# DIHOMOTOPY AND THE CUBE PROPERTY

#### SAMUEL MIMRAM

École Polytechnique

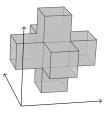
joint work with ÉRIC GOUBAULT

GETCO conference

April 10, 2015

## General idea

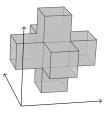
Concurrent programs can be interpreted as directed spaces, but methods in algebraic topology have been devised for non-directed spaces.



Dihomotopy and homotopy coincide for common programs!

## General idea

Concurrent programs can be interpreted as directed spaces, but methods in algebraic topology have been devised for non-directed spaces.



Dihomotopy and homotopy coincide for common programs!

Here, I will focus on some algebraic and topological aspects.

## PART I

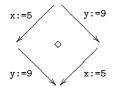


## CUBICAL SEMANTICS OF CONCURRENT PROGRAMS

## Commutation of actions concurrent programs

In concurrent programs, some actions do commute

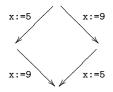
in the sense that their order do not matter



## Commutation of actions concurrent programs

In concurrent programs, some actions do not commute

in the sense that their order does matter



In fact, the resulting x could even be different from 5 and 9!

In order to prevent incompatible actions from running in parallel, one uses **mutexes**, which are *resources* on which two actions are available

- P<sub>a</sub>: take the resource a
- ► V<sub>a</sub>: *release* the resource a

and implementation

- guarantees that a resource has been taken at most once at any moment,
- ► forbids releasing a resource which as not been taken.

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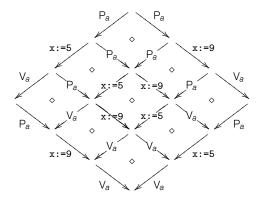
Our earlier program should be rewritten as

$$P_a; x:=5; V_a \parallel P_a; x:=9; V_a$$

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 $P_a; x:=5; V_a \parallel P_a; x:=9; V_a$ 

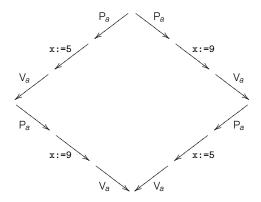
Possible executions are



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 $P_a; x:=5; V_a \parallel P_a; x:=9; V_a$ 

Possible executions are



## Concurrent programs

We consider concurrent programs defined by

$$p$$
 ::=  $A \mid p; p \mid p+p \mid p \parallel p \mid p^* \mid P_a \mid V_a$   
where

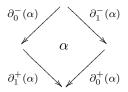
- A an action (e.g. x := 5)
- p;q do p then q
- p + q do p or q (if / then / else)
  - p\* repeat p (while)
  - P<sub>a</sub> take mutex a
  - V<sub>a</sub> release mutex a

## Cubical graphs

A cubical graph C consists of

- ▶ a set C<sub>0</sub> of vertices
- a set C<sub>1</sub> of edges
- ▶ source and target maps  $\partial_0^-, \partial_0^+ : C_1 \to C_0$
- a set C<sub>2</sub> of squares
- ▶ source and target maps  $\partial_0^-, \partial_0^+, \partial_1^-, \partial_1^+ : C_2 \to C_1$
- a transposition  $\tau: C_2 \rightarrow C_2$

satisfying axioms so that

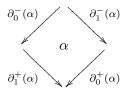


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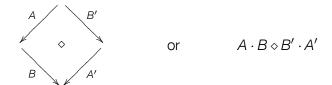
satisfying axioms so that



We sometimes add labels on edges.



#### We write



to indicate that there exists a square  $\alpha$  with

$$\partial_0^-(\alpha) = A \qquad \partial_1^+(\alpha) = B \qquad \dots$$

To every every program p we can associate a cubical graph  $C_p$ , together with *beginning* vertex  $b_p$  and *end* vertex  $e_p$ , by induction:

► A:

$$C_A = b_A \bullet A \bullet e_A$$

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$$C_{A} = b_{A} \cdot \underbrace{A}_{A} \cdot e_{A}$$

$$P_{a}:$$

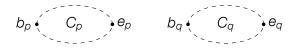
$$C_{P_{a}} = b_{P_{a}} \cdot \underbrace{P_{a}}_{P_{a}} \cdot e_{P_{a}}$$

$$V_{a}:$$

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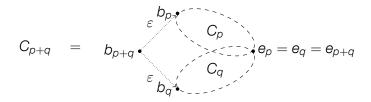
$$C_{p;q} = b_p \left( \begin{array}{c} C_p & e_p \\ \end{array} \right) \left( \begin{array}{c} b_q & C_q \\ \end{array} \right) \left( \begin{array}{c} e_q \end{array} \right) \left( \begin{array}{c} e_q \\ \end{array} \right) \left( \begin{array}{c} e_q \end{array} \right) \left( \begin{array}{c} e_q \\ \end{array} \right) \left( \begin{array}{c} e_q \end{array} \right) \left( \left( \left( \begin{array}{c} e_q \end{array} \right) \right) \left( \left( \left( \begin{array}{c} e_q \end{array} \right) \right) \left( \left( \left( \left( \left( \left( \left$$

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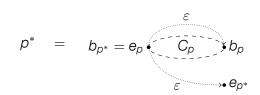
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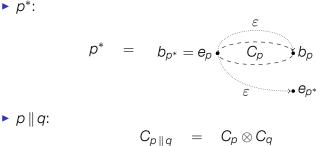


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▶ p\*:



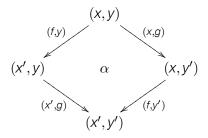
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## Tensor product of cubical graphs

The **tensor product**  $C \otimes D$  of two cubical graphs C and D has

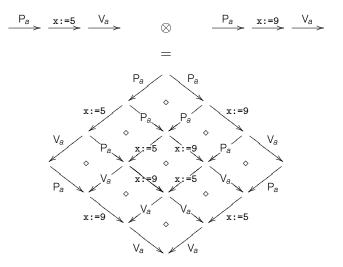
- vertices:  $(C \otimes D)_0 = C_0 \times D_0$
- edges:  $(C \otimes D)_1 = (C_1 \times D_0) \sqcup (C_0 \times D_1)$
- squares are of the form



for  $f : x \to x'$  in C and  $g : y \to y'$  in D.

## Tensor product of cubical graphs

For instance:



## Cubical semantics

#### Definition

The **cubical semantics**  $\check{C}_p$  of a program *p* is the cubical graph obtained from  $C_p$  by removing vertices (as well as adjacent vertices and squares) which are **forbidden** because some resource is taken more than once.

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#### Remark

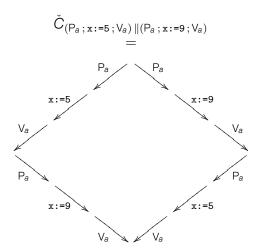
This supposes that the resource consumption is unambiguously defined for a vertex. A program for which this is the case is called *conservative*, e.g. not



## Paths as executions

#### Proposition

Paths in  $\check{C}_p$  starting from  $b_p$  are in bijection with executions of the program p.



## Homotopy between paths

#### Definition

The **homotopy** relation  $\sim$  between paths is the smallest congruence such that  $A \cdot B \sim B' \cdot A'$  whenever  $A \cdot B \diamond B' \cdot A'$ :



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#### Proposition

For "reasonable" programs, two homotopic executions lead to the same state.

It seems interesting to study the space of paths up to homotopy.

## PART II



## HOMOTOPY VS DIHOMOTOPY

### Path direction

In classical topology paths are not *directed*: given a path  $p: I \to X$  we also have a reverse path  $\overline{p}: I \to X$  defined by

$$\overline{\rho}(t) = \rho(1-t)$$

and most constructions in algebraic topology depend on this (the fundamental *group*, etc.)

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On the contrary our paths must follow the directions indicated by arrows.

How can we compare the two?

## Dipaths

We call a **dipath** what we have been calling a path, i.e. a sequence of composable arrows:

$$\xrightarrow{A} \xrightarrow{B} \xrightarrow{C} \text{ or } A \cdot B \cdot C$$

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$$\xrightarrow{A} \xrightarrow{B} \xrightarrow{C}$$
 or  $A \cdot B \cdot C$ 

We call a **path** a sequence of *possibly reversed* composable arrows:

$$\xrightarrow{A} \xleftarrow{B} \xrightarrow{C} \text{ or } A \cdot \overline{B} \cdot C$$

## Dihomotopy



we have

$A \cdot B \iff B' \cdot A'$	$\overline{A} \cdot B' \iff B \cdot \overline{A'}$	$\overline{B} \cdot \overline{A} \iff \overline{A'} \cdot \overline{B'}$
		B / 1 / B

## Dihomotopy

We call **dihomotopy** between paths, the smallest congruence www such that for every square



we have

 $A \cdot B \longleftrightarrow B' \cdot A' \qquad \overline{A} \cdot B' \Longleftrightarrow B \cdot \overline{A'} \qquad \overline{B} \cdot \overline{A} \longleftrightarrow \overline{A'} \cdot \overline{B'}$ 

#### Remark

A path dihomotopic to a dipath is necessarily a dipath.

### Homotopy

The **homotopy** relation on paths  $\sim$  is the smallest congruence containing dihomotopy and such that for every edge

$$x \xrightarrow{A} y$$

we have

$$\operatorname{id}_{X} \sim A \cdot \overline{A}$$
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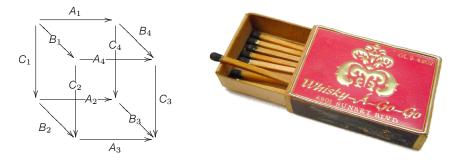
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Remark

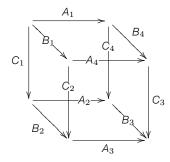
Clearly  $f \leftrightarrow g$  implies  $f \sim g$ , but converse is *not* generally true.

Consider the following "matchbox":



where every square is filled excepting the top one:

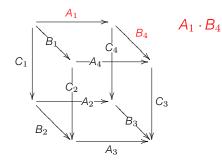
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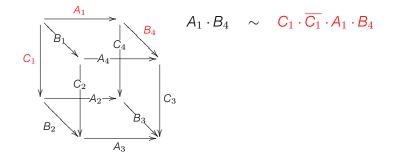


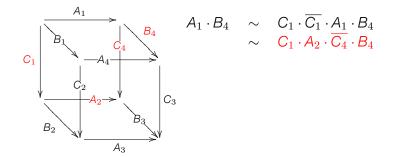


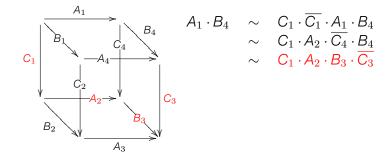
We have

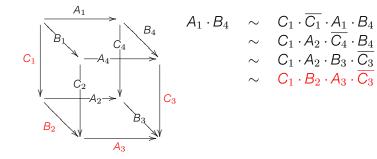
 $A_1 \cdot B_4 \sim B_1 \cdot A_4$  but not  $A_1 \cdot B_4 \iff B_1 \cdot A_4$ 

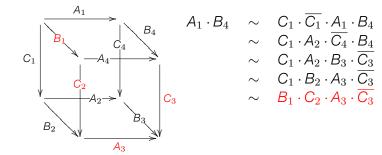


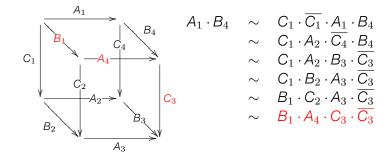


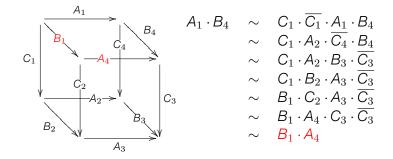


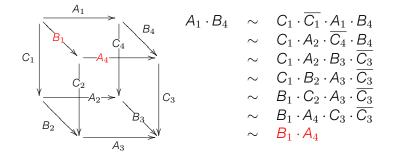








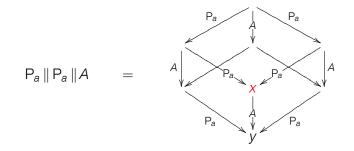




This example cannot be obtained as the semantics of a program!

### **Binary conflicts**

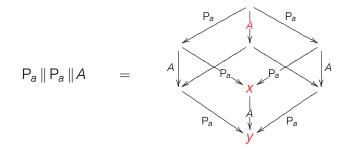
#### In a situation such as



the vertex x is forbidden (and has to be removed).

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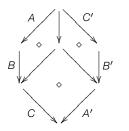
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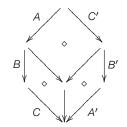
In this case, the vertex y has to be removed too, because  $A \neq V_a$ !

### The cube property

Semantics of programs satisfy the cube property:

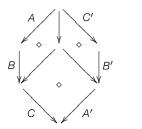
 $\Leftrightarrow$ 

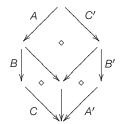




### The cube property

Semantics of programs satisfy the cube property:





and other more minor properties, e.g.



 $\Leftrightarrow$ 

implies A' = A'' and B' = B''.

Theorem In a cubical graph satisfying the cube property, two dipaths are dihomotopic if and only if they are homotopic.

# PART III



# PRESENTING THF FUNDAMENTAL CATEGORY AND GROUPOID

# Fundamental groupoid and category

To every cubical graph C, we can associate

- 1. a **fundamental groupoid**  $\Pi_1(C)$  of vertices and paths up to homotopy,
- 2. a **fundamental category**  $\vec{\Pi}_1(C)$  of vertices and *di*paths up to *di*homotopy.

# Fundamental groupoid and category

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Notice that previous theorem can be reformulated as

Theorem

If C satisfies the cube property, then the inclusion functor

 $\vec{\Pi}_1(C) \quad \hookrightarrow \quad \Pi_1(C)$ 

is faithful.

# The fundamental 2-category

In order to study the relationships between the two categories, we in introduce:

#### Definition

The fundamental 2-category  $\vec{\Pi}_2(C)$  is the 2-category whose

- 0-cells are vertices of C,
- 1-cells are paths in C,
- 2-cells are generated by

$$\gamma^{A,B}_{B',\mathcal{A}'}:A\cdot B\Rightarrow B'\cdot A'$$
 whenever



 $\eta_{A}: \mathsf{id}_{x} \Rightarrow A \cdot \overline{A} \qquad \varepsilon_{A}: \overline{A} \cdot A \Rightarrow \mathsf{id}_{y} \qquad \text{for}$ 

 $X \xrightarrow{A} Y$ 

- quotiented by relations on 2-cells
- horizontal composition is concatenation of paths

### Towards a proof

Notice that

two paths f, g are homotopic if and only if there is a 2-cell

$$\alpha$$
 :  $f \Rightarrow g$ 

 the paths *f*, *g* are *dihomotopic* if and only if there is such a 2-cell constructed without generators η<sub>A</sub> and ε<sub>A</sub>:

$$\eta_{A}: \mathrm{id}_{X} \Rightarrow A \cdot \overline{A} \qquad \qquad \varepsilon_{A}: \overline{A} \cdot A \Rightarrow \mathrm{id}_{Y}$$

### Towards a proof

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▶ two paths *f*, *g* are *homotopic* if and only if there is a 2-cell

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#### Remark

Notice that this does not depend on the relations on 2-cells.

### Towards a proof

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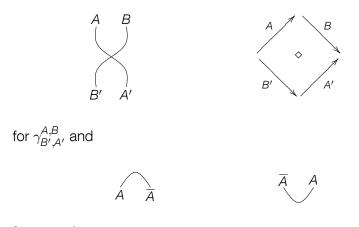
$$\eta_{A}: \mathrm{id}_{X} \Rightarrow A \cdot \overline{A} \qquad \qquad \varepsilon_{A}: \overline{A} \cdot A \Rightarrow \mathrm{id}_{Y}$$

#### Theorem

Any 2-cell  $\alpha$  :  $f \Rightarrow g$  between f and g is equal to one without the bad generators (with the right relations!).

### String diagrams

For the 2-cells I will use the string-diagrammatic notation:

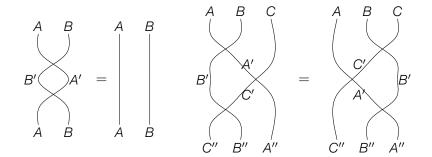


for  $\eta_A$  and  $\varepsilon_A$ .

### Relations on 2-cells

We relations on 2-cells so that

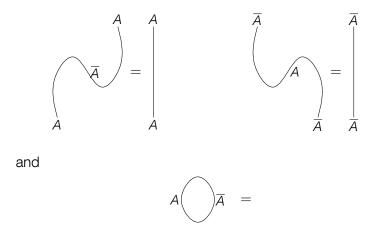
• 
$$\gamma^{A,B}_{B',A'}$$
 acts like a symmetry:



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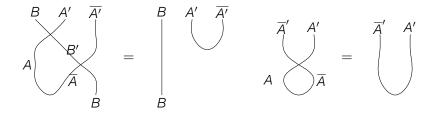
•  $\eta_A$  and  $\varepsilon_A$  act as (co)units of an adjunction:



### Relations on 2-cells

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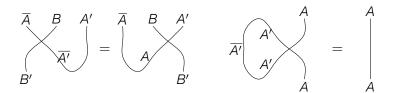
the two are "naturally" compatible:



+ dual and symmetric relations

### Derivable relations

Some other relations are derivable:



### Well-definedness

Notice that "not every diagram makes sense": if we cannot commute some actions for instance.

Lemma

If the left member of a relation is well-defined then the right member too.

### Well-definedness

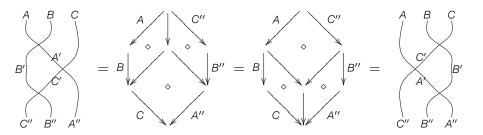
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#### Lemma

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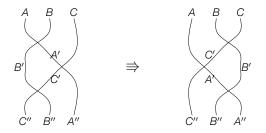
#### Proof.

This is where we use our properties on the cubical graph:



# A rewriting system

We can turn our relations into a rewriting system (from left to right), e.g.



#### Conjecture

The rewriting system is convergent, thus normal forms are canonical representatives of equivalence classes.

# A proof for our theorem

Suppose given a 2-cell between <u>dipaths</u>  $\alpha : f \Rightarrow g$ . This 2-cell is equal to a normal form, so we suppose that we are in this case. Proposition

The 2-cell  $\alpha$  does not contain  $\eta_A$  or  $\varepsilon_A$  generators.

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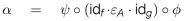
The 2-cell  $\alpha$  does not contain  $\eta_A$  or  $\varepsilon_A$  generators.

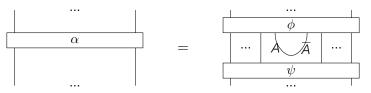
#### Proof.

Suppose that it "contains"

$$\varepsilon_{\mathcal{A}}:\overline{\mathcal{A}}\cdot\mathcal{A}\Rightarrow \mathrm{id}_{x}$$

i.e.





# A proof for our theorem

What can  $\phi$  be?



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Notice that φ cannot be an identity, otherwise α would contain A in its source (a reversed edge), which would not be a dipath.

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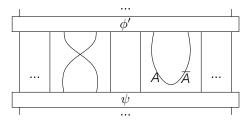
- Notice that φ cannot be an identity, otherwise α would contain A in its source (a reversed edge), which would not be a dipath.
- Thus  $\phi$  is thus of the form



where  $\rho$  is a generator.

We then proceed on case analysis on  $\rho$  and its position, keeping in mind that  $\alpha$  must be in normal form. For instance, if  $\rho = \gamma$ ,

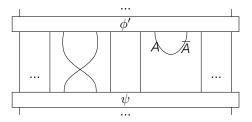
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we can use the exchange law to "put the  $\gamma$  down in the  $\psi$ " and reason by induction on  $\phi'$ .

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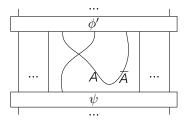
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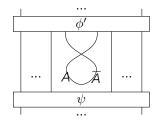


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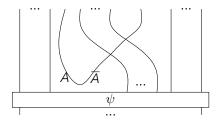




otherwise  $\alpha$  would not be normal.

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and thus the morphism would contain  $\overline{A}$  (a reversed transition in its source).

## A real proof

Showing that the rewriting system is convergent is difficult:

- there is an infinite number of critical pairs even though there is a finite number of rules (they can however be grouped in a finite number of families),
- there is an awful lot of cases to be checked.

## A real proof

Showing that the rewriting system is convergent is difficult:

- there is an infinite number of critical pairs even though there is a finite number of rules (they can however be grouped in a finite number of families),
- there is an awful lot of cases to be checked.

In practice, we only need a representative (not necessarily unique), which can be defined by hand, and the proof goes on roughly as indicated before. So we actually have a proof here.

### Notes on the axioms

### In the category Vect we have bjiections

$A \otimes B \to C$	$A \rightarrow B \otimes C$
$\overline{A  o C \otimes B^*}$	$\overline{B^* \otimes A \to C}$

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$$\eta: \Bbbk \to A \otimes A^* \qquad \qquad \varepsilon: A^* \otimes A \to \Bbbk$$

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To be precise, we also have to satisfy the axiom

$$(\dim A) \operatorname{id}_k = \operatorname{tr}(\operatorname{id}_A) = A \bigcirc \overline{A} = \operatorname{id}_k$$

i.e. dim A = 1.

# PART IV



# UNIVERSAL DICOVERING

(or not)

# The universal covering

### Definition

A map  $p : \tilde{X} \to X$  is a **covering** when every point  $x \in X$  admits an open neighborhood U such that  $p^{-1}(U)$  is a disjoint union of open sets homeomorphic to U.

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A covering is **universal** when it is "most general" (most unfolded).

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### Theorem

The universal dicovering can be constructed as the space of homotopy classes [f] of paths f with origin  $x_0 \in X$ .

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A **directed** topological space X is a space equipped with a coherent set dX of *directed paths*.

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A dicovering is **universal** when it is "most general".

#### Theorem

Consider a precubical set C satisfying the cube property. Consider its geometric realization |C| (as a directed space) and a point  $x_0 \in |C|$ .

The subspace of the universal dicovering reachable from  $x_0$  can be constructed as the space of <u>di</u>homotopy classes [f] of directed paths f with origin  $x_0 \in X$ .

$$\bigcup_{x_0} \xrightarrow{p} \bigcup_{x_0}$$

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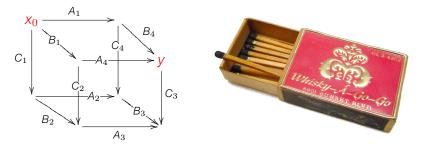
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It can be seen as the traditional covering together with the "inherited direction".

In the general case, the two do not coincide and the characterization can be taken as a definition [Fajstrup&Rosický10].

For instance, consider the "matchbox" again:



- ► Topologically is it S<sup>2</sup>, so identity is the only covering.
- ▶ However, there are two non-dihomotopic paths from *x*<sub>0</sub> to *y*.

# PART V



# GEOMETRIC POINT OF VIEW

(or not)

### Precubical sets

A cubical graph consists of

- O-cubes: vertices
- 1-cubes: edges
- 2-cubes: squares

There is a well-known generalization of this to any dimension:

### Definition

A **precubical set** *C* is a family  $(C_n)_{n \in \mathbb{N}}$ , the elements of  $C_n$  being called *n*-cubes, together with suitable *face maps* 

$$\partial_i^-, \partial^+ : C_{n+1} \to C_n$$

with  $0 \le i < n$ .

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In the following, a cubical graph *C* will be seen a precubical set with  $C_n$ , for n > 2, being the set of all possible hollow *n*-cubes in *C*.

## Precubical sets as presheaves

There is a category  $\Box$ , whose objects are integers, such that precubical sets are presheaves over it:

### **PCSet** $\cong$ $\hat{\Box}$

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The geometric realization can also be performed in **Met**, the category of metric spaces!

## Geometric realization in metric spaces

A realization in metric spaces is desirable.

We want to have a notion of length of paths (corresponding to the duration of an execution).

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## Geometric realization in metric spaces

A realization in metric spaces is desirable.

- We want to have a notion of length of paths (corresponding to the duration of an execution).
- The category of metric spaces is not cocomplete: we have to take a variant of metric spaces.
- We would also like to encode the time direction in the metric.

### Definition

A **metric space** is a space *X* equipped with a metric  $d: X \times X \rightarrow [0, \infty]$  such that, given  $x, y, z \in X$ ,

$$\begin{array}{ll} (1) & \text{point equality:} & d(x,x) = 0 \\ (2) & \text{triangle inequality:} & d(x,z) \leq d(x,y) + d(y,z) \\ (3) & \text{finite distances:} & d(x,y) < \infty \\ (4) & \text{separation:} & d(x,y) = 0 \text{ implies } x = y \\ (5) & \text{symmetry:} & d(x,y) = d(y,x) \end{array}$$

We consider contracting maps  $f: X \to Y$ :

$$d_Y(f(x), f(x')) \leq d_X(x, x')$$

Unfortunately, the resulting category is not cocomplete!

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Intuitively, X + Y should be such that

$$d(x,y) = \infty$$

for  $x \in X$  and  $y \in Y$ .

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Consider the relation  $\approx$  on *X* identifying a family of points  $(x_i)_{i \in \mathbb{N}}$  such that  $d(x_i, y) = 1/i$  for some *y* 

$$x_1$$
  $x_2$   $x_3$   $x_4$   $x_5$   $y$ 

Intuitively, in  $X / \approx$ , we should have  $d([x_i], [y]) = 0$ .

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A **metric space** is a space *X* equipped with a metric  $d: X \times X \rightarrow [0, \infty]$  such that, given  $x, y, z \in X$ ,

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We can encode direction in the distance!

$$d(x,y) = \bigwedge \left\{ \rho - \theta \ \Big| \ x = e^{i2\pi\theta}, y = e^{i2\pi\rho}, \rho \ge \theta \right\}$$



### Definition (Lawvere)

A generalized metric space is a space X equipped with a metric  $d: X \times X \rightarrow [0, \infty]$  such that, given  $x, y, z \in X$ ,

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The category **GMet** enjoys the following:

- the category GMet is complete and cocomplete,
- the forgetful functor  $\mathbf{GMet} \rightarrow \mathbf{Set}$  has left and right adjoints,
- the forgetful functor **GMet**  $\rightarrow$  **Top** preserves finite (co)limits.

We write  $\vec{l}$  for the **directed interval** [0, 1] equipped with

$$d(x,y) = \begin{cases} y-x & \text{if } y \ge x \\ \infty & \text{if } y < x \end{cases}$$

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The product  $\vec{l}^n$  is equipped with

$$d((x_1,\ldots,x_n),(y_1,\ldots,y_n)) = d(x_1,y_1) \vee \ldots \vee d(x_n,y_n)$$

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#### Proposition

For finite-dimensional precubical sets, geometric realization commutes with forgetful functor  $GMet \rightarrow Top$  and produces geodesic length spaces.

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$$I_{\infty} = \prod_{n \in \mathbb{N}} I_n / \approx$$



where  $\approx$  identifies 0 (resp. 1) in various  $I_n$ .

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where  $\approx$  identifies 0 (resp. 1) in various  $I_n$ .

We have d(0,1) = 0 and therefore the points 0 and 1 are not separated in  $I_{\infty}$  (see Bridson & Haefliger).

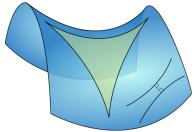
Geometric realization in metric spaces works well.

Moreover, the resulting spaces are non-positively curved.

Interestingly, the cube property was used by Gromov to characterize non-positively curved spaces.

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- A geodesic triangle ∆(x, y, z) in a metric space X consists of three points x, y, z and geodesics joining any pairs.
- ► A comparison triangle for a geodesic triangle  $\Delta(x, y, z)$ consists of an isometry  $\underline{-} : \Delta(x, y, z) \to \mathbb{R}^2$  whose image  $\underline{\Delta}(\underline{x}, \underline{y}, \underline{z})$  is a geodesic triangle.

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#### Definition

A geodesic space is **CAT(0)** if for every geodesic triangle  $\Delta(x, y, z)$ , there exists a comparison triangle  $\underline{\Delta}(\underline{x}, \underline{y}, \underline{z})$  such that for every points  $p, q \in \Delta(x, y, z)$ , we have  $d(p, q) \leq d_{\mathbb{R}^2}(p, q)$ .

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A locally CAT(0) space is called **non-positively curved** (NPC).



## Gromov's theorem

Reformulating ("flag links") in our setting (and omitting minor details):

## Theorem (Gromov)

The geometric realization of a precubical set is NPC if and only iff it satisfies the cube property.

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The geometric realization of a precubical set is NPC if and only iff it satisfies the cube property.

Such a space is locally uniquely geodesic. In particular, directed paths are local geodesics:

an analogue of the least action principle

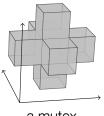
Moreover, it enjoys many nice properties (e.g. Greedy normal forms for paths, universal cover is CAT(0), fundamental group is automatic, ...).

## A small example

Consider

$$P_a \parallel P_a \parallel P_a$$

whose realization of geometric semantics is



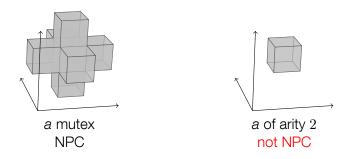
a mutex NPC

## A small example

Consider

$$P_a \parallel P_a \parallel P_a$$

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# CONCLUSION

# Going further

For a cubical graph satisfying the cube property:

- universal dicovering has a simple definition,
- its unfolding corresponds to the configuration space of an event structure (Chepoi, Ardilla et al., ...)
- its trace space can be computed thanks to (traditional) homology
- metric geometric realization is non-positively curved (= locally CAT(0))

Also:

- Relations on 2-cells are meaningful?
- Variants for *n*-semaphores, etc.
- Links with motion planning (Ghrist et al.)
- Links with geometric group theory (Dehornoy, ...)