Simulation and bisimulation

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Concurrency 4

CCS - Simulation and bisimulation. Coinduction.

Catuscia Palamidessi INRIA Futurs and LIX - Ecole Polytechnique

The other lecturers for this course:

Jean-Jacques Lévy (INRIA Rocquencourt) James Leifer (INRIA Rocquencourt) Eric Goubault (CEA)

http://pauillac.inria.fr/~leifer/teaching/mpri-concurrency-2005/

Simulation and bisimulation

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Exercises

Announcement

The class of Wednesday 26 October will follow the usual schedule (16h15 - 19h15).

Simulation and bisimulation

Outline

- Solution to exercises from previous time
- 2 Modern definition of CCS (1999)
 - Syntax
 - Labeled transition System
- Simulation and bisimulation
 - Simulation
 - Bisimulation
 - Proof methods
 - Examples and exercises
 - Alternative characterization of bisimulation
 - Bisimulation in CCS is a congruence

4 Exercises

Simulation and bisimulation

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The semaphore

Define in CCS a semaphore with initial value n

First Solution

 $\operatorname{rec}_{S_n} \operatorname{down.rec}_{S_{n-1}}(up.S_n + \operatorname{down.rec}_{S_{n-2}}(\dots(up.S_2 + \operatorname{down.rec}_{S_0}up.S_1)\dots))$

Second solution

- Let S = rec_X down.up.X
- Then $S_n = S | S | \dots | S$ *n* times

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- Let S = rec_X down.up.X
- Then $S_n = S \mid S \mid \ldots \mid S \mid n$ times

Simulation and bisimulation

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Exercises

Maximal trace equivalence is not a congruence

Consider the following processes

- P = a.(b.0 + c.0)
- Q = a.b.0 + a.c.0
- $R = \bar{a}.\bar{b}.\bar{d}.0$

P and *Q* have the same maximal traces, but $(\nu a)(\nu b)(\nu c)(P | R)$ and $(\nu a)(\nu b)(\nu c)(Q | R)$ have different maximal traces.

Simulation and bisimulation

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Exercises

Maximal trace equivalence is not a congruence

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Simulation and bisimulation

Syntax

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Exercises

Modern definition of CCS (1999) $\circ \bullet \circ \circ$

Simulation and bisimulation

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Exercises

Syntax

Syntax of "modern" CCS

- (channel, port) names: *a*, *b*, *c*, . . .
- co-names: $\bar{a}, \bar{b}, \bar{c}, \dots$ Note: $\bar{\bar{a}} = a$
- silent action: au
- actions, prefixes: $\mu ::= a \mid \bar{a} \mid \tau$
- processes: P, Q ::= 0 inaction | $\mu . P$ prefix | $P \mid Q$ parallel | P + Q (external) choice | $(\nu a)P$ restriction | $K(\vec{a})$ process name with parameters
- Process definitions: $D := K(\vec{x})^{\frac{def}{def}} F$

where P may contain only the \vec{x} as channel names

Modern definition of CCS (1999) $\circ \bullet \circ \circ$

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- co-names: $\bar{a}, \bar{b}, \bar{c}, \dots$ Note: $\bar{\bar{a}} = a$
- silent action: τ
- actions, prefixes: $\mu ::= a \mid \bar{a} \mid \tau$
- processes: P, Q ::= 0 inaction $| \mu.P \text{ prefix}$ | P | Q parallel | P+Q (external) choice $| (\nu a)P \text{ restriction}$ $| K(\vec{a}) \text{ process name with parameters}$

Process definitions:

D ::= $K(\vec{x}) \stackrel{\text{def}}{=} P$ where P may contain only the \vec{x} as channel names

Simulation and bisimulation

Exercises

Labeled transition System

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Exercises

Simulation and bisimulation

Exercises

Labeled transition System

Labeled transition system for "modern" CCS

We assume a given set of definitions D

 $\begin{bmatrix} \operatorname{Act} \end{bmatrix} \frac{p \xrightarrow{\mu} P'}{\mu \cdot P \xrightarrow{\mu} P} \qquad \begin{bmatrix} \operatorname{Res} \end{bmatrix} \frac{P \xrightarrow{\mu} P'}{(\nu a) P \xrightarrow{\mu} (\nu a) P'}$ $\begin{bmatrix} \operatorname{Sum1} \end{bmatrix} \frac{P \xrightarrow{\mu} P'}{P + Q \xrightarrow{\mu} P'} \qquad \begin{bmatrix} \operatorname{Sum2} \end{bmatrix} \frac{Q \xrightarrow{\mu} Q'}{P + Q \xrightarrow{\mu} Q'}$ $\begin{bmatrix} \operatorname{Par1} \end{bmatrix} \frac{P \xrightarrow{\mu} P'}{P|Q \xrightarrow{\mu} P'|Q} \qquad \begin{bmatrix} \operatorname{Par2} \end{bmatrix} \frac{Q \xrightarrow{\mu} Q'}{P|Q \xrightarrow{\mu} P|Q'}$ $\begin{bmatrix} \operatorname{Com} \end{bmatrix} \frac{P \xrightarrow{a} P' Q \xrightarrow{\overline{a}} Q'}{P|Q \xrightarrow{\tau} P'|Q'} \qquad \begin{bmatrix} \operatorname{Rec} \end{bmatrix} \frac{P[\vec{a}/\vec{x}] \xrightarrow{\mu} P' K(\vec{x}) \xrightarrow{def} P \in D}{K(\vec{a}) \xrightarrow{\mu} P'}$

The reason for moving to "modern" CCS was to get static scope (thanks to the presence of the parameters). The old version had dynamic scope.

Simulation and bisimulation

Simulation

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Simulation

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• Definition We say that a relation R on processes is a simulation if

- Note that this property does not uniquely defines *R*. There may be several relations that satisfy it.
- Define $\leq = \bigcup \{ \mathcal{R} \mid \mathcal{R} \text{ is a simulation} \}$
- Theorem
 subscript is a bisimulation (Proof: Exercise)
- $P \leq Q$ intuitively means that Q can do everything that P can do. Q simulates P.

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• Definition We say that a relation R on processes is a simulation if

 $P \mathcal{R} Q$ implies that if $P \xrightarrow{\mu} P'$ then $\exists Q' \text{ s.t. } Q \xrightarrow{\mu} Q'$ and $P' \mathcal{R} Q'$

- Note that this property does not uniquely defines *R*. There may be several relations that satisfy it.
- Define $\leq = \bigcup \{ \mathcal{R} \mid \mathcal{R} \text{ is a simulation} \}$
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Bisimulation

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- Again, this property does not uniquely defines *R*. There may be several relations that satisfy it.
- Define $\sim = \bigcup \{ \mathcal{R} \mid \mathcal{R} \text{ is a bisimulation} \}$
- **Theorem** ~ is a bisimulation (Proof: Exercise)
- P ~ Q intuitively means that Q can do everything that P can do, and vice versa, at every step of the computation. Q is bisimilar to P.

Simulation and bisimulation

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```

- Again, this property does not uniquely defines \mathcal{R} . There may be several relations that satisfy it.
- Define $\sim = \bigcup \{ \mathcal{R} \mid \mathcal{R} \text{ is a bisimulation} \}$
- Theorem ~ is a bisimulation (Proof: Exercise)
- P ~ Q intuitively means that Q can do everything that P can do, and vice versa, at every step of the computation. Q is bisimilar to P.

Simulation and bisimulation

Proof methods

Outline

- Solution to exercises from previous time
- 2 Modern definition of CCS (1999)
 - Syntax
 - Labeled transition System
- Simulation and bisimulation
 - Simulation
 - Bisimulation

Proof methods

- Examples and exercises
- Alternative characterization of bisimulation
- Bisimulation in CCS is a congruence

4 Exercises

Simulation and bisimulation

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Proof methods

Proof methods

- Simulation and bisimulation are coinductive definitions.
- In order to prove that P ≤ Q it is sufficient to find a simulation R such that P R Q
- Similarly, in order to prove that P ~ Q it is sufficient to find a bisimulation R such that P R Q

Simulation and bisimulation

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Simulation and bisimulation

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Examples and exercises

Outline

- Solution to exercises from previous time
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 - Simulation
 - Bisimulation
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Exercises

Simulation and bisimulation

Examples and exercises

Examples and exercises

Consider the following processes
P = a.(b.0 + c.0)
Q = a.b.0 + a.c.0
Prove that Q ≤ P but P ≤ Q and Q ≠ P

- Assume that $Q \leq P$ and $P \leq Q$ (for two generic *P* and *Q*). Does it follow that $P \sim Q$?
- Consider the following processes
 R = a.(b.0 + b.0)
 S = a.b.0 + a.b.0
 Prove that Q ~ P
- Consider the two definitions of semaphore given at the beginning of this lecture. Prove that they are bisimilar.
- Consider the processes H(a) and K(a) defined by $H(x) \stackrel{\text{def}}{=} x.H(x)$ and $K(x) \stackrel{\text{def}}{=} x.K(x) | x.K(x)$. Are they bisimilar?
- What is the smallest bisimulation?

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Simulation and bisimulation

Examples and exercises

Examples and exercises

Consider the following processes

• P = a.(b.0 + c.0)

• Q = a.b.0 + a.c.0Prove that $Q \leq P$ but $P \leq Q$ and $Q \neq P$

- Assume that Q
 P and P
 Q (for two generic P and Q). Does it follow that P
 Q?
- Consider the following processes
 R = a.(b.0 + b.0)
 S = a.b.0 + a.b.0
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Simulation and bisimulation

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Examples and exercises

Examples and exercises

- Consider the following processes
 - P = a.(b.0 + c.0)
 - Q = a.b.0 + a.c.0

Prove that $Q \leq P$ but $P \not\leq Q$ and $Q \not\sim P$

Assume that Q
 P and P
 Q (for two generic P and Q). Does it follow that P
 Q?

```
Consider the following processes
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Examples and exercises

Examples and exercises

- Consider the following processes
 - P = a.(b.0 + c.0)

• Q = a.b.0 + a.c.0

Prove that $Q \lesssim P$ but $P \not\lesssim Q$ and $Q \not\sim P$

- Consider the following processes
 - R = a.(b.0 + b.0)
 - S = a.b.0 + a.b.0
 - Prove that $Q \sim P$
- Consider the two definitions of semaphore given at the beginning of this lecture. Prove that they are bisimilar.
- Consider the processes H(a) and K(a) defined by $H(x) \stackrel{\text{def}}{=} x.H(x)$ and $K(x) \stackrel{\text{def}}{=} x.K(x) | x.K(x)$. Are they bisimilar?
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Simulation and bisimulation

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Simulation and bisimulation

Examples and exercises

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Simulation and bisimulation

Examples and exercises

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Simulation and bisimulation

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Alternative characterization of bisimulation

Outline

- Solution to exercises from previous time
- 2 Modern definition of CCS (1999)
 - Syntax
 - Labeled transition System
- Simulation and bisimulation
 - Simulation
 - Bisimulation
 - Proof methods
 - Examples and exercises
 - Alternative characterization of bisimulation
 - Bisimulation in CCS is a congruence

Exercises

Modern definition of CCS (1999)

Simulation and bisimulation

Exercises

Alternative characterization of bisimulation

Bisimulation as greatest fixpoint

- Consider the set of relations on processes (that is, on the powerset of the cartesian product on processes) ordered by set inclusion. Obviously, this is a complete lattice.
- **Definition** Let \mathcal{F} be a function on relation defined in the following way:

$$P \mathcal{F}(\mathcal{R}) Q \quad \text{iff} \quad \text{if } P \xrightarrow{\mu} P' \text{ then } \exists Q' \text{ s.t. } Q \xrightarrow{\mu} Q' \text{ and } P' \mathcal{R} Q'$$
$$if Q \xrightarrow{\mu} Q' \text{ then } \exists P' \text{ s.t. } P \xrightarrow{\mu} P' \text{ and } P' \mathcal{R} Q'$$

- Lemma \mathcal{F} is monotonic
- Theorem (Knaster-Tarski) F has (unique) least and greatest fixpoints, and

$$lfp(\mathcal{F}) = \bigcap \{ \mathcal{R} \mid \mathcal{F}(\mathcal{R}) \subseteq \mathcal{R} \}$$
$$gfp(\mathcal{F}) = \bigcup \{ \mathcal{R} \mid \mathcal{R} \subseteq \mathcal{F}(\mathcal{R}) \}$$

- Corollary $\sim = gfp(\mathcal{F})$
- A similar characterization, of course, holds for \leq as well.

Modern definition of CCS (1999) 0000

Simulation and bisimulation

Exercises

Alternative characterization of bisimulation

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Modern definition of CCS (1999) 0000

Simulation and bisimulation

Exercises

Alternative characterization of bisimulation

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Modern definition of CCS (1999) 0000

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Exercises

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Modern definition of CCS (1999) 0000

Simulation and bisimulation

Exercises

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Modern definition of CCS (1999) 0000

Simulation and bisimulation

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Simulation and bisimulation

Bisimulation in CCS is a congruence

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4) Exercises

Modern definition of CCS (1999)

Simulation and bisimulation

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Exercises

Bisimulation in CCS is a congruence

Bisimulation in CCS is a congruence

- **Definition** A relation R on a language is called *congruence* if
 - ${\cal R}$ is an equivalence relation (i.e. it is reflexive, symmetric, and transitive), and
 - *R* is preserved by all the operators of the language, namely if *P R Q* then op(*P*, *R*) *R* op(*P*, *R*)
- Theorem \sim is a congruence relation

Modern definition of CCS (1999)

Simulation and bisimulation

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Exercises

Bisimulation in CCS is a congruence

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- **Theorem** \sim is a congruence relation

Simulation and bisimulation

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Exercises

- Complete the proof that bisimulation in CCS is a congruence
- Prove that if P \le Q then the traces of P are contained in the traces of Q
- Prove that if $P \sim Q$ then $P \lesssim Q$ and $Q \lesssim P$
- Prove that
 - $P + 0 \sim P$ and $P|0 \sim P$
 - $P + P \sim P$ but (in general) $P | P \not\sim P$
 - $P + Q \sim Q + P$ and $P|Q \sim Q|P$
 - $(P+Q) + R \sim P + (Q+R)$ and $(P|Q)|R \sim P|(Q|R)$