



INF421, Lecture 1

Lists and Complexity

Leo Liberti

LIX, École Polytechnique, France

INF421, Lecture 1 – p. 1

Course



- **Objective:** to teach you some data structures and associated algorithms
- **Evaluation:** TP noté en salle info le 16 septembre, Contrôle à la fin.
Note: $\max(CC, \frac{3}{4}CC + \frac{1}{4}TP)$
- **Organization:** fri 26/8, 2/9, 9/9, 16/9, 23/9, 30/9, 7/10, 14/10, 21/10, amphi 1030-12 (Arago), TD 1330-1530, 1545-1745 (SI31,32,33,34)
- **Books:**
 1. Ph. Baptiste & L. Maranget, *Programmation et Algorithmique*, Ecole Polytechnique (Polycopié), 2006
 2. G. Dowek, *Les principes des langages de programmation*, Editions de l'X, 2008
 3. D. Knuth, *The Art of Computer Programming*, Addison-Wesley, 1997
 4. K. Mehlhorn & P. Sanders, *Algorithms and Data Structures*, Springer, 2008
- **Website:** www.enseignement.polytechnique.fr/informatique/INF421
- **Contact:** liberti@lix.polytechnique.fr (e-mail subject: INF421)

INF421, Lecture 1 – p. 2

Lecture summary

- Reminders
- Complexity
- Lists

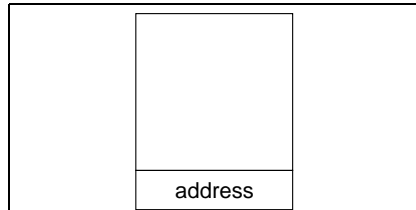
Reminders

INF421, Lecture 1 – p. 3

INF421, Lecture 1 – p. 4



Memory

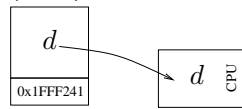


Memory cell

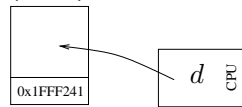
- has an address
- stores a datum d

Two operations

- Move datum from cell to CPU (read)



- Move datum from CPU to cell (write)



Representation of memory: a sequence of cells

d_0	d_1	d_2	d_3	d_4	d_5
0x0	0x1	0x2	0x3	0x4	0x5

A function $D : \mathbb{A} \rightarrow \mathbb{D}$
 \mathbb{A} : set of addresses
 \mathbb{D} : set of data elements



Assumptions

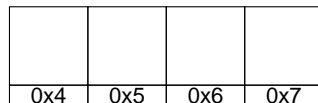
- For theoretical purposes, assume memory is infinite
- In practice it is finite
- Each datum can be stored in a single cell
- Different data elements might have different sizes



Naming memory

A program variable is just a name for a chunk of memory

x denotes:



- We simply associate a name to the starting address
- The size of the chunk is given by the name's type
- **Basic types:** int, long, char, float, double
- **Composite types:** Cartesian products of basic types

if $y.a \in \text{int}$ and $y.b \in \text{float}$ then $y \in \text{int} \times \text{float}$



Basic operations

- **Assignment:** write value in memory cell(s) named by variable (i.e. "variable=value")
- **Arithmetic:** $+$, $-$, \times , \div for integer and floating point numbers
- **Test:** evaluate a logical condition: if true, change address of next instruction to be executed
- **Loop:** instead of performing next instruction in memory, jump to an instruction at a given address (more like a "go to")

WARNING! In these slides, I use "=" to mean two different things:

1. in assignments, "variable = value" means "put value in the cell whose address is named by variable"
2. in tests, "variable = value" is TRUE if the cell whose address is named by variable contains value, and FALSE otherwise

in C/C++/Java "=" is used for assignments, and "==" for tests



Composite operations: programs

Programs are built recursively from basic operations

- If A, B are ops, then concatenation " $A ; B$ " is an op

Semantics: execute A , then execute B

- If A, B are ops and T is a test, " $\text{if } (T) A \text{ else } B$ " is an op

Semantics: if T is true execute A , else B

- If A is an op and T is a test, " $\text{while } (T) A$ " is an op

Semantics: 1:(if $(T) A$ else (go to 2)) (go to 1) 2:



Complexity

Complexity

- Several different programs can yield the same result: which is best?
- Evaluate their time (and/or space) complexity
 - **time complexity:** how many "basic operations"
 - **space complexity:** how much memory used by the program during execution
- *Worst case:* max values during execution
- *Best case:* min values during execution
- *Average case:* average values during execution

P : a program

t_P : number of basic operations performed by P



Time complexity (worst case)

- $\forall P \in \{\text{assignment, arithmetic, test}\}$:

$$t_P = 1$$

- **Concatenation:** for P, Q programs:

$$t_{P;Q} = t_P + t_Q$$

- **Test:** for P, Q programs and R a test:

$$t_{\text{if } (T) P \text{ else } Q} = t_T + \max(t_P, t_Q)$$

max: worst-case policy

- **Loop:** it's complicated

(depends on how and when loop terminates)



Loop complexity example

The complete loop

Let P be the following program:

```

1:  $i = 0$  ;
2: while ( $i < n$ ) do
3:    $A$ ;
4:    $i = i + 1$ ;
5: end while

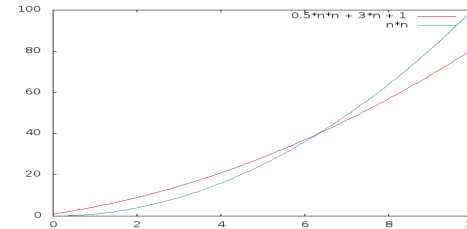
```

- Assume A does not change the value of i
- Body of loop executed n times
- $t_P(n) = 1 + n(t_A + 3)$
- Why the '3'? Well, $t_{(i < n)} = 1, t_{(i+1)} = 1, t_{(i=.)} = 1$



Orders of complexity

- In the above program, suppose $t_A = \frac{1}{2}n$
- Then $t_P = \frac{1}{2}n^2 + 3n + 1$
- No one really cares about the constants 2, 3, 1: all that matters is that t_P "behaves no worse than" the fn. n^2



$\frac{1}{2}n^2 + 3n + 1$ is $O(n^2)$

- A function $f(n)$ is order of $g(n)$ (notation: $O(g(n))$) if:

$$\exists c > 0 \exists n_0 \in \mathbb{N} \forall n > n_0 (f(n) \leq cg(n)) \quad (1)$$
- For $f(n) = \frac{1}{2}n^2 + 3n + 1$ and $g(n) = n^2, c = 1$ and $n_0 = 6$



Some examples

Functions	Order
$an + b$ with a, b constants	$O(n)$
polynomial of degree d' in n	$O(n^d)$ with $d \geq d'$
$n + \log n$	$O(n)$
$n + \sqrt{n}$	$O(n)$
$\log n + \sqrt{n}$	$O(\sqrt{n})$
$n \log n^3$	$O(n \log n)$
$\frac{an+b}{cn+d}, a, b, c, d$ constants	$O(1)$

- Make an effort to find the best (most slowly increasing) function $g(n)$ when saying " $f(n)$ is $O(g(n))$ "
- E.g. no one would say that $2n + 1$ is $O(n^4)$ (although it's technically true) — rather say $2n + 1$ is $O(n)$



Remark

- The complexity order is an asymptotic description of $t_P(n)$
- If $t_P(n)$ does not depend on n , its order of complexity is $O(1)$ (i.e. constant)
- Example:** looping 10^{1000} times over an $O(1)$ code still yields an $O(1)$ program
- In other words, n must appear as a parameter of the program for the complexity order to be anything other than constant

Complexity of easy loops



```

1: input n;
2: int s = 0;
3: int i = 1;
4: while (i ≤ n) do
5:   s = s + i;
6:   i = i + 1;
7: end while
8: output s;
    
```

- $t(n) = 3 + 5n + 1 = 5n + 4$
- $\Rightarrow t(n)$ is $O(n)$

```

1: for i = 0; i < n - 1; i = i + 1 do
2:   for j = i + 1; j < n; j = j + 1 do
3:     print i, j;
4:   end for
5: end for
    
```

$$\begin{aligned}
 t(n) &= 1 + \underbrace{(5(n-1) + 6) + \dots + (5 + 6)}_{n-1} \\
 &= 1 + 5((n-1) + \dots + 1) + 6(n-1) \\
 &= \frac{5}{2}n(n-1) + 6n - 5 \\
 &= \frac{5}{2}n^2 + \frac{7}{2}n - 5 \\
 t(n) &\text{ is } O(n^2)
 \end{aligned}$$

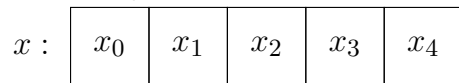
Arrays



Like a vector in maths



- A vector $x \in \mathbb{Q}^n$ is an n -tuple (x_1, \dots, x_n) for some $n \in \mathbb{N}$
- In computers: x is the name for a memory address with n successive cells
- Indexing starts from 0 (last cell is called x_{n-1})



- An array is **allocated** when the memory is reserved
- The size of the array, n , is decided at allocation time
- Usually, the size of the array does not change
- When the array is no longer useful, the reserved memory can be **deallocated OR freed**

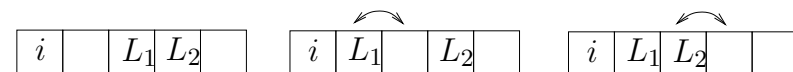
Array operations



For an array of size n :

Operations	Complexity
Read value of i -th component	$O(1)$
Write value in i -th component	$O(1)$
Size	$O(1)$
Remove element (cell)	forget it*
Insert element (cell)	forget it*
Move subsequence to position i	$O(n)$

Moving subsequence L to position i :
 extract (contiguous) subsequence L from the array, and re-insert it after position i and before position $i + 1$



*: can simulate these operations using pointers, or de-alloc



Norm of a vector in \mathbb{R}^5

```

1: input  $x \in \mathbb{Q}^5$ ;
2: int  $i = 0$ ;
3: float  $a = 0$ ;
4: while ( $i < 5$ ) do
5:    $a = a + x_i \times x_i$ ;
6: end while
7:  $a = \text{sqrt}(a)$ ;

```

- Computes $\sqrt{\sum_{i=0}^4 x_i^2}$
- Complexity: $O(1)$ (why?)



Incomplete loop

```

1: input  $x \in \{0, 1\}^n$ ;
2: int  $i = 0$ ;
3: while ( $i < n \wedge x_i = 1$ ) do
4:    $x_i = 0$ ;
5:    $i = i + 1$ ;
6: end while
7: if ( $i < n$ ) then
8:    $x_i = 1$ ;
9: end if
10: output  $x$ ;

```

Input	Output
(0,0,0,0)	(1,0,0,0)
(1,1,0,0)	(0,0,1,0)
(0,1,1,0)	(1,1,1,0)
(1,1,1,1)	(0,0,0,0)

- Components of x can only be 0 or 1
- Loop continues over all components as long as their value is 1; at the first 0 component, it stops
- Complexity?



Worst case complexity of incomplete loop

- Among all inputs of the algorithm, find those yielding the worst complexity
- In the case above, $x = (1, 1, \dots, 1)$ always makes the loop continue to the end, i.e. for n iterations

Thm.

$(1, 1, \dots, 1)$ is the input yielding worst complexity

Proof

Suppose false, then there is a vector $x \neq (1, \dots, 1)$ yielding a complexity $t(n) > n$. Since $x \neq (1, \dots, 1)$, x contains at least one 0 component. Let $j < n$ be the smallest index such that $x_j = 0$: at iteration j the loop breaks, and the complexity is $t(n) = j$, which is smaller than n : contradiction.

- Since the other operations are $O(1)$, get $O(n)$

Potential difficulty of this approach: identifying the worst-case inputs and *proving* no other input is worse



Average case complexity of incomplete loop (1/2)

- Average case analysis needs a probability space:

- assume the event $x_i = b$ is independent of the events $x_j = b$ for all $i \neq j$
- assume each cell x_i of the array contains 0 or 1 with equal probability $\frac{1}{2}$

- For any vector having first $k + 1$ components $(\underbrace{1, \dots, 1}_k, 0)$, the loop is executed k times (for all $0 \leq k < n$)

Event of a binary $(k + 1)$ -vector having given components has probability $(\frac{1}{2})^{k+1}$

- If the vector is $(\underbrace{1, \dots, 1}_n)$ the loop is executed n times

Event of a binary n -vector having given components has probability $(\frac{1}{2})^n$



Average case complexity of incomplete loop (2/2)

- The loop is executed k times with probability $(\frac{1}{2})^{k+1}$, for $k < n$
- The loop is executed n times with probability $(\frac{1}{2})^n$
- Average number of executions:

$$\sum_{k=0}^{n-1} k2^{-(k+1)} + n2^{-n} \leq \sum_{k=0}^{n-1} k2^{-k} + n2^{-n} = \sum_{k=0}^n k2^{-k}$$

Thm.

$$\lim_{n \rightarrow \infty} \sum_{k=0}^n k2^{-k} = 2$$

Proof

Geometric series $\sum_{k \geq 0} q^k = \frac{1}{1-q}$ for $q \in [0, 1)$. Differentiate w.r.t. q , get $\sum_{k \geq 0} kq^{k-1} = \frac{1}{(1-q)^2}$; multiply by q , get $\sum_{k \geq 0} kq^k = \frac{q}{(1-q)^2}$. For $q = \frac{1}{2}$, get $\sum_{k \geq 0} k2^{-k} = (1/2)/(1/4) = 2$.

Hence, the average complexity is constant $O(1)$



Jagged arrays

- Jagged array:** a vector whose components are vectors of possibly different sizes
- E.g. $x = ((x_{00}, x_{01}), (x_{10}, x_{11}, x_{12}))$

$$x :$$

$x_0 :$	x_{00}	x_{01}	
$x_1 :$	x_{10}	x_{11}	x_{12}

- Special case:** when all subvector sizes are the same, get a matrix: `int x[][] = new int [2][3];`

$$x = \begin{pmatrix} x_{00} & x_{01} & x_{02} \\ x_{10} & x_{11} & x_{12} \end{pmatrix}$$



Representing relations

- Jagged arrays can be used to represent a relation on a finite set
- Let $V = \{v_1, \dots, v_n\}$ and E a relation on V
 E is a set of ordered pairs (u, v)
- Representation:**
 - array of n components
 - the i -th component is the array of v_j related to v_i
- Example:** $V = \{1, 2, 3\}$,
 $E = \{(1, 1), (1, 2), (2, 3), (3, 1), (3, 2), (3, 3)\}$

$$E :$$

1	1	2	
2	3		
3	1	2	3



Application: Networks

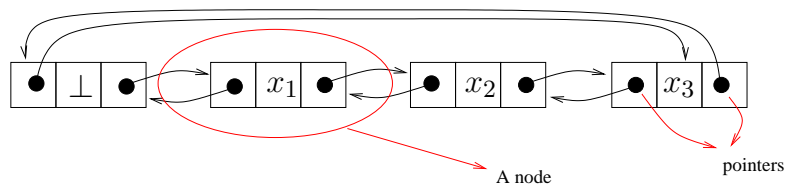


Array shortcomings

- Essentially fixed size
- Size must be known in advance
- Changing relative positions of elements is inefficient

Lists

Doubly linked list



INF421, Lecture 1 – p. 29

- **Node N :** a list element

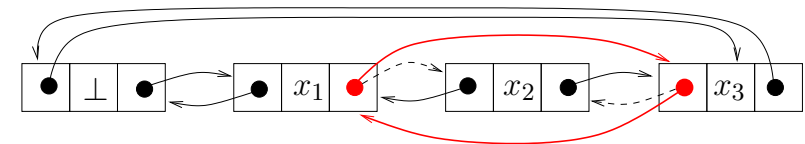
$N.\text{prev}$	=	address of previous node in list
$N.\text{next}$	=	address of next node in list
$N.\text{datum}$	=	the data element stored in the node

- **Placeholder node \perp :** before the first element, after the last element, no stored data
- *Every node has two pointers, and is pointed to by two nodes*

INF421, Lecture 1 – p. 31

Remove a node

Remove current node (*this*)



In the example, $\text{this} = x_2$

- 1: `this.prev.next = this.next;`
- 2: `this.next.prev = this.prev;`

Worst case complexity: $O(1)$

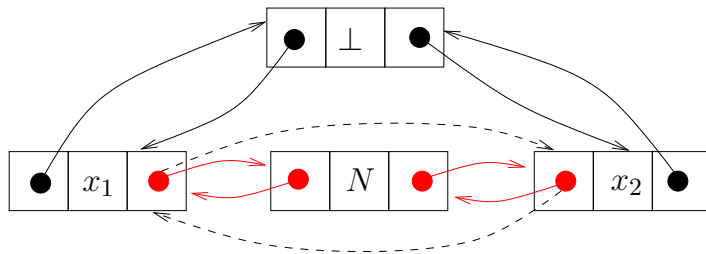
INF421, Lecture 1 – p. 30

INF421, Lecture 1 – p. 32



Insert a node

Insert current node (*this*) after node x_1



In the example, $this = N$

- 1: $this.prev = x_1;$
- 2: $this.next = x_1.next;$
- 3: $x_1.next = this;$
- 4: $this.next.prev = this;$

Worst case complexity: $O(1)$



Find next

- Given a list L and a node x , find next occurrence of element b
- If $b \in L$ return node where b is stored, else return \perp

- 1: **while** ($x.datum \neq b \wedge x \neq \perp$) **do**
- 2: $x = x.next$
- 3: **end while**
- 4: **return** x

Warning: every test costs 2 basic operations, inefficient

- 1: $\perp.datum = b$
 - 2: **while** ($x.datum \neq b$) **do**
 - 3: $x = x.next$
 - 4: **end while**
 - 5: **return** x
- Now $t_{test} = 1$



List operations

For a doubly-linked list of size n :

Operations	Complexity
Read/write value of i -th node	$O(n)$
Find next	$O(n)$
Size ^a	$O(n)$
Is it empty?	$O(1)$
Read/write value of first/last node	$O(1)$
Remove element	$O(1)$
Insert element	$O(1)$
Move subsequence to position i	$O(1)$
Pop from front/back	$O(1)$
Push to front/back	$O(1)$
Concatenate	$O(1)$



End of Lecture 1

^aSome implementations are $O(1)$ by storing and updating size