# Exact ensemble properties in combinatorial dynamic programming schemes

Yann Ponty Cédric Saule

École Polytechnique/CNRS/INRIA AMIB - France

#### Optimization problem=

- Search space S
- Objective function f

Problem: Find element  $e \in S$  which min(max)-imizes f(s)?

Dynamic programming scheme relates the minimal value of f to its minimal value(s) on some *smaller* search space(s) (Substructure property).

DP scheme = Efficient factorization (traversal) of S. Alt.: DP scheme is generating search space. In order to say something general, let us be specific...

#### Definition (Combinatorial DP)

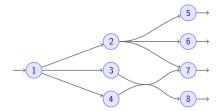
A combinatorial DP scheme computes functions that are locally additive and relies on a decomposition that is:

- Unambiguous: Each solution generated at most once!
- Complete: Each solution generated at least once!

Based on this property, DP schemes for optimization readily translate into *DP* schemes for counting, generating... Remark: None of this above is strictly required by DP!

What is a decomposition?

### Hypergraphs as decompositions



Hypergaphs generalize directed graphs to arcs of arbitrary in/out degrees.

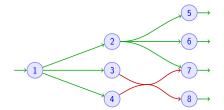
#### Definition (Hypergraph)

A directed hypergaph  $\mathcal{H}$  is a couple (V, E) such that:

- V is a set of vertices
- E is a set of hyperarcs  $e = (t(e) \rightarrow h(e))$  such that  $t(e), h(e) \subset E$

Forward hypergraphs, or F-graphs, are hypergraphs whose arcs have ingoing degree exactly 1.

### Hypergraphs as decompositions



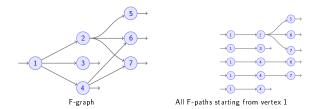
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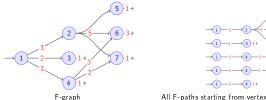
A F-path is a tree having root  $s \in V$ , whose children are F-paths built from the outgoing vertices of some arc  $e = (s \rightarrow t) \in E$ .

Remark: Vertices of out degree 0 ( $t = \emptyset$ ) provide an elegant terminal case to the above recursive definition.

F-graph is independent iff each F-path sees at most once each arc.

A numerical valued-fonction  $\pi: E \to \mathbb{R}$  can be assigned to each arc:

- Weight of a path is the product of its arcs' values
- Score of a path is the sum of its arcs' values

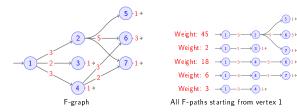




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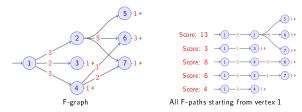
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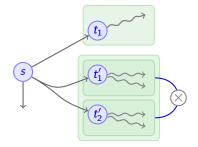
 $\mathcal{H} = (s_0, V, E, \pi)$ : acyclic F-graph  $s_0$ : Init. node  $\pi$ : value fun.

$$m_{s} = \min_{e=(s \to t)} \left( w(e) + \sum_{u \in t} m_{u} \right)$$

Problem	Recurrence	Complexities time/space
Min score	$m_{s} = \min_{e=(s \to t)} \left( w(e) + \sum_{u \in t} m_{u} \right)$	$\Theta( E + V )/\Theta( V )$
Num. paths	$n_s = \sum \prod n_u$	$\Theta( E + V )/\Theta( V )$
Total weight	$w_s = \sum_{e=(s \to t)}^{(s \to t)^{u \in t}} w(e) \cdot \prod_{s' \in t} w_{s'}$	$\Theta( E + V )/\Theta( V )$

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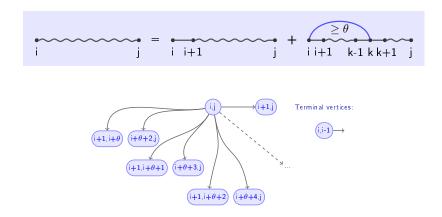


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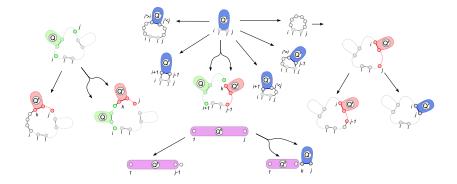
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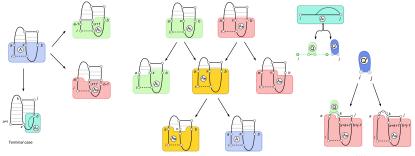


This decomposition is unambiguous! (Proof may use length generating functions).

## Mfold/Unafold decomposition

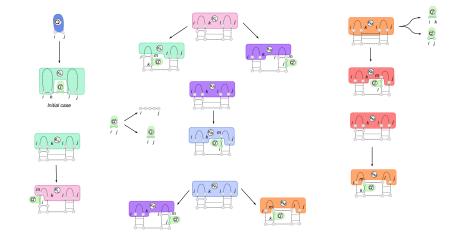


# Akutsu's simple pseudoknots



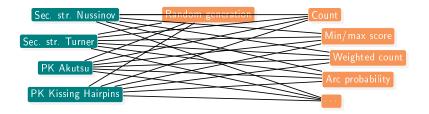
Initial cases

## Kissing hairpins



#### Message #1

Applications of DP could (and should) be detached from the equation, and be expressed at an abstract – combinatorial – level.

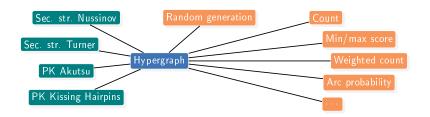


Credits: Roytberg and Finkelstein for Hypergraph DP in Bioinformatics, L. Hwang for algebraic hypergraph DP, R. Giegerich for ADP...

Let us extend applications of DP.

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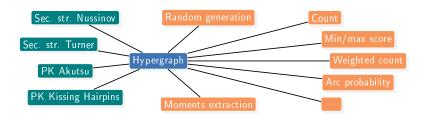


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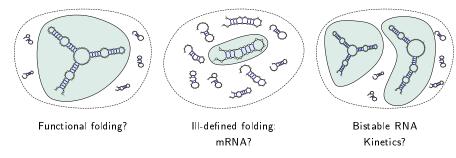
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Let us extend applications of DP....

## Distribution of solutions



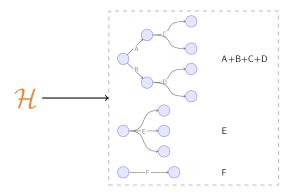
- An acyclic F-graph H = (s<sub>0</sub>, V, E, π), defining a search space T the set of F-paths (trees) in H.
- Feature functions  $\alpha_1, \ldots, \alpha_k : E \to \mathbb{R}$  extended **additively** on  $\mathcal{T}$ .

What can we say about the distribution(s) of  $\alpha_i(s)$ ?

Naive approach: Compute the distribution exactly, accessible values being choices of  $\mathcal{O}(n)$  values among |E|, n = #arcs in largest F-path.  $\Rightarrow$  DP count the #ways of accessing each value in exponential time...

## Example: Mean value of a feature function

What is the average values of  $\alpha$  assuming a uniform distribution on  $\mathcal{T}$ ?

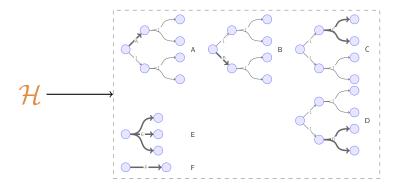


Mean value = Weighted sum = 
$$rac{\sum_{t \in \mathcal{T}} lpha(t)}{|\mathcal{T}|}$$

Remark: Dropping the terminal edges (Alt.  $\alpha(e) = 0$ )...

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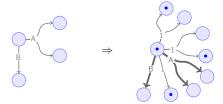


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## Principle and main equation

By introducing a controlled ambiguity, one can extract the feature expectation from a combinatorial DP scheme.

Idea: Passing a dot  $\bullet$  along or drop it ( $\equiv \alpha(e)$ ) on some arc e.



$$\Rightarrow c_s^{\bullet_\alpha} = \sum_{o \in \mathcal{T}} \alpha(o) = \sum_{e=(s \to t)} \left( \alpha(e) \cdot \prod_{t_i \in t} c_{t_i} + \sum_{t_i \in t} c_{t_i}^{\bullet_\alpha} \prod_{t_j \neq t_i \in t} c_{t_j} \right)$$

 $\Rightarrow \mathbb{E}(\alpha) := c_{s_0}^{\bullet_\alpha}/c_{s_0} \text{ obtained in } \Theta(|V| + |E| \cdot D^2) / \Theta(|V|) \text{ time/space,}$  with  $D := \max_{e \in E}(|h(e)|)$ 

Remark: Similar to the *folklore* pointing operator in enumerative combinatorics, and to the formal derivative.

## Low-hanging fruits

- $D: \max_{e \in E}(|h(e)|)$ 
  - Boltzmann-like distribution

Unconvinced by the uniform distribution? Got an energy fonction  $\Delta: E \to \mathbb{R}$  extended additively, and a good reason to expect convergence toward a Boltzmann distribution  $e^{\frac{-\Delta}{kT}}$ ? (We do...)  $\Rightarrow$  Expectation in the Boltzmann distribution is just a weight away.

$$c_{s}^{\bullet \alpha} = \sum_{o \in \mathcal{T}} \alpha(o) \cdot e^{-\Delta(o)/RT}$$
$$= \sum_{e=(s \to \mathbf{t})} e^{\frac{-\Delta(e)}{kT}} \left( \alpha(e) \cdot \prod_{t_{i} \in \mathbf{t}} c_{t_{i}} + \sum_{t_{i} \in \mathbf{t}} c_{t_{i}}^{\bullet \alpha} \prod_{t_{j} \neq t_{i} \in \mathbf{t}} c_{t_{j}} \right)$$

 $\Rightarrow \Theta(|V| + |E| \cdot D^2) / \Theta(|V|)$ 

- Higher-order moments
- Exact correlations

Nb: Specializes into Miklos et al 2005 for RNA secondary structures.

## Low-hanging fruits

- $D: \max_{e \in E}(|h(e)|)$ 
  - Boltzmann-like distribution  $\Rightarrow \Theta(|V| + |E| \cdot D^2) / \Theta(|V|)$
  - Higher-order moments

Want to go beyond the expected value of  $\alpha$ ? No problem (almost), compute higher-order moments.

$$c_{s}^{\bullet_{\alpha}^{m}} = \sum_{o \in \mathcal{T}} \alpha(o)^{m} \cdot e^{-\Delta(o)/RT}$$
$$= \sum_{e=(s \to t)} e^{\frac{-\Delta(e)}{kT}} \left( \sum_{\substack{(m'_{1}, \cdots, m'_{|t|}) \\ \text{s.t.} \sum m'_{i} := m' \le m}} \alpha(e)^{m-m'} \prod_{t_{i} \in t} c_{t_{i}}^{\bullet_{\alpha}^{m'_{i}}} \right)$$

 $\Rightarrow \Theta(|V| + |E| \cdot m^{D+2}) / \Theta(m \cdot |V|)$ 

• Exact correlations

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# Low-hanging fruits

- $D: \max_{e \in E}(|h(e)|)$ 
  - Boltzmann-like distribution  $\Rightarrow \Theta(|V| + |E| \cdot D^2) / \Theta(|V|)$
  - Higher-order moments  $\Rightarrow \Theta(|V| + |E| \cdot m^{D+2}) / \Theta(m \cdot |V|)$
  - Exact correlations Given two lpha and lpha', correlation is given by

$$c_{s}^{\bullet \alpha \bullet \alpha'} = \sum_{o \in \mathcal{T}} \alpha(o) \cdot \alpha'(o) \cdot e^{-\Delta(o)/RT}$$
$$= \sum_{e=(s \to \mathbf{t})} e^{\frac{-\Delta(e)}{k\tau}} \left( \sum_{\substack{((m_{1} \cdot m_{|\mathbf{t}|}), \\ (m'_{1} \cdot m'_{|\mathbf{t}|})) \\ m := \sum m_{i} \leq 1, \\ m' := \sum m'_{i} \leq 1}} \alpha(e)^{1-m} \alpha'(e)^{1-m'} \prod_{t_{i} \in \mathbf{t}} c_{t_{i}}^{\bullet m'_{i} \bullet m'_{i}} \right)$$

 $\Rightarrow \Theta(|V| + |E| \cdot D^2) / \Theta(|V|)$ 

Nb: Specializes into Miklos et al 2005 for RNA secondary structures.

- Many algorithms in Bioinformatics rely on dynamic programming
- Adopting a combinatorial vision over the search space greatly, and hypergraph representations, helped:
  - Prove correctness.
  - Instant transposal of new applications.
- Implementation tricky (avoid explicit representations).
- Use in combination with machine-learning as classifier/scanner for ncRNAs.
- How to transpose usual DP tricks (four-russians, cutting corners, sparsification)?
- Are there even more compact ways to describe more specific search spaces (e.g. CFGs, split-types??)