Concurrency 1 Shared Memory

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Motivation Overview of the course Concurrency in Shared Memory: Effects and Issues Critical Sections and Mutual Exclusion

Motivation

Why Concurrency?

- Programs for multi-processors
- Drivers for slow devices
- Human users are concurrent
- Distributed systems with multiple clients
- Reduce latency
- Increase efficiency, but Amdahl's law

$$S = \frac{N}{b * N + (1 - b)}$$

(S = speedup, b = sequential part, N processors)

Motivation Overview of the course Concurrency in Shared Memory: Effects and Issues Critical Sections and Mutual Exclusion

Outline

- Motivation
- Overview of the course
- Concurrency in Shared Memory: Effects and Issues
- Critical Sections and Mutual Exclusion
 - Some attempts to implement a critical section
 - Some famous algorithms
 - Semaphores
 - The dining philosophers
 - Exercises

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Overview of the course

09-28	CP	Shared memory: atomicity
10-05	CP/JJL	Shared memory: verification, report on Ariane 501
10-12	CP	CCS: syntax and transitions, coinduction
10-19	CP	CCS: weak and strong bisimulations, axiomatization
10-26	CP	CCS: examples, Hennessy-Milner logic
11-02	JL	π-calculus: syntax; reduction, transitions, strong bisimulation
11-09	JL	π -calculus: sum, abstractions, data structures, bisimulation proof
11-16	JL	π -calculus: bisimulation "up to", congruence, barbed bisimulation
11-23	Review	• • • •
11-30	MT exam	
12-07	JL	π -calculus: comparison between equivalences
12-14	JJL	Expressivity of the pi-calculus and its variants
12-21	vacation	
12-28	vacation	
01-04	JJL	Distributed pi-calculus
01-11	JJL	Problems with distributed implementation
01-18	EG	True concurrency versus interleaving semantics
01-25	EG	Event structures and Petri nets
02-01	EG	Application to the semantics of CCS
02-08	EG	Comparison of the expressiveness of different models
02-15	Review	
02-22	Final exam	

- Note: we assume that the update of a variable is atomic
- Let x be a global variable. Assume that at the beginning x = 0
- Consider two simple processes

$$S = [x := 1;]$$
 and $T = [x := 2;]$

- After the execution of $S \mid\mid T$, we have $x \in \{1, 2\}$
- Conclusion:
 - Result is not unique.
 - Concurrent programs are not described by functions.



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Input-output behavior

- Let x be a global variable.
- Consider the two processes

$$S = [x := 1]$$
 and $T = [x := 0; x := x + 1]$

- S and T are the same function on memory state.
- However, $S \parallel S$ and $T \parallel S$ are different "functions" on memory state.
- A process is an atomic action, followed by a process:

$$\mathcal{P} \simeq \textit{Null} + 2^{\textit{action} \times \mathcal{P}}$$

 Part of the concurrency course aims at giving sense to this equation. ◆□▶◆□▶◆□▶◆■▶ ■ 9QC

Implicit Communication

- Let x be a global variable. Assume that at the beginning x = 0
- Consider the two processes

$$S = [x := x + 1; x := x + 1 || x := 2 * x]$$

 $T = [x := x + 1; x := x + 1 || wait (x = 1); x := 2 * x]$

- After the execution of S, we have $x \in \{2, 3, 4\}$
- After the execution of T, we have $x \in \{3, 4\}$
- T may be blocked
- Conclusion: The parallel subcomponents of a program may interact via their shared variables

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Atomicity

- Let x be a global variable. Assume that at beginning x = 0
- Consider the process $S = [x := x + 1 \mid | x := x + 1]$
- After the execution of S we have x = 2.
- However [x := x + 1] may be compiled into [A := x + 1; x := A]
- So, S may behave as [A := x + 1; x := A] || [B := x + 1; x := B],which, after execution, gives $x \in \{1, 2\}$.
- To avoid such effect, [x := x + 1] has to be atomic
- Atomic statements, aka critical sections can be implemented via mutual exclusion

The problem

- Let $P_0 = [\cdots; C_0; \cdots]$ and $P_1 = [\cdots; C_1; \cdots]$
- We intent C_0 and C_1 to be critical sections, i.e. they should not be executed simultaneously.

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• Use two boolean variables a_0 , a_1 . At beginning, $a_0 = a_1 = \text{false}$.

```
P0
...;
while a1 do;
a0 := true;
C0;
a0 := false;
...
```

```
P1
...;
while a0 do;
a1 := true;
C1;
a1 := false;
...
```

• Incorrect. It does not ensure mutual exclusion.

• Use a variable *turn*. At beginning, *turn* = 0.

```
P0
...;
while turn != 0 do;
C0;
turn := 1;
...
```

```
P1
...;
while turn != 1 do;
C1;
turn := 0;
...
```

However the method is unfair, because P₀ is privileged.
 Worse yet, until P₀ executes its critical section, P₁ is blocked.

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Use two boolean variables a₀, a₁.
 At beginning, a₀ = a₁ = false.

```
P0
...;
a0 := true;
while a1 do;
a0 := true;
C0;
a0 := false;
...
```

```
P1
...;
a1 := true;
while a0 do;
a1 := true;
C1;
a1 := false;
...
```

• We may get a deadlock. Both P_0 and P_1 may block.

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Dekker's Algorithm (early Sixties)

- The first correct mutual exclusion algorithm
- Use both the variable *turn* and the boolean variables a_0 and a_1 . At beginning, $a_0 = a_1 = \text{false}$, $turn \in \{0, 1\}$

```
P0
...;
a0 := true;
while a1 do
if turn != 0 begin
a0 := false;
while turn != 0 do;
a0 := true;
end;
C0;
turn := 1; a0 := false;
...
```

```
P1
...;
a1 := true;
while a0 do
if turn!= 1 begin
a1 := false;
while turn!= 1 do;
a1 := true;
end;
C1;
turn := 0; a1 := false;
...
```

 A variant of Dekker's algorithm for the case of n processes was presented by Dijkstra (CACM 1965).

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• To show the correctness it is convenient to add two variables, pc_0 , pc_1 , which represent a sort of program counters for P_0 and P_1 .

```
At beginning pc_0 = pc_1 = 1
```

```
P0 ...;  \{\neg a_0 \land pc_0 \neq 2\}  a0 := true ; pc0 := 2;  \{a_0 \land pc_0 = 2\}  turn := 1; pc0 := 1;  \{a_0 \land pc_0 \neq 2\}  while a1 and turn != 0 do;  \{a0 \land pc_0 \neq 2 \land (\neg a_1 \lor turn = 0 \lor pc_1 = 2)\}  C0;  a0 := false; \\ \{\neg a_0 \land pc_0 \neq 2\}  ...
```

```
P1
...;
\{\neg a_1 \land pc_1 \neq 2\}
a1 := true ; pc1 := 2;
\{a_1 \land pc_1 = 2\}
turn := 0; pc1 := 1;
\{a_1 \land pc_1 \neq 2\}
while a0 and turn != 1 do;
\{a_1 \land pc_1 \neq 2 \land (\neg a_0 \lor turn = 1 \lor pc_0 = 2)\}
C1;
a1 := false;
\{\neg a_1 \land pc_1 \neq 2\}
...
```

```
Motivation Overview of the course Concurrency in Shared Memory: Effects and Issues Critical Sections and Mutual Exclusion 0000 ● 0000000 Some famous algorithms

Peterson's Algorithm (IPL 1981)
```

- The simplest and most compact mutual exclusion algorithm in literature
- Use both the variable *turn* and the boolean variables a_0 and a_1 . At beginning, $a_0 = a_1 = \text{false}$, $turn \in \{0, 1\}$

```
P0
...;
a0 := true;
turn := 1;
while a1 and turn != 0 do;
C0;
a0 := false;
...
```

```
P1
...;
a1 := true;
turn := 0;
while a0 and turn != 1 do;
C1;
a1 := false;
...
```

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Correctness of Peterson's Algorithm (2/2)

We can prove the correctness by contradiction. If both programs were in their critical section, then the formulas $\{a0 \land pc_0 \neq 2 \land (\neg a_1 \lor turn = 0 \lor pc_1 = 2)\}$ and $\{a1 \land pc_1 \neq 2 \land (\neg a_0 \lor turn = 1 \lor pc_0 = 2)\}$ should be true at the same time, but:

```
a_0 \wedge pc_0 \neq 2 \wedge (\neg a_1 \vee turn = 0 \vee pc_1 = 2)
\wedge a_1 \wedge pc_1 \neq 2 \wedge (\neg a_0 \vee turn = 1 \vee pc_0 = 2)
\equiv turn = 0 \wedge turn = 1
```

Contradiction!

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Some famous algorithms

Synchronization in Concurrent/Distributed algorithms

- Dekker's algorithm (early sixties). Quite complex.
- Peterson is simpler and can be generalized to N processes more easily
- Both algorithms by Dekker and Peterson use busy waiting
- Fairness relies on fair scheduling
- Many other algorithms for mutual exclusion have been proposed in literature. Particularly by Lamport: barber, baker, . . .
- Proofs ? By model checking ? With assertions ? In temporal logic (eg Lamport's TLA)?

Need for higher constructs in concurrent programming.

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The dining philosophers

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The dining philosophers

- Problem proposed by Dijkstra for testing concurrency primitives
- 5 philosophers spend their time around a table thinking or eating spaghetti. In order to eat, each philosopher needs two forks.
 However, there are only 5 forks on the table.



- Desiderata
 - if one philosopher gets hungry, some philosopher will eventually eat (progress)
 - if one philosopher gets hungry, he will eventually eat (starvation-freedom)

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Semaphores

Semaphores

A generalized semaphore s is an integer variable with 2 operations

- acquire(s): If s > 0 then s := s 1, otherwise suspend on s. (atomically)
- release(s): If some process is suspended on s, wake it up, otherwise s := s + 1. (atomically)

```
Now mutual exclusion is easy: At beginning, s = 1. Then
```

```
[\cdots; acquire(s); C_0; release(s); \cdots] \mid\mid [\cdots; acquire(s); C_1; release(s); \cdots]
```

Question Consider another definition for semaphore: acquire(s): If s > 0 then s := s - 1. Otherwise restart. release(s): Do s := s + 1. Are these definitions equivalent?

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Exercises

Exercises

- (Difficult) Generalize Dekker's algorithm to the case of n processes
- Generalize Petersons's algorithm to the case of n processes
- Implement the Semaphore in Java
- Write a program for the dining philosophers which ensure progress
- Discuss how to modify the solution so to ensure starvation-freedom
- Problem: A certain file is shared by some Reader and some Writer processes: we want that only one writer can write on the file at a time, while the readers are allowed to do it concurrently. Write the code for the Reader and the Writer.