

CONCURRENT/DISTRIBUTED DATA TYPES

Correctness Criteria, Verification

Constantin Enea

Ecole Polytechnique

Parallel Data Processing

Software systems that support **high-frequency** parallel accesses to **high-quantity** data.

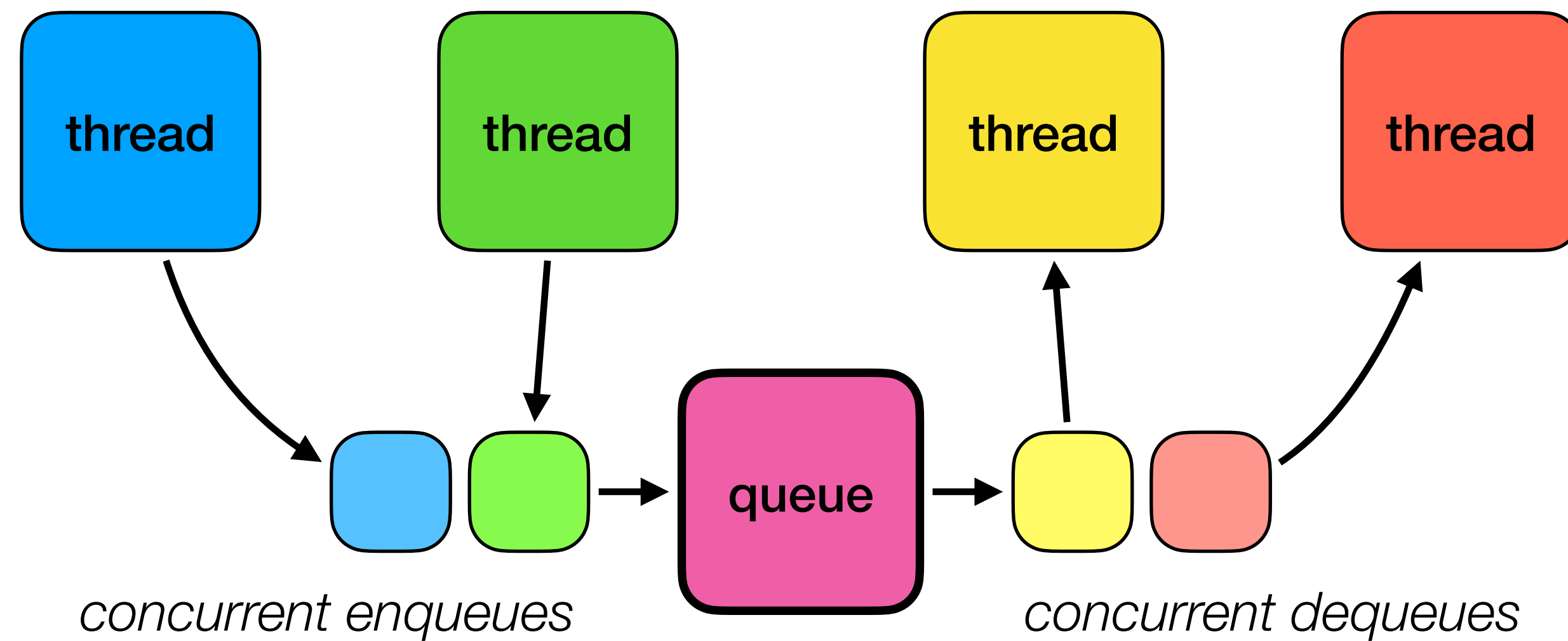
Rely on high-performance shared resources (**data types**).

- key-value maps, sets, queues, stacks, etc.

Deployed over a **shared-memory** or a **network**

Concurrent Objects

Multi-threaded programming



e.g. Java Development Kit SE

dozens of objects, including queues, maps, sets, lists, locks, atomic integers, ...

Shared-State in Parallel Applications

- ▶ Parallelizing applications for efficiency

Sequential

```
// reading data for  
future processing  
q = new Queue();  
while(...) {  
    X = readFile();  
    q.enqueue(X);  
}
```

Shared-State in Parallel Applications

► Parallelizing applications for efficiency

- multi-threading
- distributed over a network

Sequential

```
// reading data for
future processing
q = new Queue();
while(...) {
    X = readFile();
    q.enqueue(X);
}
```

Parallel

```
q = new Queue();

while(...) {
    X = readFile1();
    q.enqueue(X);
} ||
while(...) {
    X = readFile2();
    q.enqueue(X);
}
```

Shared-State in Parallel Applications

► Parallelizing applications for efficiency

- multi-threading
- distributed over a network

Sequential

```
// reading data for  
future processing
```

```
q = new Queue();  
while(...) {  
    X = readFile();  
    q.enqueue(X);  
}
```

Parallel

```
q = new Queue();  
l = new Lock();
```

```
while(...) {  
    X = readFile1();  
    l.lock();  
    q.enqueue(X);  
    l.unlock();  
}
```

```
while(...) {  
    X = readFile2();  
    l.lock();  
    q.enqueue(X);  
    l.unlock();  
}
```

Shared-State in Parallel Applications

► Parallelizing applications for efficiency

- multi-threading
- distributed over a network

Sequential

```
// reading data for  
future processing
```

```
q = new Queue();  
while(...) {  
    X = readFile();  
    q.enqueue(X);  
}
```

Parallel

```
q = new Queue();  
l = new Lock();
```

```
while(...) {  
    X = readFile1();  
    l.lock();  
    q.enqueue(X);  
    l.unlock();  
}
```

```
while(...) {  
    X = readFile2();  
    l.lock();  
    q.enqueue(X);  
    l.unlock();  
}
```

How to implement concurrent/distributed objects ?

How is correctness defined ? Verification ?

Verification Ingredients

- ▶ Specifying a Library: φ
- ▶ Implementing a Library: $\mathbb{L}$
- ▶ Verifying a Library implementation: $\mathbb{L} \models \varphi$

Specifying Sequential Objects

Object Specification

- ▶ How can we specify an object?
(Library)
 - ▶ Objects API
 - ▶ Use cases
 - ▶ Pre and Post Conditions?
- ▶ What are the behaviors of a client using the library?
- 💡 for any client making library calls record the inputs and outputs of each call

```
java.util
Class Stack<E>
java.lang.Object
  java.util.AbstractCollection<E>
    java.util.AbstractList<E>
      java.util.Vector<E>
        java.util.Stack<E>
```

Method Summary

Methods

Modifier and Type	Method and Description
boolean	empty () Tests if this stack is empty.
E	peek () Looks at the object at the top of this stack without removing it from the stack.
E	pop () Removes the object at the top of this stack and returns that object as the value of this function.
E	push (E item) Pushes an item onto the top of this stack.
int	search (Object o) Returns the 1-based position where an object is on this stack.

Methods inherited from class java.util.Vector

add, add, addAll, addAll, addElement, capacity, clear, clone, contains, containsAll, copyInto, elementAt, elements, ensureCapacity, equals, firstElement, get, hashCode

What is a client?

- ▶ What is a client of the Library?
 - ▶ Program that issues calls to a library instance

```
// do something
q.enqueue(v)
// do something
x = q.dequeue()
// ...
```

Diagram illustrating the interaction between a client and a library instance:

- Client code: `// do something`, `q.enqueue(v)`, `// do something`, `x = q.dequeue()`, `// ...`
- Library instance timeline: `//do something` (black bracket), `q.enqueue(v) return` (red bracket), `q.dequeue() return` (red bracket), `...` (black bracket)

- ▶ How do we specify a Data Structure (DS) generically?
 - ▶ Histories of calls and returns
 - ▶ Constraint possible return values

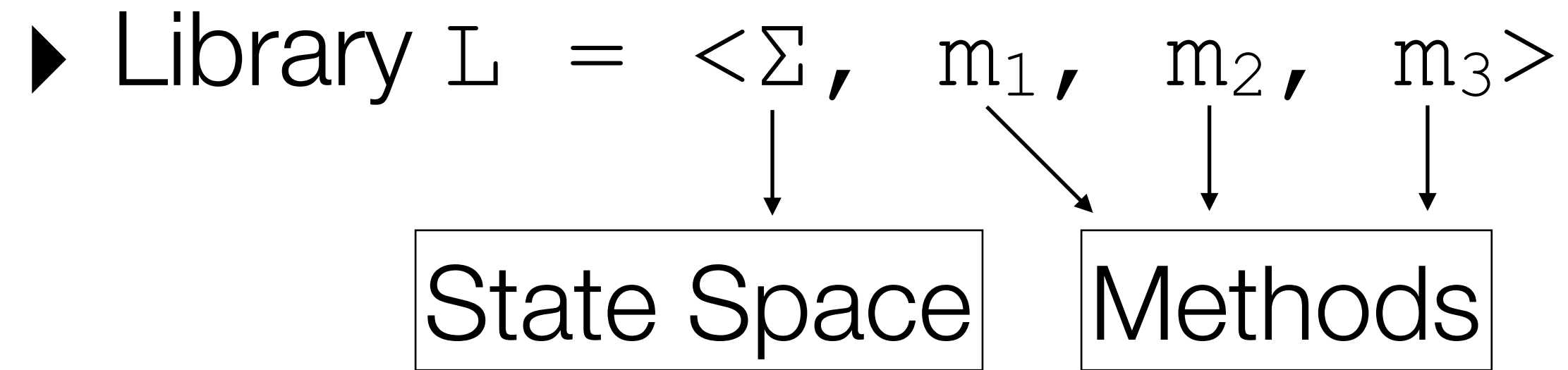
Diagram illustrating the interaction between a client and a library instance, showing the return values of the calls:

- Library instance timeline: `q.enqueue(v) return ?` (red bracket), `q.dequeue() return ?` (red bracket)

Well Encapsulated Objects

- ▶ *Global* object state:
 - ▶ Possibly *local* thread state
- ▶ A set of *operations* or *methods*
 - ▶ Input and output types
 - ▶ Methods are the only way to operate on the state

Sequential Object Specifications



- Client C: Issues calls to the library methods
 - (Sequential) Most General Client [SMGC]

```
SMGC(L) :  
  while true do  
    mi = choseMethodFrom(L) ;  
    args = choseInputsFor(m) ;  
    mi(args) ;  
  od
```

- We will talk about histories of calls with values
 - ϵ denotes the empty sequence,
 - o denotes an operation (eg. $\langle \text{pop}(), v \rangle$), and
 - δ denotes a sequence of operations

Specifying a Register

► Inductive histories of a Register:

1. ϵ is a Register History (RH)
2. $\langle \text{read}(), 0 \rangle^*$ is a Register History
3. if δ is a RH, then so is $\delta \cdot \langle \text{write}(v), _ \rangle$
4. if $\delta \cdot \langle \text{write}(v), _ \rangle$ is a RH, then so it is $\delta \cdot \langle \text{read}(), v \rangle^*$

Some examples on the board

Specifying a Stack

► Inductive histories of a Stack:

1. ϵ is a Stack History (SH)
2. if $\delta \cdot \langle \text{pop}(), v \rangle$ is a SH, then so is $\langle \text{push}(w), _ \rangle \cdot \delta$
3. if δ is a SH, and $|\{\langle \text{pop}(), v \rangle : \delta \mid v \neq \perp\}| = |\text{push}(v), _ \rangle : \delta|$, then so it is $\delta \cdot \langle \text{pop}(), \perp \rangle^*$
4. same conditions as 3, and $\langle \text{pop}(), \perp \rangle$ does not occur in δ then, $\langle \text{push}(w), \perp \rangle \cdot \delta \cdot \langle \text{pop}(), w \rangle$ is a SH
5. if $\delta_0 \cdot \langle \text{pop}(), \perp \rangle$ is a SH, and δ_1 is a SH, then $\delta_0 \cdot \delta_1$ is SH

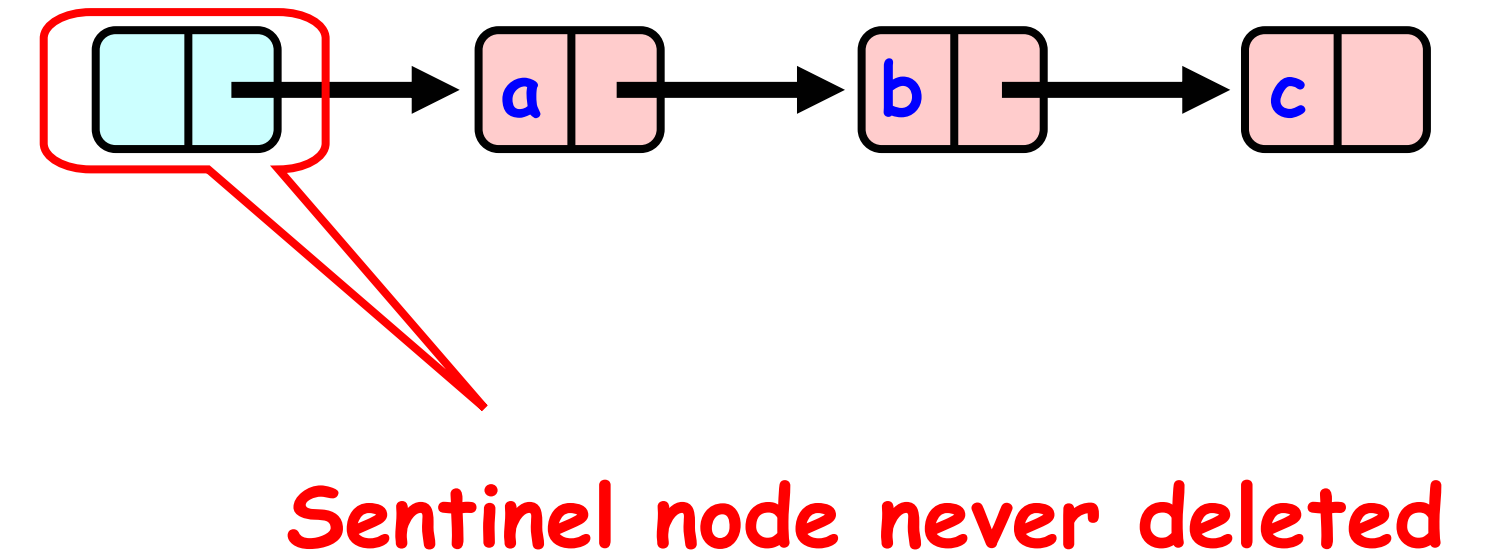
Specifying a Queue

Exercise

Implementations

- A set implementation based on sorted linked lists

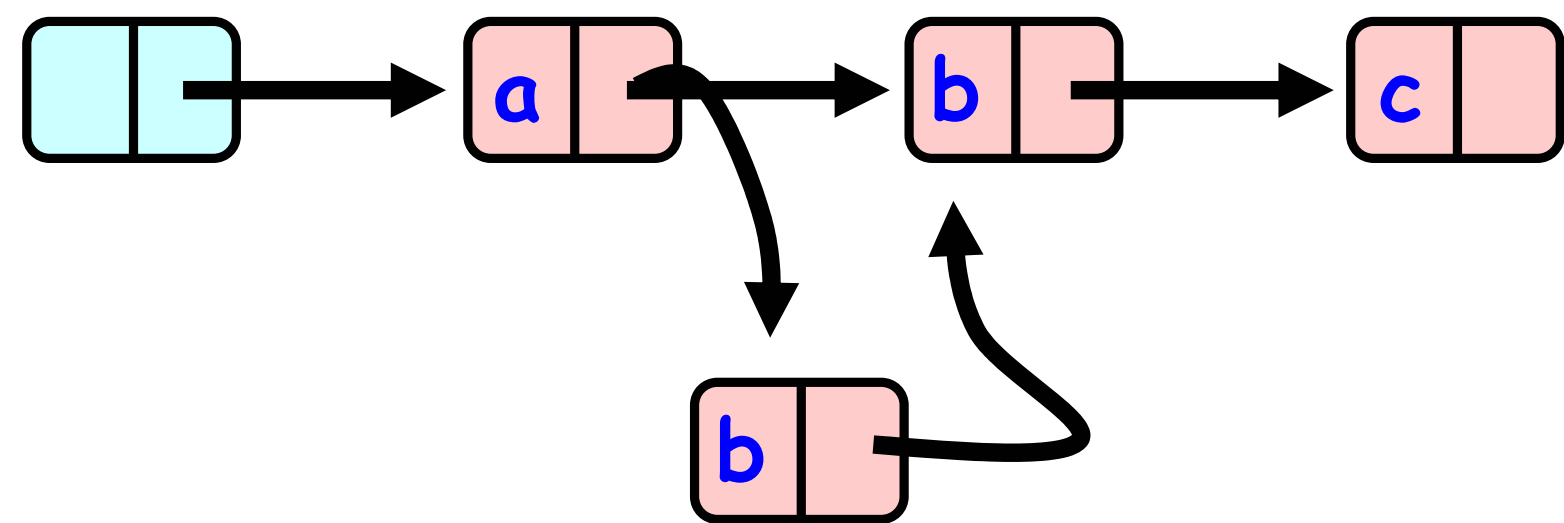
```
public class Entry {  
    public Object value;  
    public Entry next;  
}  
  
public class Set {  
    Entry first;  
    public boolean add(Object x) {...}  
    public boolean remove(Object x) {...}  
    public boolean contains(Object x) {...}  
}
```



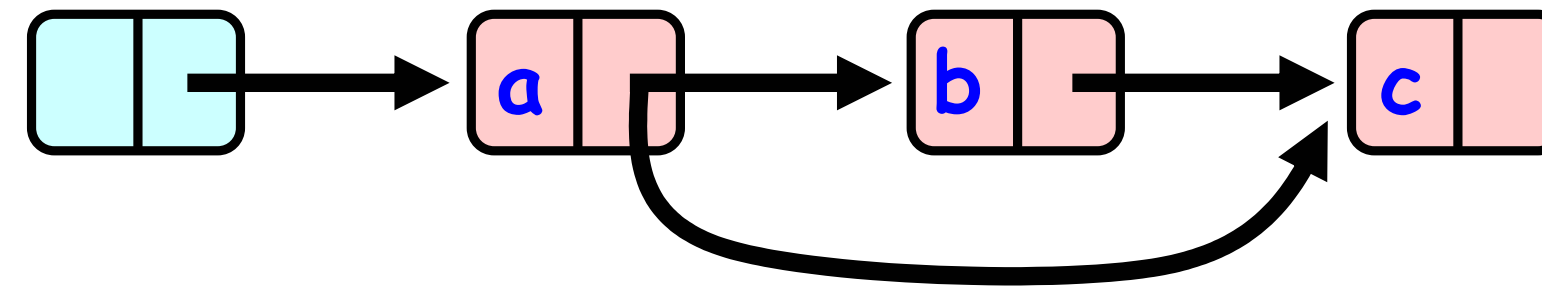
Implementations

- A set implementation based on sorted linked lists

adding an entry



removing an entry



Specifying Concurrent Objects

What about Concurrency?

```
while true do  
  mi = choseMethodFrom(L) ;  
  args = choseInputsFor(m) ;  
  mi(args) ;  
od
```

```
while true do  
  mi = choseMethodFrom(L) ;  
  args = choseInputsFor(m) ;  
  mi(args) ;  
od
```

`s.push(v)` `return` `s.pop()` `return v` ?

Concurrent Consistency Criteria

Should this be legal?

Concurrent Clients

SMGC(L) :

while true do

$m_i = \text{choseMethodFrom}(L) ;$

$\text{args} = \text{choseInputsFor}(m) ;$

$m_i(\text{args}) ;$

od

- Most General Client (seq)

- Most General Client (concurrent n threads)

CMGC_n(L) :

SMGL(L) || SMGL(L) ... || SMGL(L)

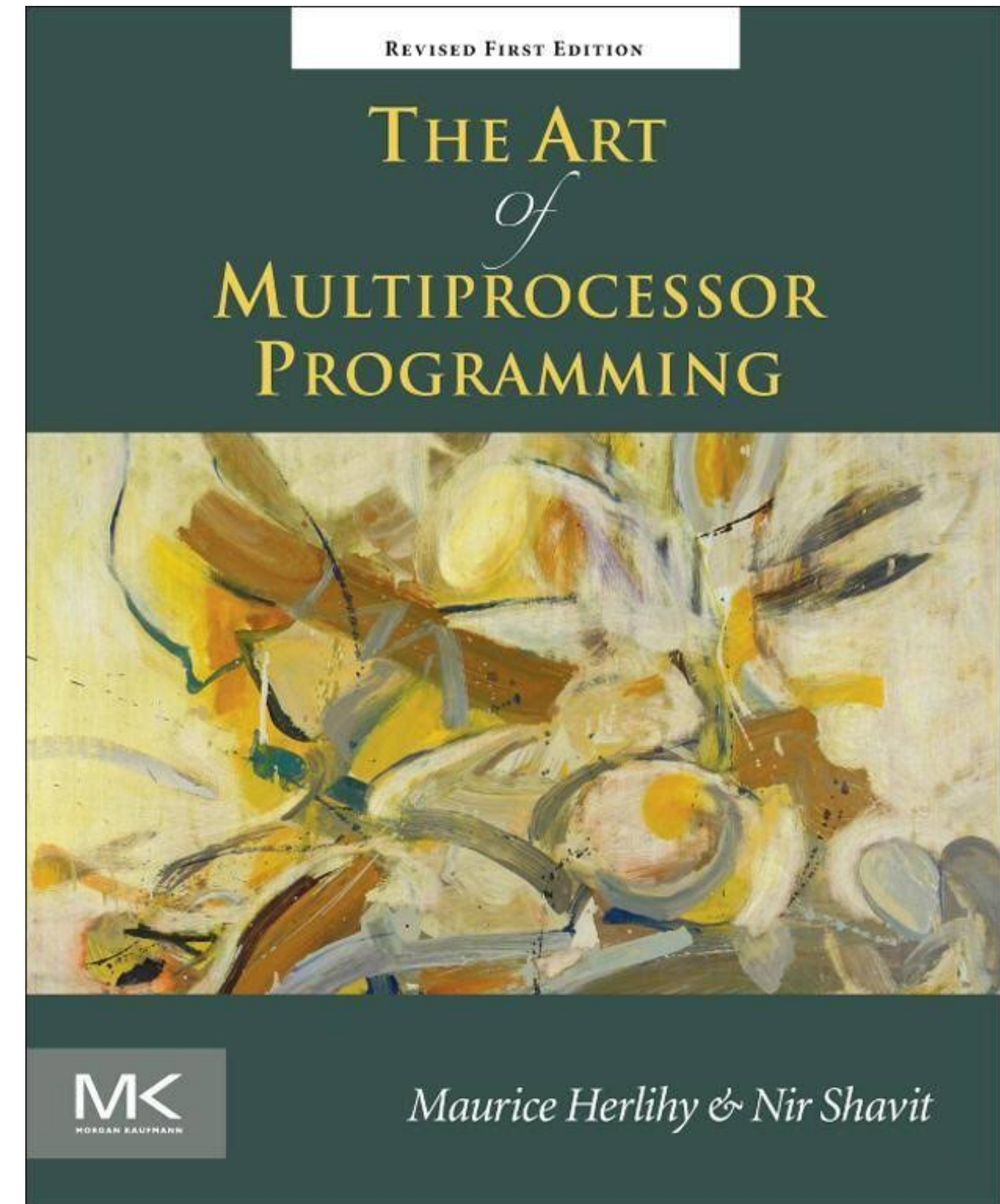
└──┘
n

- Concurrent Library Verification w.r.t. CMGC_n(L) for any n

Concurrent Consistency Criteria

- ▶ Quiescence Consistency
- ▶ Sequential Consistency
- ▶ Linearizability

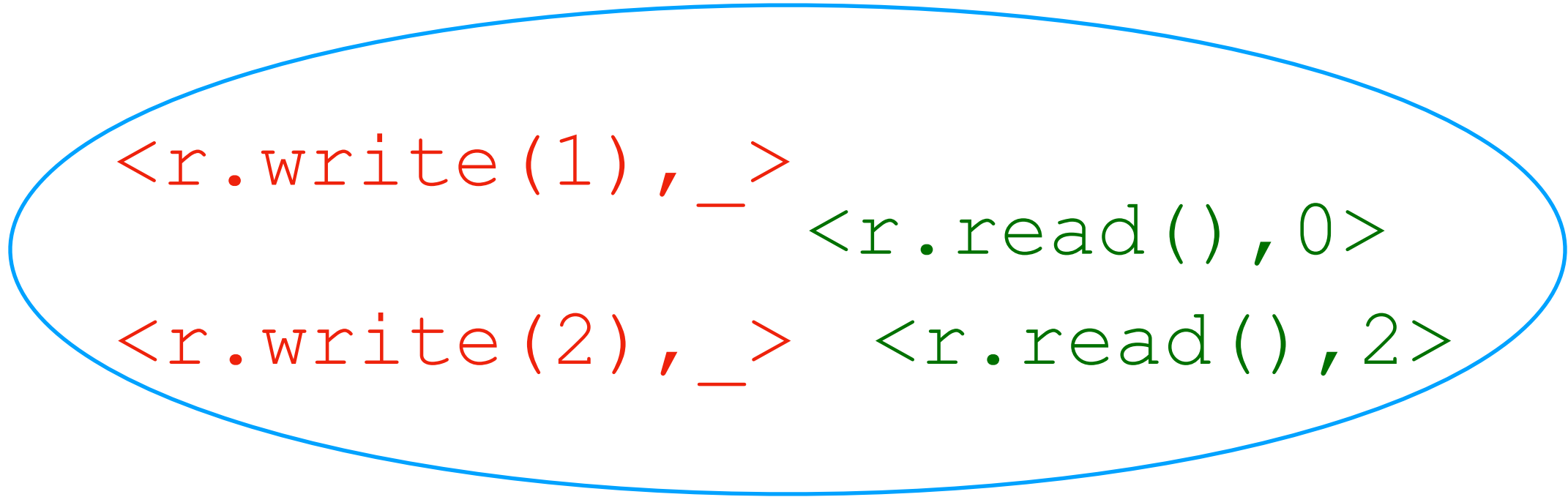
We will work with Registers
to exemplify the definitions



Quiescent Consistency

- ▶ Method calls should appear to happen one-at-a-time, sequential order

```
r.write(1); || r.read(); r.write(1)      ret      r.write(2)      ret
r.write(2); || r.read(); r.read()      ret 2      r.read()      ret 0
```



`<r.write(1), _>`
`<r.read(), 0>`
`<r.write(2), _>` `<r.read(), 2>`

`<r.read(), 0>` `<r.write(1), _>` `<r.write(2), _>` `<r.read(), 2>`

Quiescent Consistency

- ▶ Method calls should appear to happen one-at-a-time, sequential order
- ▶ Method calls separated by a period of quiescence should appear to take effect in their real time order

`r.write(1)` `ret`
`r.read()` `ret 2`

`<r.write(1), _>`
`<r.read(), 2>`

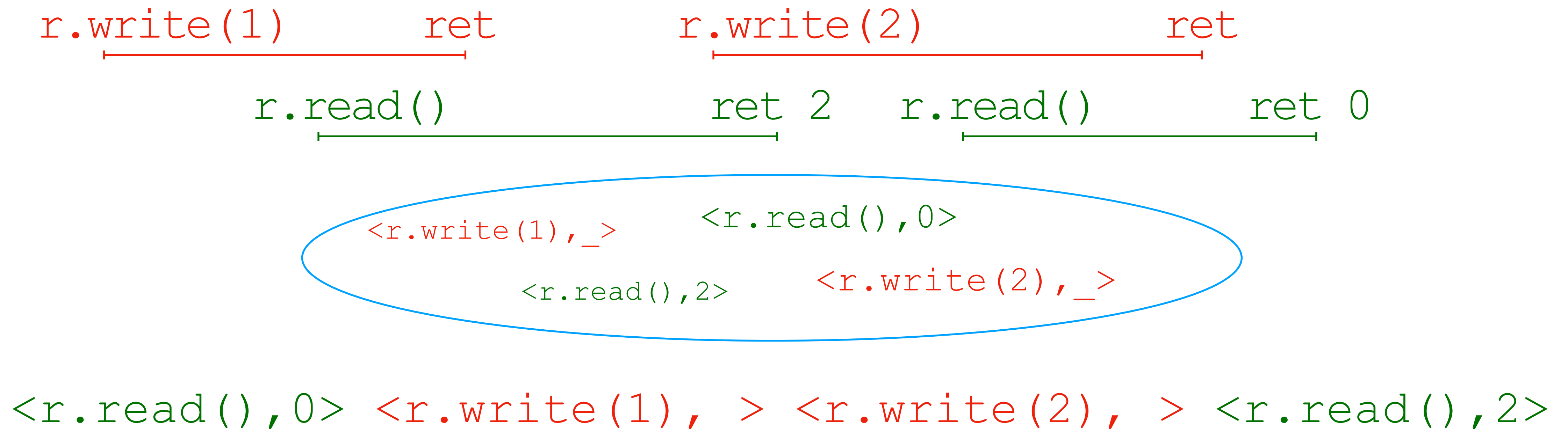
`r.write(2)` `ret`
`r.read()` `ret 0`

`<r.read(), 0>`
`<r.write(2), _>`



Quiescent Consistency

- ▶ Method calls should appear to happen one-at-a-time, sequential order
- ▶ Method calls separated by a period of quiescence should appear to take effect in their real time order



Sequential Consistency

- ▶ *How to Make a Multiprocessor Computer that Correctly Executes Multiprocess Computer Programs* [Lamport'79]
 - ▶ Each process issues operations in the order specified by its program.
 - ▶ Operations from all processors issued to a single object are serviced from a single FIFO queue. Issuing an operation consists in entering a request on this queue.

Sequential Consistency

```
r.write(1); | r.read();  
r.write(2); | r.read();
```

r.write(1) ret

r.read() ret 2

r.write(2) ret

r.read() ret 0

$\langle r.write(1), _ \rangle \longrightarrow \langle r.write(2), _ \rangle$

$\langle r.read(), 2 \rangle \longrightarrow \langle r.read(), 0 \rangle$



Sequential Consistency

```
r.write(1); | r.read();  
r.write(2); | r.read();
```

r.write(1) ret
r.read() ret 0

r.write(2) ret
r.read() ret 1

$\langle r.write(1), _ \rangle \longrightarrow \langle r.write(2), _ \rangle$

$\langle r.read(), 0 \rangle \longrightarrow \langle r.read(), 1 \rangle$

$\langle r.read(), 0 \rangle \quad \langle r.write(1), _ \rangle \quad \langle r.read(), 1 \rangle \quad \langle r.write(2), _ \rangle$

Sequential Consistency

- ▶ Quiescent Consistency +
- ▶ Method calls should appear to take effect in Program Order

program order $\downarrow$ `r.write(1);` || `r.read();` $\downarrow$ program order
 $\downarrow$ `r.write(2);` || `r.read();` $\downarrow$ program order

- ▶ Each history δ induces a per-thread total order of operations
 - ▶ $o_1 \prec_{\delta} o_2$ iff o_1 and o_2 are on the same thread, and o_1 occurs before o_2 in δ
- ▶ A history δ is Sequentially Consistent if there exists an equivalent *Sequential* history δ' (i.e. same operations), and
 - ▶ $o_1 \prec_{\delta} o_2$ implies $o_1 \prec_{\delta'} o_2$

Sequential Consistency

`x.write(1)` `ret`
|-----|

`x.write(2)` `ret`
|-----|

`x.read()` `ret1`
|-----|



`x.write(1)` `ret`
|-----|

`x.write(2)` `ret`
|-----|

`x.read()` `ret0`
|-----|



Linearizability

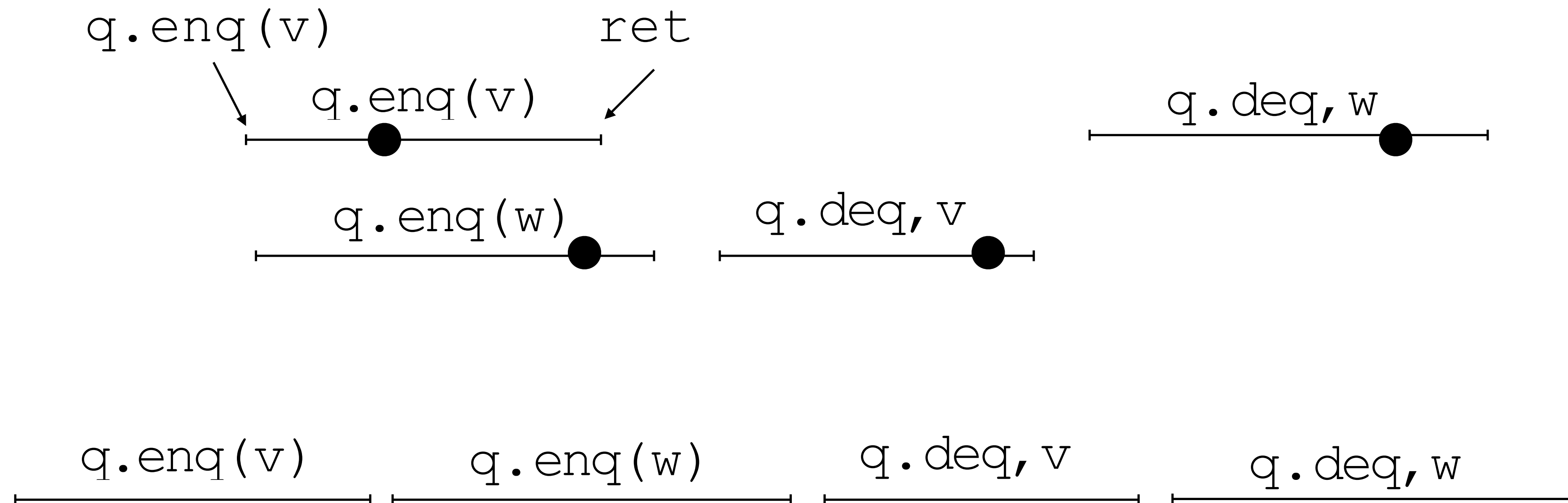
- ▶ Same conditions as Sequential Consistency +
- ▶ Each method call should appear to take effect instantaneously at some moment between its invocation (call) and response (return)
- ▶ That is: we can pretend that the execution of each method is uninterrupted by other calls to the object
- ▶ De-facto standard for Concurrent Object Correctness (eg. `java.util.concurrent`)

Linearizability

- ▶ Each history δ induces a partial order on operations such that
 - ▶ $o_1 \sqsubseteq_{\delta} o_2$ iff `ret` o_1 occurs before `call` o_2 in δ
- ▶ A history δ is Linearizable if there exists an equivalent *Sequential* history δ' (i.e. same operations), and
 - ▶ $o_1 \sqsubseteq_{\delta} o_2$ implies $o_1 \sqsubseteq_{\delta'} o_2$
- ▶ Ignoring uncompleted operations
- ▶ Strictly stronger than Sequential Consistency

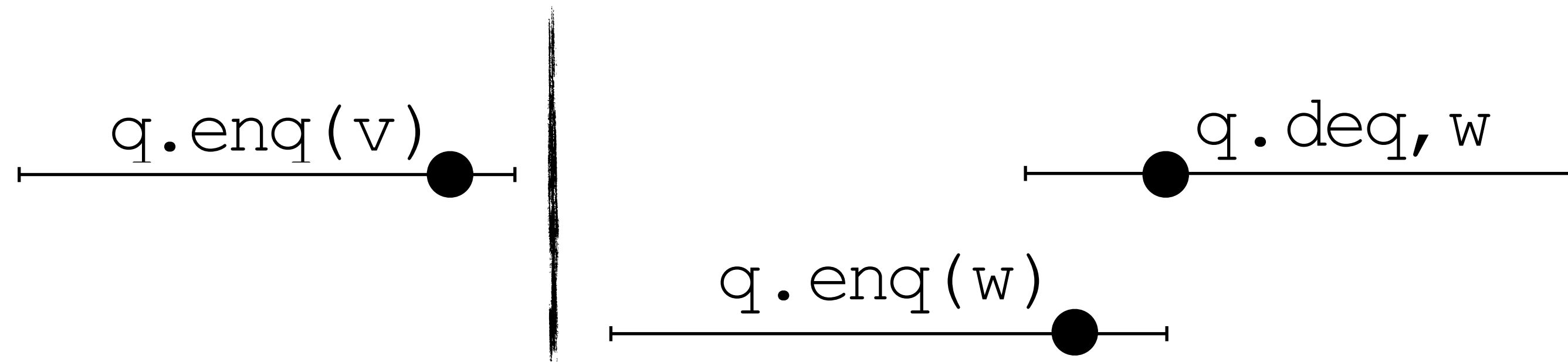
Linearizability

- Each operation takes place atomically within its call/return



Linearizability

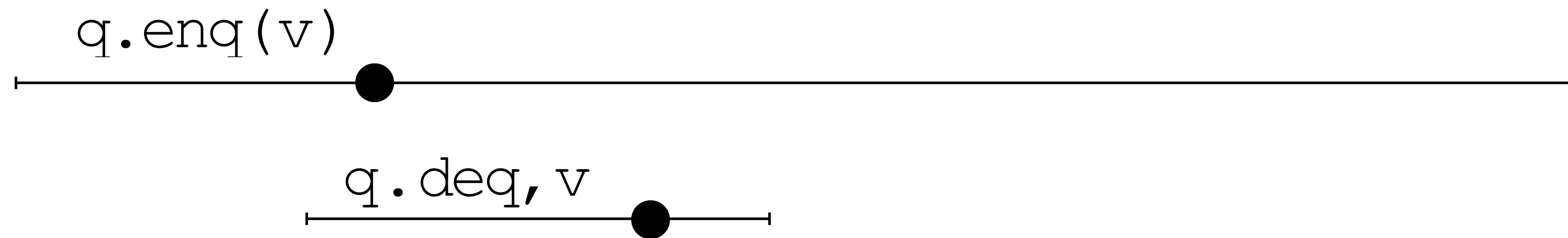
- Each operation takes place atomically within its call/return



Not Linearizable

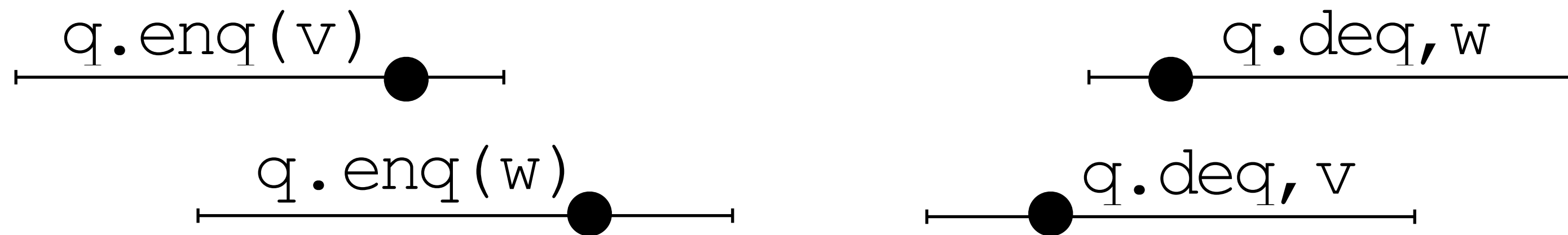
Linearizability

- Each operation takes place atomically within its call/return

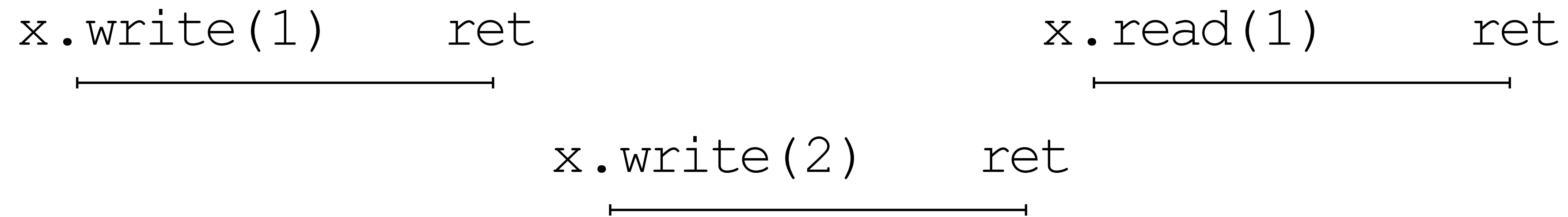


Linearizability

- Each operation takes place atomically within its call/return



Linearizability vs. Sequential Consistency



Not linearizable to begin with!

Observational Refinement

► Linearizability => observational refinement

Reference implementation

```
class AtomicStack {
  cell* top;
  Lock l;

  void push (int v) {
    l.lock();
    top->next = malloc(sizeof *x);
    top = top->next;
    top->data = v;
    l.unlock();
  }

  int pop () {
    ...
  }
}
```

minimize
contention

Efficient implementation

```
class TreiberStack {
  cell* top;

  void push (int v) {
    cell* t;
    cell* x = malloc(sizeof *x);
    x->data = v;
    do {
      t = top;
      x->next = top;
    } while (!CAS(&top, t, x));
  }

  int pop () {
    ...
  }
}
```

For every Client,
Client x Impl included in Client x Spec

Linearizability: Compositionality

- ▶ Theorem: A history δ is linearizable if and only if for each object o in δ , δ_o is linearizable

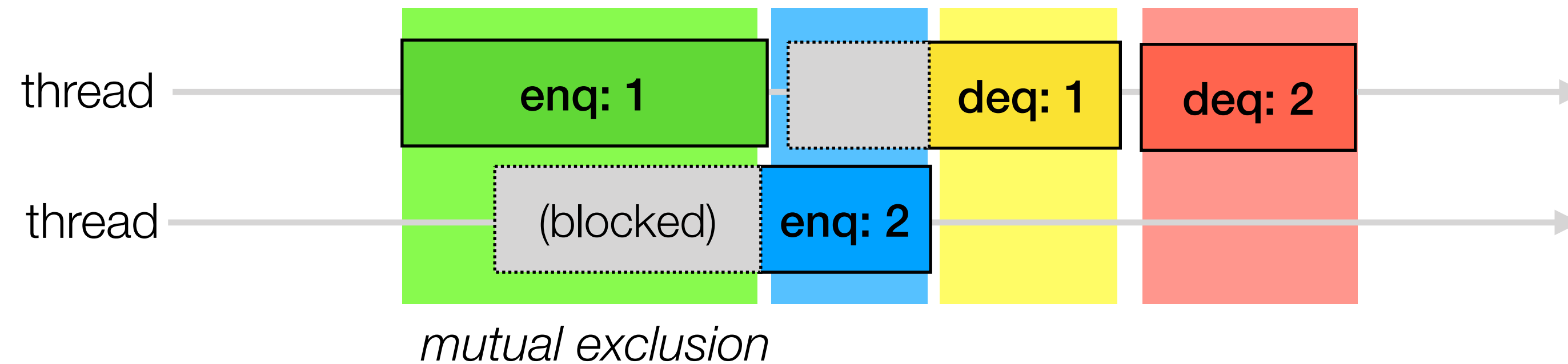
Proof: Simple induction on the number of operations appearing in δ

- ▶ Corollary: It is enough to show that each Library is linearizable to know that the system is

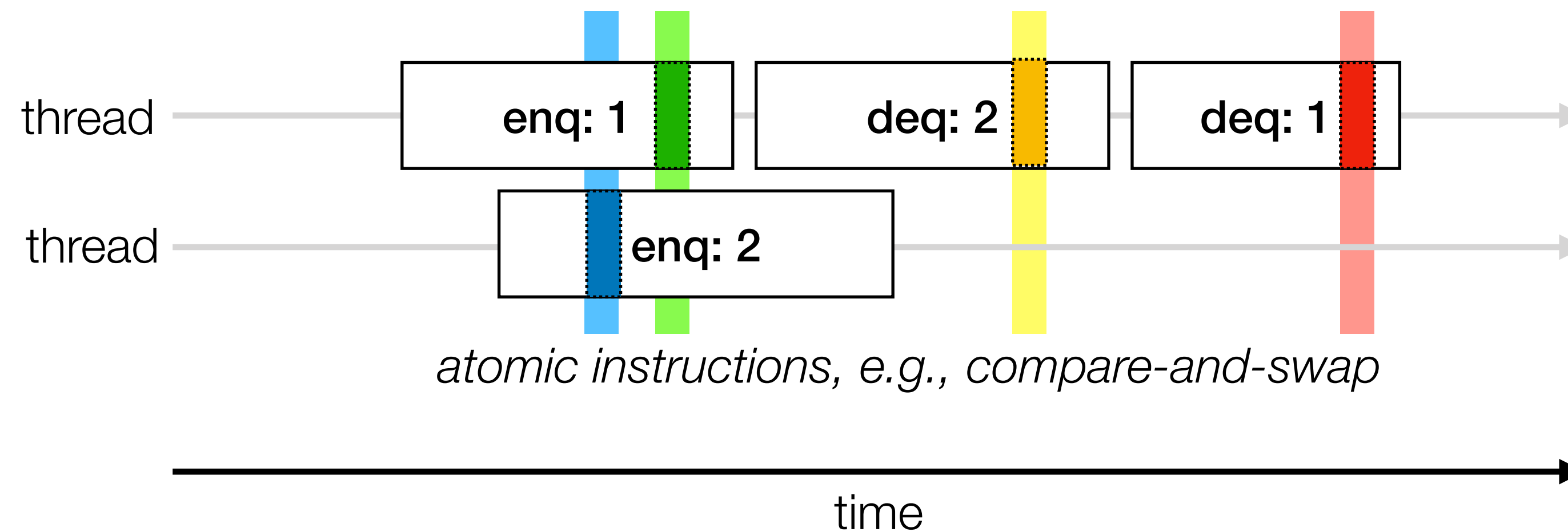
Some Object Implementations

Lock-Free Implementations

blocking reference implementation



efficient nonblocking implementation



“Basic” Objects

Spin Lock

```
int Lock = 0;  
TID owner = null;
```

```
void lock() {  
    bool l;  
    do {  
        while(Lock == 1);  
        l = cas(Lock, 0, 1);  
    } until (l);  
    owner = getTID();  
    return;  
}
```

```
void unlock() {  
    owner = null;  
    Lock = 0;  
    return;  
}
```

Counter

```
class IntPtr {
    int val;
}
IntPtr COU;

void inc(int v) {
    int n;
    while(true) {
        n = COU->val;
        if (cas(COU->val, n, n+v))
            break;
    }
    return;
}

void dec(int v) {
    int n;
    while(true) {
        n = COU->val;
        if (cas(COU->val, n, n-v))
            break;
    }
    return;
}

int read() {
    return COU->val;
}
```

Stack Implementations

Treiber Stack

```
class Node {
    Node tl;
    int val;
}

class NodePtr {
    Node val;
} TOP;
```

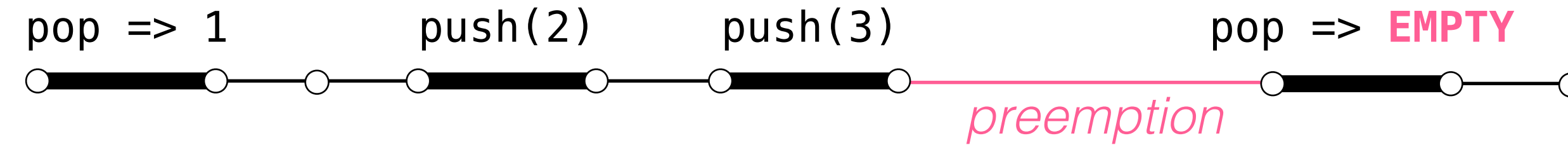
```
void push(int e) {
    Node y, n;
    y = new();
    y->val = e;
    while(true) {
        n = TOP->val;
        y->tl = n;
        if (cas(TOP->val, n, y))
            break;
    }
}
```

```
int pop() {
    Node y, z;
    while(true) {
        y = TOP->val;
        if (y==0) return EMPTY;
        z = y->tl;
        if (cas(TOP->val, y, z))
            break;
    }
    return y->val;
}
```

Treiber Stack (ABA bug)



Thread2



pushed: 1, **2**, 3
popped: 1, 3, **EMPTY**

PROBLEM

not admitted by atomic stack

HSY Elimination Stack

Extremely simplified version: 1 collision

```
class Node {
    Node tl;
    int val;
}

class NodePtr {
    Node val;
} TOP;

class TidPtr {
    int val;
} clash;
```

```
void push(int e) {
    Node y, n;
    TID hisId;
    y = new();
    y->val = e;

    while (true) {
        n = TOP->val;
        y->tl = n;
        if (cas(TOP->val, n, y))
            return;
        //elimination scheme
        TidPtr t = new TidPtr();
        t->val = e;
        if (cas(clash, null, t)) {
            wait(DELAY);
            //not eliminated
            if (cas(clash, t, null))
                continue;
            else break; //eliminated
        }
    }
}
```

```
int pop() {
    Node y, z;
    int t;
    TID hisId;
    while (true) {
        y = TOP->val;
        if (y == 0)
            return EMPTY;
        z = y->tl;
        t = y->val;
        if (cas(TOP->val, y, z))
            return t;
        //elimination scheme
        pusher = clash;
        while (pusher != null) {
            if (cas(clash, pusher, null))
                //eliminated push
                return pusher->val;
        }
    }
}
```

Queue Implementations

Two Locks Queue

```
class Node {
    int val;
    Node tl;
}

class Queue {
    Node head;
    Node tail;
    thread_id hlock;
    thread_id tlock;
} Q;

void enqueue(int v) {
    Node n, t;
    n = new();
    n->val = v;
    n->tl = NULL;
    lock (&Q->tlock);
    temp = Q->tail;
    temp->tl = node;
    Q->tail = node;
    unlock (&Q->tlock);
}

int dequeue() {
    Node n, new_h;
    int v;
    lock (&Q->hlock);
    n = Q->head;
    new_h = n->tl;
    if (new_h == NULL) {
        unlock (&Q->hlock);
        return EMPTY;
    } else {
        value = new_h->val;
        Q->head = new_h;
        unlock (&Q->hlock);
        //dispose(n);
        return v;
    }
}
```

Michael and Scott Queue

```
class Node {
    int val;
    Node tl;
}

class Queue {
    Node head;
    Node tail;
} Q;

void enqueue(int v) {
    Node nd, nxt, tl;
    int b1;
    nd = new();
    nd->val = v;
    nd->tl = NULL;
    while(true) {
        tl = Q->tail;
        nxt = tl->tl
        if (Q->tail == tl) b1 = 1;
        else b1 = 0;
        if (b1!=0)
            if (nxt == 0)
                if (cas(tl->tl,nxt,nd))
                    break;
            else cas(Q->tail,tl, nxt);
    }
    cas(Q->tail, tl, nd);
}

int dequeue() {
    Node nxt, hd, tl;
    int pval;
    while(true) {
        hd = Q->head;
        tl = Q->tail;
        nxt = hd->tl;
        if (Q->head != hd) continue;
        if (hd == tl) {
            if (nxt == NULL)
                return EMPTY;
            cas(Q->tail, tl, nxt);
        } else {
            pval = next->val;
            if (cas(Q->head, hd, nxt))
                return pval;
        }
    }
}
```

Herlihy Wing Queue

```
class Node {
    int val; // -1 NAN
    Node tl;
    thread_id alloc;
}

class Queue {
    Node head;
    Node tail;
} Q;

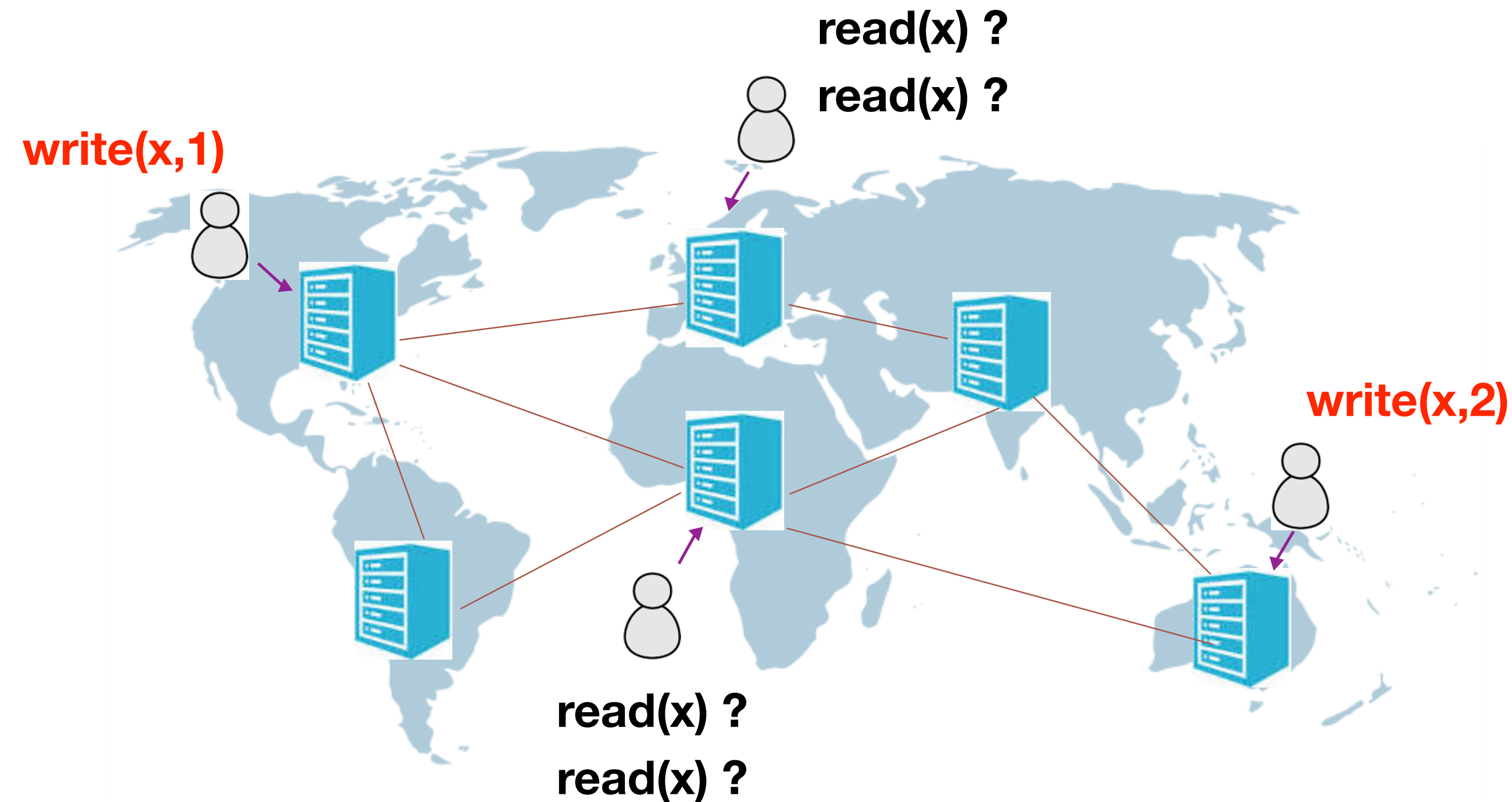
void enqueue(int value) {
    Node nd, tl;
    nd = new();
    nd->alloc = TID;
    nd->val = -1;
    nd->tl = NULL;
    atomic {
        tl = Q->tail;
        tl->tl = nd;
        Q->tail = nd;
    } // end of slot reservation;
    nd->val = value; // value written;
}

int dequeue() {
    Node curr, tail;
    int pval;
    while (true) {
        curr = Q->head;
        tail = Q->tail;
        while (curr != tail) {
            atomic { // atomic swap
                pval = curr->val;
                curr->val = -1;
                if (pval != -1)
                    return pval;
                curr = curr->tl;
            }
        }
    }
}
```

Set Implementations (TAMP slides)

Replicated objects

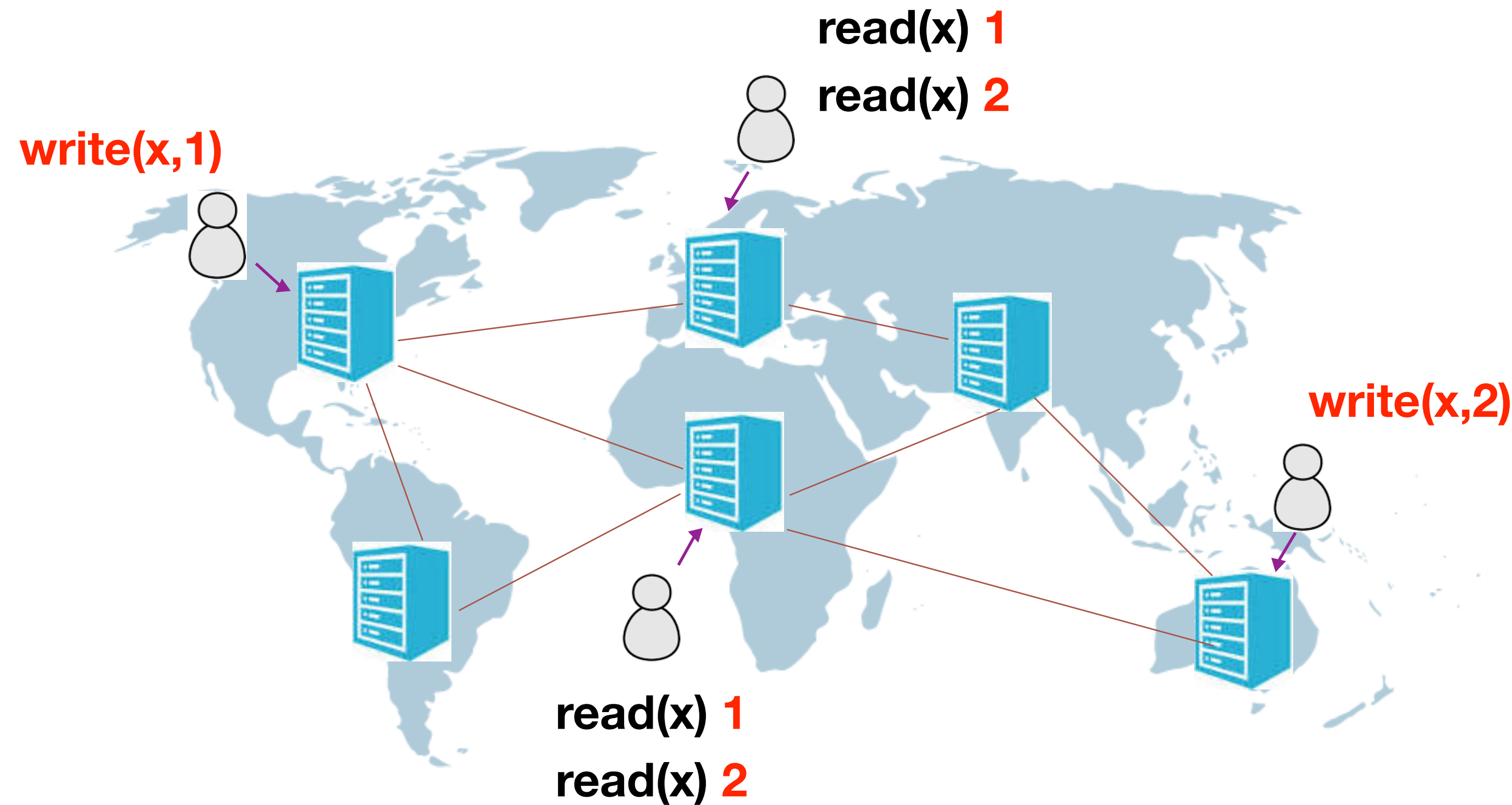
Distributed systems



Conflicting **concurrent** updates: how are they observed on different replicas ?

Adversarial environments: crashes, network partitions

Pessimistic Replication



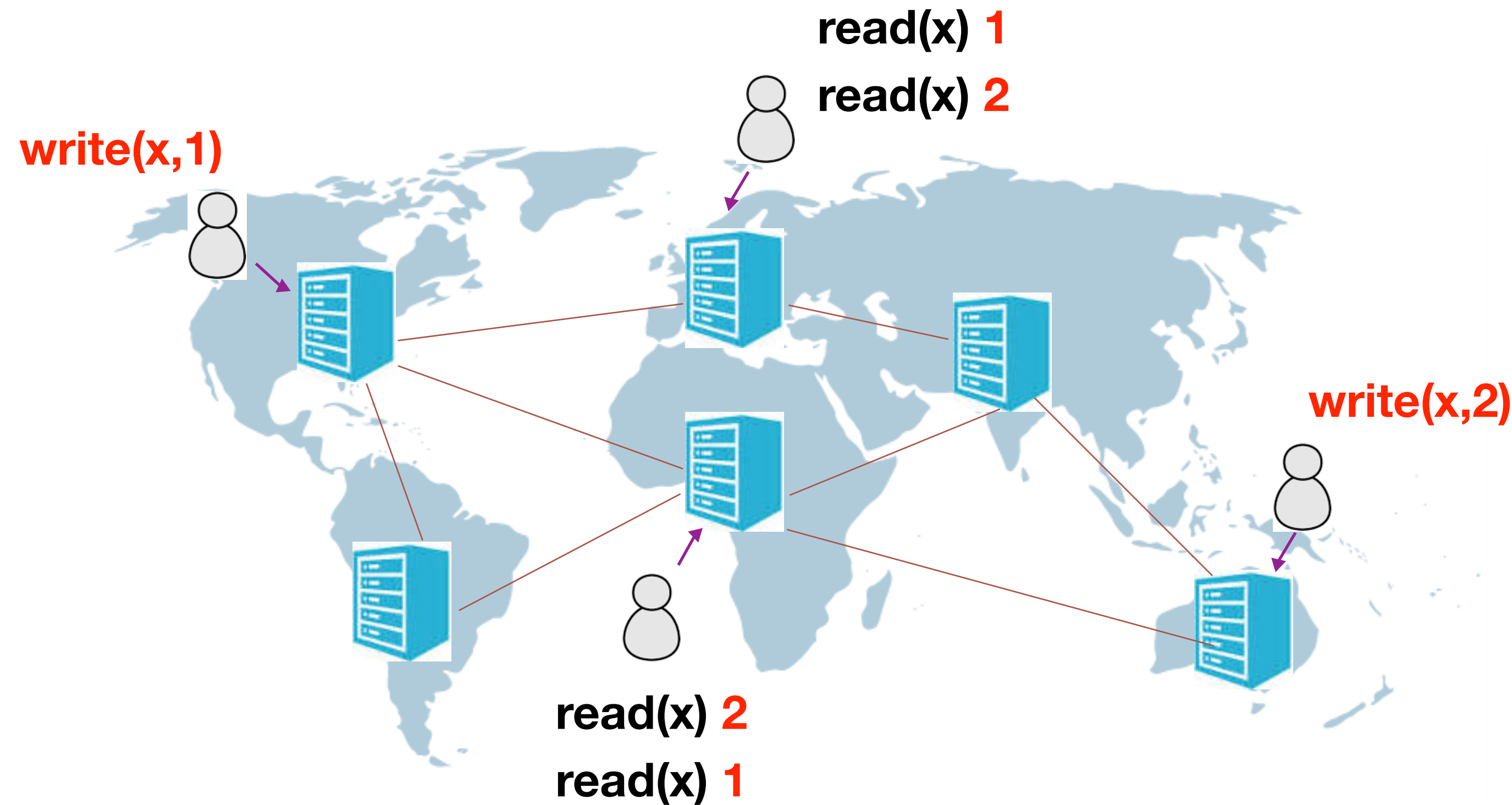
Using consensus algorithms to agree on an order between **conflicting** **concurrent** updates

✓ strong consistency

✗ availability

CAP theorem [Gilbert et al.'02]: strong cons. + availability + partition tolerance is impossible

Optimistic Replication



Each update is applied on the **local** replica and propagated **asynchronously** to other replicas

✗ strong consistency

✓ availability

Replicas may store different versions of data: **weak consistency**