#### Decomposition Connectivity

Minimally 2-connected graphs

Critically 2-connected graphs

Open questions

# Decomposition theorems for classes of graphs defined by constraints on connectivity

### Nicolas Trotignon — CNRS — LIAFA Université Paris 7

Danish Graph Theory Meeting April – May 2011

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Minimally 2-connected graphs



### 1 Minimally 2-connected graphs

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### Decomposition Connectivity

Minimally 2-connected graphs

Critically 2-connected graphs

Open questions • A graph is **minimally 2-connected** if it is 2-connected and the removal of any edge yields a graph that is not 2-connected.

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### Decomposition Connectivity

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Open questions • A graph is **minimally 2-connected** if it is 2-connected and the removal of any edge yields a graph that is not 2-connected.

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• A graph is chordless if every cycle is chordless.

# Links between "chordless" and "minimally 2-connected"

#### Decomposition Connectivity

Minimally 2-connected graphs

Critically 2-connected graphs

Open questions Plummer's observations [1968]:

• A graph G is chordless if and only if for every subgraph H, either H has connectivity at most 1, or H is minimally 2-connected.

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• A 2-connected graph is chordless if and only if it is minimally 2-connected.

# Decomposing chordless graphs



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# Basic class Decomposition Connectivity A graph G is sparse if no vertices of degree at least 3 are Minimally adjacent. 2-connected graphs

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### Decomposition Connectivity

Minimally 2-connected graphs

Critically 2-connected graphs

Open questions A graph G is **sparse** if no vertices of degree at least 3 are adjacent.

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Obviously:

• If G is sparse, then it is chordless.

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Obviously:

• If G is sparse, then it is chordless.

• The converse is false:



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Obviously:

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 From any graph, one can obtain a sparse graph by subdividing several edges.



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Open questions



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# Applications (1): reproving Plummer's Theorem

#### Decomposition Connectivity

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### Theorem (Plummer 1968)

Let G be a 2-connected graph. Then G is minimally 2-connected if and only if either

- G is a cycle; or
- if S denotes the set of nodes of degree 2 in G, then there are at least two components in G \ S, each component of G \ S is a tree and if C is any cycle in G and T is any component of G \ S, then the graph (V(C) ∩ V(T), E(C) ∩ E(T)) is empty or connected.

# Applications (2): edge- and total-colouring



 $\Delta(G)$ -edge-colourable and  $(\Delta(G) + 1)$ -total-colourable.

# Generalization: unichord-free graphs

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Open questions • A graph is chordless if it does not contain as a subgraph.

# Generalization: unichord-free graphs

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- A graph is chordless if it does not contain as a subgraph.
- What about not containing as an induced subgraph?

# Generalization: unichord-free graphs

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- A graph is chordless if it does not contain as a subgraph.
- What about not containing as an induced subgraph?
- A graph is **unichord-free** if it does not contain a cycle with a unique chord.

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# Unichord-free graphs defined by connectivity constraints



A graph G is unichord-free if and only if every minimal cutset of G is a stable set.

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# Decomposing unichord-free graphs



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has a decomposition.

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• graphs obtained from Petersen

**Heawood** by deleting vertices and subdividing edges incident to at least one vertex of degree 2

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### sparse graphs

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### • 0- and 1-cutset

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Decomposition Connectivity

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### • 0- and 1-cutset

• proper 2-cutset:



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Decomposition Connectivity

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Open questions









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### Decomposition Connectivity

Minimally 2-connected graphs

Critically 2-connected graphs

Open questions  Detections of cycle with a unique chord: in time O(nm) [NT, Vušković]

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 Vertex colouring: a unichord-free graph G is either 3-colourable or ω(G)-colourable [NT, Vušković].

#### Decomposition Connectivity

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### Theorem (de Figueiredo, Machado 2010)

• Edge- and total-colouring problems are NP-hard for unichord free graphs.

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- If squares are also exluded, then edge-colouring problem stays NP-hard, but the total colouring problems becomes polynomial.

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- Edge- and total-colouring problems are NP-hard for unichord free graphs.
- If squares are also exluded, then edge-colouring problem stays NP-hard, but the total colouring problems becomes polynomial.
- If squares are excluded and Δ ≥ 4, then both problems become polynomial.

# Outline

Decomposition Connectivity

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### Decomposition Connectivity

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Critically 2-connected graphs

Open questions • A graph is **critically 2-connected** if it is 2-connected and the removal of any vertex yields a graph that is not 2-connected.

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#### Decomposition Connectivity

Minimally 2-connected graphs

Critically 2-connected graphs

Open questions

- A graph is **critically 2-connected** if it is 2-connected and the removal of any vertex yields a graph that is not 2-connected.
- A **propeller** is a cycle together with a vertex (called the center), not in the cycle, that has at least two neighbors in the cycle.

#### Decomposition Connectivity

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- A graph is **critically 2-connected** if it is 2-connected and the removal of any vertex yields a graph that is not 2-connected.
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• A *k*-**propeller** is a propeler such that the center has *k* neighbors in the cycle.

Decomposition Connectivity

Minimally 2-connected graphs

Critically 2-connected graphs

Open questions

- A graph G contains no propeller (as a subgraph) if and only if for every subgraph H, either H has connectivity at most 1, or H is critically 2-connected.
- FALSE A 2-connected graph does not contain a propeller if and only if it is critically 2-connected.

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- A graph G contains no propeller (as a subgraph) if and only if for every subgraph H, either H has connectivity at most 1, or H is critically 2-connected.
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• In fact, any graph is a subgraph of some critically 2-connected graph.

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- FALSE A 2-connected graph does not contain a propeller if and only if it is critically 2-connected.
- In fact, any graph is a subgraph of some critically 2-connected graph.
  So, the only class closed under taking subgraph that contains all critically 2-connected graphs is the class of all graphs.

Decomposition Connectivity

Minimally 2-connected graphs

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- A graph G contains no propeller (as a subgraph) if and only if for every subgraph H, either H has connectivity at most 1, or H is critically 2-connected.
- FALSE A 2-connected graph does not contain a propeller if and only if it is critically 2-connected.

 In fact, any graph is an induced subgraph of some critically 2-connected graph.
 So, the only class closed under taking induced subgraph that contains all critically 2-connected graphs is the class

of all graphs.

# Decomposing propeller-free graphs



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G is basic or G has a decomposition.

### Decomposition Connectivity

Minimally 2-connected graphs

Critically 2-connected graphs

Open questions A graph G is **sparse** if no vertex has at least two neighbors of degree at least 3.

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### Decomposition Connectivity

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Obviously:

• If G is sparse, then it is propeller-free.

### Decomposition Connectivity

Minimally 2-connected graphs

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Obviously:

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 From any graph, one can obtain a sparse graph by subdividing several edges.

Decomposition Connectivity

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# Decomposing graphs with no propeller as an induced subgraph

Decomposition Connectivity

Minimally 2-connected graphs

Critically 2-connected graphs

Open questions

- To decompose graphs with no propeller as an **induced subgraph**, one more decomposition is needed.
- An *I*-cutset in a graph *G* is cutset *S* made of three vertices, with only one edge linking them, and such that *G* \ *I* has at least two components containing neighbors of all vertices of *S*.







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# Application (1): detecting an induced propeller in polytime

Decomposition Connectivity

Minimally 2-connected graphs

Critically 2-connected graphs

Open questions • From the decomposition theorem, it is easy to deduce an algorithm that decides in polytime whether a graph contains a propeller or not (as an induced subgraph).

# Application (1): detecting an induced propeller in polytime

Decomposition Connectivity

Minimally 2-connected graphs

Critically 2-connected graphs

Open questions

- From the decomposition theorem, it is easy to deduce an algorithm that decides in polytime whether a graph contains a propeller or not (as an induced subgraph).
- Consider the following algorithm: Test for all paths *a-b-c* whether in G \ b, an induced cycle goes through *a*, *c*.

# Application (1): detecting an induced propeller in polytime

#### Decomposition Connectivity

- Minimally 2-connected graphs
- Critically 2-connected graphs

Open questions

- From the decomposition theorem, it is easy to deduce an algorithm that decides in polytime whether a graph contains a propeller or not (as an induced subgraph).
- Consider the following algorithm: Test for all paths *a-b-c* whether in G \ b, an induced cycle goes through *a*, *c*.
- Difficult to implement in polytime because Bienstock proved that testing for an induced cycle through 2 given vertice is NPC.
- Detecting a k-propeller such that  $k \ge 4$  is NP-complete.

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# Application (2): edge-colouring

#### Decomposition Connectivity

Minimally 2-connected graphs

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Open questions

### Theorem (Aboulker, Radovanović, NT, Vusković 2011)

A 2-connected graph with no induced propeller contains an edge with both ends of degree at most 2. Hence, every graph G with no induced propeller, and which is not an odd cycle, is  $\Delta(G)$ -edge colourable.

# Outline

Decomposition Connectivity

Minimally 2-connected graphs

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Open questions Minimally 2-connected graphs

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# Higher connectivity?



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# Higher connectivity?



Minimally 2-connected graphs

Critically 2-connected graphs

Open questions

Is there any chance that some classes of higher connectivity have interesting decomposition theorems? Minimally 3-connected graphs?

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• Wheels

### Decomposition Connectivity

Minimally 2-connected graphs

Critically 2-connected graphs

Open questions A **wheel** is a cycle together with a vertex that has at least 3 neighbors in the cycle.

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### Decomposition Connectivity

Minimally 2-connected graphs

Critically 2-connected graphs

Open questions A wheel is a cycle together with a vertex that has at least 3 neighbors in the cycle. Rephrased: a k-propeller with  $k \ge 3$ .



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### Decomposition Connectivity

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**Open question:** detecting a wheel as an induced subgraph in polytime.

### Decomposition Connectivity

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**Open question:** detecting a wheel as an induced subgraph in polytime.

It is **NPC** to detect *k*-propeller with  $k \ge 4$ .



Critically 2-connected graphs

Open questions  Is there a constant C such that any graph G with no induced wheel satisfies χ(G) ≤ C?

#### Decomposition Connectivity

- Minimally 2-connected graphs
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Open questions  Is there a constant C such that any graph G with no induced wheel satisfies χ(G) ≤ C?

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• Do they have a structure?

#### Decomposition Connectivity

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Open questions

- Is there a constant C such that any graph G with no induced wheel satisfies χ(G) ≤ C?
- Do they have a structure?
- Yes if induced subdivisions of K<sub>4</sub> are also excluded [Lévêque, Maffray, NT].

#### Decomposition Connectivity

- Minimally 2-connected graphs
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Open questions

- Is there a constant C such that any graph G with no induced wheel satisfies χ(G) ≤ C?
- Do they have a structure?
- Yes if induced subdivisions of K<sub>4</sub> are also excluded [Lévêque, Maffray, NT].
- Yes in the particular case of unichord-free graphs.

# Excuding 2-propellers and colouring

### Decomposition Connectivity

Minimally 2-connected graphs

Critically 2-connected graphs

Open questions Let G be a graph with no triangle, no cube and no 2-propeller (as induced subgraphs). Is it true that G contains a vertex of degree 2?

# Excuding 2-propellers and colouring

#### Decomposition Connectivity

Open auestions

Let G be a graph with no triangle, no cube and no 2-propeller (as induced subgraphs). Is it true that G contains a vertex of degree 2?

### Theorem (Radovanović, Vusković 2010)

If a graph contains no triangle, no cube and no theta (as induced subgraphs), then it has a vertex of degree at most 2.

Remind that a theta is:  $-\infty$ 

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# **Detecting 2-propellers**



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