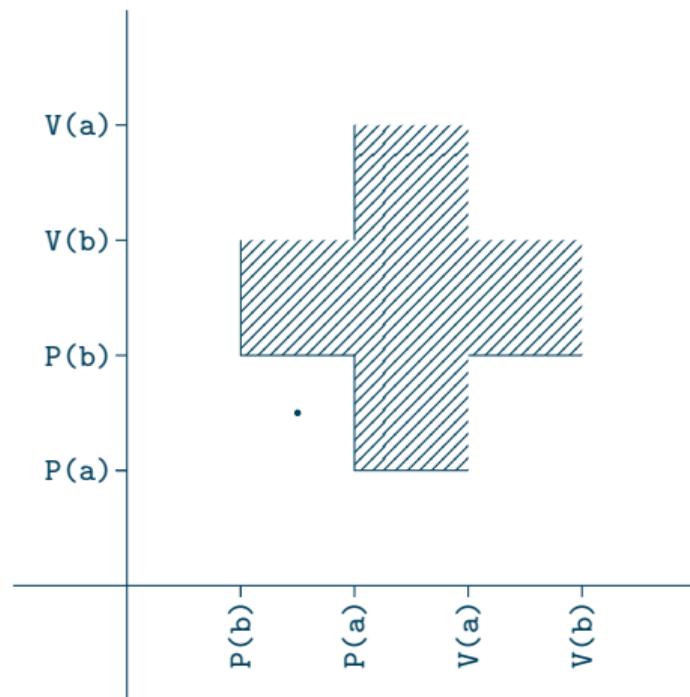
# Deadlock attractor of the Swiss Cross

```
sem 1 a b
proc:
p = P(a).P(b).V(b).V(a)
q = P(b).P(a).V(a).V(b)
init: p q
```



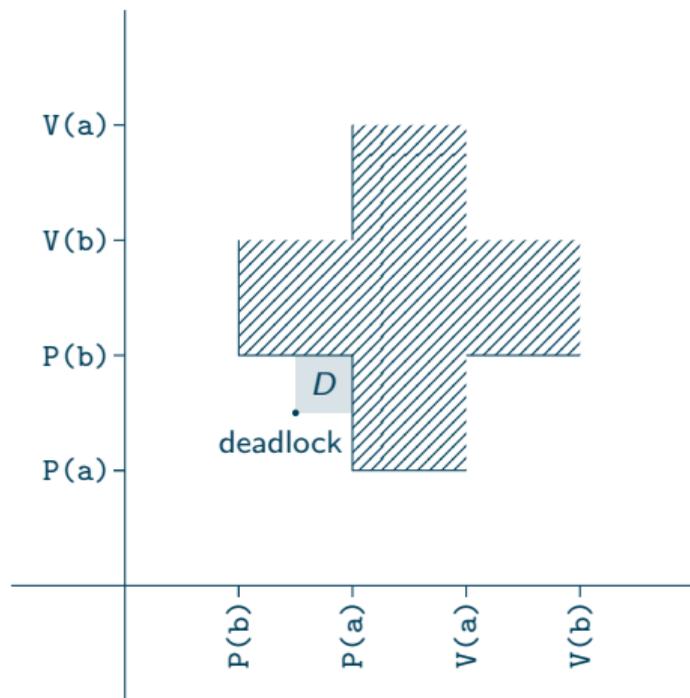
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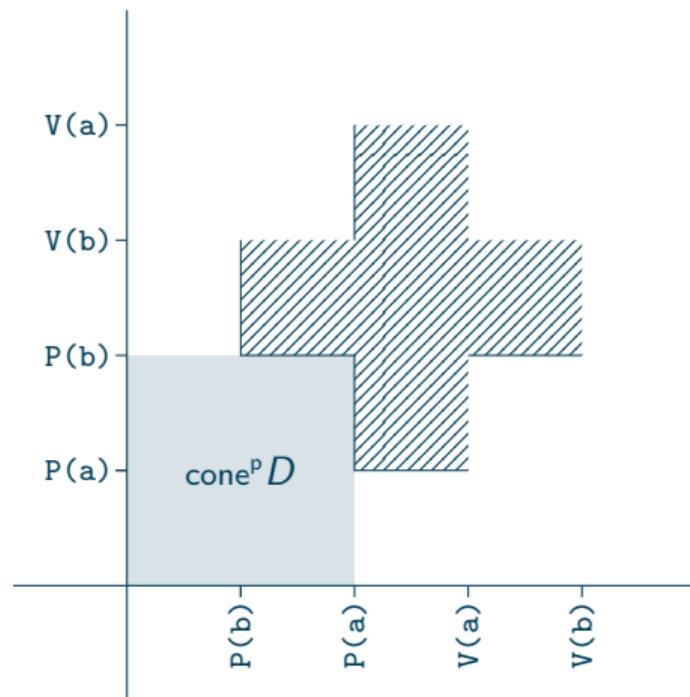
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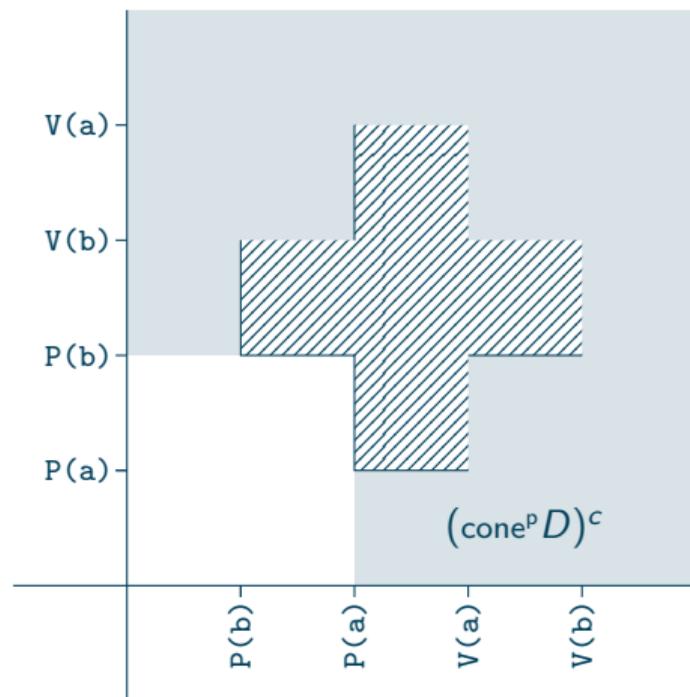
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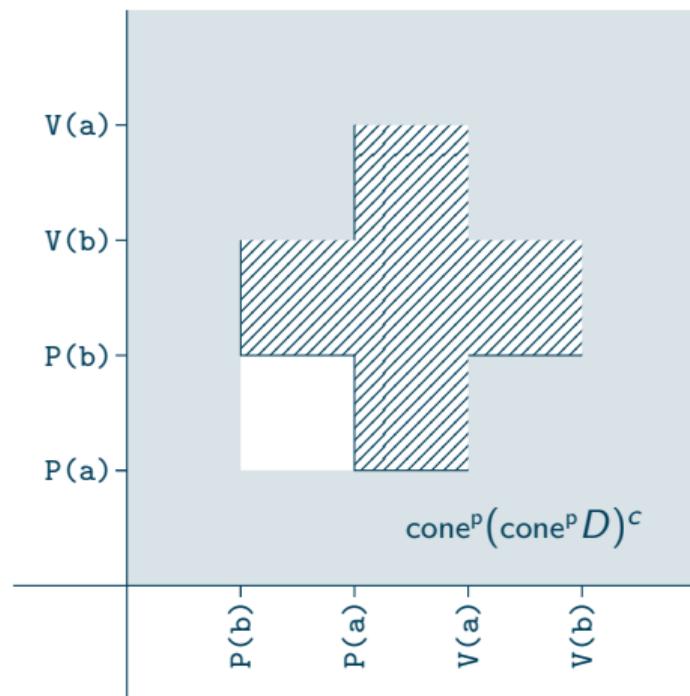
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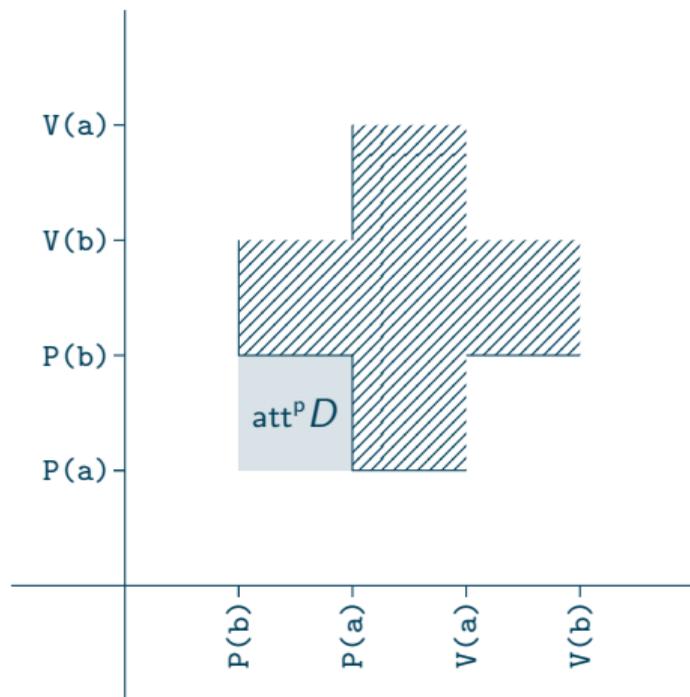
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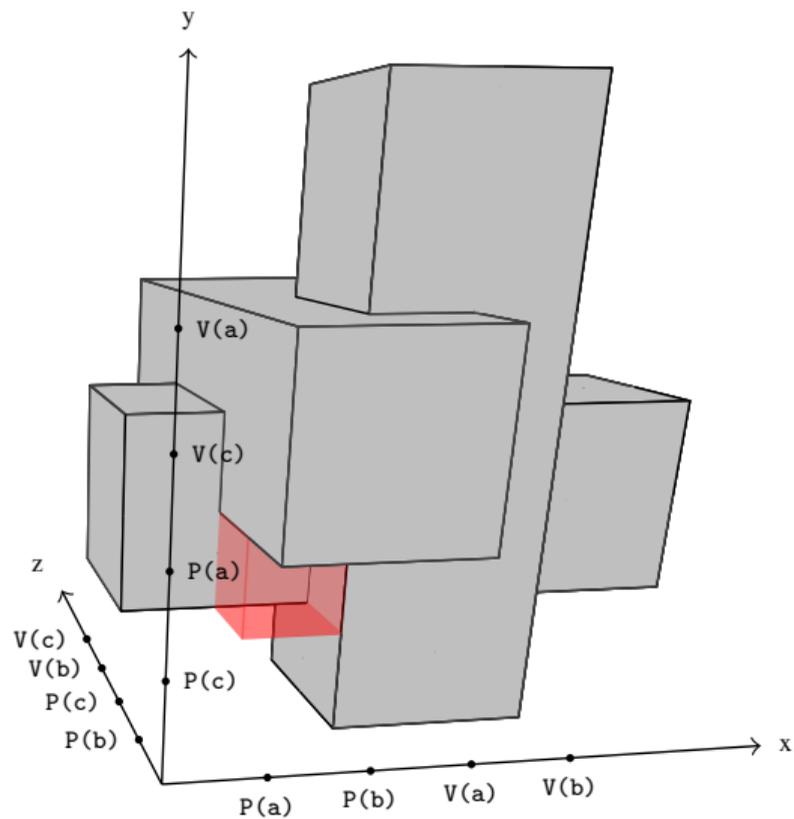


# Deadlock attractor of the Swiss Cross

```
sem 1 a b
proc:
p = P(a).P(b).V(b).V(a)
q = P(b).P(a).V(a).V(b)
init: p q
```



# Three dining philosophers



# Commutative monoids

- $(M, *, \varepsilon)$  such that for all  $a, b, c \in M$ ,
  - $(ab)c = a(bc)$
  - $\varepsilon a = a = a\varepsilon$
  - $ab = ba$
- For all set  $X$  the collection  $MX$  of **multisets** over  $X$   
 i.e. maps  $\phi : X \rightarrow \mathbb{N}$  s.t.  $\{x \in X \mid \phi(x) \neq 0\}$  is finite  
 forms a commutative monoid with pointwise addition
- A commutative monoid is said to be **free** when  
 it is isomorphic with some  $MX$
- Functor  $M : Set \rightarrow Cmon$ 
  - A multiset  $\phi$  can be written as

$$\sum_{x \in X} \phi(x)x$$

- In particular, if  $f : X \rightarrow Y$  is a set map, then

$$M(f)(\phi) = \sum_{x \in X} \phi(x)f(x)$$

# Prime vs irreducible

- $d$  divides  $x$ , denoted by  $d|x$ , when there exists  $x'$  such that  $x = dx'$
- $u$  unit: exists  $u'$  s.t.  $uu' = \varepsilon$  then write  $x \sim y$  when  $y = ux$  for some unit  $u$
- $i$  irreducible:  $i$  nonunit and  $x|i$  implies  $x \sim i$  or  $x$  unit
- $p$  prime:  $p$  nonunit and  $p|ab$  implies  $p|a$  or  $p|b$
- If  $M$  contains nontrivial units, then one can consider the quotient monoid  $M/\sim$  where  $x \sim y$  stands for: there exists a unit  $u$  s.t.  $y = ux$

# Examples

monoid	irreducibles	primes	units
$\mathbb{N} \setminus \{0\}, \times, 1$	{prime numbers}		{1}
$\mathbb{N}, +, 0$	{1}		{0}
$\mathbb{R}_+, +, 0$	$\emptyset$		{0}
$\mathbb{R}_+, \vee, 0$	$\emptyset$	$\mathbb{R}_+ \setminus \{0\}$	{0}
$\mathbb{Z}_6, \times, 1$	$\emptyset$	{2, 3, 4}	{1, 5}

# Graded commutative monoid

- $(M, *, \varepsilon)$  **graded**: there is a morphism  $g : (M, *, \varepsilon) \rightarrow (\mathbb{N}, +, 0)$   
s.t.  $g^{-1}(\{0\}) = \{\text{units of } M\}$
- If  $M$  is graded then
  - $\{\text{irreducibles of } M\}$  generates  $M$
  - $\{\text{primes of } M\} \subseteq \{\text{irreducibles of } M\}$

# Irreducible that are not prime

$$M = (\{a + b\sqrt{10} \mid a, b \in \mathbb{Z}; a \neq 0 \text{ or } b \neq 0\}, \times, 1)$$

- $N : M \rightarrow (\mathbb{Z} \setminus \{0\}, \times, 1)$ ;  $N(a + b\sqrt{10}) = a^2 - 10b^2$   
 $N(uv) = N(u)N(v)$   
 $u$  unit iff  $N(u) \in \{\pm 1\}$  [hint:  $u^{-1} = N(u)\bar{u}$  with  $\bar{u} = a - b\sqrt{10}$  if  $u = a + b\sqrt{10}$ ]  
 $N(a + b\sqrt{10}) \bmod 10 \in \{0, 1, 4, 5, 6, 9\}$   
 therefore  $N(a + b\sqrt{10}) \notin \{\pm 2, \pm 3\}$

$uv$	$N(uv)$	$N(u)$
2	4	$\pm 1, \pm 2, \pm 4$
3	9	$\pm 1, \pm 3, \pm 9$
$4 \pm \sqrt{10}$	6	$\pm 1, \pm 2, \pm 3, \pm 6$

- 2, 3, and  $4 \pm \sqrt{10}$  are irreducible but not prime  
 since  $2 \cdot 3 = (4 + \sqrt{10}) \cdot (4 - \sqrt{10})$
- $\{a + b\sqrt{10} \mid a, b \in \mathbb{Z}\} \setminus \{0\}$  is graded by the number of prime factors of  $N(u)$

# $\mathbb{N}[X]$ polynomials with coefficients in $\mathbb{N}$

*On Direct Product Decomposition of Partially Ordered Sets.* Junji Hashimoto

Annals of Mathematics 2(54), pp 315-318 (1951)

$$X^5 + X^4 + X^3 + X^2 + X + 1 =$$

$$\begin{cases} (X + 1)(X^4 + X^2 + 1) = (X^3 + 1)(X^2 + X + 1) & \text{in } \mathbb{N}[X] \\ (X + 1)(X^2 + X + 1)(X^2 - X + 1) & \text{in } \mathbb{Z}[X] \end{cases}$$

- therefore  $X + 1$ ,  $X^2 + X + 1$ ,  $X^3 + 1$ , and  $X^4 + X^2 + 1$  are **irreducible but not prime**
- $\mathbb{N}[X] \setminus \{0\}$  is graded by the degree

# Characterization of the free commutative monoids

## Unique factorization

- The following are equivalent:
  - $M$  is free commutative
  - any element of  $M$  can be written as a product of irreducibles in a unique way up to reordering
  - $\{\text{primes of } M\} = \{\text{irreducibles of } M\}$  and generates  $M$
  - $M$  is graded and  $\{\text{irreducibles of } M\} \subseteq \{\text{primes of } M\}$
- Standard examples:
  - $(\mathbb{N} \setminus \{0\}, \times, 1)$
  - $(\mathbb{N}, +, 0)$  and its finite products in the category of commutative monoids.  
Indeed  $(\mathbb{N}, +, 0)^n \cong M(\{1, \dots, n\})$
  - $(\mathbb{Z}[X] \setminus \{0\}, \times, 1)$  (if  $F$  is a factorial ring, then so is  $F[X]$ ) *Algebra*, Serge Lang. Springer (2002)
  - Note that two free commutative monoids are isomorphic in  $\mathit{Cmon}$  iff their set of prime elements have the same cardinality  
e.g.  $(\mathbb{N} \setminus \{0\}, \times, 1) \cong (\mathbb{Z}[X] \setminus \{0\}, \times, 1)$  in  $\mathit{Cmon}$

# Connected sum of manifolds

## A less common example

In differential geometry, the compact, connected, oriented, smooth  $n$ -dimensional manifolds without boundary equipped with the connected sum  $\#$  form a commutative monoid  $\mathcal{M}_n$  whose neutral element is the  $n$ -sphere.

tom Dieck, T. Algebraic Topology. European Mathematical Society 2008. p.390

$\mathcal{M}_2$  is freely generated by the torus  $T^2$ .

Massey, W.S. A Basic Course in Algebraic Topology. Springer 1991. Chapter 1.

$\mathcal{M}_3$  is freely generated by countably many elements.

Hempel, J. 3-Manifolds. American Mathematical Society 1976. Chapter 3.

Jaco, W. Lectures on Three-Manifold Topology. American Mathematical Society 1980. Chapter 2.

- existence of the decomposition is due to Hellmuth Kneser (1929)

Kneser, H. Geschlossene Flächen in dreidimensionalen Mannigfaltigkeiten.

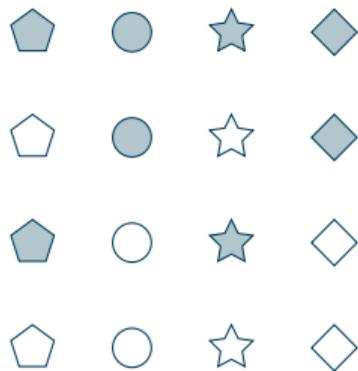
Jahresbericht der Deutschen Mathematiker-Vereinigung 38:248–259 1929.

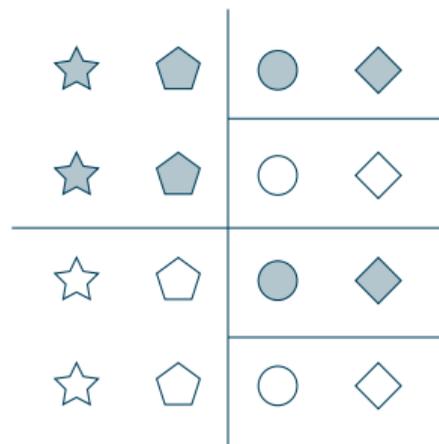
- uniqueness of the decomposition is due to John W. Milnor (1962)

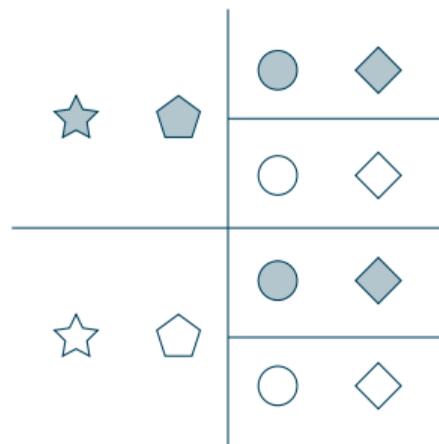
Milnor, J. A Unique Decomposition Theorem for 3-Manifolds.

American Journal of Mathematics 84(1):1–7 1962.

In particular  $\mathcal{M}_2 \cong (\mathbb{N}, +, 0)$  and  $\mathcal{M}_3 \cong (\mathbb{N} \setminus \{0\}, \times, 1)$









# The noncommutative monoid of languages

- $\mathbb{A}^*$  (non commutative) monoid of words on the alphabet  $\mathbb{A}$ .  
Let  $\varepsilon$  denotes the empty word
- A language is a set of words on  $\mathbb{A}$ . Let  $D$  and  $D'$  be languages
  - define  $D \cdot D' := \{w \cdot w' \mid w \in D; w' \in D'\}$
  - one has  $\emptyset \cdot D = D \cdot \emptyset = \emptyset$  and  $\{\varepsilon\} \cdot D = D \cdot \{\varepsilon\} = D$
  - The monoid of **nonempty** languages is  $\mathcal{D}(\mathbb{A})$
  - $\mathcal{D}(\mathbb{A})$  is commutative iff  $\text{Card}(\mathbb{A}) \leq 1$ . Note that  $\mathcal{D}(\emptyset) \cong \{\{\varepsilon\}\}$
  - however  $\mathcal{D}(\{a\})$  is not freely commutative

# The noncommutative monoid of homogeneous languages

- $H \in \mathcal{D}(\mathbb{A})$  is homogeneous when all the words in  $H$  have the same length
- Define  $\dim(H)$  as the length common to all the words of  $H$ .  
It is well defined since  $H$  is nonempty.
- $H \cdot H' = \{w \cdot w' \mid w \in H ; w' \in H'\}$  is homogeneous iff so are  $H$  and  $H'$
- $\mathcal{D}_h(\mathbb{A}) \subseteq \mathcal{D}(\mathbb{A})$  the pure submonoid of homogeneous languages.
- $H \in \mathcal{D}_h(\mathbb{A}) \mapsto \dim(H) \in (\mathbb{N}, +, 0)$  is a morphism of monoid
- $\dim(H) = 0$  iff  $H = \{\varepsilon\}$
- $\mathcal{D}_h(\mathbb{A})$  is commutative iff  $\text{Card}(\mathbb{A}) \leq 1$
- $\mathcal{D}_h(\{a\}) \cong (\mathbb{N}, +, 0)$

# Action of the symmetric groups

## on the left of the homogeneous languages

- The  $n^{\text{th}}$  symmetric group  $\mathfrak{S}_n$  acts on the left of the set of words of length  $n$  i.e. mappings from  $\{1, \dots, n\}$  to  $\mathbb{A}$ , by  $\sigma \cdot \omega := \omega \circ \sigma^{-1}$
- Then  $\mathfrak{S}_n$  acts on the left of the homogeneous languages of dimension  $n$
- Write  $H \sim H'$  when  $\dim(H) = \dim(H')$  and  $H' = \sigma \cdot H$  for some  $\sigma \in \mathfrak{S}_{\dim(H)}$
- If  $\sigma \in \mathfrak{S}_n$  and  $\sigma' \in \mathfrak{S}_{n'}$  then define  $\sigma \otimes \sigma' \in \mathfrak{S}_{n+n'}$  as:

$$\sigma \otimes \sigma'(k) := \begin{cases} \sigma(k) & \text{if } 1 \leq k \leq n \\ (\sigma'(k-n)) + n & \text{if } n+1 \leq k \leq n+n' \end{cases}$$

- A Godement exchange law is satisfied, which ensures that  $\sim$  is actually a congruence:

$$(\sigma \cdot H) \cdot (\sigma' \cdot H') = (\sigma \otimes \sigma') \cdot (H \cdot H')$$

i.e.  $H \sim K$  and  $H' \sim K'$  implies  $HH' \sim KK'$

# The commutative monoid of homogeneous languages

- The commutative monoid of homogeneous languages is  $\mathcal{H}(\mathbb{A}) = (\mathcal{D}_h(\mathbb{A}), \cdot, \{\varepsilon\}) / \sim$
- The monoid  $\mathcal{H}(\mathbb{A})$  is graded by  $H \in \mathcal{H}(\mathbb{A}) \mapsto \dim(H) \in (\mathbb{N}, +, 0)$

The commutative monoid  $\mathcal{H}(\mathbb{A})$  is free

- For any homogeneous language  $H$  and  $\sigma \in \mathfrak{S}_{\dim(H)}$ ,  $\text{card}(H) = \text{card}(\sigma \cdot H)$  so we can define the cardinality of any element of  $\mathcal{H}(\mathbb{A})$

# The commutative monoid of finite homogeneous languages

- $M' \subseteq M$  is said to be **pure** when for all  $x, y \in M$ ,  $xy \in M'$  implies  $x, y \in M'$
- A pure submonoid of a free commutative monoid is free
- The submonoid  $\mathcal{H}_f(\mathbb{A}) \subseteq \mathcal{H}(\mathbb{A})$  of finite languages is pure, therefore it is free
- $H \in \mathcal{H}_f(\mathbb{A}) \mapsto \text{Card}(H) \in (\mathbb{N} \setminus \{0\}, \times, 1)$  is a morphism of monoid
- The primality of  $\text{Card}(H)$  does not imply that of  $H$   
e.g.  $H = \{ab, ac\} = \{a\} \cdot \{b, c\}$  though  $\text{card}(H) = 2$
- The primality of  $H$  does not imply that of  $\text{Card}(H)$   
e.g.  $H = \{a, b, c, d\}$  is prime though  $\text{card}(H) = 4$

# The brute force algorithm for factoring in $\mathcal{H}_f(\mathbb{A})$

## Theory

Given  $w \in \mathbb{A}^n$  and  $I \subseteq \{1, \dots, n\}$ , we write  $w|_I$  for the subword of  $w$  consisting of letters with indices in  $I$ .

Given a homogeneous language  $H$  of dimension  $n$ , we write

$$H|_I = \{w|_I \mid w \in H\}$$

Denoting  $I^c$  for  $\{1, \dots, n\} \setminus I$ , we have

$$[H] = [H|_I] \cdot [H|_{I^c}]$$

in  $\mathcal{H}_f(\mathbb{A})$  if and only if for all words  $u, v \in H$  there exists a word  $w \in H$  such that

$$w|_I = u|_I \quad \text{and} \quad w|_{I^c} = v|_{I^c}$$

# The brute force algorithm for factoring in $\mathcal{H}_f(\mathbb{A})$

## Practice

For  $I \subseteq \{1, \dots, n\}$  let  $\pi_{|I}$  be the “projection” that sends  $w \in H$  to  $w_{|I} \in \mathbb{A}^{\text{card}(I)}$ .

1. choose  $I \subseteq \{1, \dots, n\}$  of cardinality  $k \leq n/2$
2. if  $\pi_{|I^c}(\pi_{|I}^{-1}(u))$  does not depend on  $u \in H_{|I}$ , then we have the factorization

$$[H] = [H_{|I}] \cdot [H_{|I^c}]$$

and we are done

3. otherwise check whether there are still subsets of  $\{1, \dots, n\}$  to check:
  - 3.1. yes: go to step 1
  - 3.2. no:  $[H]$  is prime

# Factoring a program

```
sem: 1 a b
```

```
sem: 2 c
```

---

```
proc:
```

```
  p = P(a);P(c);V(c);V(a)
```

```
  q = P(b);P(c);V(c);V(b)
```

---

```
init: p q p q
```

# Factoring the space of states

brute force

$[0,1[$	$[0,1[$	$[0,+\infty[$	$[0,+\infty[$
$[0,1[$	$[4,+\infty[$	$[0,+\infty[$	$[0,+\infty[$
$[0,1[$	$[0,+\infty[$	$[0,+\infty[$	$[0,1[$
$[0,1[$	$[0,+\infty[$	$[0,+\infty[$	$[4,+\infty[$
$[4,+\infty[$	$[0,1[$	$[0,+\infty[$	$[0,+\infty[$
$[4,+\infty[$	$[4,+\infty[$	$[0,+\infty[$	$[0,+\infty[$
$[4,+\infty[$	$[0,+\infty[$	$[0,+\infty[$	$[0,1[$
$[4,+\infty[$	$[0,+\infty[$	$[0,+\infty[$	$[4,+\infty[$
$[0,+\infty[$	$[0,1[$	$[0,1[$	$[0,+\infty[$
$[0,+\infty[$	$[0,1[$	$[4,+\infty[$	$[0,+\infty[$
$[0,+\infty[$	$[4,+\infty[$	$[0,1[$	$[0,+\infty[$
$[0,+\infty[$	$[4,+\infty[$	$[4,+\infty[$	$[0,+\infty[$
$[0,+\infty[$	$[0,+\infty[$	$[0,1[$	$[0,1[$
$[0,+\infty[$	$[0,+\infty[$	$[0,1[$	$[4,+\infty[$
$[0,+\infty[$	$[0,+\infty[$	$[4,+\infty[$	$[0,1[$
$[0,+\infty[$	$[0,+\infty[$	$[4,+\infty[$	$[4,+\infty[$

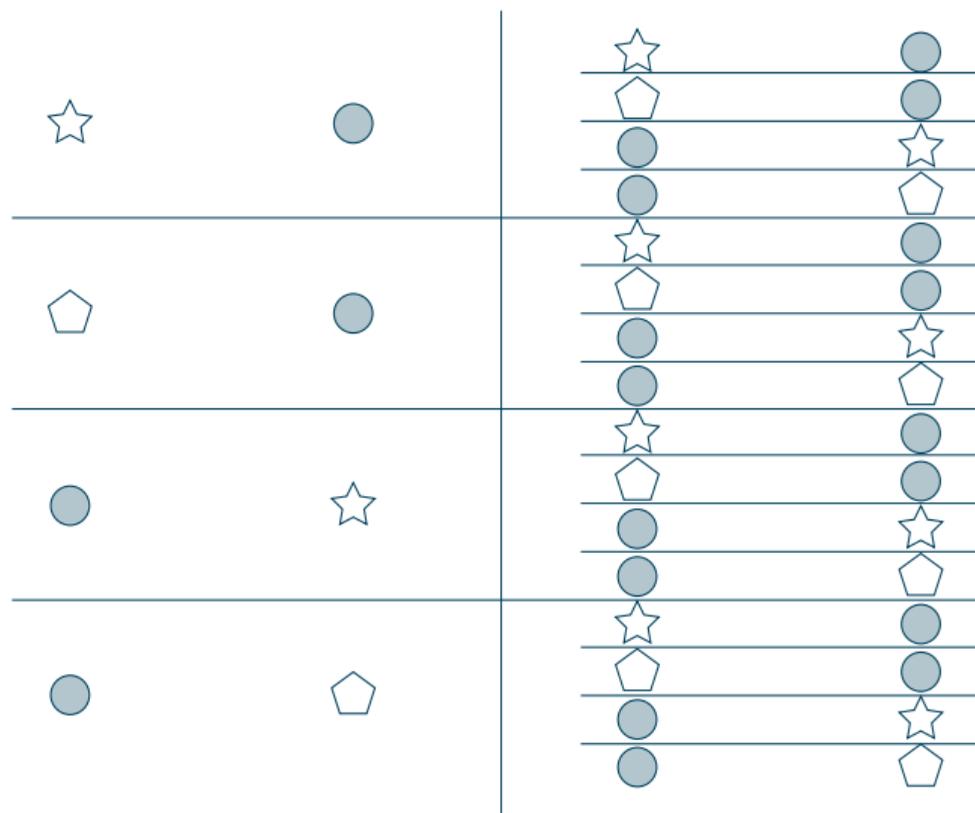
# Factoring the space of states

brute force



# Factoring the space of states

brute force



# Factoring the space of states

brute force

	☆ ●	⬠ ●	● ☆	● ⬠
☆ ●	☆ ● ☆ ●	☆ ● ⬠ ●	☆ ● ● ☆	☆ ● ● ⬠
⬠ ●	⬠ ● ☆ ●	⬠ ● ⬠ ●	⬠ ● ● ☆	⬠ ● ● ⬠
● ☆	● ☆ ☆ ●	● ☆ ⬠ ●	● ☆ ● ☆	● ☆ ● ⬠
● ⬠	● ⬠ ☆ ●	● ⬠ ⬠ ●	● ⬠ ● ☆	● ⬠ ● ⬠

# Factoring a program

```
sem: 1 a b
```

```
sem: 2 c
```

---

```
proc:
```

```
  p = P(a);P(c);V(c);V(a)
```

```
  q = P(b);P(c);V(c);V(b)
```

---

```
init: p q p q
```

# Factoring a program

```
sem: 1 a
```

```
proc:  
p = P(a);V(a)
```

```
init: 2p
```

```
sem: 1 b
```

```
proc:  
q = P(b);V(b)
```

```
init: 2q
```

# The preorder $\preceq$ over $\mathcal{H}(\mathbb{A})$

inherited from a preorder  $\preceq$  over  $\mathbb{A}$

- Let  $\preceq^n$  be the product preorder on the words of length  $n$
- Given  $H, H' \in \mathcal{D}_h(\mathbb{A})$  of the same dimension  $n$ , write  $H \preceq H'$  when for all  $\omega \in H$  there exists  $\omega' \in H'$  such that  $\omega \preceq^n \omega'$
- Given  $X, Y \in \mathcal{H}(\mathbb{A})$  of the same dimension  $n$  write  $X \preceq Y$  when there exist  $H \in X$  and  $K \in Y$  such that  $H \preceq K$
- $X \preceq Y$  and  $X' \preceq Y'$  implies  $X \cdot X' \preceq Y \cdot Y'$   
i.e.  $(\mathcal{H}(\mathbb{A}), \preceq)$  is a preordered commutative monoid
- If  $\preceq$  is actually a partial order on  $\mathbb{A}$ , then so is  $\preceq$  on  $\mathcal{H}(\mathbb{A})$
- If  $\preceq$  is the equality relation, then  $X \preceq Y$  amounts to  $H_X \subseteq H_Y$  for some representatives  $H_X$  and  $H_Y$  of  $X$  and  $Y$ .

# Homogeneous languages

over the alphabets  $|G|$  and  $\mathcal{R}_1 G \setminus \{\emptyset\}$  with  $G$  being a finite graph

- $\mathbb{A} = |G|$  is the geometric realization of a finite graph:
  - a point of  $|G|^n$  can be seen as a word of length  $n$  on  $\mathbb{A}$
  - a nonempty subset of  $|G|^n$  is thus a homogeneous language on  $\mathbb{A}$
  - the product of the monoid  $\mathcal{D}_h(\mathbb{A})$  corresponds to the cartesian product of isothetic regions
- $\mathbb{A} = \mathcal{R}_1 G \setminus \{\emptyset\}$  is the collection of **nonempty** finite unions of connected subsets of  $|G|$ :
  - an  $n$ -block is an  $n$ -fold product of nonempty elements of  $\mathcal{R}_1 G$   
i.e. a word of length  $n$  on  $\mathbb{A}$
  - a nonempty family of  $n$ -blocks is thus an homogeneous language on  $\mathbb{A}$  (of dimension  $n$ )
  - the concatenation of words on  $\mathbb{A}$  corresponds to the cartesian product of blocks

# The canonical morphism of monoids $\gamma : \mathcal{H}(\mathcal{R}_1 G \setminus \{\emptyset\}) \rightarrow \mathcal{H}(\lfloor G \rfloor)$

- Let  $\gamma$  be the map sending an homogeneous language on  $\mathcal{R}_1 G \setminus \{\emptyset\}$  to the union of its elements
  - $\gamma$  is a morphism of monoids from  $\mathcal{D}_h(\mathcal{R}_1 G \setminus \{\emptyset\})$  to  $\mathcal{D}_h(\lfloor G \rfloor)$
  - $\gamma$  is compatible with the action of the symmetric groups in the sense that
 
$$H' = \sigma \cdot H \Rightarrow \bigcup H' = \sigma \cdot (\bigcup H)$$
  - $\gamma$  induces a morphism of monoids from  $\mathcal{H}(\mathcal{R}_1 G \setminus \{\emptyset\})$  to  $\mathcal{H}(\lfloor G \rfloor)$
- The induced morphism  $\gamma$  does not preserve the prime elements e.g. consider a covering of  $[0, 1]^2$  with 3 distinct rectangles

# The canonical morphism of monoids $\alpha : \mathcal{H}(\downarrow G \downarrow) \rightarrow \mathcal{H}(\mathcal{R}_1 G \setminus \{\emptyset\})$

- Define  $\alpha(X)$  as the collection of maximal blocks of  $X$ :
  - given  $X \subseteq \downarrow G \downarrow^n$  and  $Y \subseteq \downarrow G \downarrow^m$ , the collection of maximal blocks of  $X \times Y$  is  $\{C \times D \mid C \text{ and } D \text{ are maximal blocks of } X \text{ and } Y\}$
  - the unique maximal block of the unique nonempty subset of  $\downarrow G \downarrow^0$  is  $\varepsilon$
  - $\alpha$  is a morphism of monoids from  $\mathcal{D}_h(\downarrow G \downarrow)$  to  $\mathcal{D}_h(\mathcal{R}_1 G \setminus \{\emptyset\})$
  - if  $C$  is a maximal block of  $X \subseteq \downarrow G \downarrow^n$  then  $\sigma \cdot C$  is a maximal block of  $\sigma \cdot X$ .
  - $\alpha$  induces a morphism of monoids from  $\mathcal{H}(\downarrow G \downarrow)$  to  $\mathcal{H}(\mathcal{R}_1 G \setminus \{\emptyset\})$
  - $\text{im}(\alpha)$  is a submonoid of  $\mathcal{H}(\mathcal{R}_1 G \setminus \{\emptyset\})$
- the morphisms  $\gamma$  and  $\alpha$  induce isomorphisms of ordered monoids between  $\text{im}(\alpha)$  and  $\mathcal{H}(\downarrow G \downarrow)$ , the order relation being inherited from inclusion over  $\mathcal{R}_1 G \setminus \{\emptyset\}$  and equality over  $\downarrow G \downarrow$ .
- therefore  $\text{im}(\alpha)$  is commutative free

# The free commutative monoids of isothetic regions

- By definition, an isothetic region is a finite union of blocks of  $X \subseteq \{G\}^n$ .
- We have seen that an isothetic region has finitely many maximal blocks .
- For  $X, Y \in \mathcal{H}(\{G\})$ ,  $\alpha(X \cdot Y)$  is finite iff  $\alpha(X)$  and  $\alpha(Y)$  are so:
  - then  $\{X \in \text{im}(\alpha) \mid \text{card}(X) \text{ is finite}\}$  is a pure submonoid of  $\text{im}(\alpha)$
  - this commutative monoid is thus free and isomorphic to the monoid of isothetic regions, the latter being defined as

$$\gamma(\{X \in \text{im}(\alpha) \mid \text{card}(X) \text{ is finite}\})$$

- The monoid of isothetic regions is thus free commutative.

# A better factoring algorithm

by Nicolas Ninin

Let  $X \subseteq |G|^n$  be an isothetic region and  $\mathcal{F}$  be a finite block covering of  $X^c$

- For each block  $(\omega_1, \dots, \omega_n)$  that belongs to  $\mathcal{F}$  define the subset

$$B_\omega = \{k \in \{1, \dots, n\} \mid \omega_k \neq |G|\}$$

- The finest partition of  $\{1, \dots, n\}$  that is coarser than the collection

$$\{B_\omega \mid \omega \in \mathcal{F}\}$$

induces a factorization of  $X$ .

If  $\mathcal{F} = \alpha(X^c)$  then we obtain the prime factorization of  $X$

# Factoring a program

```
sem: 1 a b
```

```
sem: 2 c
```

---

```
proc:
```

```
  p = P(a);P(c);V(c);V(a)
```

```
  q = P(b);P(c);V(c);V(b)
```

---

```
init: p q p q
```

# Factoring the space of states

subtle

$[2,3[$	$[2,3[$	$[2,3[$	$[0,+\infty[$
$[2,3[$	$[2,3[$	$[0,+\infty[$	$[2,3[$
$[1,4[$	$[0,+\infty[$	$[1,4[$	$[0,+\infty[$
$[2,3[$	$[0,+\infty[$	$[2,3[$	$[2,3[$
$[0,+\infty[$	$[1,4[$	$[0,+\infty[$	$[1,4[$
$[0,+\infty[$	$[2,3[$	$[2,3[$	$[2,3[$

# Factoring the space of states

subtle

$[1,4[$   
 $[0,+\infty[$

$[0,+\infty[$   
 $[1,4[$

$[1,4[$   
 $[0,+\infty[$

$[0,+\infty[$   
 $[1,4[$