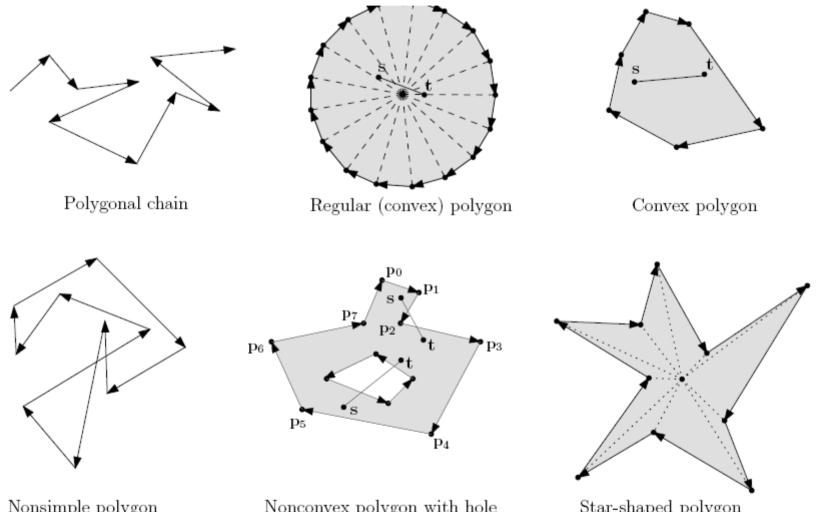


Fundamentals of 3D Lecture 8: Introduction to meshes

Frank Nielsen nielsen@lix.polytechnique.fr

Polygons

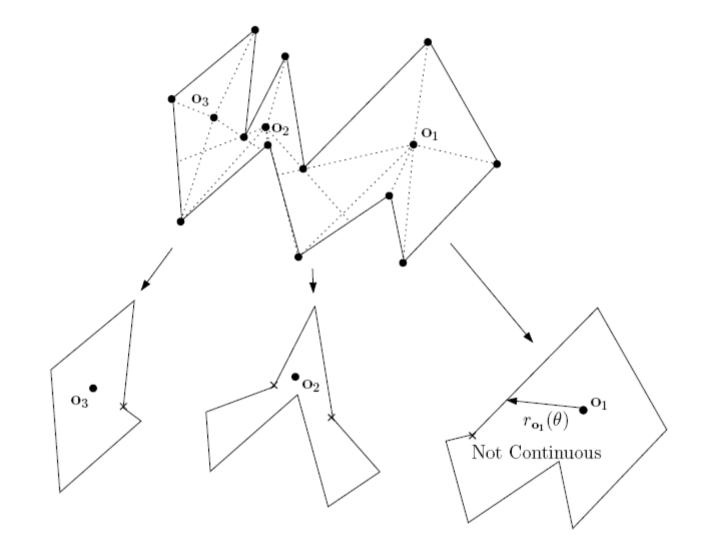


Nonsimple polygon

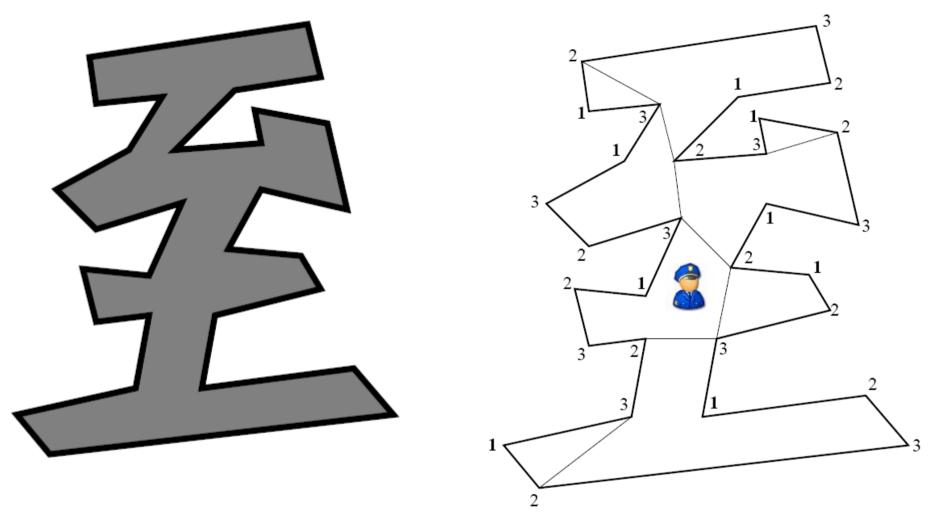
Nonconvex polygon with hole

Star-shaped polygon

Polygons: Star-shaped decomposition

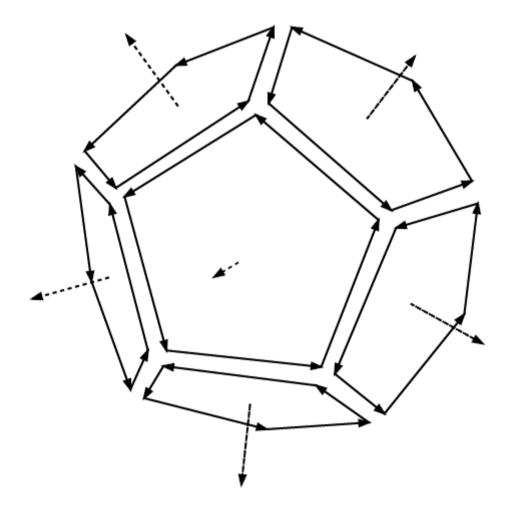


Polygons: Star-shaped decomposition



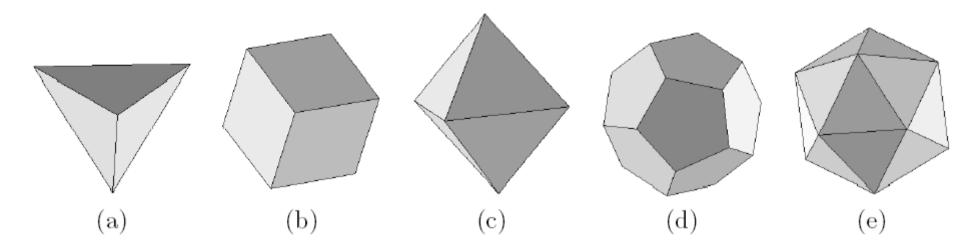
Art gallery, illumination problems, robots'race, etc. Place guards...

Orienting the fact edges for outer normals



Polyhedron, convex polyhedra

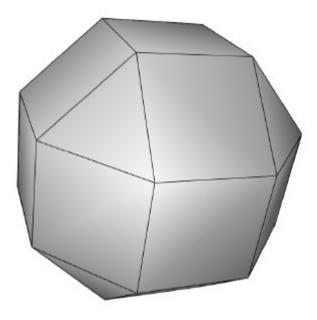
Platonic solids: 5 convex polyhedra

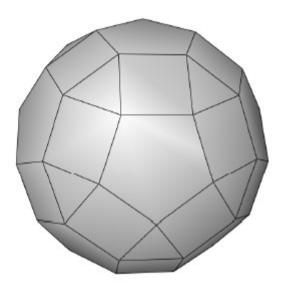


Platonic solid	Schläfli symbol	# Vertices	# Faces	# Edges
Tetrahedron (a)	(3,3)	4	4	6
Hexahedron (b)	(4,3)	8	6	12
Octahedron (c)	(3,4)	6	8	12
Dodecahedron (d)	(5,3)	20	12	30
Icosahedron (e)	(3, 5)	12	20	30

Identical faces

Uniform polyhedra



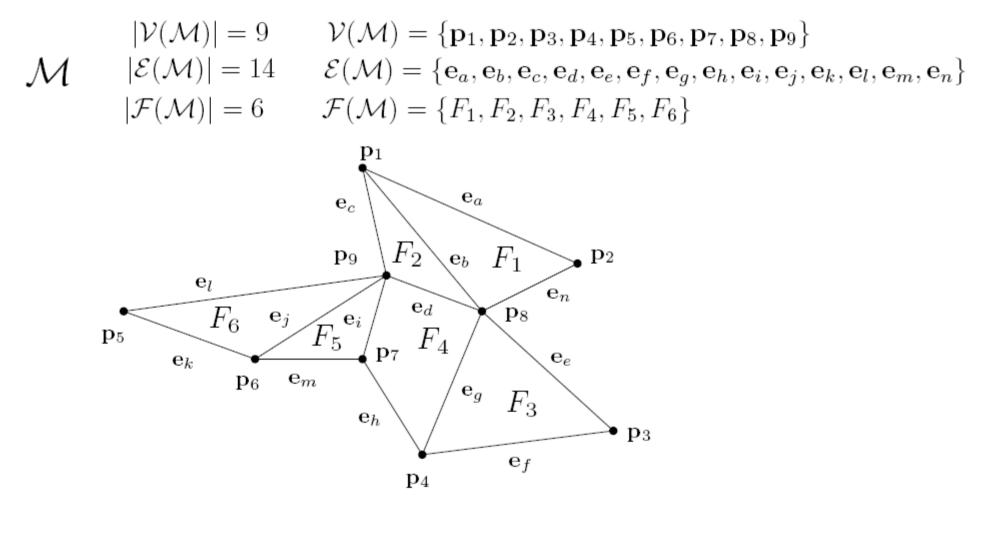


rhombicuboctahedron

rhombicosidodecahedron

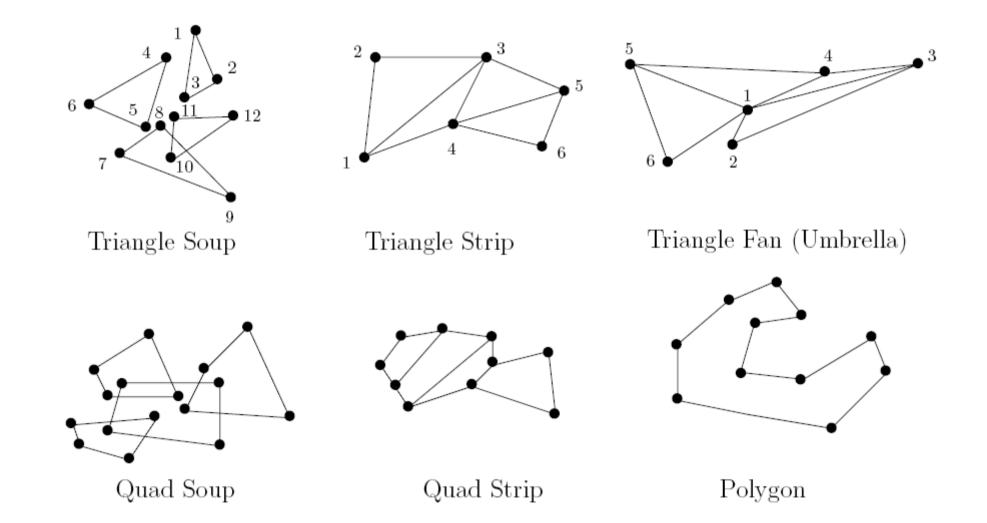
faces=regular polygons (not necessarily the same), isometry mapping of its vertices (=symmetry)

Meshes: Notations

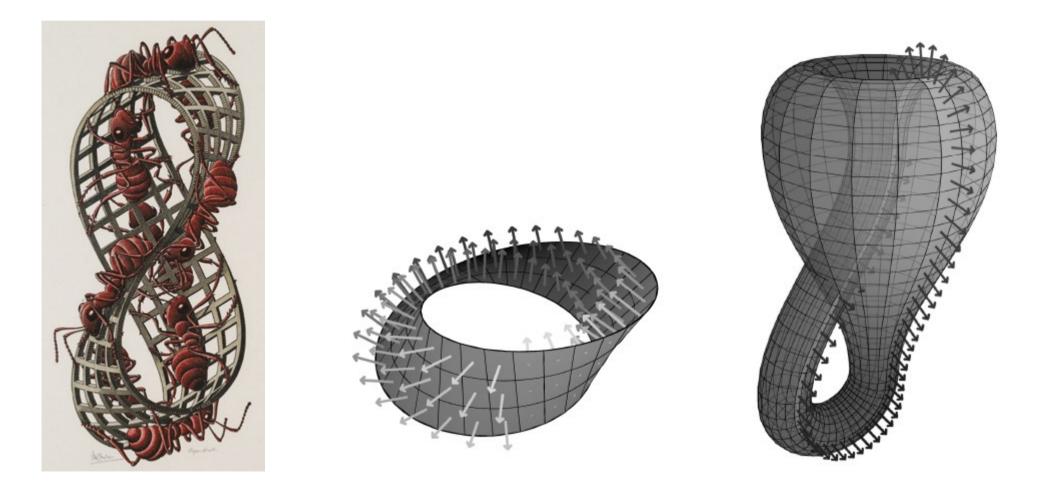


 $E(\mathbf{p}_8) = \{ \mathbf{e}_b, \mathbf{e}_d, \mathbf{e}_g, \mathbf{e}_e, \mathbf{e}_n \} \qquad N(\mathbf{p}_8) = \{ \mathbf{p}_1, \mathbf{p}_2, \mathbf{p}_3, \mathbf{p}_4, \mathbf{p}_9 \}$

Meshes: Connectivity



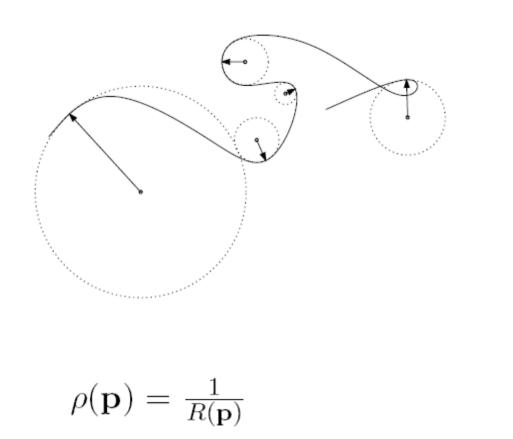
Meshes: Non-orientable surfaces

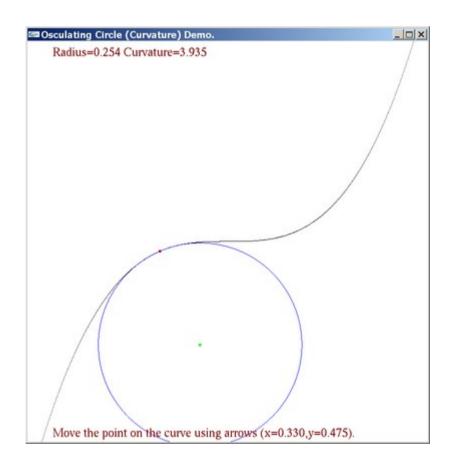


Textured meshes



Osculating circles and curvature

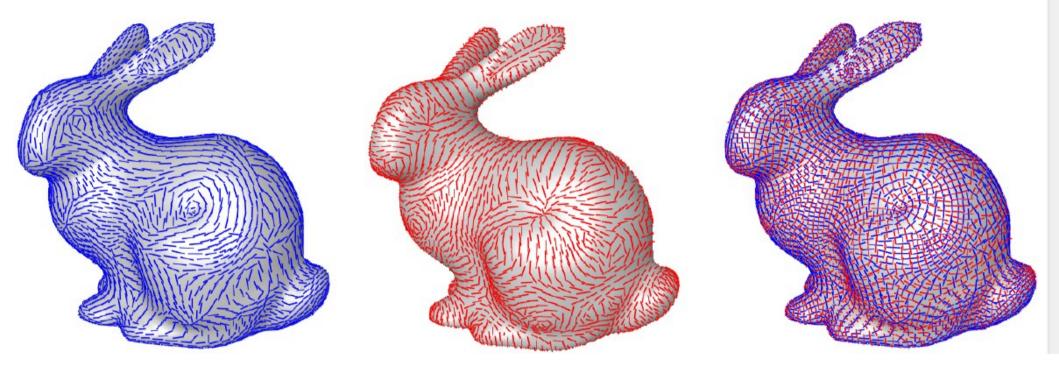




Curvature is the inverse of the radius of the osculating circle.

Mesh: Sectional curvatures and principal directions

Directions are perpendicular to each other



Minimum curvature

Maximum curvature

sectional curvatures.

Intersection of a surface s with a plane containing point p and its normal: 2D curve that can be analyzed using the osculating circles.

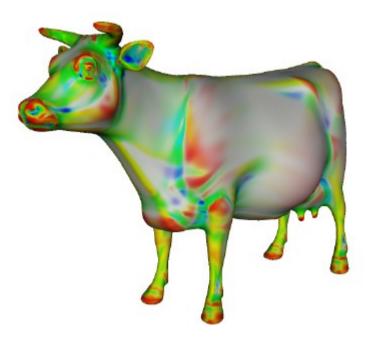
Mesh: Gaussian and mean curvatures

Gaussian curvature:

 $\rho_G = \rho_{\max} \times \rho_{\min}$

Mean curvature:

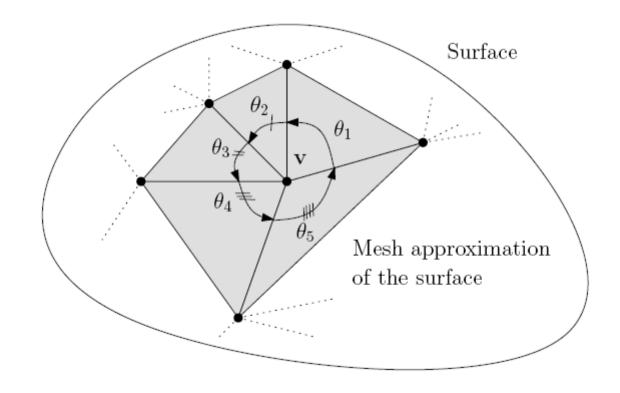
 $\frac{\rho_{\max} + \rho_{\min}}{2}$



Mesh: Integral Gaussian curvature/angle excess

$$\int \int_{A \in T(\mathbf{v})} \rho_G(A) dA \simeq -\theta(\mathbf{v}).$$

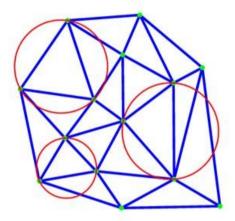
$$\rho(\mathbf{v}) = 2\pi - \sum_{i=1}^{|T(\mathbf{v})|} \theta_i.$$



Mesh: Ingredients of topology

Euler's formula is a topological invariant:

#Vertices - #Edges + #Faces = 2.

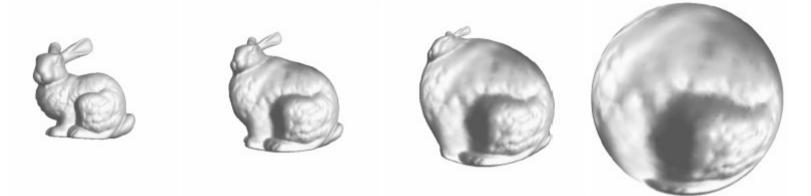




Closed triangulated manifold:

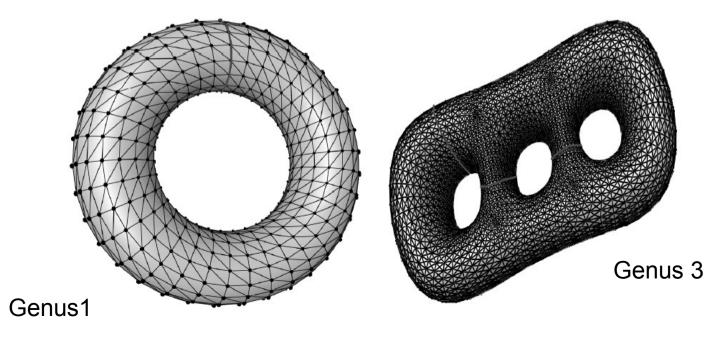
$$\begin{aligned} &\# \text{Vertices} \leq \frac{2}{3} \# \text{Edges}, \quad \text{and} \quad \# \text{Vertices} \leq 2 \# \text{Faces} - 4. \\ &\# \text{Edges} \leq 3 \# \text{Vertices} - 6, \quad \text{and} \quad \# \text{Edges} \leq 3 \# \text{Faces} - 6. \\ &\# \text{Faces} \leq \frac{2}{3} \# \text{Edges}, \quad \text{and} \quad \# \text{Faces} \leq 2 \# \text{Vertices} - 4. \end{aligned}$$

Mesh topology: Genus, polyhedra with holes

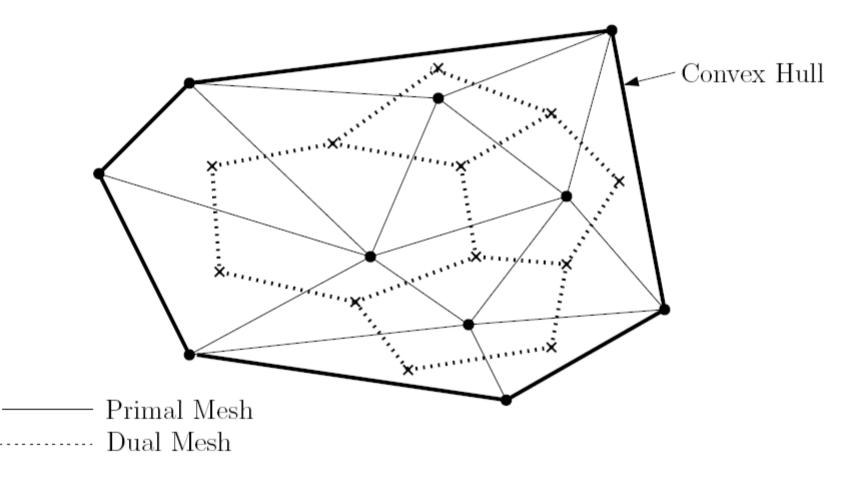


Genus 0

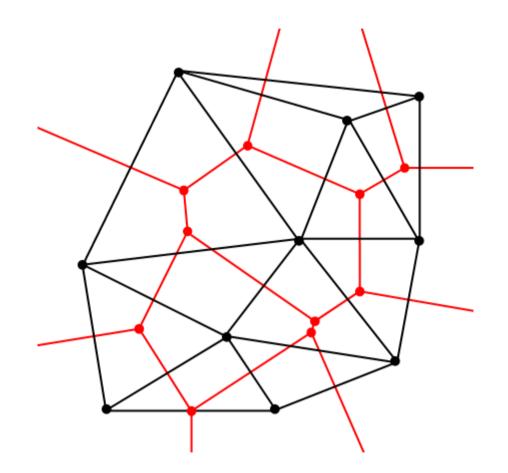
#Vertices – #Edges + #Faces = 2 – 2#Genus



Mesh: Primal/Dual graph representations

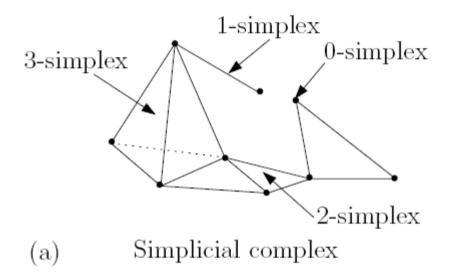


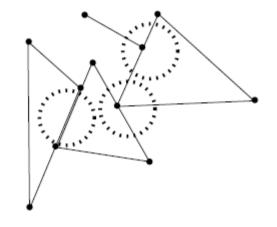
Mesh: Primal/Dual graph representations



Primal Voronoi/Dual Delauny triangulation

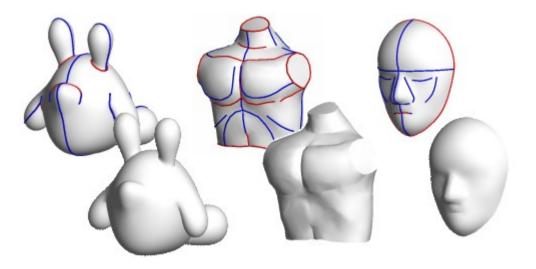
Simplicial complexes

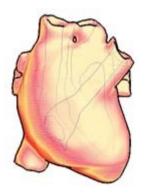


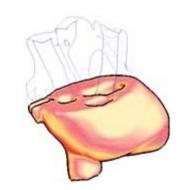


(b) Nonsimplicial complex

Sketching meshes: Pen computing



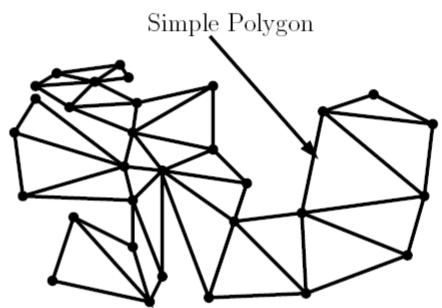


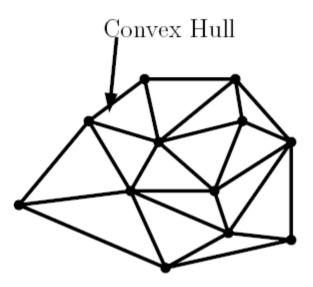


http://www.sonycsl.co.jp/person/nielsen/PT/vteddy/vteddy-desc.html

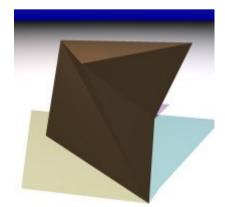
Triangulation meshes:

Always possible in 2D (but difficult)





NOT Always possible in 3D!!! (require additional Steiner points)



Untetrahedralizable Objects

Schonhardt's polyhedron

Chazelle's polyhedron

Meshes: Procedural modeling/ city(buildings)







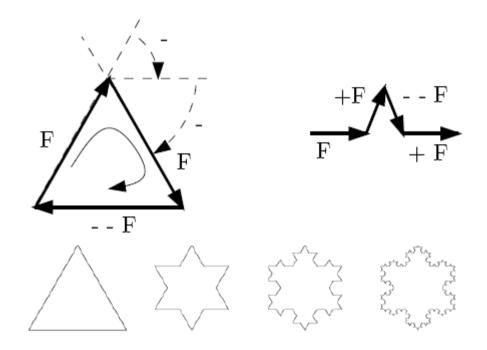
L-system (Lindenmayer) process

 $\begin{array}{c} \mathrm{START} \longrightarrow A \\ A \longrightarrow B \\ B \longrightarrow AB \end{array}$

Fibonacci's sequences

Step	String	String Length
0	А	1
1	В	1
2	AB	2
3	BAB	3
4	ABBAB	5
5	BABABBAB	8
6	ABBABBABABBAB	13
7	BABABBABABBABBABBABBAB	21

L-system (Lindenmayer) process / LOGO



 $\begin{array}{l} \mathrm{START} \longrightarrow F - -F - -F \\ F \longrightarrow F + F - -F + F \end{array}$



Data-structures for meshes: Indexed face list

Object Oriented Graphics Library (OOGL) / OFF format

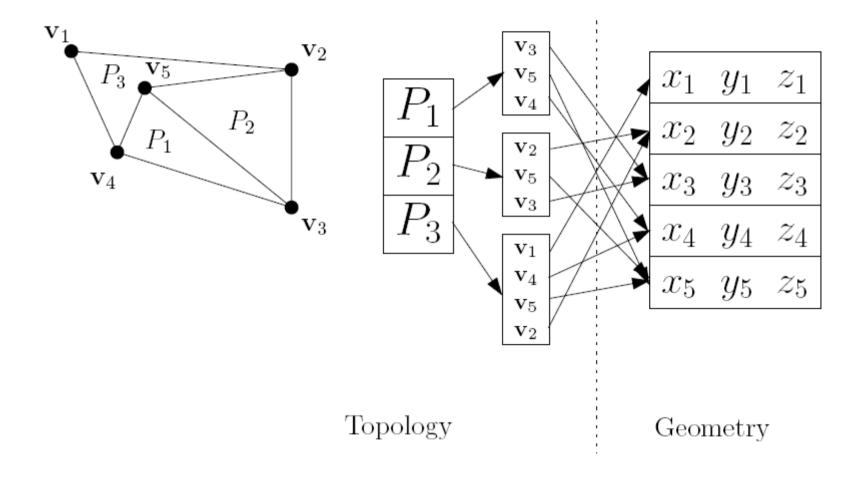
- O X

```
Camera (Euclidean view)
1 OFF
2 # Geomview OOGL format cube.off
3 # #Vertices #Faces #Edge
4860
5 # Vertex table
6 - 0.500000 - 0.500000 0.500000
7 0.500000 - 0.500000 0.500000
8 - 0.500000 \ 0.500000 \ 0.500000
9 0.500000 0.500000 0.500000
10 - 0.500000 0.500000 - 0.500000
11 \ 0.500000 \ 0.500000 \ -0.500000
12 - 0.500000 - 0.500000 - 0.500000
13 \ 0.500000 \ -0.500000 \ -0.500000
14 \# Face index table (first vertex index: 0)
15 4 0 1 3 2
16 \ 4 \ 2 \ 3 \ 5 \ 4
17 4 4 5 7 6
18 4 6 7 1 0
                                         Geomview.org viewer
19 4 1 7 5 3
20 4 6 0 2 4
```

Data-structures for meshes: Indexed face list

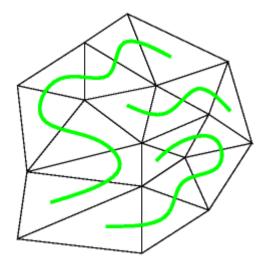


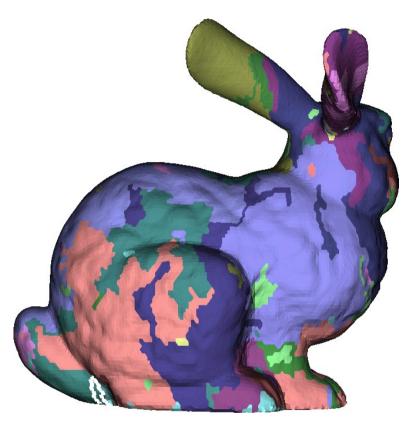
Vertex Table



Optimizing bandwidth: Triangle/quad strips

Compress mesh vertices Compress mesh connectivity





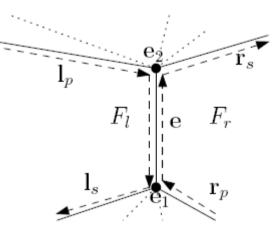
Runny with 150 strins

$GREEDYSTRIPMESH(\mathcal{M})$

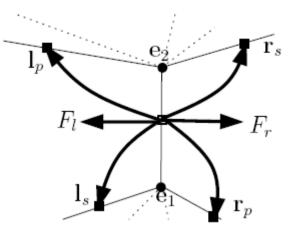
- 1. \triangleleft Overview of the greedy stripping method \triangleright
- 2. while there remains triangles in \mathcal{M}
- 3. do Pick a triangle T of \mathcal{M} that has minimum number of adjacent triangles
- 4. For each edge \mathbf{e} of T, build the strip passing through T and \mathbf{e}
- 5. Choose the longuest strip and remove its triangles from \mathcal{M}

Many data-structures for meshes....

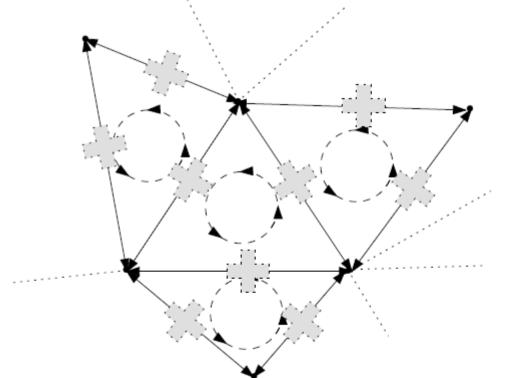
Winged edges Half edges Quad edges

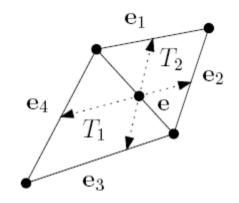


A Winged Edge



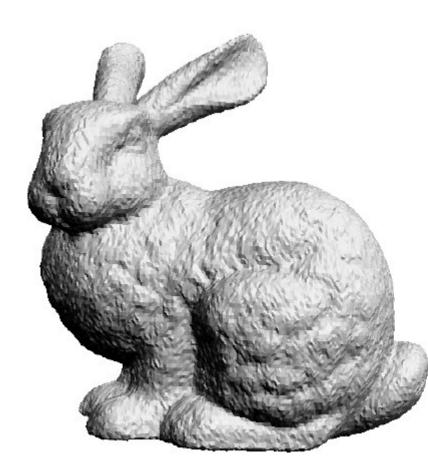
Pointer References

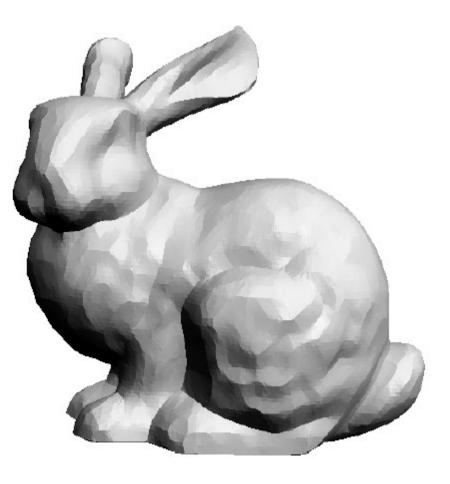




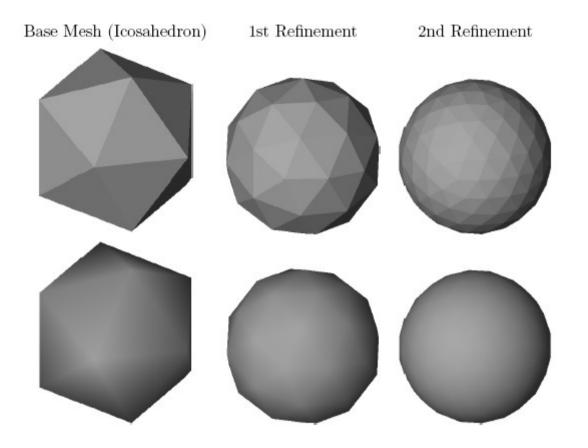
Laplacian smoothing on meshes

 $\mathbf{v} \leftarrow \mathbf{v} + \frac{\lambda}{|N(\mathbf{v})|} \sum_{i=1}^{|N(\mathbf{v})|} (N(\mathbf{v}, i) - \mathbf{v})$

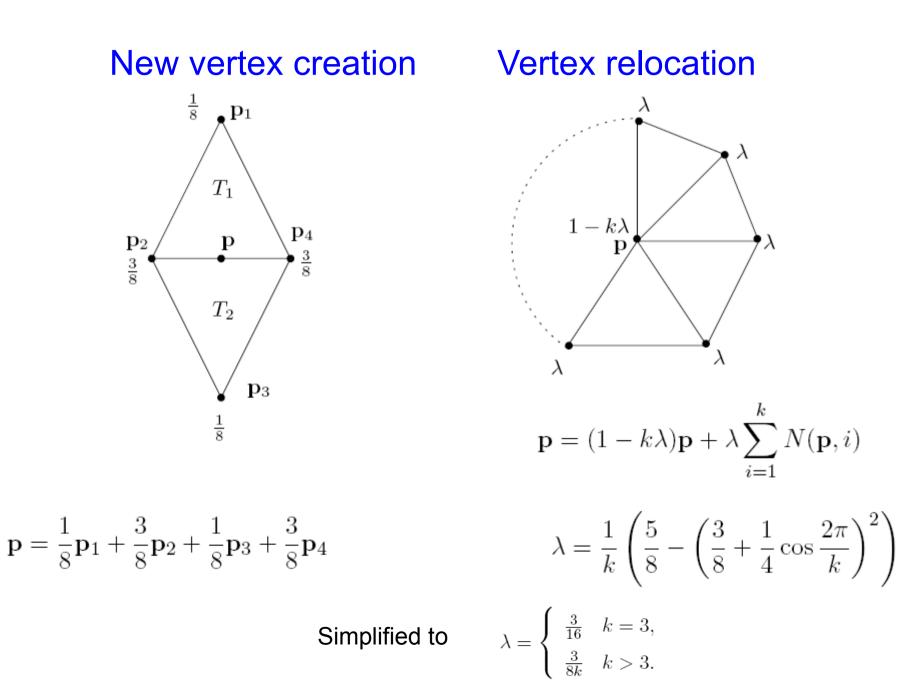




Surface subdivision



Surface subdivision: Loop scheme



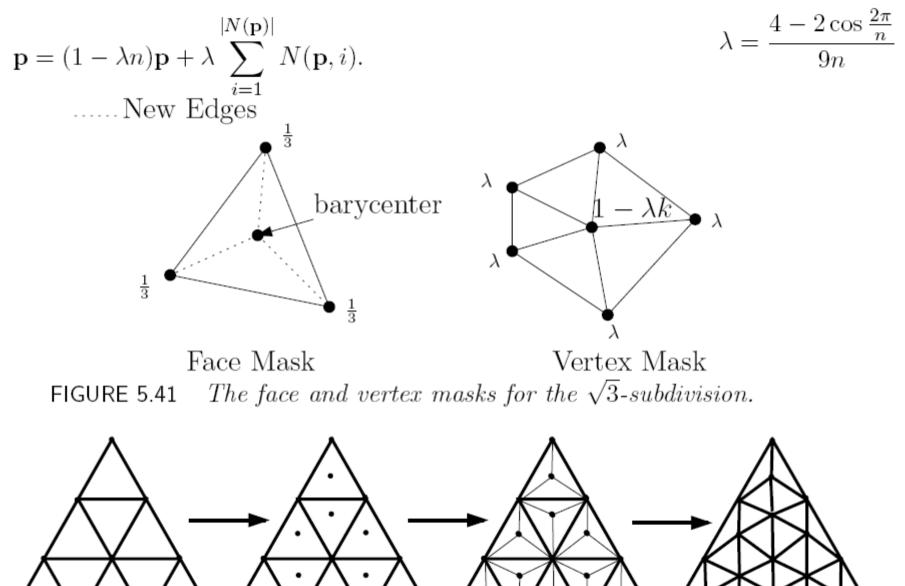
SUBDIVISION (\mathcal{M}, k)

- 1. \triangleleft General subdivision framework \triangleright
- 2. \triangleleft Depend on whether the scheme is approximating/interpolating and primal/dual \triangleright
- 3. for $e \in \mathcal{M}$
- 4. **do** \triangleleft for each edge \triangleright
- 5. Create new vertex using the vertex creation mask
- 6. \triangleleft Could be several for *n*-adic subdivision \triangleright
- 7. for $\mathbf{v} \in \mathcal{M}$
- 8. **do** Move original vertex using the vertex displacement mask
- 9. Reconnect all vertices as a triangular mesh based on \mathcal{M}

Limit position, smoothness properties

$$\lambda_{\infty} = \frac{1}{\frac{3}{8}\lambda + k}$$

Kobbelt's subdivision (+edge flipping)



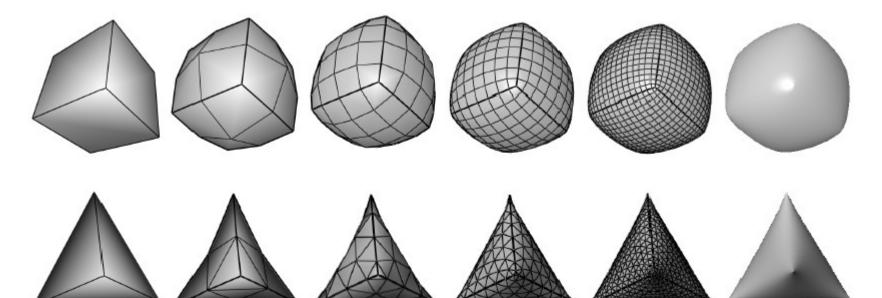


Vertex creation

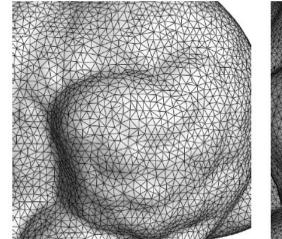
Adding edges

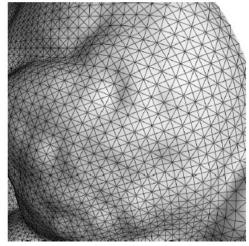
Mesh subdivision

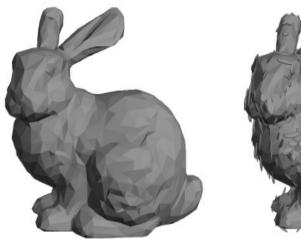
	Cube			Tetrahedron		
Level	#Vertices	#Faces	#Edges	#Vertices	#Faces	#Edges
0	8	6	12	4	4	6
1	26	24	48	10	16	24
2	98	96	192	34	64	96
3	386	384	768	130	256	384
4	1538	1536	3072	514	1024	1536
:	:	:	:	:	:	÷
8	393218	393216	786432	131074	262144	393216



Remeshing Decimating mesh







(a)

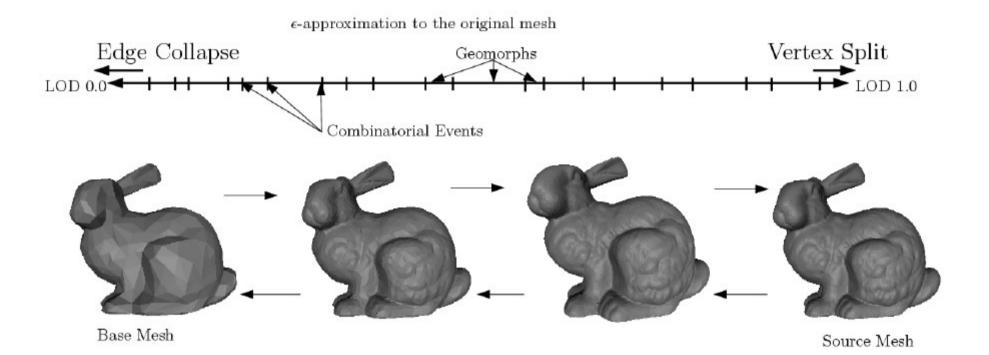




(b)

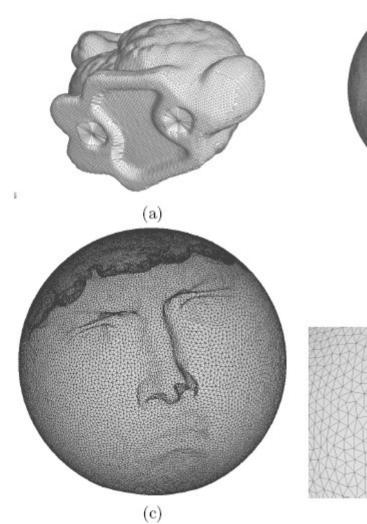


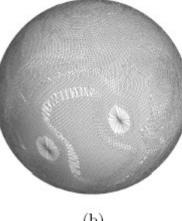
Progressive mesh representations



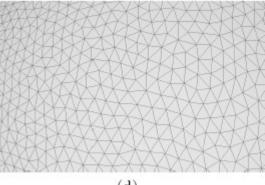
Level of details

Parameterization and texture mapping



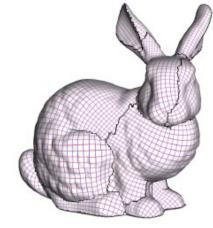


(b)

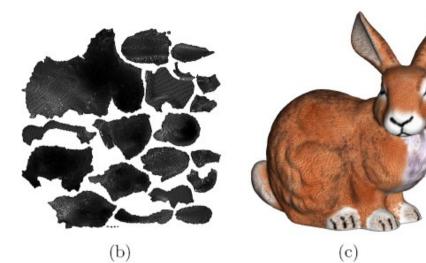


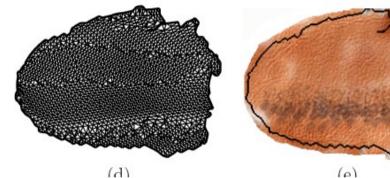
(d)

Parameterization and texture mapping

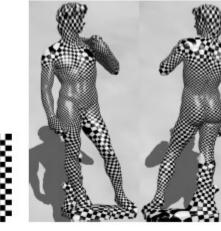


(a)









Minimize distortion

Conformal mapping (preserve angles)

H- and V- representations of polytopes

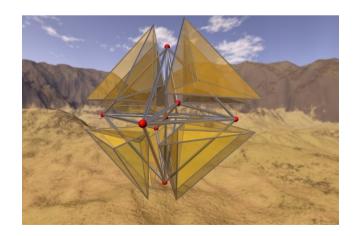
Half-spaces representation

$$P = \{x \in \mathbb{R}^n : Ax \le b\}$$



Vertex representation (convex hull)

$$\bar{P} = \{ x \in \mathbb{R}^n : x = \sum_i \lambda_i x_i, \sum_i \lambda_i = 1, \lambda_i \ge 0 \}$$



http://www.math.tu-berlin.de/polymake/index.html

