# Bag-of-components: an online algorithm for batch learning of mixture models

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## Exponential families

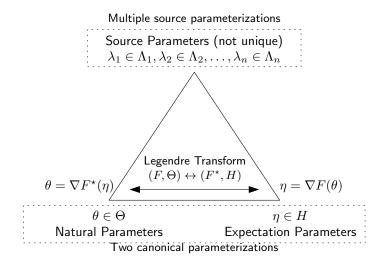
## Exponential families

#### Definition

$$p(x; \lambda) = p_F(x; \theta) = \exp(\langle t(x) | \theta \rangle - F(\theta) + k(x))$$

- $\blacktriangleright$   $\lambda$  source parameter
- t(x) sufficient statistic
- $\triangleright$   $\theta$  natural parameter
- $\blacktriangleright$   $F(\theta)$  log-normalizer
- $\blacktriangleright$  k(x) carrier measure
- F is a stricly convex and differentiable function  $\langle \cdot | \cdot \rangle$  is a scalar product

#### Multiple parameterizations: dual parameter spaces



## Bregman divergences

Definition and properties

$$B_F(x||y) = F(x) - F(y) - \langle x - y, \nabla F(y) \rangle$$

- ► F is a stricly convex and differentiable function
- No symmetry!

#### Contains a lot of common divergences

 Squared Euclidean, Mahalanobis, Kullback-Leibler, Itakura-Saito...

Exponential families Bregman divergences Mixture models

## Bregman centroids

Left-sided centroid

Right-sided centroid

$$\min_{c}\sum_{i}\omega_{i}B_{F}(c\|x_{i})$$

$$\min_{c}\sum_{i}\omega_{i}B_{F}\left(x_{i}\|c\right)$$

Closed-form

$$c^{L} = \nabla F^{*}\left(\sum_{i} \omega_{i} \nabla F(x_{i})\right)$$

$$c^R = \sum_i \omega_i x_i$$

Exponential families Bregman divergences Mixture models

## Link with exponential families [Banerjee 2005]

Bijection with exponential families

$$\log p_F(x|\theta) = -B_{F^*}\left(t(x)\|\eta\right) + F^*(t(x)) + k(x)$$

#### Kullback-Leibler between exponential families

between members of the same exponential family

$$\mathsf{KL}(\mathsf{p}_{\mathsf{F}}(x,\theta_1),\mathsf{p}_{\mathsf{F}}(x,\theta_2))=\mathsf{B}_{\mathsf{F}}(\theta_2\|\theta_1)=\mathsf{B}_{\mathsf{F}^\star}(\eta_1\|\eta_2)$$

#### Kullback-Leibler centroids

In closed-form through the Bregman divergence

Exponential families Bregman divergences Mixture models

## Maximum likelihood estimator

#### A Bregman centroid

$$\hat{\eta} = \arg \max_{\eta} \sum_{i} \log p_{F}(x_{i}, \eta)$$

$$= \arg \min_{\eta} \sum_{i} B_{F^{*}}(t(x_{i}) || \eta) \underbrace{-F^{*}(t(x_{i})) - k(x_{i})}_{\text{does not depend on } \eta}$$

$$= \arg \min_{\eta} \sum_{i} B_{F^{*}}(t(x_{i}) || \eta)$$

$$= \sum_{i} t(x_{i})$$

And  $\hat{\theta} = \nabla F^{\star}(\hat{\eta})$ 

#### Exponential families Bregman divergence Mixture models

## Mixtures of exponential families

$$m(x; \omega, \theta) = \sum_{1 \le i \le k} \omega_i p_F(x; \theta_i)$$

#### Fixed

- Family of the components P<sub>F</sub>
- Number of components k (model selection techniques to choose)

#### Learning a mixture

- ▶ Input: observations *x*<sub>1</sub>,...,*x*<sub>N</sub>
- Output:  $\omega_i$  and  $\theta_i$

#### Parameters

- Weights  $\sum_i \omega_i = 1$
- Component parameters  $\theta_i$

## Bregman Soft Clustering: EM for exponential families [Banerjee 2005]

E-step

$$p(i,j) = rac{\omega_j p_F(x_i, heta_j)}{m(x_i)}$$

M-step

$$\eta_{j} = \arg \max_{\eta} \sum_{i} p(i,j) \log p_{F}(x_{i},\theta_{j})$$

$$= \arg \min_{\eta} \sum_{i} p(i,j) \left( B_{F^{*}}(t(x_{i}) \| \eta) \underbrace{-F^{*}(t(x_{i})) - k(x_{i})}_{\text{does not depend on } \eta} \right)$$

$$= \sum_{i} \frac{p(i,j)}{\sum_{u} p(u,j)} t(x_{u})$$

## Joint estimation of mixture models

#### Exploit shared information between multiple pointsets

- to improve quality
- to improve speed

#### Inspiration

- Dictionary methods
- Transfer learning

#### Efficient algorithms

- Building
- Comparing

## Co-Mixtures

#### Sharing components of all the mixtures

$$m_1(x|\omega^{(1)},\eta) = \sum_{i=1}^k \omega_i^{(1)} p_F(x|\eta_j)$$
  
...  
$$m_S(x|\omega^{(S)},\eta) = \sum_{i=1}^k \omega_i^{(S)} p_F(x|\eta_j)$$

- Same  $\eta_1 \ldots \eta_k$  everywhere
- Different weights  $\omega^{(I)}$

Motivation Algorithms Applications

## co-Expectation-Maximization

Maximize the mean of the likelihoods on each mixtures

- E-step
  - A posterior matrix for each dataset

$$p^{(I)}(i,j) = rac{\omega_j^{(I)} p_F(x_i, heta_j)}{m(x_i^{(I)} | \omega^{(I)}, \eta)}$$

M-step

Maximization on each dataset

$$\eta_j^{(l)} = \sum_i \frac{p(i,j)}{\sum_u p^{(l)}(u,j)} t(x_u^{(l)})$$

Aggregation

$$\eta_j = \frac{1}{S} \sum_{l=1}^S \eta_j^{(l)}$$

## Variational approximation of Kullback-Leibler [Hershey Olsen 2007]

$$\widetilde{\mathrm{KL}}_{\mathrm{Variationnal}}(m_1, m_2) = \sum_{i=1}^{K} \omega_i^{(1)} \log \frac{\sum_j \omega_j^{(1)} e^{-\mathrm{KL}(p_F(\cdot; \theta_i) \| p_F(\cdot; \theta_j))}}{\sum_j \omega_j^{(2)} e^{-\mathrm{KL}(p_F(\cdot; \theta_i) \| p_F(\cdot; \theta_j))}}$$

#### With shared parameters

• Precompute 
$$D_{ij} = e^{-\mathrm{KL}(p_F(\cdot|\eta_i), p_F(\cdot|\eta_j))}$$

#### Fast version

$$\operatorname{KL}_{\mathsf{var}}(m_1 \| m_2) = \sum_i \omega_i^{(1)} \log \frac{\sum_j \omega_j^{(1)} e^{-D_{ij}}}{\sum_j \omega_j^{(2)} e^{-D_{ij}}}$$

Information Geometry for mixtures Co-Mixture Models Applications

## co-Segmentation

#### Segmentation from 5D RGBxy mixtures



Co-EM

## Transfer learning

Increase the quality of one particular mixture of interest

- ▶ First image: only 1% of the points
- Two other images: full set of points



Not enough points for EM

## Bag of Components

#### Training step

- Comix on some training set
- Keep the parameters
- Costly but offline

$$\mathcal{D} = \{\theta_1, \ldots, \theta_K\}$$

#### Online learning of mixtures

- For a new pointset
- For each observation arriving:

$$rg\max_{ heta\in\mathcal{D}}p_{\mathcal{F}}(x_j, heta) \quad ext{ or } \quad rg\min_{ heta\in\mathcal{D}}B_{\mathcal{F}}(t(x_j), heta)$$

## Nearest neighbor search

#### Naive version

- Linear search
- ► O(number of samples × number of components)
- Same order of magnitude as one step of EM

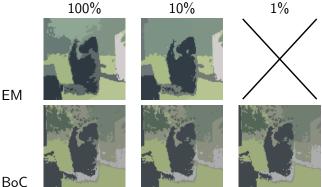
#### Improvement

- Computational Bregman Geometry to speed-up the search
- Bregman Ball Trees
- Hierarchical clustering
- Approximate nearest neighbor

#### Experiments

## Image segmentation

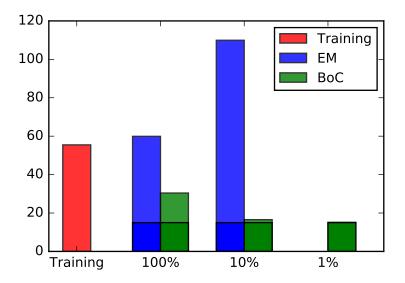
#### Segmentation on a random subset of the pixels



BoC

Algorithm Experiments

## Computation times



## Summary

#### Comix

- Mixtures with shared components
- Compact description of a lot of mixtures
- Fast KL approximations
- Dictionary-like methods

### Bag of Components

- Online method
- Predictable time (no iteration)
- Works with only a few points
- Fast