

On learning statistical mixtures maximizing the complete likelihood

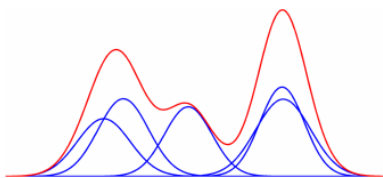
The k -MLE methodology using geometric hard clustering

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Finite mixtures: Semi-parametric statistical models



- ▶ Mixture $M \sim \text{MM}(W, \Lambda)$ with density

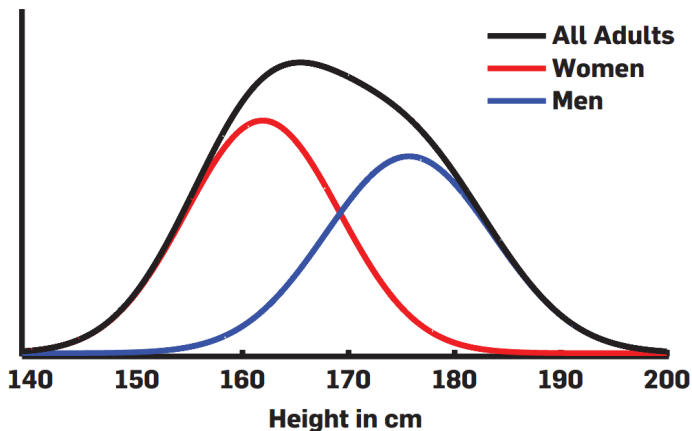
$$m(x) = \sum_{i=1}^k w_i p(x|\lambda_i)$$

not sum of RVs!. $\Lambda = \{\lambda_i\}_i$, $W = \{w_i\}_i$

- ▶ Multimodal, universally modeling smooth densities
- ▶ Gaussian MMs with support $\mathcal{X} = \mathbb{R}$, Gamma MMs with support $\mathcal{X} = \mathbb{R}^+$ (modeling distances [34])
- ▶ Pioneered by Karl Pearson [29] (1894). precursors: Francis Galton [13] (1869), Adolphe Quetelet [31] (1846), etc.
- ▶ Capture **sub-populations** within an overall population ($k = 2$, crab data [29] in Pearson)

Example of $k = 2$ -component mixture [17]

Sub-populations ($k = 2$) within an overall population...



Sub-species in species, etc.

Truncated distributions (what is the support! black swans ?!)

Sampling from mixtures: Doubly stochastic process

To sample a variate x from a MM:

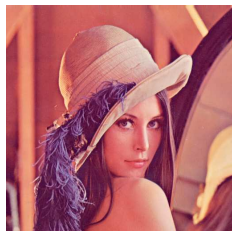
- ▶ Choose a component l according to the weight distribution w_1, \dots, w_k (multinomial),
- ▶ Draw a variate x according to $p(x|\lambda_l)$.

Statistical mixtures: Generative data models

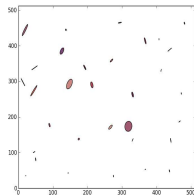
Image = 5D $xyRGB$ point set

GMM = *feature descriptor* for information retrieval (IR)

Increase dimension d using color image $s \times s$ patches: $d = 2 + 3s^2$



Source



GMM



Sample (stat img)

Low-frequency information encoded into compact statistical model.

Mixtures: ϵ -statistically learnable and ϵ -estimates

Problem statement: Given n IID d -dimensional observations $x_1, \dots, x_n \sim \text{MM}(\Lambda, W)$, estimate $\text{MM}(\hat{\Lambda}, \hat{W})$:

- ▶ **Theoretical Computer Science (TCS)** approach: ϵ -closely parameter recovery (π : permutation)
 - ▶ $|w_i - \hat{w}_{\pi(i)}| \leq \epsilon$
 - ▶ $\text{KL}(p(x|\lambda_i) : p(x|\hat{\lambda}_{\pi(i)})) \leq \epsilon$ (or other divergences like TV, etc.)

Consider ϵ -learnable MMs:

- ▶ $\min_i w_i \geq \epsilon$
- ▶ $\text{KL}(p(x|\lambda_i) : p(x|\lambda_j)) \geq \epsilon, \forall i \neq j$ (or other divergence)
- ▶ **Statistical approach:**
Define the **best** model/MM as the one maximizing the *likelihood function* $l(\Lambda, W) = \prod_i m(x_i|\Lambda, W)$.

Mixture inference: Incomplete versus complete likelihood

- ▶ Sub-populations within an overall population: observed data x_i *does not* include the subpopulation label l_i
- ▶ $k = 2$: Classification and Bayes error (upper bounded by Chernoff information [24])
- ▶ Inference: Assume IID, maximize (log)-likelihood:
 - ▶ **Complete** using **indicator variables** $z_{i,j}$ (for l_i : $z_{i,l_i} = 1$):

$$l_c = \log \prod_{i=1}^n \prod_{j=1}^k (w_j p(x_i | \theta_j))^{z_{i,j}} = \sum_i \sum_j z_{i,j} \log(w_j p(x_i | \theta_j))$$

- ▶ **Incomplete** (hidden/latent variables) and *log-sum intractability*:

$$l_i = \log \prod_i m(x_i | W, \Lambda) = \sum_i \log \left(\sum_j w_j p(x_i | \theta_j) \right)$$

Mixture learnability and inference algorithms

- ▶ **Which criterion to maximize? incomplete or complete likelihood? What kind of evaluation criteria?**
- ▶ From Expectation-Maximization [8] (1977) to *TCS methods*: Polynomial learnability of mixtures [22, 15] (2014), mixtures and core-sets [10] for massive data sets, etc.

Some technicalities:

- ▶ Many local maxima of *likelihood functions* l_i and l_c (EM converges locally and *needs* a stopping criterion)
- ▶ Multimodal density ($\#modes > k$ [9], *ghost modes* even for isotropic GMMs)
- ▶ Identifiability (permutation of labels, parameter distinctness)
- ▶ Irregularity: Fisher information may be zero [6], convergence speed of EM
- ▶ etc.

Learning MMs: A geometric hard clustering viewpoint

$$\begin{aligned}\max_{W, \Lambda} l_c(W, \Lambda) &= \max_{\Lambda} \sum_{i=1}^n \max_{j=1}^k \log(w_j p(x_i | \theta_j)) \\ &\equiv \min_{W, \Lambda} \sum_i \min_j (-\log p(x_i | \theta_j) - \log w_j) \\ &= \boxed{\min_{W, \Lambda} \sum_{i=1}^n \min_{j=1}^k D_j(x_i)},\end{aligned}$$

where $c_j = (w_j, \theta_j)$ (**cluster prototype**) and $D_j(x_i) = -\log p(x_i | \theta_j) - \log w_j$ are **potential distance-like functions**.

- ▶ Maximizing the complete likelihood amounts to a *geometric hard clustering* [37, 11] for fixed w_j 's (distance $D_j(\cdot)$ depends on cluster prototypes c_j): $\min_{\Lambda} \sum_i \min_j D_j(x_i)$.
- ▶ Related to classification EM [5] (CEM), hard/truncated EM
- ▶ Solution of $\arg \max l_c$ to initialize l_i (optimized by EM)

The k -MLE method: k -means type clustering algorithms

k -MLE:

1. Initialize weight W (in open probability simplex Δ_k)
 2. Solve $\min_{\Lambda} \sum_i \min_j D_j(x_i)$ (**center-based clustering**, W fixed)
 3. Solve $\min_W \sum_i \min_j D_j(x_i)$ (Λ fixed)
 4. Test for convergence and go to step 2) otherwise.
- \Rightarrow group coordinate ascent (ML)/descent (distance) optimization.

k -MLE: Center-based clustering, W fixed

Solve $\min_{\Lambda} \sum_i \min_j D_j(x_i)$

k -means type convergence proof for assignment/relocation:

► **Data assignment:**

$$\forall i, l_i = \arg \max_j w_j p(x|\lambda_j) = \arg \min_j D_j(x_i), \mathcal{C}_j = \{x_i | l_i = j\}$$

► **Center relocation:** $\forall j, \lambda_j = \text{MLE}(\mathcal{C}_j)$

Farthest Maximum Likelihood (FML) Voronoi diagram:

$$\text{Vor}_{\text{FML}}(c_i) = \{x \in \mathcal{X} : w_i p(x|\lambda_i) \geq w_j p(x|\lambda_j), \forall i \neq j\}$$

$$\text{Vor}(c_i) = \{x \in \mathcal{X} : D_i(x) \leq D_j(x), \forall i \neq j\}$$

FML Voronoi \equiv **additively weighted Voronoi** with:

$$D_l(x) = -\log p(x|\lambda_l) - \log w_l$$

k-MLE: Example for mixtures of exponential families

Exponential family:

Component density $p(x|\theta) = \exp(t(x)^\top \theta - F(\theta) + k(x))$ is *log-concave* with:

- ▶ $t(x)$: sufficient statistic in \mathbb{R}^D , D : family order.
- ▶ $k(x)$: auxiliary carrier term (wrt Lebesgue/counting measure)
- ▶ $F(\theta)$: log-normalized, cumulant function, log-partition.

$D_j(x)$ is convex: **Clustering k-means wrt convex “distances”**.

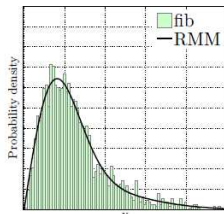
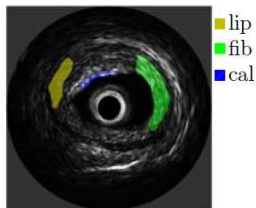
Farthest ML Voronoi \equiv *additively-weighted Bregman Voronoi* [4]:

$$\begin{aligned} -\log p(x; \theta) - \log w &= F(\theta) - t(x)^\top \theta - k(x) - \log w \\ &= B_{F^*}(t(x) : \eta) + F^*(t(x)) + k(x) - \log w \end{aligned}$$

$F^*(\eta) = \max_{\theta} (\theta^\top \eta - F(\theta))$: Legendre-Fenchel convex conjugate

Exponential families: Rayleigh distributions [36, 25]

Application: IntraVascular UltraSound (IVUS) imaging:



Rayleigh distribution:

$$p(x; \lambda) = \frac{x}{\lambda^2} e^{-\frac{x^2}{2\lambda^2}}$$

$$x \in \mathbb{R}^+ = \mathbb{X}$$

$d = 1$ (univariate)

$D = 1$ (order 1)

$$\theta = -\frac{1}{2\lambda^2}$$

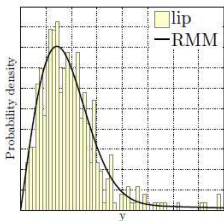
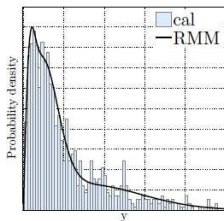
$$\Theta = (-\infty, 0)$$

$$F(\theta) = -\log(-2\theta)$$

$$t(x) = x^2$$

$$k(x) = \log x$$

(Weibull for $k = 2$)



Coronary plaques: fibrotic tissues, calcified tissues, lipidic tissues

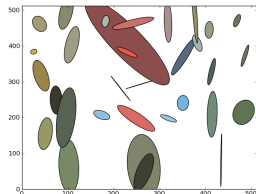
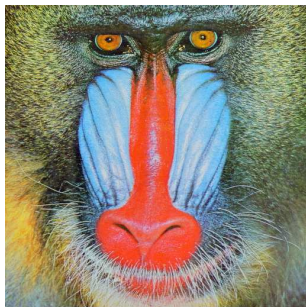
Rayleigh Mixture Models (RMMs):

for *segmentation* and *classification* tasks

Exponential families: Multivariate Gaussians [14, 25]

Gaussian Mixture Models (GMMs).

(Color image interpreted as a $5D$ $xyRGB$ point set)



Gaussian distribution $p(x; \mu, \Sigma)$:

$$\frac{1}{(2\pi)^{\frac{d}{2}} \sqrt{|\Sigma|}} e^{-\frac{1}{2} D_{\Sigma^{-1}}(x-\mu, x-\mu)}$$

Squared Mahalanobis distance:

$$D_Q(x, y) = (x - y)^T Q (x - y)$$

$$x \in \mathbb{R}^d = \mathbb{X}$$

d (multivariate)

$$D = \frac{d(d+3)}{2} \text{ (order)}$$

$$\theta = (\Sigma^{-1} \mu, \frac{1}{2} \Sigma^{-1}) = (\theta_v, \theta_M)$$

$$\Theta = \mathbb{R} \times S_{++}^d$$

$$F(\theta) = \frac{1}{4} \theta_v^T \theta_M^{-1} \theta_v - \frac{1}{2} \log |\theta_M| +$$

$$\frac{d}{2} \log \pi$$

$$t(x) = (x, -xx^T)$$

$$k(x) = 0$$

The k -MLE method for exponential families

k -MLEEF:

1. Initialize weight W (in open probability simplex Δ_k)
2. Solve $\min_{\Lambda} \sum_i \min_j (B_{F^*}(t(x) : \eta_j) - \log w_j)$
3. Solve $\min_W \sum_i \min_j D_j(x_i)$
4. Test for convergence and go to step 2) otherwise.

Assignment condition in Step 2: additively-weighted Bregman Voronoi diagram.

k-MLE: Solving for weights given component parameters

$$\text{Solve } \boxed{\min_W \sum_i \min_j D_j(x_i)}$$

Amounts to $\arg \min_W -n_j \log w_j = \arg \min_W -\frac{n_j}{n} \log w_j$ where $n_j = \#\{x_i \in \text{Vor}(c_j)\} = |C_j|$.

$$\boxed{\min_{W \in \Delta_k} H^\times(N : W)}$$

where $N = (\frac{n_1}{n}, \dots, \frac{n_k}{n})$ is *cluster point proportion vector* $\in \Delta_k$.

Cross-entropy H^\times is minimized when $H^\times(N : W) = H(N)$ that is $W = N$.

Kullback-Leibler divergence:

$$\text{KL}(N : W) = H^\times(N : W) - H(N) = 0 \text{ when } W = N.$$

MLE for exponential families

Given a ML farthest Voronoi partition, computes MLEs θ_j 's:

$$\hat{\theta}_j = \arg \max_{\theta \in \Theta} \prod_{x_i \in \text{Vor}(c_j)} p_F(x_i; \theta)$$

is *unique* (***) maximum since $\nabla^2 F(\theta) \succ 0$:

$$\text{Moment equation : } \nabla F(\hat{\theta}_j) = \eta(\hat{\theta}_j) = \frac{1}{n_j} \sum_{x_i \in \text{Vor}(c_j)} t(x_i) = \bar{t} = \hat{\eta}$$

MLE is *consistent, efficient* with *asymptotic normal distribution*:

$$\hat{\theta}_j \sim N\left(\theta_j, \frac{1}{n_j} I^{-1}(\theta_j)\right)$$

Fisher information matrix

$$I(\theta_j) = \text{var}[t(X)] = \nabla^2 F(\theta_j) = (\nabla^2 F^*)^{-1}(\eta_j)$$

MLE may be biased (eg, normal distributions).

Existence of MLEs for exponential families (***)

For minimal and full EFs, MLE guaranteed to exist [3, 21] provided that matrix:

$$T = \begin{bmatrix} 1 & t_1(x_1) & \dots & t_D(x_1) \\ \vdots & \vdots & \vdots & \vdots \\ 1 & t_1(x_n) & \dots & t_D(x_n) \end{bmatrix} \quad (1)$$

of dimension $n \times (D + 1)$ has *rank* $D + 1$ [3].

For example, problems for MLEs of MVNs with $n < d$ observations (undefined with likelihood ∞).

Condition: $\bar{t} = \frac{1}{n_j} \sum_{x_i \in \text{Vor}(c_j)} t(x_i) \in \text{int}(C)$, where C is *closed convex support*.

MLE of EFs: Observed point in IG/Bregman 1-mean

$$\hat{\theta} = \arg \max_{\theta} \prod_{i=1}^n p_F(x_i; \theta) = \arg \max_{\theta} \sum_{i=1}^n \log p_F(x_i; \theta)$$

$$\begin{aligned} & \operatorname{argmax}_{\theta} \sum_{i=1}^n -B_{F^*}(t(x_i) : \eta) + \underbrace{F^*(t(x_i)) + k(x_i)}_{\text{constant}} \\ & \equiv \operatorname{argmin}_{\theta} \sum_{i=1}^n B_{F^*}(t(x_i) : \boxed{\eta}) \end{aligned}$$

Right-sided *Bregman centroid* = *center of mass*:

$$\boxed{\hat{\eta} = \frac{1}{n} \sum_{i=1}^n t(x_i)}$$

$$\begin{aligned} \bar{l} &= \frac{1}{n} \sum_{i=1}^n (-B_{F^*}(t(x_i) : \hat{\eta}) + F^*(t(x_i)) + k(x_i)) \\ &= \langle \hat{\eta}, \hat{\theta} \rangle - F(\hat{\theta}) + \bar{k} = \boxed{F^*(\hat{\eta}) + \bar{k}} \end{aligned}$$

The k -MLE method: Heuristics based on k -means

k -means is NP-hard (non-convex optimization) when $d > 1$ and $k > 1$ and solved exactly using dynamic programming [26] in $O(n^2k)$ and $O(n)$ memory when $d = 1$.

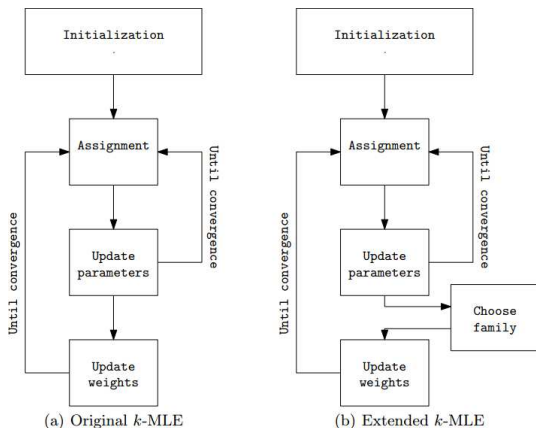
Heuristics:

- ▶ Kanungo et al. [18] swap: yields a $(9 + \epsilon)$ -approximation
- ▶ Global seeds: random seed (Forgy [12]), k -means++ [2], global k -means initialization [38],
- ▶ Local refinements: Lloyd batched update [19], MacQueen iterative update [20], Hartigan single-point swap [16], etc.
- ▶ etc.

Generalized k -MLE

Weibull or generalized Gaussians are *parametric families of exponential families* [35]: $F(\gamma)$.

Fixing some parameters yields *nested families* of (sub)-exponential families [34]: obtain one free parameter with convex conjugate F^* approximated by line search (Gamma distributions/generalized Gaussians).



Generalized k -MLE

k -GMLE:

1. Initialize weight $W \in \Delta_k$ and family type (F_1, \dots, F_k) for each cluster
2. Solve $\min_{\Lambda} \sum_i \min_j D_j(x_i)$ (center-based clustering for W fixed) with potential functions:
$$D_j(x_i) = -\log p_{F_j}(x_i|\theta_j) - \log w_j$$
3. Solve family types maximizing the MLE in each cluster \mathcal{C}_j by choosing the parametric family of distributions $F_j = F(\gamma_j)$ that yields the best likelihood:
$$\min_{F_1=F(\gamma_1), \dots, F_k=F(\gamma_k) \in F(\gamma)} \sum_i \min_j D_{w_j, \theta_j, F_j}(x_i).$$
4. Update W as the cluster point proportion
5. Test for convergence and go to step 2) otherwise.

$$D_{w_j, \theta_j, F_j}(x) = -\log p_{F_j}(x; \theta_j) - \log w_j$$

Generalized k -MLE: Convergence

- ▶ Lloyd's batched generalized k -MLE maximizes **monotonically** the complete likelihood
- ▶ Hartigan single-point relocation generalized k -MLE maximizes **monotonically** the complete likelihood [32], improves over Lloyd local maxima, and avoids the problem of the existence of MLE inside clusters by ensuring $n_j \geq D$ in general position ($T \text{ rank } D + 1$).
- ▶ **Model selection:** Learn k automatically using DP k -means [32] (Dirichlet Process)

k -MLE [23] versus EM for Exponential Families [1]

	k -MLE/Hard EM [23] (2012-) = Bregman hard clustering	Soft EM [1] (1977) = Bregman soft clustering
Memory	lighter $O(n)$	heavier $O(nk)$
Assignment	NNs with VP-trees [27], BB-trees [30]	all k -NNs
Conv.	always finitely	∞ , need stopping criterion

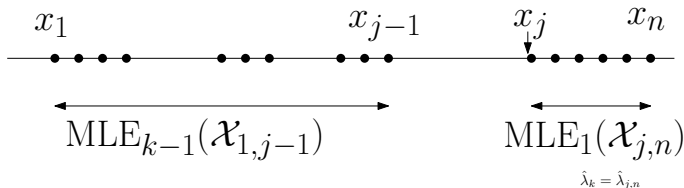
Many (probabilistically) guaranteed initialization for k -MLE [18, 2, 28]

k -MLE: Solving for $D = 1$ exponential families

- ▶ Rayleigh, Poisson or (nested) univariate normal with constant σ are order 1 EFs ($D = 1$).
- ▶ Clustering problem: Dual 1D Bregman clustering [1] on 1D scalars $y_i = t(x_i)$.
- ▶ FML Voronoi diagrams have **connected cells**: Optimal clustering yields *interval clustering*.
- ▶ 1D k -means (with additive weights) can be solved exactly using **dynamic programming** in $O(n^2k)$ time [26]. Then update the weights W (cluster point proportion) and reiterate...

Dynamic programming for $D = 1$ -order mixtures [26]

Consider W fixed. k -MLE cost: $\sum_{j=1}^k l(\mathcal{C}_j)$ where \mathcal{C}_j are clusters.



Dynamic programming optimality equation:

$$\text{MLE}_k(x_1, \dots, x_n) = \max_{j=2}^n (\text{MLE}_{k-1}(\mathcal{X}_{1,j-1}) + \text{MLE}_1(\mathcal{X}_{j,n}))$$

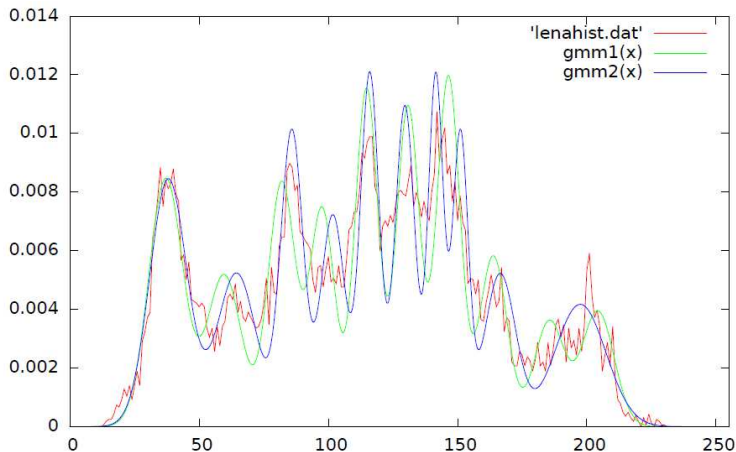
$\mathcal{X}_{l,r} : \{x_l, x_{l+1}, \dots, x_{r-1}, x_r\}$.

- ▶ Build dynamic programming *table* from $l = 1$ to $l = k$ columns, $m = 1$ to $m = n$ rows.
- ▶ Retrieve \mathcal{C}_j from DP table by *backtracking* on the $\arg \max_j$.
- ▶ For $D = 1$ EFs, $O(n^2k)$ time [26].

Experiments with: 1D Gaussian Mixture Models (GMMs)

gmm_1 score = -3.075 (Euclidean k -means, σ fixed)

gmm_2 score = -3.038 (Bregman k -means, σ fitted, better)



Summary: k -MLE methodology for learning mixtures

Learn MMs from sequences of **geometric hard clustering** [11].

- ▶ Hard k -MLE (\equiv dual Bregman hard clustering for EFs) versus soft EM (\equiv soft Bregman clustering [1] for EFs):
 - ▶ k -MLE maximizes the **complete likelihood** l_c .
 - ▶ EM maximizes locally the **incomplete likelihood** l_i .
- ▶ The component parameters η geometric clustering (Step 2.) can be implemented using **any** Bregman k -means heuristic on conjugate F^*
- ▶ Consider *generalized k -MLE* when F^* not available in closed form: nested exponential families (eg., Gamma)
- ▶ Initialization can be performed using k -means initialization: k -MLE++, etc.
- ▶ Exact solution with dynamic programming for order 1 EFs (with prescribed weight proportion W).
- ▶ Avoid **unbounded likelihood** (eg., ∞ for location-scale member with $\sigma \rightarrow 0$: Dirac) using Hartigan's heuristic [32]

Discussion: Learning statistical models FAST!

- ▶ (EF) Mixture Models allow one to approximate universally smooth densities
- ▶ A single (multimodal) EF can approximate any smooth density too [7] but F not in closed-form
- ▶ Which criterion to maximize is best/realistic: incomplete or complete, or parameter distortions? **Leverage** many recent results on k -means clustering to learning mixture models.
- ▶ Alternative approach: Simplifying mixtures from kernel density estimators (KDEs) is one **fine-to-coarse** solution [33]
- ▶ *Open problem*: How to constrain the MMs to have a prescribed number of modes/antimodes?

Thank you.

Experiments and performance evaluations on generalized k -MLE:

- ▶ k -GMLE for generalized Gaussians [35]
- ▶ k -GMLE for Gamma distributions [34]
- ▶ k -GMLE for singly-parametric distributions [26]

(compared with Expectation-Maximization [8])

Frank Nielsen (5793b870).

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