

**[CSE301 / Lecture 5]**  
**Laziness and infinite objects**

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# What is laziness?

The dominant state of most students.

Also, an **evaluation strategy** used by Haskell.

Idea: only evaluate something if it is needed to compute the result of the overall computation, and once you've evaluated something, don't evaluate it again.

## You can try this on the lab machines...

In ghci:

```
ghci> :set +m
ghci> ack m n = if m == 0 then n+1
ghci|           else if n == 0 then ack (m-1) 1
ghci|           else ack (m-1) (ack m (n-1))
ghci> let x = ack 4 3 in 1+1
2
```

In ocaml:

```
# let rec ack m n = if m == 0 then n+1
                    else if n == 0 then ack (m-1) 1
                    else ack (m-1) (ack m (n-1)) ;;
val ack : int -> int -> int = <fun>
# let x = ack 4 3 in 1+1 ;;
Warning 26: unused variable x.
[...this will take a while...]
```

# Laziness in Haskell

In Haskell, evaluation is lazy by default, for better or worse:

- Often can be used to turn seemingly naive mathematical formulas into efficient algorithms.
- Allows for elegant encodings of infinite objects

But...

- It makes it harder to write a compiler
- Often much harder to reason about performance

## Example: the Fibonacci sequence

The following is valid Haskell code, defining the infinite sequence of Fibonacci numbers.

$$\text{fibseq} = 0 : 1 : \text{zipWith } (+) \text{ fibseq } (\text{tail fibseq})$$

We can use it to give another definition of the function *fib*:

$$\text{fib } n = \text{fibseq} !! n$$

This runs in linear time, and remembers (memoizes) its results!

# Plan for today

We will try to cover these topics:

1. Evaluation
2. Evaluation strategies for functional languages
3. Laziness and infinite objects
4. Computational duality
5. Overcoming laziness

# Evaluation

Recall that an **expression** denotes a computation towards a **value**. The process of computing that value is called **evaluation**.

Evaluation may be visualized as a series of reductions<sup>1</sup> from one expression to another expression, ending in a value, e.g.:

$$\begin{aligned}(1 + 2) * 3 &\rightarrow 3 * 3 \\ &\rightarrow 9\end{aligned}$$

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<sup>1</sup>In practice, this is not the way evaluation is implemented. Rather, a program may be compiled and executed as machine code, or alternatively evaluated by an interpreter using an *abstract machine*. Nevertheless, thinking of evaluation of a functional program as a series of reductions is a good mental model to have when reasoning about its behavior, to a first approximation.

# Evaluation

In general, an expression may also produce some side-effects along the way towards computing a value (even in Haskell).

$$(putStrLn "hi" \gg return ((1 + 2) * 3)) \longrightarrow (1 + 2) * 3 \twoheadrightarrow 9$$

$\downarrow$   
*hi*

So the general shape of evaluation looks like this:

$$expression \xrightarrow{\quad} value$$

$\downarrow$   
*side-effects*



# Evaluation

To make evaluation precise, we need to explain:

- What counts as a value
- How to perform reductions (and execute side-effects, if any)
- *Where* to perform reductions

Such an explanation is called an **evaluation strategy**.

## Evaluation in pure $\lambda$ -calculus (aka normalization)

One rule of reduction ( $\beta$ ):

$$(\lambda x. e_1)(e_2) \rightarrow e_1[e_2/x]$$

Can be performed *anywhere* (i.e., on any matching “redex”).

Value = expression with no redex

The order we perform  $\beta$ -reductions does not matter for the final value (Church-Rosser Theorem), but might make a difference to how quickly we reach a value, and even to whether we reach one.

## Evaluation in pure $\lambda$ -calculus (aka normalization)

A term with two  $\beta$ -redices:

$$\underline{(\lambda x. \lambda y. y)((\lambda z. zz)(\lambda z. zz))}_2 \underline{\quad}_1$$

Two very different reduction paths:

$$\begin{array}{c} (\lambda x. \lambda y. y)((\lambda z. zz)(\lambda z. zz)) \xrightarrow{1} \lambda y. y \\ \downarrow 2 \\ (\lambda x. \lambda y. y)((\lambda z. zz)(\lambda z. zz)) \\ \downarrow 2 \\ \vdots \end{array}$$

## Evaluation in pure $\lambda$ -calculus (aka normalization)

There is a deterministic evaluation strategy that always succeeds to find a  $\beta$ -normal form, if it exists: pick the leftmost redex which is not contained in another redex (“leftmost outermost” reduction).

But this is *not* the evaluation strategy used in Haskell or OCaml...

## Call-by-value<sup>2</sup>

In **call-by-value** (CBV) evaluation, the argument to a function is always reduced to a value before calling the function.

Now, a value can be *any* function (e.g., may contain  $\beta$ -redices), or a constructor applied to some *values*.

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<sup>2</sup>Used by OCaml, Python, C, Java, and many other languages.

## Call-by-value

For example, let  $\text{sqr } x = x * x$  and  $\text{const0 } x = 0$

Under CBV evaluation:

$$\text{sqr } (1 + 2) \rightarrow \text{sqr } 3 \rightarrow 3 * 3 \rightarrow 9$$

$$\text{const0 } (\text{sqr } 3) \rightarrow \text{const0 } (3 * 3) \rightarrow \text{const0 } 9 \rightarrow 0$$

## Call-by-name<sup>3</sup>

In **call-by-name** (CBN) evaluation, the argument to a function is passed as an unevaluated expression (“by name”).

A value is any function, or a constructor applied to *expressions*.

Under CBN evaluation:

$$\text{sqr } (1 + 2) \rightarrow (1 + 2) * (1 + 2) \rightarrow 3 * (1 + 2) \rightarrow 3 * 3 \rightarrow 9$$

$$\text{const0 } (\text{sqr } 3) \rightarrow 0$$

---

<sup>3</sup>Of historical interest (e.g., Algol 60), but *not* used by Haskell...

## CBV vs CBN

“CBV is better”: avoid re-evaluating the argument to a function.

“CBN is better”: avoid evaluating an argument that is unneeded.

How do you decide?





## Call-by-need<sup>4</sup>

In **call-by-need** evaluation, the argument to a function is only evaluated when it is needed, and then stored for later reuse.

Call-by-need is also called *lazy evaluation*.

Roughly, it is implemented by giving names to intermediate computations (“thunks”), and evaluating them on demand.

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<sup>4</sup>Used by Haskell.

## Call-by-need

$sqr\ (1 + 2) \rightarrow \mathbf{let}\ x = 1 + 2\ \mathbf{in}\ sqr\ x$	[introduce thunk]
$\rightarrow \mathbf{let}\ x = 1 + 2\ \mathbf{in}\ x * x$	[apply function]
$\rightarrow \mathbf{let}\ x = 3\ \mathbf{in}\ x * x$	[evaluate thunk]
$\rightarrow \mathbf{let}\ x = 3\ \mathbf{in}\ 3 * 3$	[fetch value]
$\rightarrow \mathbf{let}\ x = 3\ \mathbf{in}\ 9$	[evaluate expression]
$\rightarrow 9$	[garbage collect]

$const0\ (sqr\ 3) \rightarrow \mathbf{let}\ x = sqr\ 3\ \mathbf{in}\ const0\ x$	[introduce thunk]
$\rightarrow \mathbf{let}\ x = sqr\ 3\ \mathbf{in}\ 0$	[apply function]
$\rightarrow 0$	[garbage collect]

## The cost of laziness

Although call-by-need is “better” than CBV or CBN in the sense of performing less evaluation, it comes at a cost:

- The computational cost (time + space) of managing thunks
- The engineering cost of implementing it correctly in a compiler
- The mental cost of reasoning about program performance

Nevertheless, it can be used to write some pretty code!!

# Understanding Fibonacci

Recall the one-liner:

$$fibseq = 0 : 1 : zipWith (+) fibseq (tail fibseq)$$

Why does this work?

# Understanding Fibonacci

We can use the definition

$$\text{fibseq} = 0 : 1 : \text{zipWith } (+) \text{ fibseq } (\text{tail fibseq})$$

to build up a table of values...

<i>fibseq</i>	0	1						
<i>tail fibseq</i>	1							
<i>tail (tail fibseq)</i>								

# Understanding Fibonacci

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<i>fibseq</i>	0	1	1					
<i>tail fibseq</i>	1	1						
<i>tail (tail fibseq)</i>	1							



# Understanding Fibonacci

We can use the definition

$$\text{fibseq} = 0 : 1 : \text{zipWith } (+) \text{ fibseq } (\text{tail fibseq})$$

to build up a table of values...

<i>fibseq</i>	0	1	1					
<i>tail fibseq</i>	1	1						
<i>tail (tail fibseq)</i>	1	2						

# Understanding Fibonacci

We can use the definition

$$\text{fibseq} = 0 : 1 : \text{zipWith } (+) \text{ fibseq } (\text{tail fibseq})$$

to build up a table of values...

<i>fibseq</i>	0	1	1	2				
<i>tail fibseq</i>	1	1	2					
<i>tail (tail fibseq)</i>	1	2						

# Understanding Fibonacci

We can use the definition

$$\text{fibseq} = 0 : 1 : \text{zipWith } (+) \text{ fibseq } (\text{tail fibseq})$$

to build up a table of values...

<i>fibseq</i>	0	1	1	2	3			
<i>tail fibseq</i>	1	1	2	3				
<i>tail (tail fibseq)</i>	1	2	3					

# Understanding Fibonacci

We can use the definition

$$\text{fibseq} = 0 : 1 : \text{zipWith } (+) \text{ fibseq } (\text{tail fibseq})$$

to build up a table of values...

<i>fibseq</i>	0	1	1	2	3	5	8	...
<i>tail fibseq</i>	1	1	2	3	5	8		
<i>tail (tail fibseq)</i>	1	2	3	5	8			

## Now in GHCi

Using the “:sprint” command to inspect a lazy value...

```
ghci> :sprint fibseq
```

```
fibseq = _
```

```
ghci> fib 3
```

```
2
```

```
ghci> :sprint fibseq
```

```
fibseq = 0 : 1 : 1 : 2 : _
```

```
ghci> fib 7
```

```
13
```

```
ghci> :sprint fibseq
```

```
fibseq = 0 : 1 : 1 : 2 : 3 : 5 : 8 : 13 : _
```

## Even and odd numbers, v1

```
nats, evens, odds :: [Integer]  
nats = [0..]  
evens = map (*2) nats  
odds = map (+1) evens
```

## Even and odd numbers, v1

```
ghci> :sprint nats
nats = _
ghci> :sprint odds
odds = _
ghci> take 5 odds
[1,3,5,7,9]
ghci> :sprint nats
nats = 0 : 1 : 2 : 3 : 4 : _
```

## Even and odd numbers, v2

```
nats', evens', odds' :: [Integer]  
evens' = 0 : map (+1) odds'  
odds' = map (+1) evens'  
nats' = interleave evens' odds'  
  where interleave (x : xs) ys = x : interleave ys xs
```



## Even and odd numbers, v2

```
ghci> :sprint nats'
nats' = _
ghci> take 5 nats'
[0,1,2,3,4]
ghci> :sprint evens'
evens' = 0 : 2 : 4 : _
ghci> :sprint odds'
odds' = 1 : 3 : _
```

## Even and odd numbers, v3

*everyOther* :: [a] → [a]  
*everyOther* (x : y : xs) = x : *everyOther* xs  
*evens''*, *odds''* :: [Integer]  
*evens''* = *everyOther* nats  
*odds''* = *everyOther* (tail nats)

## Even and odd numbers, v3

```
ghci> :sprint nats
nats = 0 : 1 : 2 : 3 : 4 : _
ghci> take 5 odds''
[1,3,5,7,9]
ghci> :sprint nats
nats = 0 : 1 : 2 : 3 : 4 : 5 : 6 : 7 : 8 : 9 : 10 : _
```

## Another version of Fibonacci

Another one-liner:

$$\text{fibseq} = \text{map fst} \$ \text{iterate } (\backslash(a, b) \rightarrow (b, a + b)) (0, 1)$$

where *iterate* is defined in the Prelude:

$$\begin{aligned} \text{iterate} &:: (a \rightarrow a) \rightarrow a \rightarrow [a] \\ \text{iterate } f \ x &= x : \text{iterate } f \ (f \ x) \end{aligned}$$

i.e., *iterate* *f* *x* (lazily) builds the infinite list  $[x, f \ x, f \ (f \ x), \dots]$ .

## Computational duality

Back in Lecture 1, we saw how to define data types by their constructors, and how to define functions over such types by pattern-matching against those possible constructors.

But there is also a dual way of defining a type by its *destructors*.

A value of such a type<sup>5</sup> can then be defined by matching against those possible destructors.

Category theory is good at making such definitions...

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<sup>5</sup>Sometimes called a “codata” type or a “negative” type.

## Products, in category theory

The product of objects  $A$  and  $B$  is an object  $A \times B$  with arrows

$$A \xleftarrow{\pi_1} A \times B \xrightarrow{\pi_2} B$$

such that for any other pair of arrows

$$A \xleftarrow{f} C \xrightarrow{g} B$$

there is a unique arrow making the diagram below “commute”:

A commutative diagram illustrating the universal property of the product. At the top, the sequence of objects and arrows is  $A \xleftarrow{\pi_1} A \times B \xrightarrow{\pi_2} B$ . Below this, the object  $C$  is positioned. A solid arrow labeled  $f$  points from  $C$  to  $A$ , and another solid arrow labeled  $g$  points from  $C$  to  $B$ . A dashed arrow labeled  $h$  points from  $C$  up to the object  $A \times B$  in the top sequence.

## Translating the category theory to Haskell?

Given  $f :: c \rightarrow a$  and  $g :: c \rightarrow b$ , we could hope to define

$$\begin{aligned}h &:: c \rightarrow (a, b) \\fst\ (h\ x) &= f\ x \\snd\ (h\ x) &= g\ x\end{aligned}$$

but unfortunately this is not (currently) legal Haskell syntax.<sup>6</sup>

Still, this “observational” perspective is good to keep in mind.

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<sup>6</sup>Although it should be! For example, Agda supports copattern-matching. For more on the theoretical foundations for copattern-matching, see the paper “Copatterns: Programming Infinite Structures by Observations” by Abel et al.

## Redefining lists, observationally

We can think of an infinite list as defined by its behavior against the destructors  $head :: [a] \rightarrow a$  and  $tail :: [a] \rightarrow [a]$ .

For example, the following (legal Haskell) definition

$$ones = 1 : ones$$

can be thought of as defining a value by the equations

$$\begin{aligned} head\ ones &= 1 \\ tail\ ones &= ones \end{aligned}$$



## Redefining lists, observationally

The reason we can manipulate infinite values in computations is because any given *observation* is finite.

$$\text{head ones} = 1$$

$$\text{head (tail (tail ones))} = \text{head (tail ones)} = \text{head ones} = 1$$

## Record syntax

Although Haskell does not have copattern-matching, it does have record types equipped with named fields.

```
data Stream a = Stream { hd :: a, tl :: Stream a }  
oneS :: Stream Integer  
oneS = Stream { hd = 1, tl = oneS }
```

```
ghci> hd (tl (tl oneS))  
1
```

# Overcoming laziness

Sometimes laziness gets in the way in Haskell. There are a few techniques for working around it:

- the *seq* operator to force evaluation
- strictness annotations for non-lazy data types
- monads (or CPS) to ensure lazy computations happen in a certain order

## But first a puzzle...

Suppose we define  $minimum = head \circ sort$ .

What is the complexity of computing  $minimum\ xs$ ?

## The *seq* operator

Takes two arguments and returns the second

$$seq :: a \rightarrow b \rightarrow b$$

but forces evaluation of the first argument.

```
ghci> seq "hello" 42  
42
```

```
ghci> seq (ack 4 3) (1+1)  
C-c C-cInterrupted.
```

## Strictness annotations

```
data StrictList a = Nil | Cons !a !(StrictList a)
  deriving (Show, Eq)
toSL :: [a] → StrictList a
toSL [] = Nil
toSL (x : xs) = Cons x (toSL xs)
nullSL :: StrictList a → Bool
nullSL Nil = True
nullSL _ = False
```

## Strictness annotations

```
ghci> xs = take 5 fibseq
ghci> null xs
False
ghci> :sprint xs
xs = 0 : _
ghci> ys = toSL (take 5 fibseq)
ghci> nullSL ys
False
ghci> :sprint ys
ys = Cons 0 (Cons 1 (Cons 1 (Cons 2 (Cons 3 Nil))))
ghci> toSL fibseq
C-c C-cInterrupted.
```

# Summary

Key points from today:

- An *evaluation strategy* is a plan for reducing expressions to values (and performing any side-effects present)
- Different languages use different evaluation strategies
- Haskell uses *call-by-need* (a.k.a. “lazy”) evaluation, meaning function arguments are only evaluated when they are needed
- Laziness can sometimes yield significant performance gains, and enables finite representations of infinite values
- But laziness comes at a cost (compiler + runtime + brain)