Mixed Integer Non Linear Optimization: Methods and Applications

Introduction

Claudia D'Ambrosio dambrosio@lix.polytechnique.fr



▲ロ ▶ ▲周 ▶ ▲ 国 ▶ ▲ 国 ▶ ● の Q @

12/06/2023	16-17	Introduction Mathematical Programming, Linear Programming	(Simplified) Unit Commitment
	17-18	Introduction to AMPL	Activities Scheduling
13/06/2023	9-11	Linear Programming, Mixed Integer Linear Programming	Unit Commitment
	14-16	MILP and AMPL	Uncapacitated Facility Location, Knapsack Problem, Assignment Problem
14/06/2023	9-11	Convex Mixed Integer Non Linear Programming	Robust Portfolio Selection
	14-16	AMPL and MINLP 1/2	Robust Portfolio Selection, Nonlinear Knapsack Problem
15/06/2023	9-11	Non-convex Mixed Integer Non Linear Programming	Pooling Problem
	14-16	AMPL and MINLP 2/2	Support Vector Machine and MINLP, Algorithm Configuration
16/06/2023	9-11	Research Talks:	Perspective Formulation Comparison for Piecewise Convex Functions
			Urban Air Mobility

◆□▶ ◆□▶ ◆目▶ ◆目▶ 目 のへで

12/06/2023	16-17	Introduction Mathematical Programming, Linear Programming	(Simplified) Unit Commitment
	17-18	Introduction to AMPL	Activities Scheduling
13/06/2023	9-11	Linear Programming, Mixed Integer Linear Programming	Unit Commitment
	14-16	MILP and AMPL	Uncapacitated Facility Location, Knapsack Problem, Assignment Problem
14/06/2023	9-11	Convex Mixed Integer Non Linear Programming	Robust Portfolio Selection
	14-16	AMPL and MINLP 1/2	Robust Portfolio Selection, Nonlinear Knapsack Problem
15/06/2023	9-11	Non-convex Mixed Integer Non Linear Programming	Pooling Problem
	14-16	AMPL and MINLP 2/2	Support Vector Machine and MINLP, Algorithm Configuration
16/06/2023	9-11	Research Talks:	Perspective Formulation Comparison for Piecewise Convex Functions
			Urban Air Mobility

https://www.lix.polytechnique.fr/~dambrosio/teaching/Pisa/

Everybody makes several decisions every day

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三三 - のへぐ

Everybody makes several decisions every day

Goal-directed behavior when options available

▲□▶ ▲□▶ ▲ □▶ ▲ □▶ □ のへぐ

Everybody makes several decisions every day

Goal-directed behavior when options available

▲□▶ ▲□▶ ▲ □▶ ▲ □▶ □ のへぐ

Normative vs. Descriptive Decision Theory

- Everybody makes several decisions every day
- Goal-directed behavior when options available
- Normative vs. Descriptive Decision Theory
- Focus on determining the optimal decisions given constraints and assumptions

- Everybody makes several decisions every day
- Goal-directed behavior when options available
- Normative vs. Descriptive Decision Theory
- Focus on determining the optimal decisions given constraints and assumptions
- Interdisciplinary field : computer scientists, mathematicians, economists, engineers, statisticians, ...

- Everybody makes several decisions every day
- Goal-directed behavior when options available
- Normative vs. Descriptive Decision Theory
- Focus on determining the optimal decisions given constraints and assumptions
- Interdisciplinary field : computer scientists, mathematicians, economists, engineers, statisticians, . . .

 Operations Research : analytical methods to help better decisions Nothing in the world takes place without optimization, and there is no doubt that all aspects of the world that have a rational basis can be explained by optimization methods.

Originally in Latin, briefly and very freely translated by Martin Grötschel in "Optimization Stories".

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ●



Abstract and formal language



- Abstract and formal language
- Aim: modeling (formulate) optimization problems

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三三 - のへぐ

- Abstract and formal language
- Aim: modeling (formulate) optimization problems

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三 のへぐ

► Formulate-and-solve paradigm

- Abstract and formal language
- Aim: modeling (formulate) optimization problems

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三 のへぐ

- Formulate-and-solve paradigm
- Available general-purpose solvers

- Abstract and formal language
- Aim: modeling (formulate) optimization problems
- Formulate-and-solve paradigm
- Available general-purpose solvers
- ▶ Algebraic Modeling Languages (AMPL) \rightarrow exercise sessions

$$\begin{array}{ll} \min_{x} & f(x) \\ & g_{i}(x) \leq & 0 \quad \forall i = 1, \dots, m \\ \underline{x} & \leq x \leq & \overline{x} \\ & x_{j} \in & \mathbb{Z} \quad \forall j \in Z \end{array}$$

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

where

x is an n-dimensional vector of the decision variables

$$egin{array}{lll} \min_{x} & f(x) \ & g_{i}(x) \leq & 0 & orall i=1,\ldots,m \ & \underline{x} & \leq x \leq & \overline{x} \ & x_{i} \in & \mathbb{Z} & orall j \in Z \end{array}$$

where

- x is an n-dimensional vector of the decision variables
- \underline{x} and \overline{x} are the given vectors of lower and upper bounds on the variables

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ●

$$egin{array}{lll} \min_{x} & f(x) \ & g_{i}(x) \leq & 0 & orall i=1,\ldots,m \ & \underline{x} & \leq x \leq & \overline{x} \ & x_{i} \in & \mathbb{Z} & orall j \in Z \end{array}$$

where

- x is an n-dimensional vector of the decision variables
- \underline{x} and \overline{x} are the given vectors of lower and upper bounds on the variables
- set Z ⊆ {1,2,..., n} is the set of the indexes of the integer variables

$$egin{array}{lll} \min_{x} & f(x) \ & g_i(x) \leq & 0 & orall i=1,\ldots,m \ & \underline{x} & \leq x \leq & \overline{x} \ & x_j \in & \mathbb{Z} & orall j \in Z \end{array}$$

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

where

• f(x) and g(x) can be written in closed form

$$egin{array}{lll} \min_{x} & f(x) \ & g_i(x) \leq & 0 & orall i=1,\ldots,m \ & \underline{x} & \leq x \leq & \overline{x} \ & x_i \in & \mathbb{Z} & orall j \in Z \end{array}$$

where

- f(x) and g(x) can be written in closed form
- ► f(x) and g_i(x) are given twice continuously differentiable functions of the variables (∀i = 1,..., m)

Mathematical Optimisation is a knowledge-based approach



▲ロ ▶ ▲周 ▶ ▲ 国 ▶ ▲ 国 ▶ ● の Q @

Let us consider a utility company that owns several production (or generating) units (like hydro plants, thermal plants, etc.).

Let us consider a utility company that owns several production (or generating) units (like hydro plants, thermal plants, etc.). Usually, the company has to decide daily how to produce power, i.e., which units to commit to power production.

Let us consider a utility company that owns several production (or generating) units (like hydro plants, thermal plants, etc.). Usually, the company has to decide daily how to produce power, i.e., which units to commit to power production. More formally, a utility company wishes to decide on the optimal scheduling of its units within a prefixed discretized time horizon, say $T = \{1, \ldots, \bar{t}\}$.

Let us consider a utility company that owns several production (or generating) units (like hydro plants, thermal plants, etc.). Usually, the company has to decide daily how to produce power, i.e., which units to commit to power production. More formally, a utility company wishes to decide on the optimal scheduling of its units within a prefixed discretized time horizon, say $T = \{1, ..., \bar{t}\}$. The set of units is called J. For each of the unit $j \in J$, we have a cost for generating electricity by unit c_j and its maximum production \overline{P}_j .

Let us consider a utility company that owns several production (or generating) units (like hydro plants, thermal plants, etc.). Usually, the company has to decide daily how to produce power, i.e., which units to commit to power production. More formally, a utility company wishes to decide on the optimal scheduling of its units within a prefixed discretized time horizon, say $T = \{1, ..., \bar{t}\}$. The set of units is called J. For each of the unit $j \in J$, we have a cost for generating electricity by unit c_j and its maximum production \overline{p}_j . For each time period $t \in T$, we are given the forecast electricity demand to be satisfied D_t .

A motivating example: the (simplified) Unit Commitment

$$\min_{p} \sum_{t \in T} \sum_{j \in J} c_{j} p_{jt} \qquad (1)$$

$$\sum_{j \in J} p_{jt} = D_{t} \qquad \forall t \in T \qquad (2)$$

$$0 \le p_{jt} \le \overline{p}_{j} \qquad \forall j \in J, t \in T \qquad (3)$$

where (1) is the objective function minimizing the cost for producing electricity, (2) is the set of constraints satisfying the demand D_t at each time period $t \in T$, and (3) are the simple bounds on the electricity production by each unit j at each time period j.

Formulation : a MO modeling an optimization problem

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三三 - のへぐ

- **Formulation** : a MO modeling an optimization problem
- \blacktriangleright An optimization problem can be modeled in different ways \rightarrow several formulations

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ●

- **Formulation** : a MO modeling an optimization problem
- ► An optimization problem can be modeled in different ways → several formulations
- ► Instance : when the expression of f(x), g(x) and the values of <u>x</u>, <u>x</u>, and <u>Z</u> are known. The set of instances of a MO problems is potentially infinite.

► Feasible solutions : $X = \{x \mid g(x) \le 0, \underline{x} \le x \le \overline{x}, x_j \in \mathbb{Z} \mid \forall j \in Z\}$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ □臣 ○のへ⊙

► Feasible solutions : $X = \{x \mid g(x) \le 0, \underline{x} \le x \le \overline{x}, x_j \in \mathbb{Z} \mid \forall j \in Z\}$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ●

• **Optimal solution** : $\arg \min_{x \in X} f(x)$

- ► Feasible solutions : $X = \{x \mid g(x) \le 0, x \le x \le \overline{x}, x_i \in \mathbb{Z} \mid \forall j \in Z\}$
- **Optimal solution** : $\arg \min_{x \in X} f(x)$
- Heuristic solution : a feasible solution (hopefully of good quality)

- ► Feasible solutions : $X = \{x \mid g(x) \le 0, \underline{x} \le x \le \overline{x}, x_i \in \mathbb{Z} \ \forall j \in Z\}$
- **Optimal solution** : $\arg \min_{x \in X} f(x)$
- Heuristic solution : a feasible solution (hopefully of good quality)

NB: difference between optimization (decisions are made) and simulation (no decision made)

$$egin{array}{lll} \min_{x} & f(x) \ & g_{i}(x) \leq & 0 & orall i=1,\ldots,m \ & \underline{x} & \leq x \leq & \overline{x} \ & x_{j} \in & \mathbb{Z} & orall j \in Z \end{array}$$

Linear Programming (LP): f(x) and g(x) are linear, $Z = \emptyset$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ 三三 - のへぐ

$$egin{array}{lll} \min_{x} & f(x) \ & g_{i}(x) \leq & 0 & orall i=1,\ldots,m_{i} \ & \underline{x} & \leq x \leq & \overline{x} \ & x_{j} \in & \mathbb{Z} & orall j \in Z \end{array}$$

▶ Linear Programming (LP): f(x) and g(x) are linear, Z = Ø
 ▶ Integer Linear Programming (ILP): f(x) and g(x) are linear, Z = {1, 2, ..., n}

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ●

$$egin{array}{lll} \min_{x} & f(x) \ & g_i(x) \leq & 0 & orall i=1,\ldots,m_i \ & \underline{x} & \leq x \leq & \overline{x} \ & x_j \in & \mathbb{Z} & orall j \in Z \end{array}$$

- ▶ Linear Programming (LP): f(x) and g(x) are linear, $Z = \emptyset$
- Integer Linear Programming (ILP): f(x) and g(x) are linear, Z = {1,2,...,n}
- ► Mixed Integer Linear Programming (MILP): f(x) and g(x) are linear, Z ⊂ {1,2,...,n}

A D N A 目 N A E N A E N A B N A C N

$$egin{array}{lll} \min_{x} & f(x) \ & g_{i}(x) \leq & 0 & orall i=1,\ldots,m \ & \underline{x} & \leq x \leq & \overline{x} \ & x_{j} \in & \mathbb{Z} & orall j \in Z \end{array}$$

- ▶ Linear Programming (LP): f(x) and g(x) are linear, $Z = \emptyset$
- Integer Linear Programming (ILP): f(x) and g(x) are linear, Z = {1, 2, ..., n}
- ▶ Mixed Integer Linear Programming (MILP): f(x) and g(x) are linear, $Z \subset \{1, 2, ..., n\}$
- ► Mixed Integer Non Linear Programming (MINLP): f(x) and g(x) are twice continuously differentiable, Z ⊂ {1,2,...,n}

$$egin{array}{ccc} \min_x & f(x) & & & \\ & g_i(x) \leq & 0 & orall i = 1, \dots, m & & \\ \underline{x} & \leq x \leq & \overline{x} & & & \ & & x_j \in & \mathbb{Z} & orall j \in Z & & \end{array}$$

- ▶ Linear Programming (LP): f(x) and g(x) are linear, $Z = \emptyset$
- Integer Linear Programming (ILP): f(x) and g(x) are linear, Z = {1, 2, ..., n}
- ▶ Mixed Integer Linear Programming (MILP): f(x) and g(x) are linear, $Z \subset \{1, 2, ..., n\}$
- ► Mixed Integer Non Linear Programming (MINLP): f(x) and g(x) are twice continuously differentiable, Z ⊂ {1,2,...,n}

Black Box Optimization: f(x) or $g(x) \rightarrow \text{no_closed form}$