

Semantics and Verification

Lecture 6

9 March 2010

Last lecture:

- Hennessy-Milner logic

This lecture:

- Hennessy-Milner logic with recursion (introduction)
- Tarski's fixed-point theorem

Next lecture:

- Hennessy-Milner logic with recursion

Tarski's Fixed-Point Theorem

- 1 Last lecture
- 2 Hennessy-Milner logic with recursion
- 3 Lattice theory
- 4 Tarski's Fixed Point Theorem

Equivalence Checking Approach

$$Impl \equiv Spec$$

- \equiv is an abstract equivalence, e.g. \sim or \approx
- *Spec* is often expressed in the same language as *Impl*
- *Spec* provides the full specification of the intended behaviour

Model Checking Approach

$$Impl \models Property$$

- \models is the satisfaction relation
- *Property* is a particular feature, often expressed via a logic
- *Property* is a partial specification of the intended behaviour

Syntax of the Formulae ($a \in Act$)

$$F, G ::= tt \mid ff \mid F \wedge G \mid F \vee G \mid \langle a \rangle F \mid [a]F$$

Intuition:

tt all processes satisfy this property

ff no process satisfies this property

\wedge, \vee usual logical AND and OR

$\langle a \rangle F$ there is at least one a -successor that satisfies F

$[a]F$ all a -successors have to satisfy F

Hennessy-Milner Logic: Denotational Semantics

For a formula F let $\llbracket F \rrbracket \subseteq Proc$ contain all states that satisfy F .

Denotational Semantics: $\llbracket _ \rrbracket : Formulae \rightarrow 2^{Proc}$

- $\llbracket tt \rrbracket = Proc$
- $\llbracket ff \rrbracket = \emptyset$
- $\llbracket F \vee G \rrbracket = \llbracket F \rrbracket \cup \llbracket G \rrbracket$
- $\llbracket F \wedge G \rrbracket = \llbracket F \rrbracket \cap \llbracket G \rrbracket$
- $\llbracket \langle a \rangle F \rrbracket = \langle \cdot a \cdot \rangle \llbracket F \rrbracket$
- $\llbracket [a] F \rrbracket = [\cdot a \cdot] \llbracket F \rrbracket$

where $\langle \cdot a \cdot \rangle, [\cdot a \cdot] : 2^{Proc} \rightarrow 2^{Proc}$ are defined by

$$\langle \cdot a \cdot \rangle S = \{p \in Proc \mid \exists p'. p \xrightarrow{a} p' \text{ and } p' \in S\}$$

$$[\cdot a \cdot] S = \{p \in Proc \mid \forall p'. p \xrightarrow{a} p' \implies p' \in S\}$$

Hennessey-Milner Theorem

Let $(Proc, Act, \{\xrightarrow{a} \mid a \in Act\})$ be an image-finite LTS and $p, q \in Proc$. Then

$$p \sim q$$

if and only if

for every HML formula F : $(p \models F \iff q \models F)$.

- One says that HML is **adequate** with respect to strong bisimilarity for image-finite LTS.

Is Hennessy-Milner Logic Powerful Enough?

Modal depth (nesting degree) for Hennessy-Milner formulae:

- $md(tt) = md(ff) = 0$
- $md(F \wedge G) = md(F \vee G) = \max\{md(F), md(G)\}$
- $md([a]F) = md(\langle a \rangle F) = md(F) + 1$

Idea: a formula F can “see” only upto depth $md(F)$.

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Idea: a formula F can “see” only upto depth $md(F)$.

Theorem (let F be a HM formula and $k = md(F)$)

If the defender has a winning strategy in the strong bisimulation game from s and t up to k rounds, then $s \models F \iff t \models F$.

Conclusion

There is no Hennessy-Milner formula F that can detect a deadlock in an arbitrary LTS.

Temporal Properties not Expressible in HM Logic

$s \models \text{Inv}(F)$ iff all states reachable from s satisfy F

$s \models \text{Pos}(F)$ iff there is a reachable state which satisfies F

Fact

Properties $\text{Inv}(F)$ and $\text{Pos}(F)$ are not expressible in HM logic.

Temporal Properties not Expressible in HM Logic

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Fact

Properties $Inv(F)$ and $Pos(F)$ are not expressible in HM logic.

Let $Act = \{a_1, a_2, \dots, a_n\}$ be a finite set of actions. We define

- $\langle Act \rangle F \stackrel{\text{def}}{=} \langle a_1 \rangle F \vee \langle a_2 \rangle F \vee \dots \vee \langle a_n \rangle F$
- $[Act]F \stackrel{\text{def}}{=} [a_1]F \wedge [a_2]F \wedge \dots \wedge [a_n]F$

$Inv(F) \equiv F \wedge [Act]F \wedge [Act][Act]F \wedge [Act][Act][Act]F \wedge \dots$

$Pos(F) \equiv F \vee \langle Act \rangle F \vee \langle Act \rangle \langle Act \rangle F \vee \langle Act \rangle \langle Act \rangle \langle Act \rangle F \vee \dots$

- no deadlock = $Inv(\langle Act \rangle tt)$

Problems

- Infinite formulae are not allowed in HM logic
- Infinite formulae are difficult to handle

Why not to use **recursion**?

- $Inv(F)$ expressed by $X \stackrel{\text{def}}{=} F \wedge [Act]X$
- $Pos(F)$ expressed by $Y \stackrel{\text{def}}{=} F \vee \langle Act \rangle Y$

Question: How to define the semantics of such equations?

- Want sets $\llbracket X \rrbracket, \llbracket Y \rrbracket \subseteq 2^{Proc}$

Solving Equations is Tricky

Equations over Natural Numbers ($n \in \mathbb{N}$)

$n = 2 * n$ one solution $n = 0$

$n = n + 1$ no solution

$n = 1 * n$ many solutions (every $n \in \mathbb{N}$ is a solution)

Equations over Sets of Integers ($M \in 2^{\mathbb{N}}$)

$M = (\{7\} \cap M) \cup \{7\}$ one solution $M = \{7\}$

$M = \mathbb{N} \setminus M$ no solution

$M = \{3\} \cup M$ many solutions (every $M \supseteq \{3\}$)

What about Equations over Processes?

$X \stackrel{\text{def}}{=} [a]ff \vee \langle a \rangle X \Rightarrow$ find $S \subseteq 2^{\text{Proc}}$ s.t. $S = [a]\emptyset \cup \langle a \rangle S$

Problem

For a set D and a function $f : D \rightarrow D$, for which elements $x \in D$ do we have

$$x = f(x) ?$$

Such elements are called **fixed points**.

Theorem (Tarski)

Let (D, \sqsubseteq) be a **complete lattice** and let $f : D \rightarrow D$ be a **monotonic function**. Then f has a unique **largest fixed point** z_{max} and a unique **least fixed point** z_{min} given by:

$$z_{max} = \sqcup \{x \in D \mid x \sqsubseteq f(x)\}$$

$$z_{min} = \sqcap \{x \in D \mid f(x) \sqsubseteq x\}$$

Partially ordered set

A partially ordered set (or simply a partial order) is a pair (D, \sqsubseteq) such that

- D is a set
- $\sqsubseteq \subseteq D \times D$ is a binary relation on D which is
 - **reflexive**: $\forall d \in D. d \sqsubseteq d$
 - **antisymmetric**: $\forall d, e \in D. d \sqsubseteq e \wedge e \sqsubseteq d \Rightarrow d = e$
 - **transitive**: $\forall d, e, f \in D. d \sqsubseteq e \wedge e \sqsubseteq f \Rightarrow d \sqsubseteq f$

Monotonic Functions

A function $f : D \rightarrow D$ is called **monotonic** if

$$d \sqsubseteq e \Rightarrow f(d) \sqsubseteq f(e)$$

for all $d, e \in D$.

Upper/Lower Bounds (Let $X \subseteq D$)

- $d \in D$ is an **upper bound** for X (written $X \sqsubseteq d$)
iff $x \sqsubseteq d$ for all $x \in X$
- $d \in D$ is a **lower bound** for X (written $d \sqsubseteq X$)
iff $d \sqsubseteq x$ for all $x \in X$

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Least Upper Bound and Greatest Lower Bound (Let $X \subseteq D$)

- $d \in D$ is the **least upper bound (supremum)** for X ($\sqcup X$) iff
 - 1 $X \sqsubseteq d$
 - 2 $\forall d' \in D. X \sqsubseteq d' \Rightarrow d \sqsubseteq d'$
- $d \in D$ is the **greatest lower bound (infimum)** for X ($\sqcap X$) iff
 - 1 $d \sqsubseteq X$
 - 2 $\forall d' \in D. d' \sqsubseteq X \Rightarrow d' \sqsubseteq d$

Complete Lattice

A partially ordered set (D, \sqsubseteq) is called a **complete lattice** iff $\sqcup X$ and $\sqcap X$ exist for all $X \subseteq D$.

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$$z_{max} \stackrel{\text{def}}{=} \sqcup \{x \in D \mid x \sqsubseteq f(x)\}$$

$$z_{min} \stackrel{\text{def}}{=} \sqcap \{x \in D \mid f(x) \sqsubseteq x\}$$

Computing Fixed Points on Finite Lattices

Let (D, \sqsubseteq) be a complete lattice and $f : D \rightarrow D$ monotonic.

Let $f^1(x) \stackrel{\text{def}}{=} f(x)$ and $f^n(x) \stackrel{\text{def}}{=} f(f^{n-1}(x))$ for $n > 1$, i.e.,

$$f^n(x) = \underbrace{f(f(\dots f(x)\dots))}_{n \text{ times}}.$$

Theorem

If D is a finite set then there exist integers $M, m > 0$ such that

- $Z_{max} = f^M(\top)$
- $Z_{min} = f^m(\perp)$

Idea (for Z_{min}): The following sequence stabilizes for any finite D

$$\perp \sqsubseteq f(\perp) \sqsubseteq f(f(\perp)) \sqsubseteq f(f(f(\perp))) \sqsubseteq \dots$$