Superellipsoids: a generalization of the interval, zonotope and ellipsoid domains

Eric Goubault, Sylvie Putot MeASI (Modelling and Analysis of Interacting Systems) CEA and Ecole Polytechnique 14th of july 2011

The Egg of Columbus

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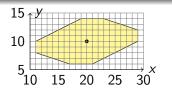


Context

- Static analysis of (numerical) programs, by abstract interpretation
- In order to infer *range* of program variables, *generate tests*, *prove functional properties* (FLUCTUAT, both f.p. and real numbers) etc.

Contents

- Recap on the (functional) zonotopic abstract domain
- Extension to *ellipsoids*, with the same kind of parametrization but a change of norm
- Some preliminary results



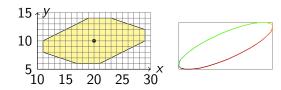
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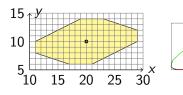
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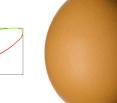
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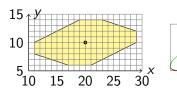


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Abstraction based on Affine Arithmetic (Stolfi 93)

• A variable x is represented by an affine form \hat{x} :

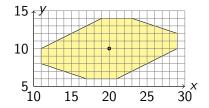
$$\hat{x} = x_0 + x_1 \varepsilon_1 + \ldots + x_n \varepsilon_n,$$

where $x_i \in \mathbb{R}$ and the ε_i are independent symbolic variables with unknown value in [-1, 1].

 Sharing ε_i between variables expresses *implicit dependency*: concretization as a zonotope

$$x = 20 - 4\varepsilon_1 + 2\varepsilon_3 + 3\varepsilon_4$$

$$y = 10 - 2\varepsilon_1 + \varepsilon_2 - \varepsilon_4$$



Affine arithmetic : arithmetic operations

 Assignment of a of a variable x whose value is given in a range [a, b] introduces a noise symbol ε_i:

$$\hat{x} = rac{(a+b)}{2} + rac{(b-a)}{2} arepsilon_i.$$

• Addition is computed componentwise (no new noise symbol): $\hat{x} + \hat{y} = (\alpha_0^x + \alpha_0^y) + (\alpha_1^x + \alpha_1^y)\varepsilon_1 + \ldots + (\alpha_n^x + \alpha_n^y)\varepsilon_n$

• Non linear operations : approximate linear form (Taylor expansion), new noise term for the approximation error. Example (gross over-approx!):

$$\hat{x}\hat{y} = \alpha_0^{\mathsf{x}}\alpha_0^{\mathsf{y}} + \sum_{i=1}^n \left(\alpha_i^{\mathsf{x}}\alpha_0^{\mathsf{y}} + \alpha_i^{\mathsf{y}}\alpha_0^{\mathsf{x}}\right)\varepsilon_i + \left(\sum_{i,j>0}^n |\alpha_i^{\mathsf{x}}\alpha_j^{\mathsf{y}}|\right)\varepsilon_{n+1}.$$

 Efficient join operator (SAS 2006, and extensions for meet operators -CAV 2010)

Standard "geometric" order on zonotopes

• Necessary for proving the analysis correct, testing the convergence of the analysis (Ifp through Kleene iteration in particular).

• Given
$$A \in \mathcal{M}(n+1,p)$$
,

$$\begin{array}{rcl} x & = & 20 - 4\varepsilon_1 + 2\varepsilon_3 + 3\varepsilon_4 \\ y & = & 10 - 2\varepsilon_1 + \varepsilon_2 - \varepsilon_4 \end{array} \qquad A = \begin{pmatrix} 20 & 10 \\ -4 & -2 \\ 0 & 1 \\ 2 & 0 \\ 3 & -1 \end{pmatrix}$$

Standard "geometric" order on zonotopes

• Given $A \in \mathcal{M}(n+1,p)$, $\forall t \in \mathbb{R}^p$ $(\|e\|_1 = \sum_{i=0}^n |e_i|, \ell_1 \text{ norm})$:

$$\sup_{y\in\gamma(A)}\langle t,y\rangle=\|At\|_1$$

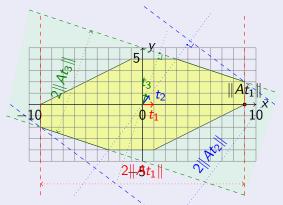
• Hence $X \subseteq Y$ iff for all $t \in \mathbb{R}^p$, $||Xt||_1 \le ||Yt||_1$

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Functional order

Standard formulation

- Let $x : \mathbb{R}^n \to \mathbb{R}^p$ be a function that we wish to abstract, and x_1, \ldots, x_p its p components.
- Instead of abstracting the set of values that x₁,..., x_p can take, given the possible input values, we introduce slack variables e₁,..., e_n which represent the initial values of the n input variables of function x,
- and we abstract the set of values that $e_1, \ldots, e_n, x_1, \ldots, x_p$ can take, conjointly
- The geometric order on this *augmented* zonotope is the functional order
- \rightarrow Many distinct parameterizations for the same functional
- \rightarrow Non-economic and non-necessary algorithmic representation!

Canonical form of the functional order

- Separate out noise symbols coming from the inputs: *central noise symbols*→matrix C
 with noise symbols not directly related to the inputs
 perturbation noise symbols→matrix P
- Let two affine sets over p variables and n input noise symbols X and Y, we say that $X \leq Y$ iff

$$\sup_{u\in\mathbb{R}^p}\left(\|(C^Y-C^X)u\|+\|P^Xu\|-\|P^Yu\|\right)\leq 0$$

The two formulations are equivalent!

Ellipsoids

Usual definition (constraints)

• In dimension 3, in suitable (x, y, z) coordinates:

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$

(in fact, we want all of the interior, so better write ≤ 1)

• In general, in dimension n:

$$(x-v)^T A(x-v) \leq 1$$

where A is symmetric positive definite

 Typical quadratic Lyapunov functions useful for proving stability/convergence of numerous systems (see also the quadratic template domain of Adjé et al., Feret's ellipsoidal domain, Kurzhanski's ellipsoidal calculus and work by Cousot, and by Féron)

Ellipsoids

Our definition (parameterization)

• Affine transformation on the *n*-dimensional disc

$$D^{n-1} = \{\varepsilon_1^2 + \ldots + \varepsilon_n^2 \le 1\}$$

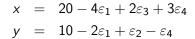
• Hence, just like zonotopes:

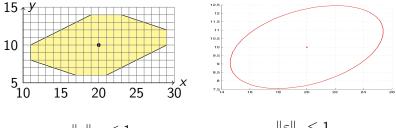
$$\hat{x} = x_0 + x_1 \varepsilon_1 + \ldots + x_n \varepsilon_n,$$

but with $\|\varepsilon\|_2 \leq 1$ (and not $\|\varepsilon\|_\infty \leq 1$)

Equivalent to the former one: if $\hat{X} = X_0 + M\varepsilon$, take $A = M^t M$, $v = X_0...$

Example





 $\|\varepsilon\|_{\infty} \leq 1$

 $\|\varepsilon\|_2 \leq 1$

Going functional

Separate out the set of symbols, again..

- We define an ellipsoidal set X by a pair of matrices $(C^X, P^X) \in \mathcal{M}(n+1, p) \times \mathcal{M}(m, p)$
- The ellipsoidal form

$$\pi_k(X) = c_{0k}^X + \sum_{i=1}^n c_{ik}^X \varepsilon_i + \sum_{j=1}^m p_{jk}^X \eta_j$$

where the ε_i are the central noise symbols and the η_j the perturbation or union noise symbols, describes the *k*th variable of *X*

 \bullet The noise symbols satisfy $\|\epsilon,\eta\|_2 \leq 1$

Order

Geometric order X < Y iff

$$\forall u \in \mathbb{R}^p, \ \|Xu\|_2 \leq \|Yu\|_2 \ .$$

Functional order

We say that $X \leq Y$ iff

$$\forall u \in \mathbb{R}^{p}, \ \|(C^{Y} - C^{X})u\|_{2} \leq \|P^{Y}u\|_{2} - \|P^{X}u\|_{2}$$
.

Once again, this can be proved to be the right order for comparing functional abstractions!

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Remarks

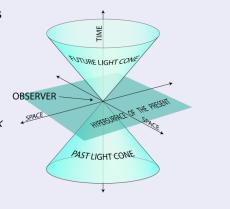
This is the Lorentz cone of special relativity!

More than just a mere remark:

- Our order is the Lorentz order (many theoretical tools available)
- Practical tools available! Second-Order Cone Programming in particular:

$$\min_{\|A_i x + b_i\|_2 \le c_i^T x + d_i, F x = g} f^T x$$

(subsumes quadratic constraints - hence concretisation in particular)



Arithmetic operations - first steps

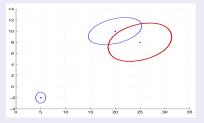
As before

Similar calculus as before:

$$\hat{x} + \hat{y} = (\alpha_0^x + \alpha_0^y) + (\alpha_1^x + \alpha_1^y)\varepsilon_1 + \ldots + (\alpha_n^x + \alpha_n^y)\varepsilon_n$$

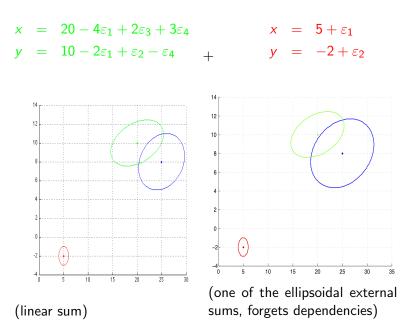
Not as before

• Ellipsoids not closed under Minkowski sum (red=sum of blue):



• Ellipsoidal calculus: find *smallest* ellipsoid containing the Minkowski sum of two ellipsoids, see for instance "Calculus Rules for Combinations of Ellipsoids and Applications" (A. Seeger)

Examples



All this can be generalized...

• Consider the transformation by an affine map of the *n*-disc for norm $\ell_p \ (p \ge 1)$:

$$\|\varepsilon\|_{p} = \left(\sum_{i=1}^{n} |\varepsilon|^{p}\right)^{\frac{1}{p}}$$

• Variables are represented as $\hat{x} = x_0 + x_1 \varepsilon_1 + \ldots + x_n \varepsilon_n$, with $\|\varepsilon\|_p \leq 1$ (not $\|\varepsilon\|_{\infty} \leq 1$)

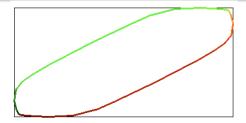
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Degree 4 super-ellipsoid



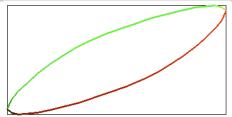
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More classically

In dimension 3, this is generally defined as

$$\left(\left|\frac{x}{a}\right|^r + \left|\frac{y}{b}\right|^r\right)^{\frac{t}{r}} + \left|\frac{z}{c}\right|^t \le 1$$

(but here, we consider only t = r)

Use ℓ_p/ℓ_q duality, or Hölder's inequality $\|fg\|_1 \leq \|f\|_p \|g\|_q$ with $\frac{1}{p} + \frac{1}{q} = 1$

Geometric order for *p*-superellipsoids $\left(q = \frac{p}{p-1}\right)$

 $X \subseteq Y$ if and only if for all $t \in \mathbb{R}^p$

 $\|Xt\|_q \le \|Yt\|_q$

Functional order $X \subseteq Y$ if and only if for all $t \in \mathbb{R}^p$ $\|(C^X - C^Y)t\|_a \le \|P^Yt\|_a - \|P^Xt\|_a$

This is the right order for functional abstractions!

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Conclusion and future work

Ellipsoids

- Has a clear potential, since it complements work on quadratic templates, quadratic Lyapunov functions etc.
- Still has to be experimented... In particular in our analyzer FLUCTUAT (with extensions of this to floating-point/error semantics)

P O O Fluctuat - Hipass_fluctuat O		
<pre>: #include "daed_builtins.h"</pre>	1.95581e-05 1.48936e-05 9.92906e-06 4.96439-06	
<pre>15 16 xnm2 = inputsignal(-2); 17 xnm1 = inputsignal(-1); 18 xn = inputsignal(0);</pre>	• • -	₹ 25 ÷
$19 \ ynm^2 = 0;$	Variables / Files	Variable Interval
$20 \underline{ynm1} = 0;$	i (integer) main (integer)	Float : -3.25309873 3.25309873
<pre>22 for (i=1;i<=N;i++) {</pre>	xn (float) xnm1 (float)	Real : -3.25307802 3.25307802
$\frac{y_{n}}{y_{n}} = (2^{*}(c^{*}c^{-1})^{*}y_{n}m_{1}^{-}(c^{*}c^{-}sqrt2^{*}c^{+1})^{*}y_{n}m_{2}^{-2} + c^{*}c^{*}x_{n}n_{2}^{-2} + c^{*}c^{*}x_{n}n_{2}^{-2})$	xnm2 (float)	Global error :
24 <u>ynm2 = ynm1;</u> 25 ynm1 = yn;	yn (float) ynm1 (float)	-2.09172228e-5 2.09172228e-5
$\frac{y_{11}}{26} = \frac{y_{11}}{x_{1}m_{2}} = \frac{y_{11}}{x_{1}m_{1}}$	ynm2 (float)	Relative error :
27 xnml = xn;		-00 +00
28 <u>xn</u> = inputsignal(i);		Higher Order error :
29 FPRINT(xn);	hipass_fluctuat.c	0 0
30 FPRINT(yn);		At current point (23) :

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Superellipsoids

- More a formal game for now
- Useful?