Continuity Analysis of Floating Point Software



David Bushnell TracLabs david.h.bushnell@nasa.gov

Robust Software Engineering NASA Ames Research Center

VVFCS element SSAT Project NASA Aviation Safety Program



Continuity:

Small changes have small effects!



Software Continuity: What is it? Why is it Important?

Continuity:

Small changes have small effects!

"... unlike physical systems, software is not continuous; small changes can cause large failures ..."

Peter Wegner, 1979



Continuity:

Small changes have small effects!

"... unlike physical systems, software is not continuous; small changes can cause large failures ..." Vote old Longitude - new Longitude Yes > 1.0 degree ? Update position

Peter Wegner, 1979

F22 Raptor Crossing International Date Line February 11, 2007

Problem Statement



Problem Statement





Where does the software's control structure cause *f* (*x*) to be discontinuous?

How to generate test cases near the discontinuities?

Approach







double	g(double	Х,	у)	{	x := -5.3 y := 3.2
				· · · · · · · · · · · · · · · · · · ·	

double z;

- if (x < y)
 - z = y x;

else

z = x - y;

return z;



〕 7/14/11



z = x - y;

return z;



Concrete Execution for Testing





double g(double x,	y) {	PC (Path Condition): <i>true</i> <i>x</i> := \$X <i>y</i> := \$Y
double z;		
if (x < y)		
z = y-x;		
else		
z = x-y;		
return z;		
}		









return z;









Java Pathfinder: JPF



- General purpose Java verification tool
 - Software model checking (concurrency bugs: deadlock, race conditions)
 - UML statechart verification
 - Floating point overflow/underflow/catastrophic cancelation
 - Symbolic execution (test case generation)
 - Many more ...
- Developed at NASA/Ames
 - Started in 1999, work continues to this day
 - Recognized by numerous awards from both NASA and the verification community
 - Open source since 2005



Symbolic Pathfinder: SPF

Symbolic Pathfinder:

Extends JPF for symbolic execution

Supports booleans, integers, floating point, complex data structures, strings

Supports many constraint solvers:

- Coral

High performance non-linear floating point constraint solver

- Choco

Solver for linear/non-linear, integer/floating point constraints, mixed constraints

- CVC3

Solver for integer/real linear constraints

Discontinuities



Discontinuities come in many forms, including:

• Non-convergence: $y = -\sum_{1}^{\infty} \frac{(1-x)^n}{n}$





 Physical discontinuities in the model e.g. shockwaves:



Discontinuities



We analyze discontinuities of another type: Those that arise from the structure of the software





Path Condition: Boolean expression in symbolic inputs specifying a single execution path through the software.

Written as PC, PC1, PC2, ...

All inputs satisfying a given path condition force the same execution path.

Example: PC1: $(x>0.0) \land (x+y<z)$



Boundary between path conditions PC1 and PC2: The set of input values at which the software changes from the execution path for PC1 to the path for PC2.





Path Function: The function computed by all inputs satisfying a single path condition.

Example: if (x < 0)return 0.0 else return cos(x); For PC1: (x < 0)PF1: 0.0 For PC2: $(x \ge 0)$ PF2: cos(x)



Discontinuity Condition: Boolean expression in symbolic inputs specifying a region where the function computed by the software is discontinuous.

Written as DC, DC1, ...

We are interested in discontinuity conditions associated with the software's control structures.

Calculating Boundaries of Path Conditions

First:	Relation Closure	
Calculate the <i>closure</i> of a relation.	F < G F ≤ G	
For the floating point relations	F≤G F≤G	
$\{<, \leq, =, \neq, \geq, >\}$	F = G F = G	
define the <i>closure</i> of the relation as in the table:	F≠G <i>true</i>	
	F≥G F≥G	
Example: The region defined by (x < y) is:	FBorder missing	
Its closure is $(x \le y)$: Borde	er included	



Calculating Boundaries of Path Conditions

Second:
Define the *closure of a path condition:*
Given a path condition PC

$$PC = R1 \land R2 \land ...$$

where R1, R2, ... are primitive relations.

Its closure is written ${\tt PC}$ or ${\tt cl}\;({\tt PC})$ and is given by

 $\overline{PC} = \overline{R1} \wedge \overline{R2} \wedge \dots$





Finally:

Define the boundary between two path conditions PC1 and PC2 as:

 $\partial (PC1, PC2) = \overline{PC1} \wedge \overline{PC2}$

Example: Boundaries



```
double step2(double x, double y)
  if (x < y)
    return 0.0;
  else
    return 1.0;</pre>
```

Path Conditions:PC1: (x < y) $PC2: (x \ge y)$ Boundary: $\partial (PC1, PC2) \equiv \overline{PC1} \land \overline{PC2}$ $\equiv (x \le y) \land (x \ge y)$



 $\equiv (x = y)$

Discontinuity Conditions From Control Structures



How can the output be discontinuous when control switches from one execution path to another?

Answer: when the values computed along Path 1 (PC1) do not match the values computed along Path 2 (PC2) at the crossover

Discontinuity Conditions From Control Structures

NASA

Crossover happens at the boundary between Path 1 and Path 2

The values computed are the path functions PF1 and PF2



So when control switches from Path 1 to Path 2, the software will be discontinuous at all points satisfying:

 $\partial (PC1, PC2) \land (PF1 \neq PF2)$

Example: Discontinuity Conditions







Example: Discontinuity Conditions

```
double sa(double x, double y)
if (x < y)
if (y < 10)
return x+y;
else
return x+10;
else
return x-y;</pre>
```



Example: Discontinuity Conditions

```
double sa(double x, double y)
if (x < y)
if (y < 10)
return x+y;
else
return x+10;
else
return x-y;</pre>
```





Implemented on top of Symbolic Path Finder:

- Open source JPF extension: jpf-continuity
- Computes boundaries between path conditions
- Computes constraints along borders:
 - Discontinuity
 - Continuity
- Integrated with Coral constraint solver
 - Can solve highly non-linear floating point constraints
- Computes symbolic derivatives of path functions

Status



Demonstrated automatic generation of test cases at border discontinuities

- Applied to selected code from TSAFE (Tactical Separation Assisted Flight Environment)
- Automatically generates test cases demonstrating discontinuities along path condition borders



Diagram from: H. Erzberger, 2009

Beyond Discontinuity Analysis

Robustness:

 Where along the border are the path functions "extremely discontinuous"?
 Discontinuous: PF1≠PF2
 Non-Robust: |PF1-PF2|>ε

Global border behavior:

- How bad do the discontinuities get?
- How badly to the continuous points behave?



- Compositional Analysis
 - If f(x1,...,xn) = h(g(x1,...,xn)) and we know the discontinuities of h() and g(), what are the discontinuities of f()?
- Guided Test Generation
 - How to verify regions for safe execution of code?
- Polynomial Approximation
 - Useful when finding min, max, zeros:
 - Approximate with low-degree polynomials
 - Need to know discontinuities

Availability



JPF (Java Path Finder), SPF (Symbolic Path Finder), and jpfcontinuity are all open source software

They are available for download at

- JPF: http://babelfish.arc.nasa.gov/trac/jpf/
- SPF: http://babelfish.arc.nasa.gov/trac/jpf/wiki/projects/jpf-symbc
- jpf-continuity: https://jpfcontinuity@bitbucket.org/jpfcontinuity/jpfcontinuity

Acknowledgments



Thanks to Saswat Anand (Georgia Tech) for discussions and clarifications

Thanks to Misty Davies, Dimitra Giannakopoulou, Michael Lowry, Corina Pasareanu, and Neha Rungta (NASA Ames Robust Software Engineering group) for critiques and suggestions.

References



"Continuity analysis of programs", Chaudhuri, S., Gulwani, S., Lublinerman, R., POPL, 2010

- "Symbolic robustness analysis", R. Majumdar and I. Saha. Real-Time Systems Symposium, IEEE International, 0:355–363, 2009
- "Continuity in Software Systems", Hamlet, D., ISSTA, 2002
- "Generalized Symbolic Execution for Model Checking and Testing", Khushid, S., Pasareanu, C., Visser, W., Proceedings of the 9th International Conference on Tools and Algorithms for the Construction and Analysis of Systems. Springer, 2003.
- "Symbolic Execution and Program Testing", King, J.C., Commu- nications of the ACM, vol. 19(7), pp. 385–394, 1976.
- "Separation Assurance in the Future Air Traffic System", Erzberger, H., ENRI International Workshop on ATM/CNS, 2009





