

Foundations of Privacy

Lecture 2

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Compositionality

Differential privacy is **compositional**:

Definition Let \mathcal{K}_1 and \mathcal{K}_2 be two mechanisms on \mathcal{X} . Their composition $\mathcal{K}_1 \times \mathcal{K}_2$ is defined as follows:

if $\mathcal{K}_1(x)$ reports z_1 and $\mathcal{K}_2(x)$ reports z_2 , then $(\mathcal{K}_1 \times \mathcal{K}_2)(x)$ reports (z_1, z_2)

Theorem (Compositionality) If \mathcal{K}_1 and \mathcal{K}_2 are respectively ε_1 and ε_2 -differentially-private, then their composition $\mathcal{K}_1 \times \mathcal{K}_2$ is $(\varepsilon_1 + \varepsilon_2)$ -differentially private.

Proof: Let x and x' be two adjacent DB. Then:

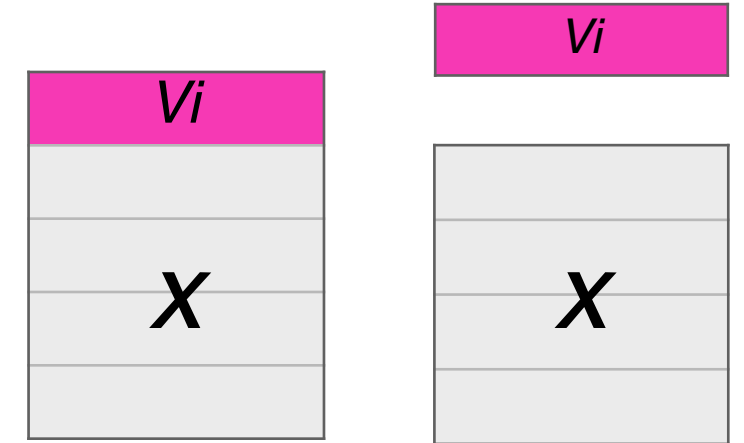
$$\begin{aligned} p((\mathcal{K}_1 \times \mathcal{K}_2)(x) = (z_1, z_2)) &= p(\mathcal{K}_1(x) = z_1) \ p(\mathcal{K}_2(x) = z_2) \\ &\leq e^{\varepsilon_1} p(\mathcal{K}_1(x') = z_1) \ e^{\varepsilon_2} p(\mathcal{K}_2(x') = z_2) \\ &= e^{\varepsilon_1 + \varepsilon_2} p((\mathcal{K}_1 \times \mathcal{K}_2)(x') = (z_1, z_2)) \end{aligned}$$

Bayesian interpretation of DP

Consider an individual i whose value is represented by the random variable V_i with the same distribution as V

The individual i may or may not be present in the DB

The rest of the elements of the DB (or the whole DB) is represented by the random variable X



Theorem \mathcal{K} is ε -differentially-private iff $\forall v \in \mathcal{V}, \forall x \in \mathcal{X}, \forall z \in \mathcal{Z}$

$$e^{-\varepsilon} p(V_i = v | X = x) \leq p(V_i = v | X = x, Z = z) \leq e^{\varepsilon} p(V_i = v | X = x)$$

where Z represents the reported answer of \mathcal{K} .

Proof

Only if) By the Bayes law, we have

$$p(V_i = v | X = x, Z = z) = \frac{p(Z = z | X = x, V_i = v) p(V_i = v | X = x)}{p(Z = z | X = x)}$$

And now, just observe that, since \mathcal{K} is ε -DP, we have

$$e^{-\varepsilon} p(Z = z | X = x) \leq p(Z = z | X = x, V_i = v) \leq e^{\varepsilon} p(Z = z | X = x)$$

Note that the above inequalities holds independently from whether the individual i is in the DB or not.

If) Analogous, just reverse the reasoning.

Strong adversary

In the Bayesian interpretation of DP, the conditioning on $X=x$ represents the fact that the adversary knows the rest of the DB. This scenario is called *strong adversary hypothesis* (SAH).

Is this hypothesis necessary for the boundaries expressed by the Bayesian interpretation of DP ?

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Yes. But we can have a similar result without this hypothesis, only with weaker bounds.

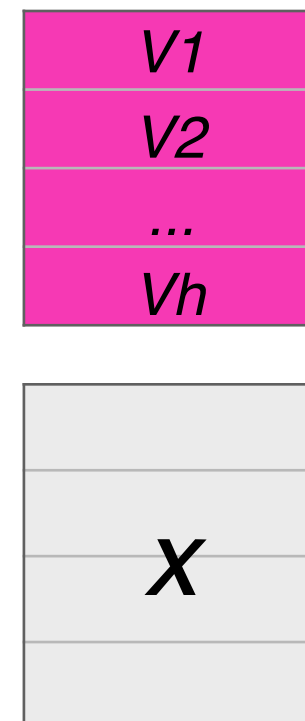
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Consider individuals $1, 2, \dots, h$ whose value is represented by the RV $\mathbf{V} = V_1 V_2 \dots V_h$



Bayesian interpretations of DP w/o the SAH

Theorem The following statements are equivalent

1. \mathcal{K} is ε -DP
2. $e^{-h\varepsilon} p(\mathbf{V} = \mathbf{v} | X = x) \leq p(\mathbf{V} = \mathbf{v} | X = x, Z = z) \leq e^{h\varepsilon} p(\mathbf{V} = \mathbf{v} | X = x)$
3. $e^{-h\varepsilon} p(V_i = v | X = x) \leq p(V_i = v | X = x, Z = z) \leq e^{h\varepsilon} p(V_i = v | X = x)$

Furthermore, we can drop the conditioning on $X = x$ if we know that there is no correlation between the V_i 's and X (given the result of \mathcal{K} , i.e., Z).

Proof

- (1) \leftrightarrow (2)) This part can be proved in a way analogous to the previous theorem
- (2) \leftrightarrow (3)) Observe that (2) holds for every tuple of values of \mathbf{V} and then marginalize w.r.t. V_i
- (3) \leftrightarrow (1)) For $h = 1$, (3) coincides with (1).

Note: The same results hold if we replace the value of V_i with the presence/absence of i in the DB.

Differential Privacy: continuous case

We now consider the **continuous** case. Namely, $\mathcal{K}(x)$ determines a probability density function on \mathcal{Z} . The only thing that change is that we consider measurable subsets \mathcal{S} of \mathcal{Z} rather than single z .

Definition (Differential Privacy) \mathcal{K} is ε -differentially-private iff for every pair of databases $x_1, x_2 \in \mathcal{X}$ s.t. $x_1 \sim x_2$ and for every measurable $\mathcal{S} \subseteq \mathcal{Z}$ we have

$$p(\mathcal{K}(x_1) \in \mathcal{S}) \leq e^\varepsilon p(\mathcal{K}(x_2) \in \mathcal{S})$$

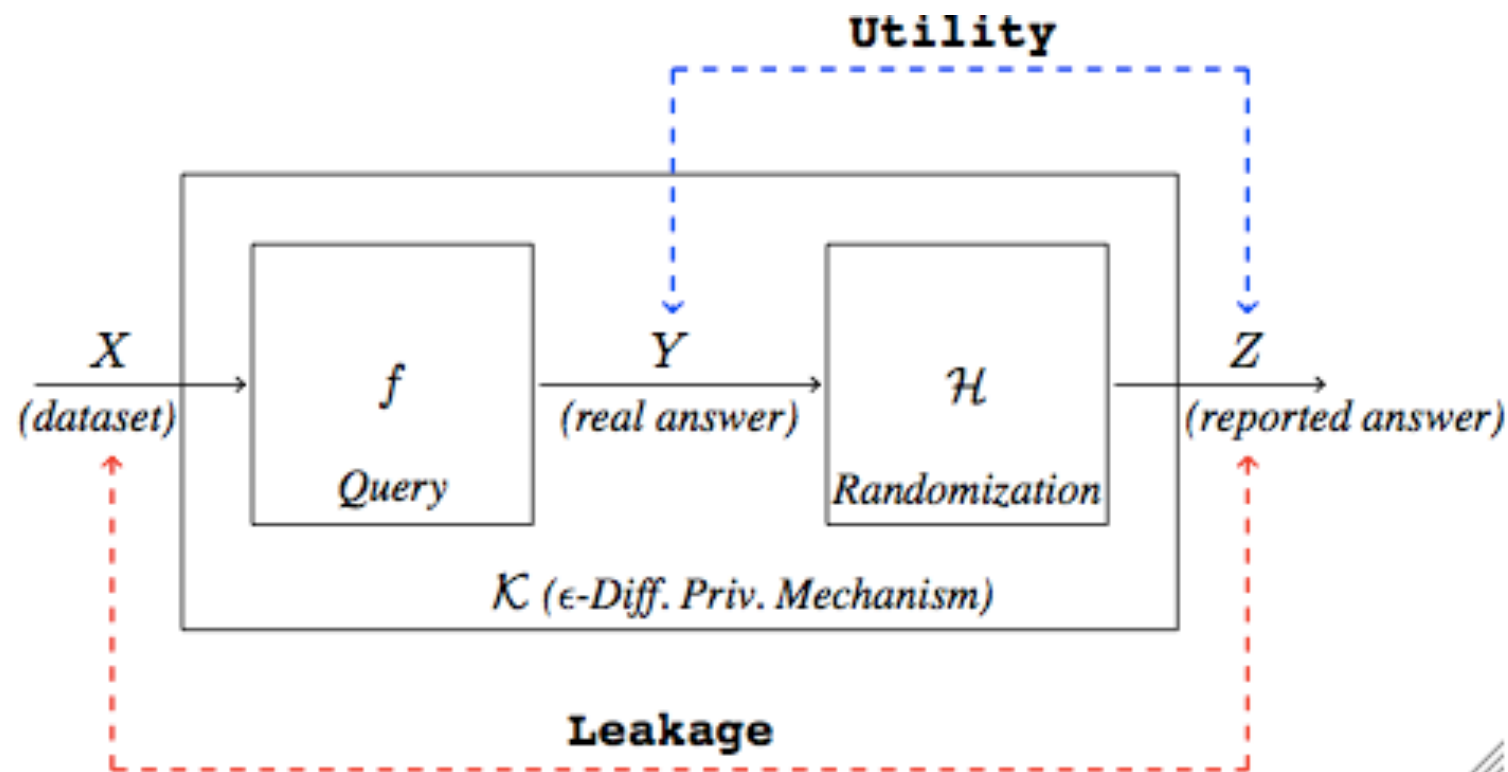
where $p(\mathcal{K}(x) \in \mathcal{S})$ represents the probability that \mathcal{K} applied to x report an answer in \mathcal{S}

Note: $p(\mathcal{K}(x) \in \mathcal{S})$ represents a conditional probability. We will write it as $p(Z \in \mathcal{S} | X = x)$ when we need to make this fact more explicit.

Some "real" DP mechanisms

Oblivious Mechanisms

- Given $f: \mathcal{X} \rightarrow \mathcal{Y}$ and $\mathcal{K}: \mathcal{X} \rightarrow \mathcal{Z}$, we say that \mathcal{K} is oblivious if it depends only on \mathcal{Y} (not on \mathcal{X})
- If \mathcal{K} is oblivious, it can be seen as the composition of f and a randomized mechanism \mathcal{H} (noise) defined on the exact answers $\mathcal{K} = \mathcal{H} \circ f$



- Privacy concerns the information flow between the databases and the reported answers, while utility concerns the information flow between the correct answer and the reported answer

Oblivious mechanisms for the continuous case

We start by considering the case of queries
which give real numbers as answers

A typical oblivious DP mechanism: Laplace noise

- Randomized mechanism for a query $f: \mathcal{X} \rightarrow \mathcal{Y}$.
- A typical randomized method: **add Laplace noise to $y=f(x)$** .
Namely, report z with a probability density function defined as:

$$dP_y(z) = c e^{-\frac{|z-y|}{\Delta f} \varepsilon}$$

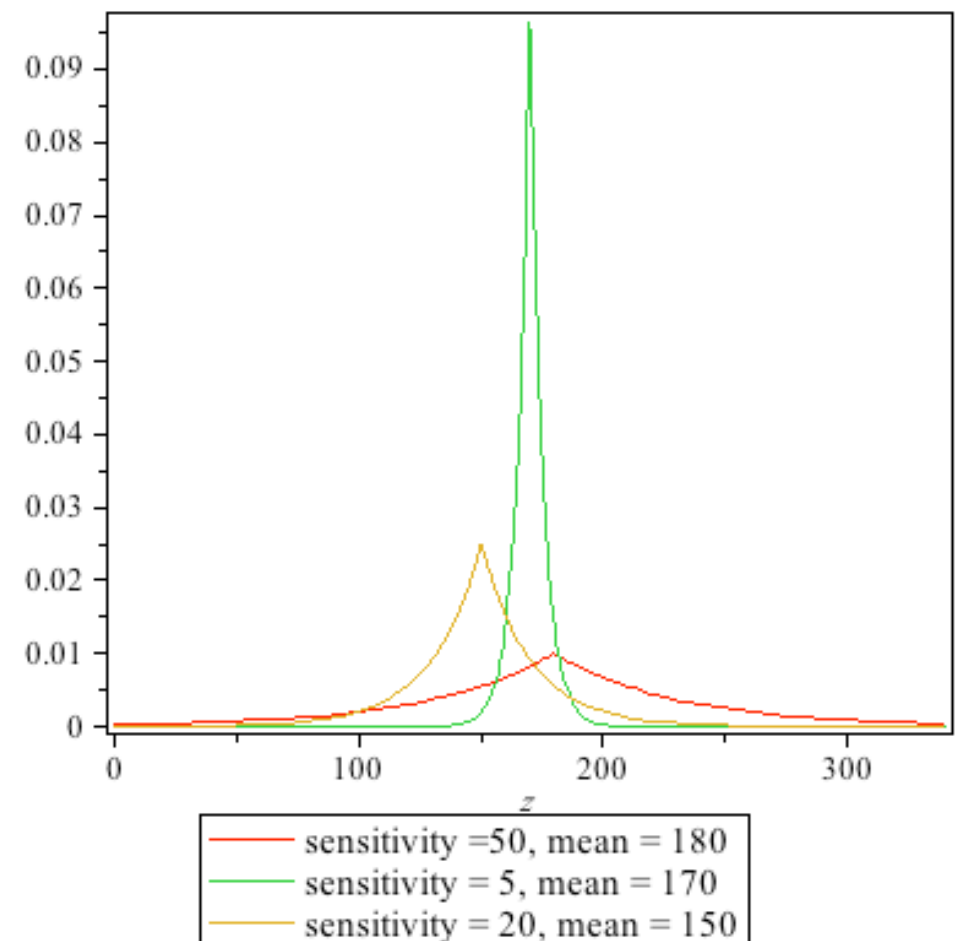
where Δf is the *sensitivity* of f :

$$\Delta f = \max_{x \sim x' \in \mathcal{X}} |f(x) - f(x')|$$

($x \sim x'$ means x and x' are adjacent,
i.e., they differ only for one record)

and c is a normalization factor:

$$c = \frac{\varepsilon}{2 \Delta f}$$



Example of Laplace Mechanism

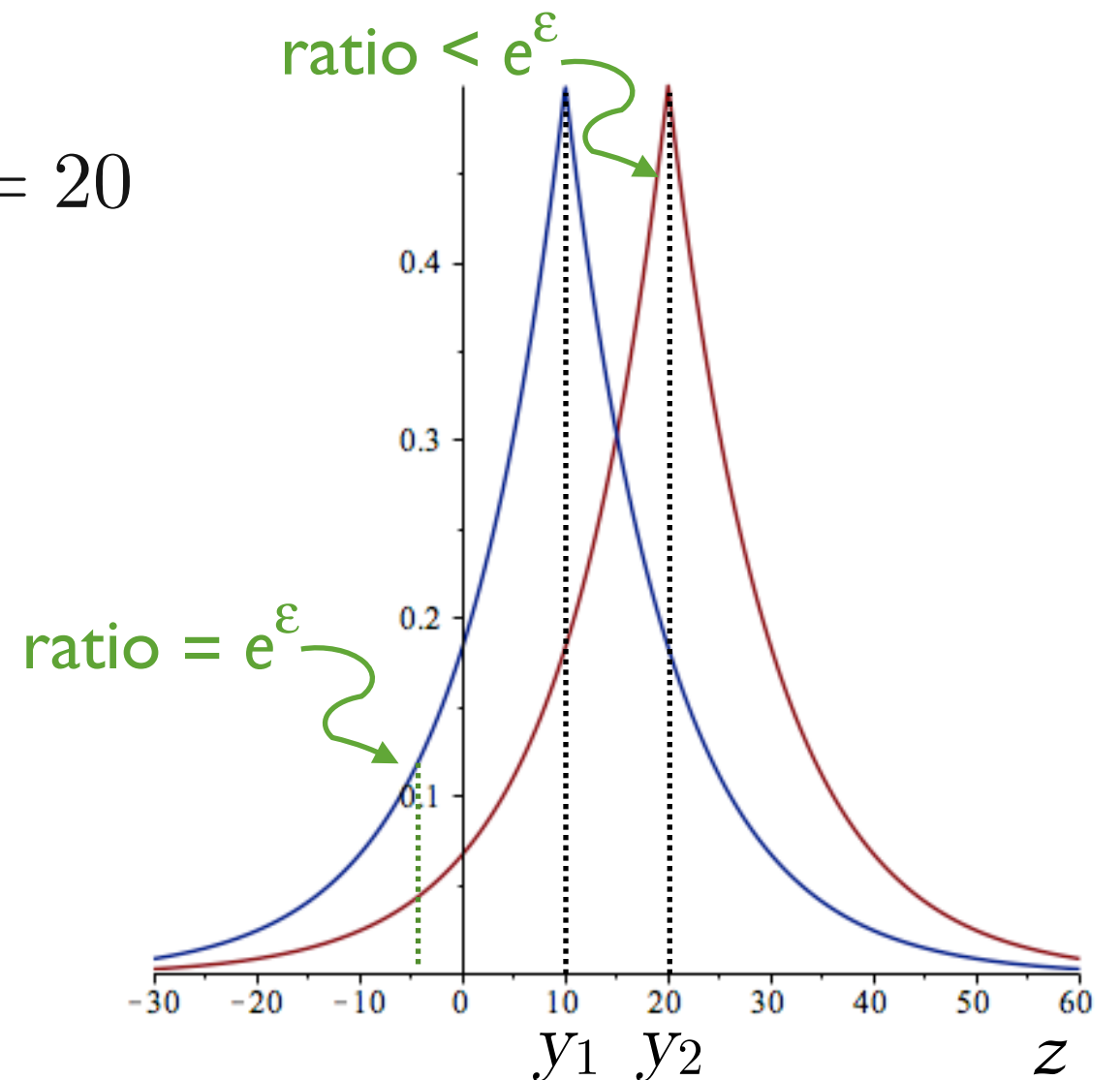
- $\varepsilon = 1$
- $\Delta_f = |f(x_1) - f(x_2)| = 10$
- $y_1 = f(x_1) = 10, y_2 = f(x_2) = 20$

Then:

- $dP_{y_1} = \frac{1}{2 \cdot 10} e^{\frac{|z-10|}{10}}$
- $dP_{y_2} = \frac{1}{2 \cdot 10} e^{\frac{|z-20|}{10}}$

The ratio between these distribution is

- $= e^\varepsilon$ outside the interval $[y_1, y_2]$
- $\leq e^\varepsilon$ inside the interval $[y_1, y_2]$



The Laplace mechanism is DP

Remember that the probability density function of the Laplace mechanism is:

$$p(Z = z | X = x) = dP_{f(x)}(z) = c e^{-\frac{|z - f(x)|}{\Delta f} \varepsilon}$$

where $c = \frac{\varepsilon}{2 \Delta f}$

Theorem: The Laplace mechanism is ε -differentially private

Proof: Let $x_1 \sim x_2$ and $y_1 = f(x_1), y_2 = f(x_2)$ We have:

$$\begin{aligned} \frac{p(Z=z | X=x_1)}{p(Z=z | X=x_2)} &= \frac{c e^{-\frac{|z - f(x_1)|}{\Delta f} \varepsilon}}{c e^{-\frac{|z - f(x_2)|}{\Delta f} \varepsilon}} \\ &= e^{\frac{|z - y_2|}{\Delta f} \varepsilon - \frac{|z - y_1|}{\Delta f} \varepsilon} \\ &\leq e^{\frac{|y_1 - y_2|}{\Delta f} \varepsilon} \\ &\leq e^{\varepsilon} \end{aligned}$$

Sensitivity of the query

- The sensitivity of the query and the level of privacy ϵ determine the amount of noise of the mechanism:
 - higher sensitivity \Rightarrow more noise
 - smaller $\epsilon \Rightarrow$ more privacy, more noise
- Intuitively, the more the mechanism is noisy, the less useful it is (the reported answer is less precise)
- To reduce the sensitivity, for some queries it may help to assume that the database contains a minimum number of individuals
- **Example:** consider the query “What is the average age of the people in the DB?”. Assume that the age can vary from 0 to 120. Check the sensitivity in the following two cases:
 - the DB contains at least 100 records, or
 - there is no restriction.

Exercises

1. Consider now a query which gives answers on the plane ($\mathcal{Y} = \mathbb{R} \times \mathbb{R}$). How can we define a DP mechanism for this query?
2. How can we generalize to a set \mathcal{Y} with generic distance d ?

Gaussian noise

The formula for gaussian noise is

$$c e^{-\frac{(y-z)^2}{\sigma^2}} \epsilon$$

where c is a normalization factor and σ is a suitable constant.

Question: does an oblivious mechanism based on this noise function satisfy ϵ -differential privacy, for some suitable value of σ ?

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Question: does an oblivious mechanism based on this noise function satisfy ϵ -differential privacy, for some suitable value of σ ?

A gaussian noise does not satisfy differential privacy.

However it satisfies a more relaxed form of privacy called (ϵ, δ) -DP

(ε, δ) -differential privacy

Definition A mechanism \mathcal{K} is (ε, δ) -DP if for every pair of databases x, x' and every reported answer y

$$p(\mathcal{K}(x) = y) \leq e^\varepsilon p(\mathcal{K}(x') = y) + \delta$$

Exercise : Compute the δ and σ so that the Gaussian noise

$$p(z, y) = c e^{-\frac{(y-z)^2}{\sigma^2}}$$

is a (ε, δ) -DP mechanism.

Notes:

- (ε, δ) -DP is important because it is practically impossible to obtain pure ε -DP, due to the precision of the machine.
- The Gaussian mechanism is important because we can get it for free by sampling the DB.

Oblivious mechanisms for the discrete case

We start by considering the case of queries
which give integer numbers as answers

The geometric mechanism

- The Laplacian noise is typically used in the case that \mathcal{Y} (the set of true answers of the query) is a **continuous** numerical set, like the Reals.
- If \mathcal{Y} is a **discrete** numerical set, like the Integers, then the typical mechanism used in this case is the **geometric mechanism**, which is a sort of discrete Laplacian.
- In the geometric mechanism, the probability distribution of the noise is:

$$p(z|y) = c e^{-\frac{|z-y|}{\Delta f} \varepsilon}$$

- In this expression, c is a normalization factor, defined so to obtain a probability distribution,
- Δf is the sensitivity of query f

Normalization constant in a geometric mechanism

- In the geometric mechanism, the probability distribution of the noise is:

$$p(z|y) = c e^{-\frac{|z-y|}{\Delta f} \varepsilon}$$

As usual, we can compute c (the normalization factor) by imposing that the sum of the probability on all Z is 1. It turns out that

$$c = \frac{1-\alpha}{1+\alpha} \quad \text{where} \quad \alpha = e^{-\frac{\varepsilon}{\Delta f}}$$

$$\text{hence} \quad p(z|y) = \frac{1-\alpha}{1+\alpha} \alpha^{|z-y|}$$

- **Exercises:** Compute the geometric mechanism for the following queries:
 - “How many diabetic people weight more than 100 kilos ?”
 - “What is the max weight (in kilos) of a diabetic person ?”

Truncated geometric

Exercise: how can we modify the definition of a geometric mechanism so to obtain a DP mechanism on an integer interval, for instance $[0, n]$?

Exponential mechanism

Exercise: Suppose now that our domain is a generic set \mathcal{Y} , not numeric. How can we define a DP mechanism?