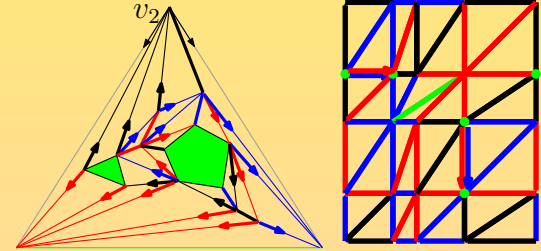
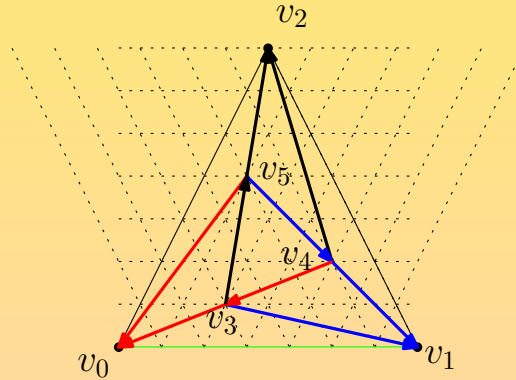
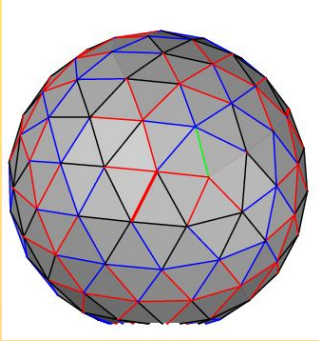


# Array-based compact data structures for triangle meshes



ISAAC, Yokohama, 6-8 december 2011

Luca Castelli Aleardi

Olivier Devillers

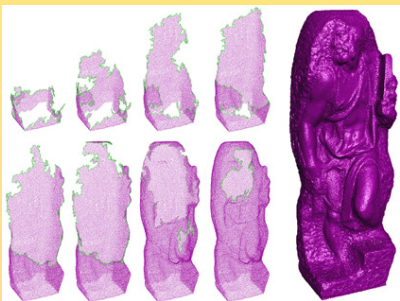


Geometrica - INRIA Sophia



# Compact Data Structures: motivation and goal

St. Matthew (Stanford's Digital Michelangelo Project, 2000)



6 Giga bytes (for storing on disk)  
186 millions vertices

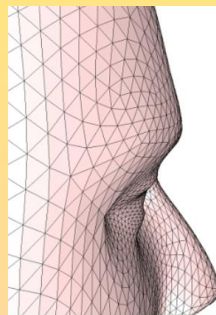
David statue (Stanford's Digital Michelangelo Project, 2000)



2 billions polygons

32 Giga bytes (without compression)

vertex  
triangle



416n bits  
connectivity

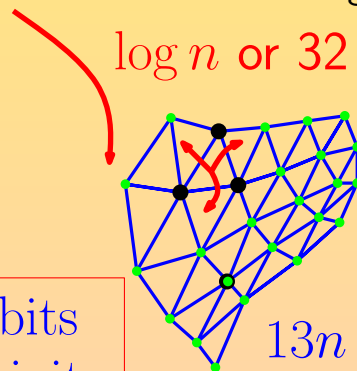
Connectivity information

1 reference to a triangle

3 references to vertices

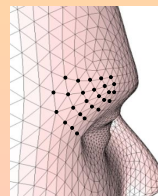
3 references to triangles

$\log n$  or 32 bits



$13n \log n$

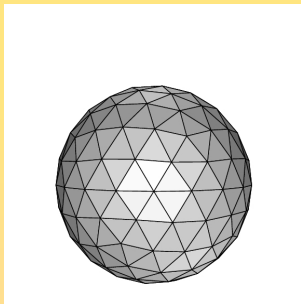
Geometric object



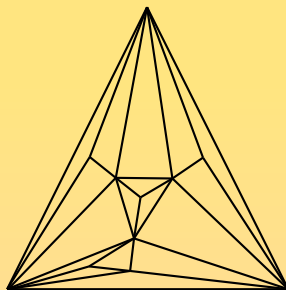
$$\begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

between 30 et 96 bits/vertex

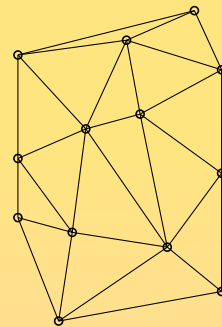
# Today we deal with triangulations



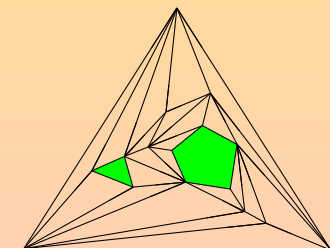
genus 0 triangle mesh



(random) planar triangulation



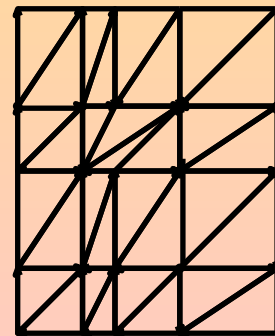
2D Delaunay triangulation



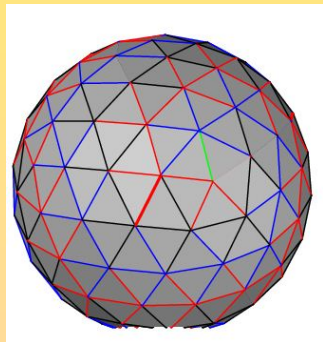
triangulations  
with boundaries



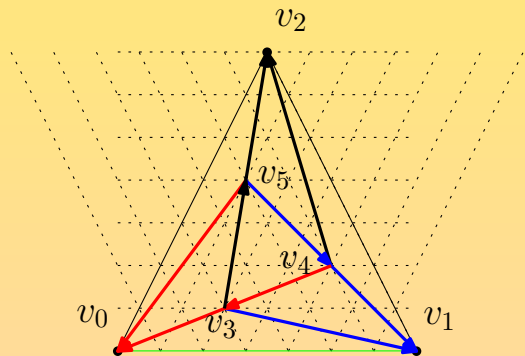
higher genus  
triangulations



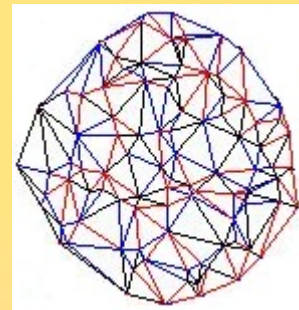
Surface triangle mesh  
endowed with a  
Schnyder wood



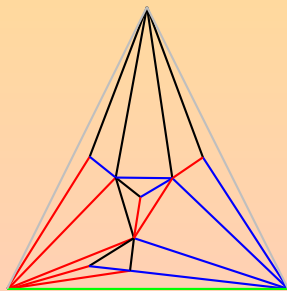
## (planar) Triangle meshes



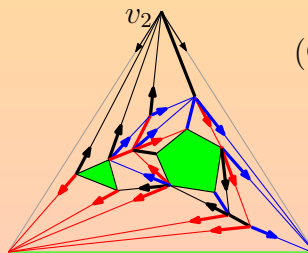
Schnyder drawing of a planar  
triangulation



Delaunay triangulation of random  
points (endowed with a Schnyder wood)

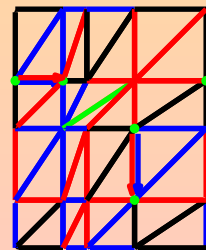


Tutte drawing of a random  
planar triangulation



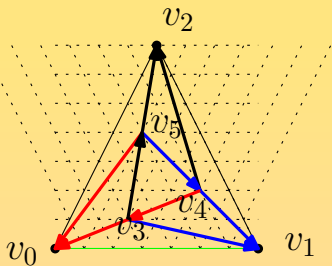
Schnyder woods for triangulations with  
multiple boundaries of arbitrary size  
(Castelli-Fusy-Lewiner, CCCG2010)

$g$ -Schnyder woods, for  
genus  $g$  triangulations  
(Castelli-Fusy-Lewiner, SoCG08)



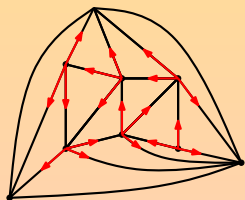
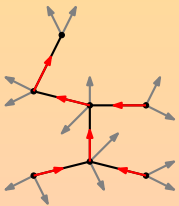
# Schnyder woods: applications (and related properties)

grid drawing



graph counting, random generation

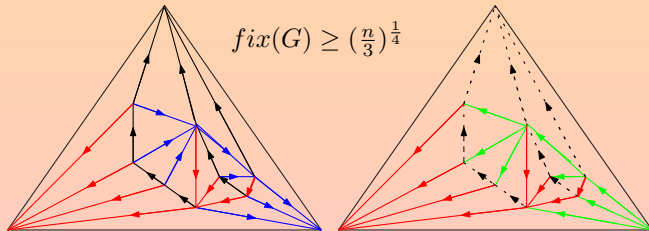
(Poulalhon-Schaeffer, Icalp 03)



Untangling geometric graphs

Bose, Dujmovic, Hurtado, Langerman, Morin, Wood (DCG 2009)

$$\text{fix}(G) \geq \left(\frac{n}{3}\right)^{\frac{1}{4}}$$



Graph encoding

(Chuang-Garg-He-Kao-Lu Icalp '98)

(He-Kao-Lu '99)

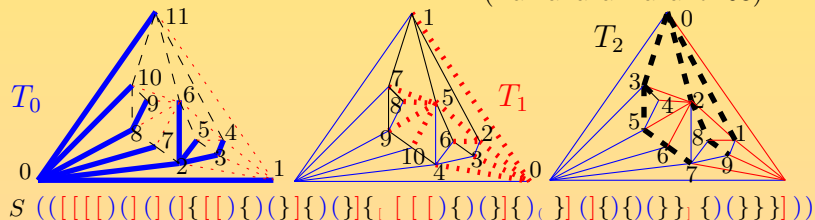
(Chiang et al. Soda'01)

(Barbay-Castelli Aleardi-He-Munro Isaac'07)

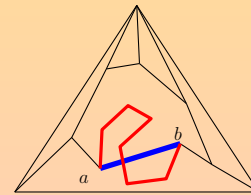
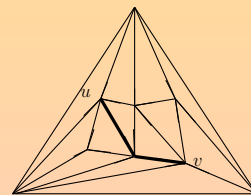
(Castelli Aleardi-Fusy-Lewiner SoCG08)

(Castelli Aleardi-Fusy-Lewiner CCCG'10)

(Yamanaka-Nakano '08)



Greedy routing

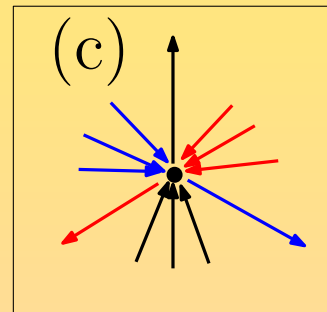
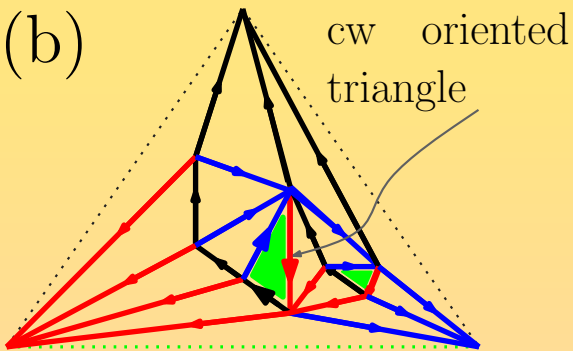
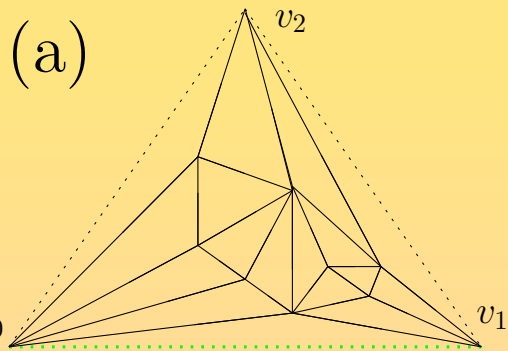


Every planar triangulation admits a *greedy drawing* (Dhandapani, Soda08)

Conjectured by Papadimitriou and Ratajczak for 3-connected planar graphs

# Schnyder woods: the definition

$v_0$   $v_1$   $v_2$  outer face



i) edge are colored and oriented in such a way that each inner node has exactly one outgoing edge of each color

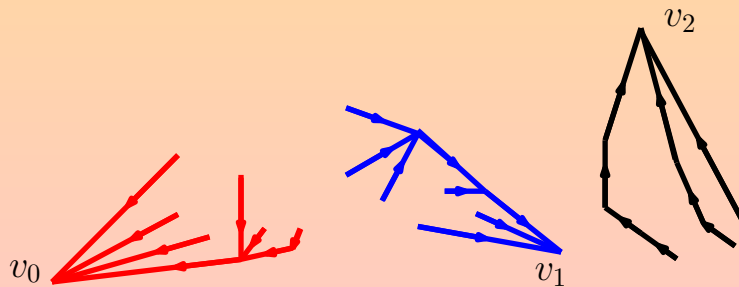
ii) colors and orientations around each inner node must respect the local Schnyder condition

## Theorem

Every planar triangulation admits a Schnyder wood, which can be computed in linear time.

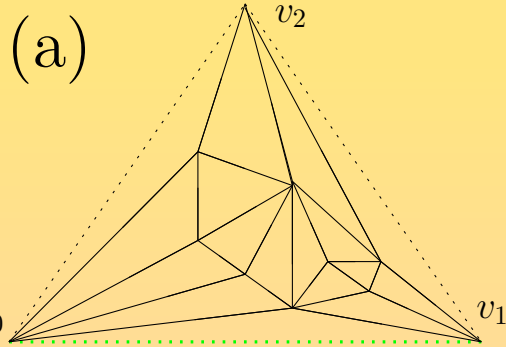
## Theorem

The three set  $T_0$ ,  $T_1$ ,  $T_2$  are spanning trees of (the inner nodes of)  $T$ :

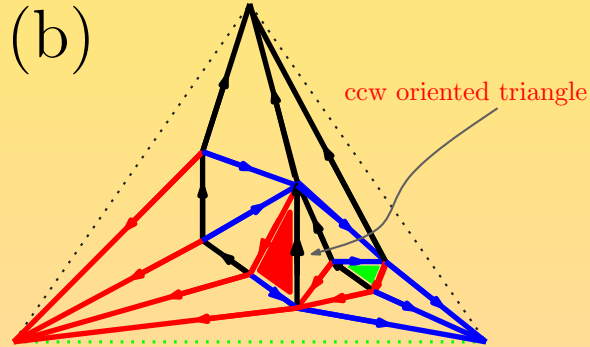


# minimal Schnyder woods: the definition (no ccw triangles)

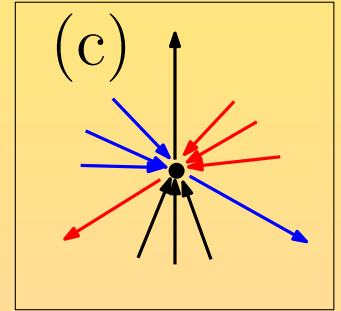
$v_0$   $v_1$   $v_2$  outer face



i) edge are colored and oriented in such a way that each inner node has exactly one outgoing edge of each color



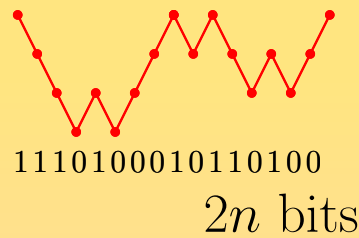
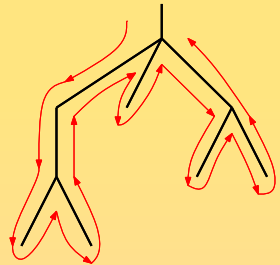
ii) colors and orientations around each inner node must respect the local Schnyder condition





# Several kinds of encodings: plane trees (with $n$ nodes)

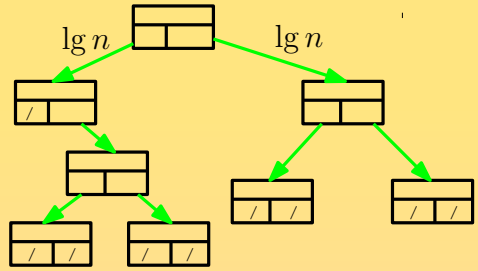
compression schemes



$$\|\mathcal{B}_n\| = \frac{1}{n+1} \binom{2n}{n} \approx 2^{2n} n^{-\frac{3}{2}}$$

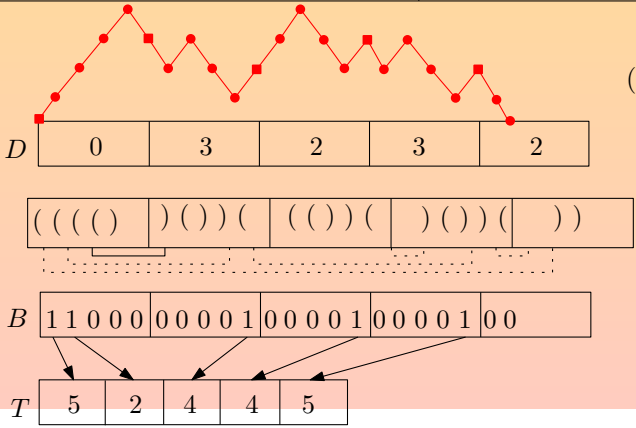
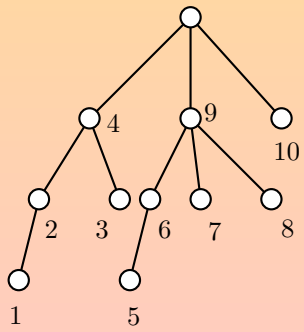
$$\log_2 \|\mathcal{B}_n\| = 2n + O(\lg n)$$

(Explicit) data structures



we need  $2n$  references, or  $\Theta(n \lg n)$  bits

Explicit (pointer based) implementation  
(array based)



Succinct representations

(Jacobson Focs89, Munro and Raman Focs97)

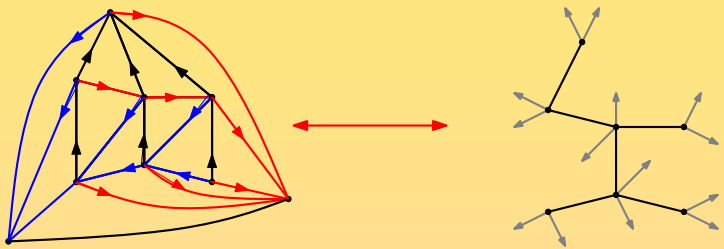
$2n + o(n)$  bits  
+  
 $O(1)$  time navigation

Word-RAM model

# Several kinds of encodings: triangle meshes ( $n$ vertices)

## Optimal compression scheme

(Poulalhon Schaeffer, Icalp03)

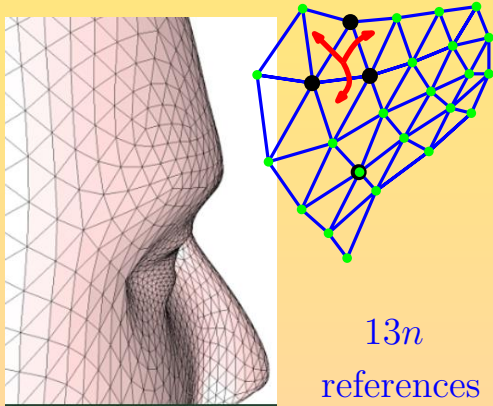


$$\Psi_n = \frac{2(4n+1)!}{(3n+2)!(n+1)!} \approx \frac{16}{27} \sqrt{\frac{3}{2\pi}} n^{-5/2} \left(\frac{256}{27}\right)^n$$

$$\frac{1}{n} \log_2 \Psi_n \approx \log_2\left(\frac{256}{27}\right) \approx 3.2451 \text{ bits/vertex}$$

## (Explicit) Geometric data structures

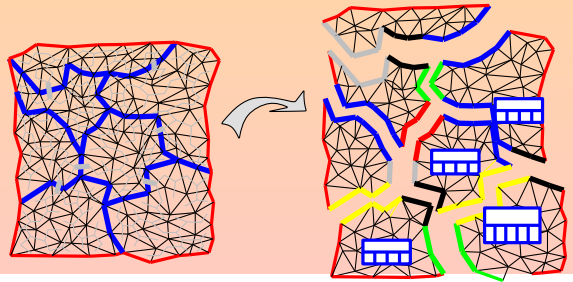
$\beta n + O(1)$  references (pointers)



$$2 \times n \times 6 \times \log n + n \times 1 \times \log n$$

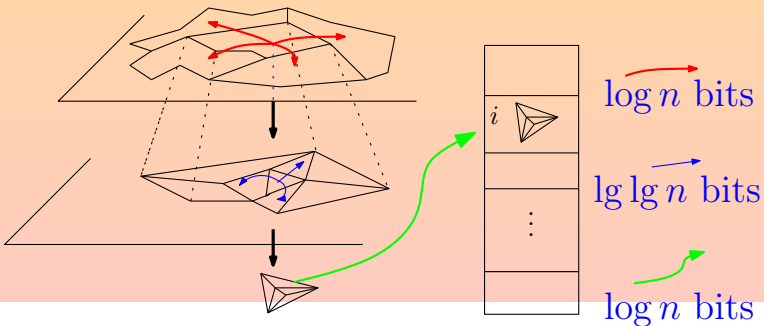
13n references or 13n log n bits

$$3.2451n + O\left(n \frac{n \log \log n}{\log n}\right) = 3.2451n + o(n) \text{ bits}$$



## Succinct representations

(Castelli Aleardi- Devillers-Schaeffer, WADS05, SoCG06)



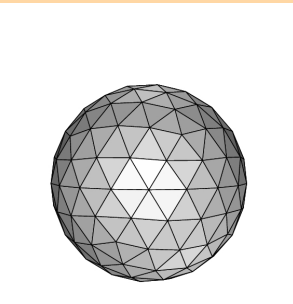
# Popular (explicit) data structures for surface meshes

(non compact) popular data structures

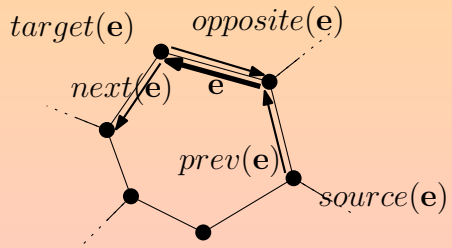
existing compact data structures

Our results

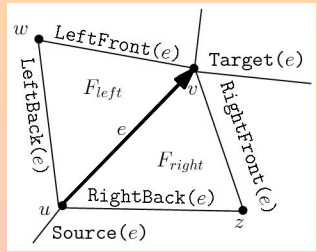
Data Structure	size	navigation time	vertex access	dynamic
Edge-based data structures	$18n + n$	$O(1)$	$O(1)$	yes
Triangle based DS / Corner Table	$12n + n$	$O(1)$	$O(1)$	yes
Directed edge (Campagna et al. '99)	$12n + n$	$O(1)$	$O(1)$	yes
2D Catalogs (Castelli Aleardi et al., '06)	$7.67n$	$O(1)$	$O(1)$	yes
Star vertices (Kallmann et al. '02)	$7n$	$O(d)$	$O(1)$	no
TRIPOD (Snoeyink, Speckmann, '99)	$6n$	$O(1)$	$O(d)$	no
SOT (Gurung et al. 2010)	$6n$	$O(1)$	$O(d)$	no
Our Thm 2 (with no vertex permutation)	$5n$	$O(1)$	$O(d)$	no
Our Thm 3 (with vertex permutation)	$4n$	$O(1)$	$O(d)$	no
Our Cor 3 (with vertex permutation)	$6n$	$O(1)$	$O(1)$	no



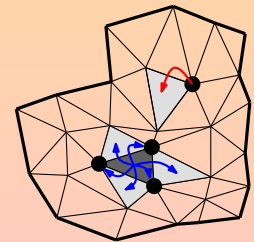
Half-edge



Winged-edge



Triangle-based



# Popular (explicit) data structures for surface meshes

(non compact) popular data structures

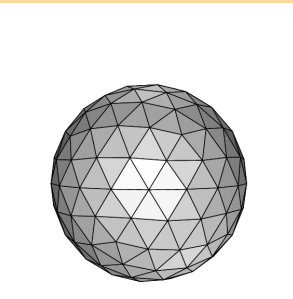
existing compact data structures

$\epsilon$  between 0.09 and 0.3

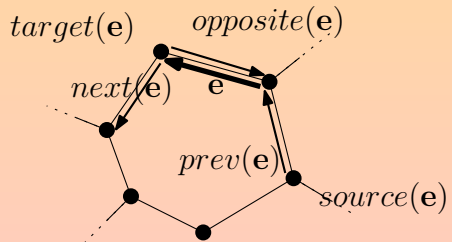
Our results

$\epsilon$  about 0.8 and 0.3

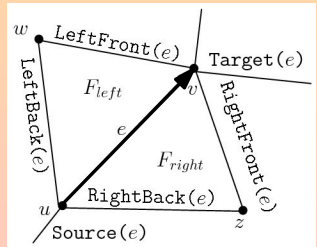
Data Structure	size	navigation time	vertex access	dynamic
Edge-based data structures	$18n + n$	$O(1)$	$O(1)$	yes
Triangle based DS / Corner Table	$12n + n$	$O(1)$	$O(1)$	yes
Directed edge (Campagna et al. '99)	$12n + n$	$O(1)$	$O(1)$	yes
2D Catalogs (Castelli Aleardi et al., '06)	$7.67n$	$O(1)$	$O(1)$	yes
Star vertices (Kallmann et al. '02)	$7n$	$O(d)$	$O(1)$	no
TRIPOD (Snoeyink, Speckmann, '99)	$6n$	$O(1)$	$O(d)$	no
SOT (Gurung et al. 2010)	$6n$	$O(1)$	$O(d)$	no
SQUAD (Gurung et al. 2011)	$(4 + \epsilon)n$	$O(1)$	$O(d)$	no
Our Thm 2 (with no vertex permutation)	$5n$	$O(1)$	$O(d)$	no
Our Thm 3 (with vertex permutation)	$4n$	$O(1)$	$O(d)$	no
Our Cor 3 (with vertex permutation)	$6n$	$O(1)$	$O(1)$	no
LR (Gurung et al. 2011)	$(2 + \epsilon)n$	$O(1)$	$O(d)$	no



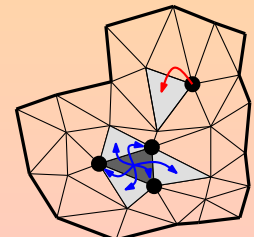
Half-edge



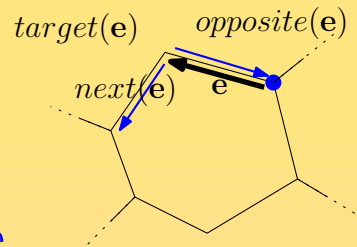
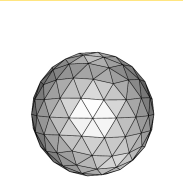
Winged-edge



Triangle-based



# Popular mesh data structures: space requirements



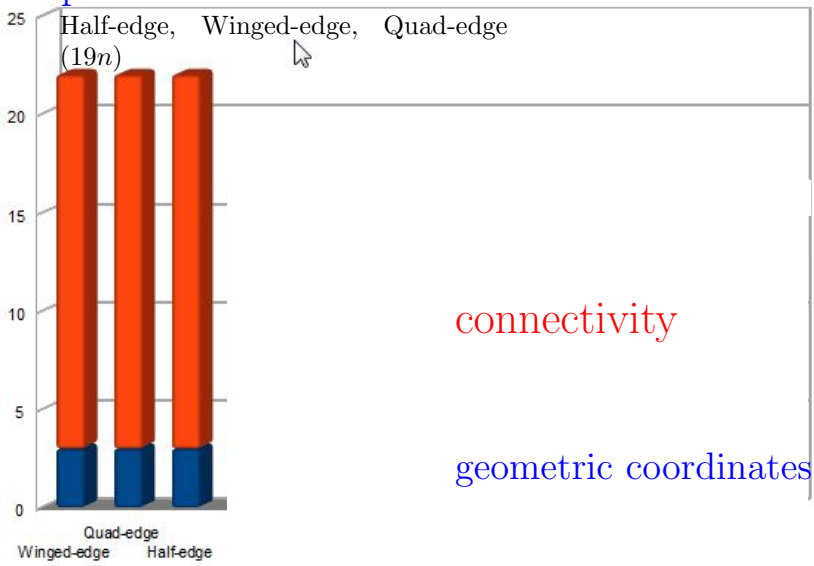
## Half-edge

```
class Point{
    float x;
    float y;
    float z;
}
```

```
class Halfedge{
    Halfedge next, opposite;
    Vertex source;
}
class Vertex{
    Halfedge e;
    Point p;
}
```

geometry

connectivity



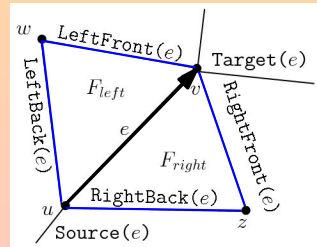
connectivity

geometric coordinates

Size (number of references)

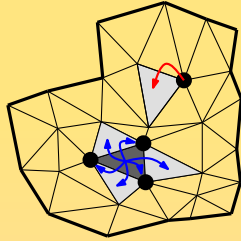
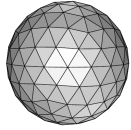
$$3 \times 2e + n = 18n + n$$

## Winged-edge



$$(4 + 2) \times e + n = 18n + n$$

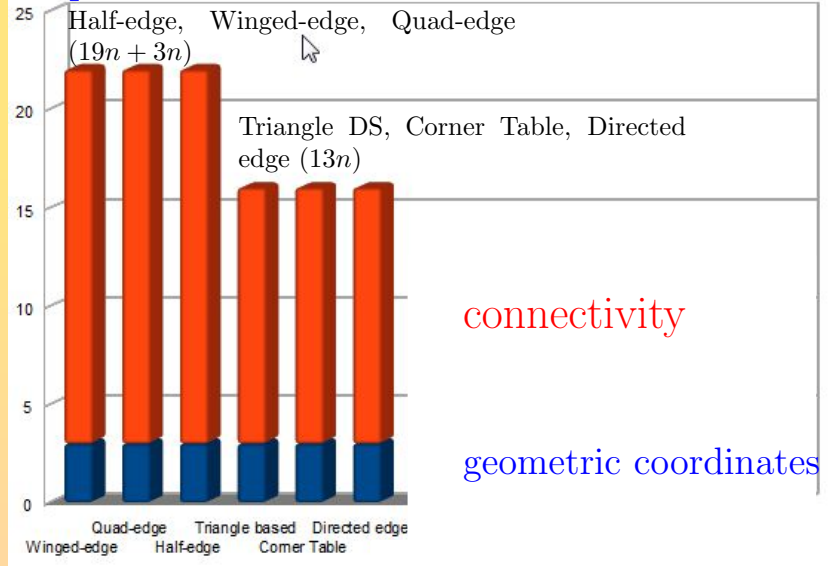
# Popular mesh data structures: space requirements



## Triangle-based

```
class Triangle{
  Triangle t1, t2, t3;
  Vertex v1, v2, v3;
}
class Vertex{
  Triangle root;
  Point p;
}
```

```
class Point{
  float x;
  float y;
  float z;
}
```

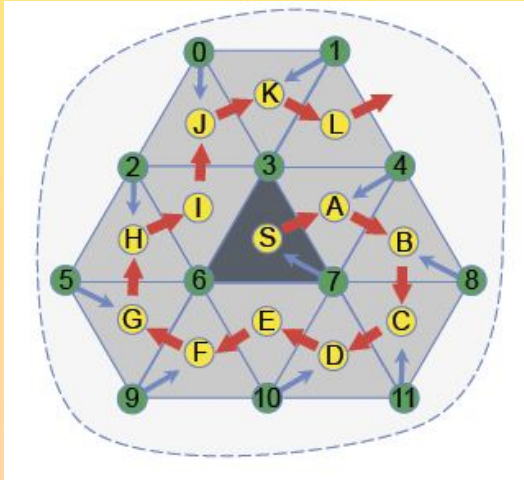


Size (number of references)

$$(3 + 3) \times f + n = 6 \times 2n + n = 13n$$

# Non compact vs. compact mesh data structures

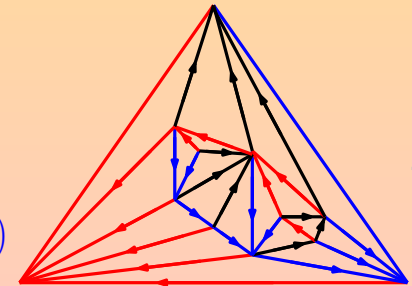
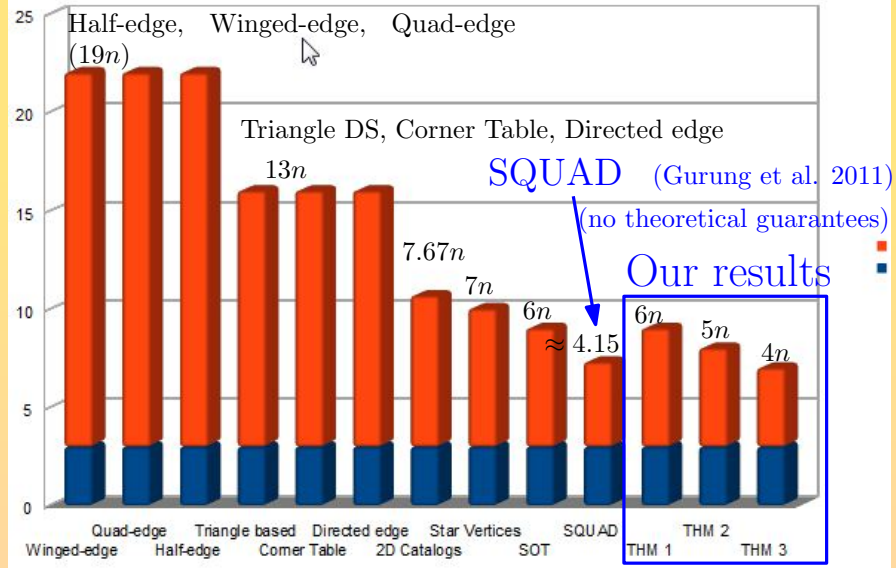
perform face reordering  
perform face reordering



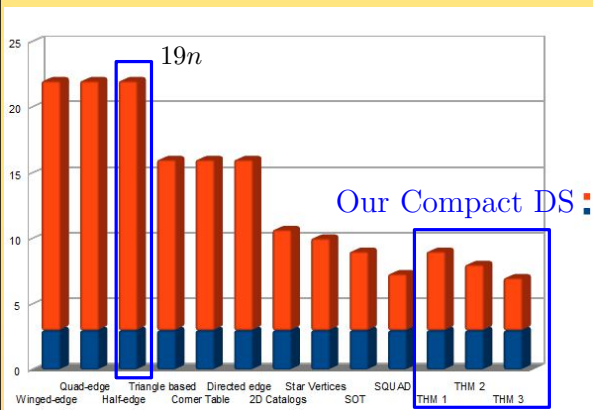
SOT data structure (Gurung et al. 2010)

TRIPOD data structure (Snoeyink and Speckmann, 1999)

use Schnyder woods (store 3 edges per vertex)



# Experimental comparison



1.2 - 1.9  
times slower

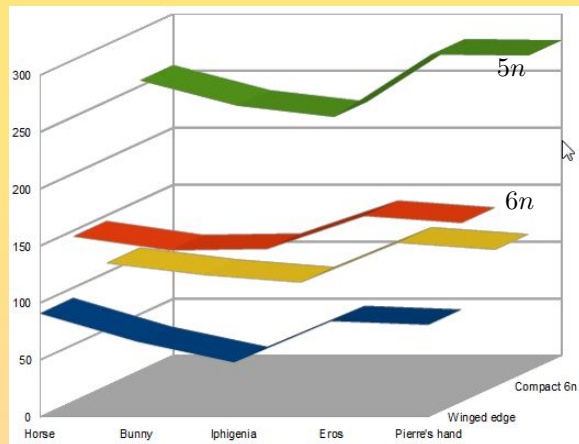
Tested on 3D models and  
random planar triangulations



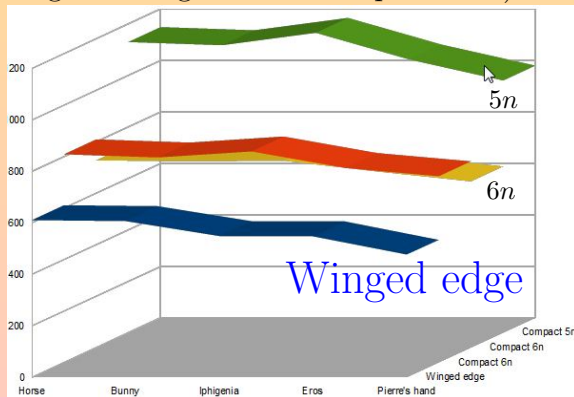
Winged edge vs. Our Compact DS

1.19 - 1.35  
times slower

(timings are expressed in nanoseconds/vertex)  
vertex degree (only topological navigation)



vertex normals  
(navigation + geometric computations)





# First simple Compact DS (size $6n$ )

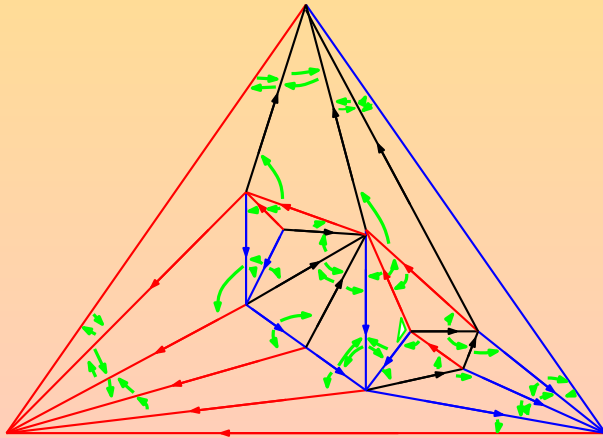
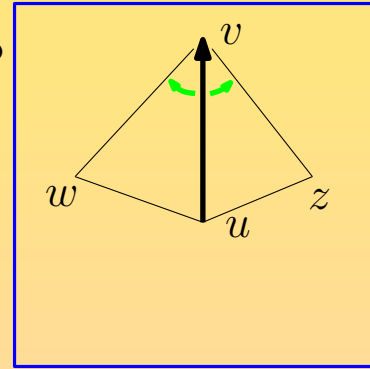
$$e := (u, v) \quad \begin{array}{l} 0 \leq v \leq n - 1 \\ 0 \leq e \leq 3n \end{array}$$

array based implementation of

a variation of TRIPOD

(J. Snoeyink and B. Speckmann, 1999)

+ reordering of edges according to the (original) vertex numbering

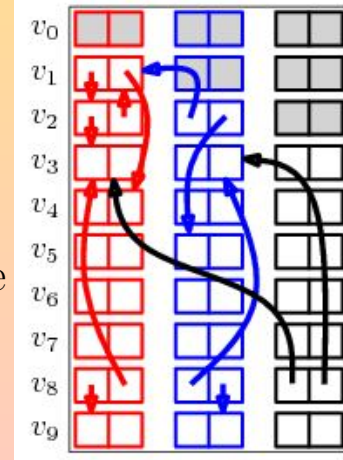


$T$

$n$  lines

3 columns

2 references per edge



# First simple Compact DS (size $6n$ )

$$e := (u, v) \quad \begin{aligned} 0 \leq v \leq n - 1 \\ 0 \leq e \leq 3n \end{aligned}$$

$$\text{retrieve } (w, u) := \begin{cases} (e + 1) \% 3 & \text{case 1} \\ (T[e] + 2) \% 3 & \text{case 2} \\ T[T[e]] & \text{case 3} \end{cases}$$

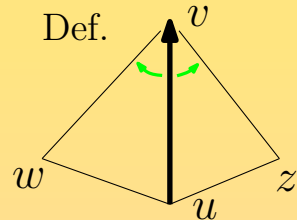
$$u := \text{source}(e) = e/3$$

$$(w, v) := T[2e]$$

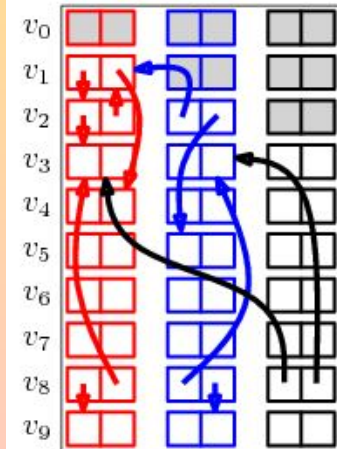
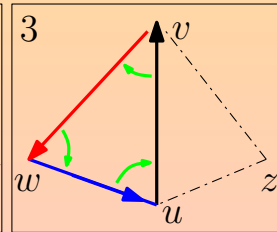
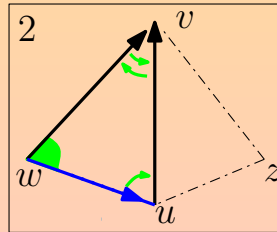
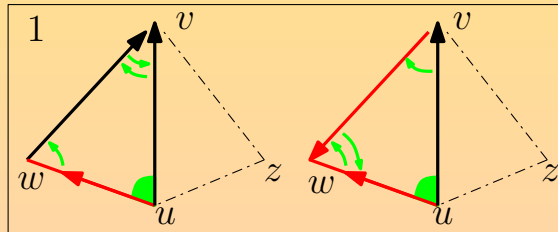
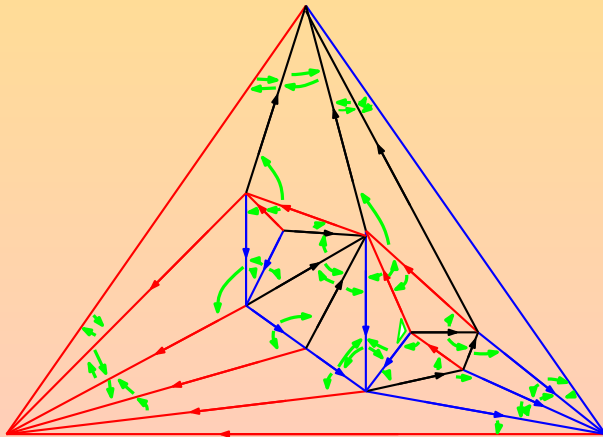
$$(z, v) := T[2e + 1]$$

$$\text{color}(e) = e \% 3$$

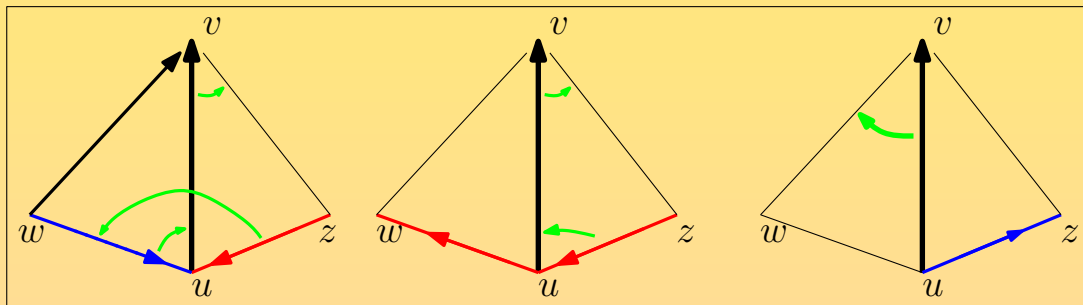
Def.



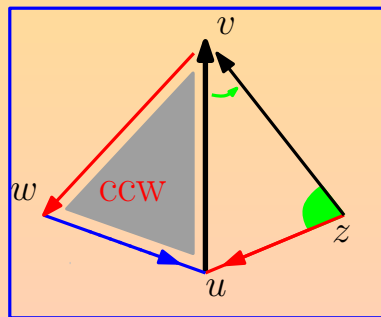
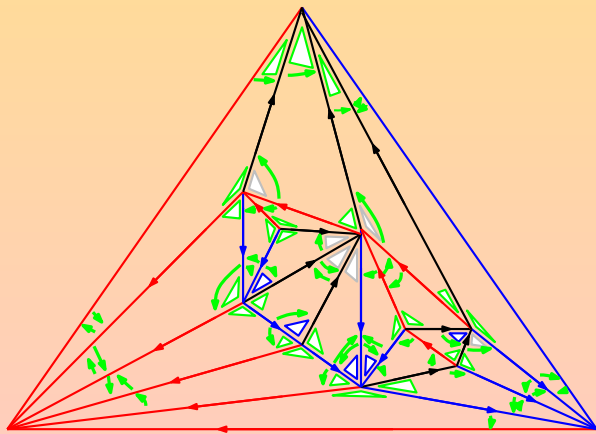
retrieving  $(z, u)$  is similar



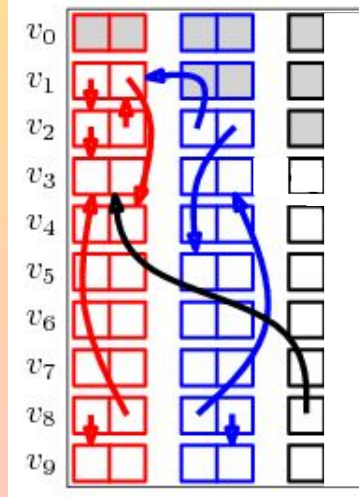
# More compact DS (size $5n$ ): use minimal Schnyder woods (less redundant and "slightly more difficult to implement")



only 1 reference for  
black edges



forbidden configuration

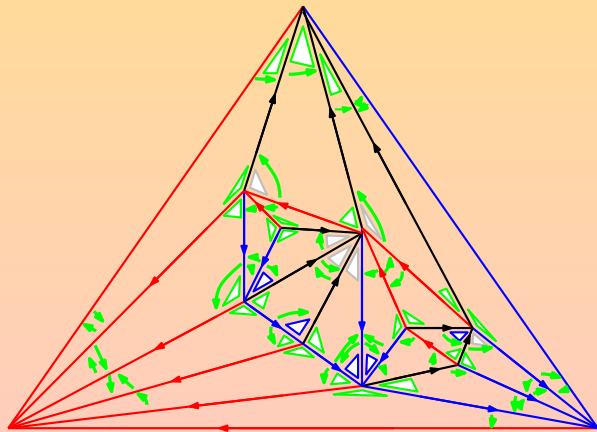
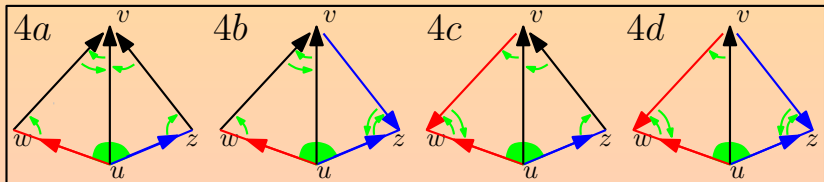
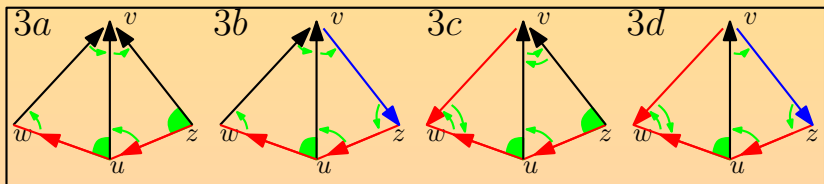
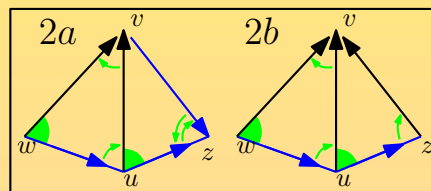
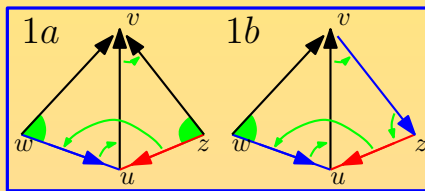


# More compact DS (size $5n$ ): use minimal Schnyder woods

(less redundant and "slightly more difficult to implement")

**implementation:** many cases to distinguish

$$\text{retrieve } (w, u) := \begin{cases} T[T[5u] - 3] & \text{case 1a} \\ T[T[T[5u]]] & \text{case 1b} \\ \dots & \dots \end{cases}$$



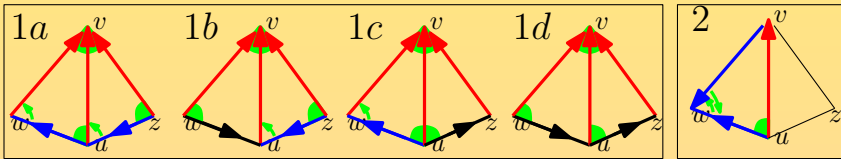
case analysis for black edges

(similar case analysis for the other two colors)

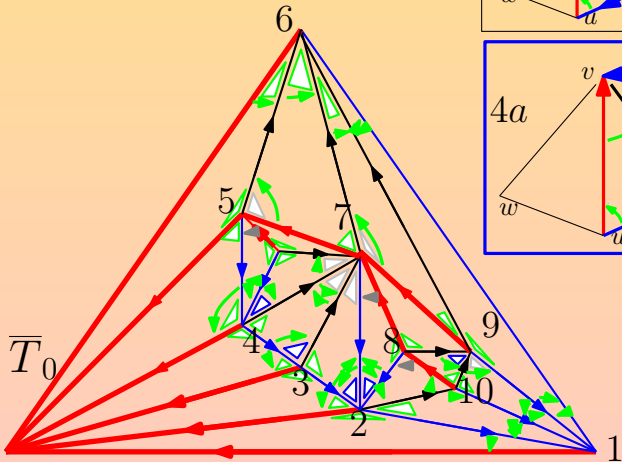
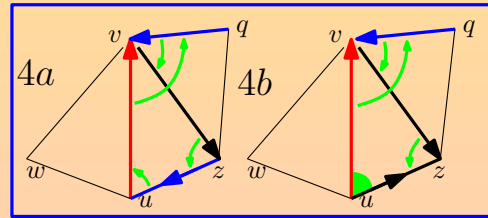
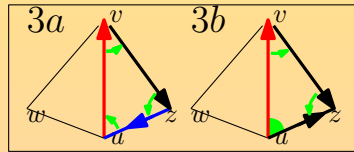
# Most compact DS ( $4n$ references)

(still more compact using vertex reordering)

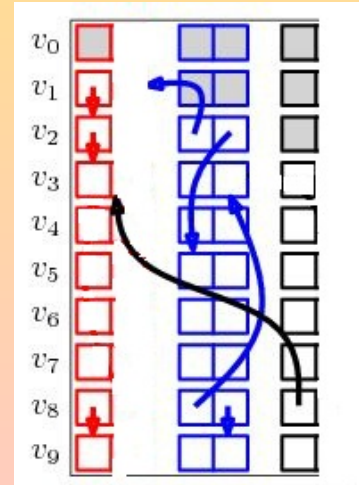
use the *DFUDS* (Depth First Unary Degree Sequence) order on  $\bar{T}_0$



case analysis for red edges



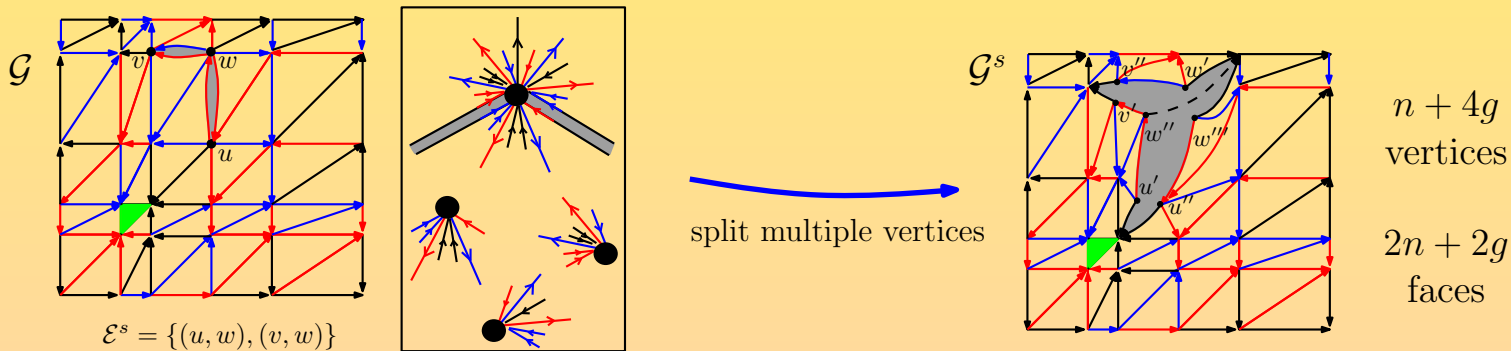
only 1 reference for  
black and red edges



# Compact DS for higher genus meshes (5n references)

combine previous ideas with the use of *genus g Schnyder woods*

(Castelli Aleardi, Fusy, Lewiner SoCG'08)



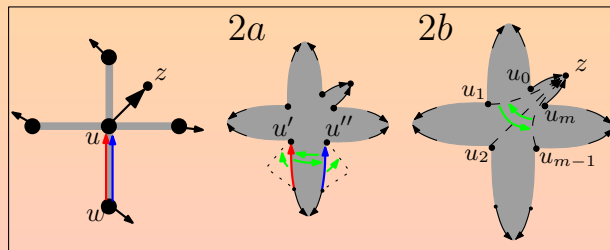
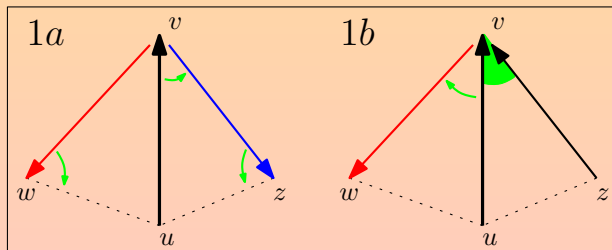
toroidal triangulation endowed with a  $g$ -Schnyder wood

almost all vertices have outgoing degree 3

all vertices have outgoing

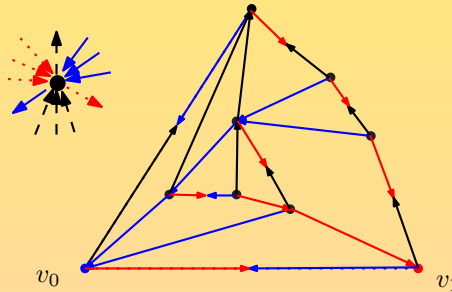
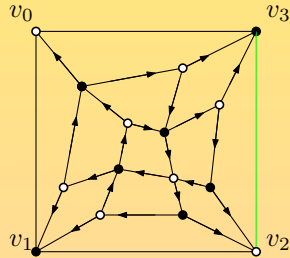
degree at most 3

more cases to  
consider



# Conclusion

- possible extension to more general surface meshes (planar quadrangulations and 3-connected planar maps)



- is it possible to further reduce the space requirements: from  $4n$  to  $3n$  or less?

