

Probabilistic affine forms

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A first step towards the static analysis of probabilistic numerical programs.

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Séminaire LMeASI - 03 novembre 2010

- CPP project funded by the ANR, started in October 2009.
- Goal of the project: study the use of probabilistic information within the static analysis of numerical programs.
 - Probabilistic abstract domains.
 - Probabilistic programs.
- We have mainly considered probabilistic versions of intervals and affine sets.

Introductory example.

- Hipass order 2 linear filter.
- Input values are usually generated by sensors (here simulated by the `inputsignal` function).
- Number of iterations (N) is usually not known.
- Output: `yn`.

```
float inputsignal(int i) {
    return sin(F*i);
}

int main() {
    float xnm2, xnm1, xn, ynm2, ynm1, yn;
    int i;

    xnm2 = inputsignal(-2);
    xnm1 = inputsignal(-1);
    xn = inputsignal(0);
    ynm2 = 0;
    ynm1 = 0;

    for (i=1; i<=N; i++) {
        yn = (2*(c*c-1)*ynm1-
            (c*c-sqrt(2)*c+1)*ynm2+
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            c*c*xnm2)/(c*c+sqrt(2)*c+1);
        ynm2 = ynm1;
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        xnm2 = xnm1;
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    }
    return 0;
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```

Introductory example.

- Hipass order 2 linear filter.
- Input values are usually generated by sensors (here simulated by the `inputsignal` function).
- *Inputs are usually not known.*
- Number of iterations (N) is usually not known.
- Output: `yn`.
- *Need to bound the values of `yn`.*

```

float inputsignal(int i) {
    return sin(F*i); [-1,1];
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Static analysis in 10 seconds.

- Goal of static analysis: compute the smallest possible $D \subseteq \mathbb{R}^n$ such that for all execution of the program, the values of the variables remain within D .
- Classical scheme: program \rightarrow control flow graph \rightarrow semantic equations

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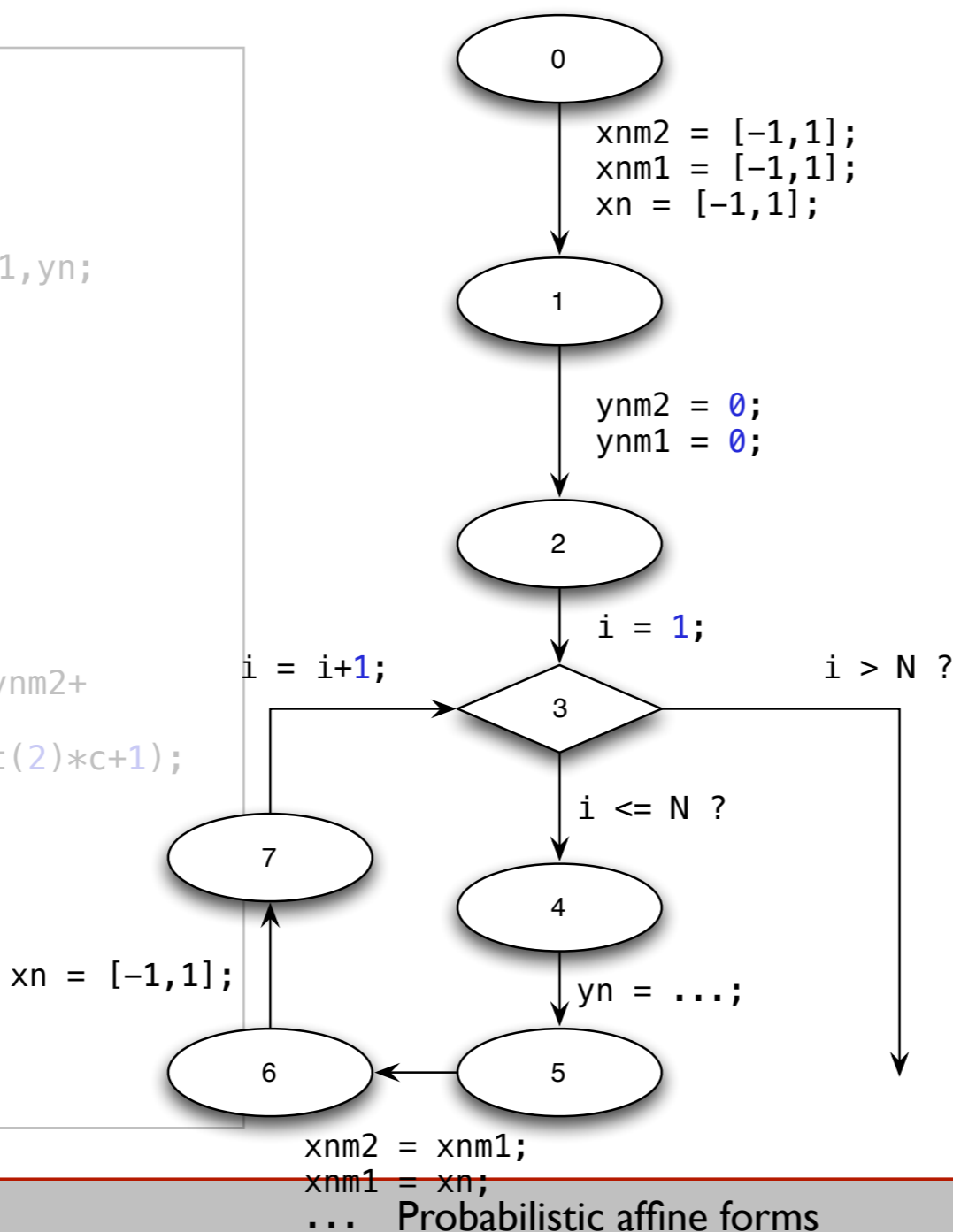
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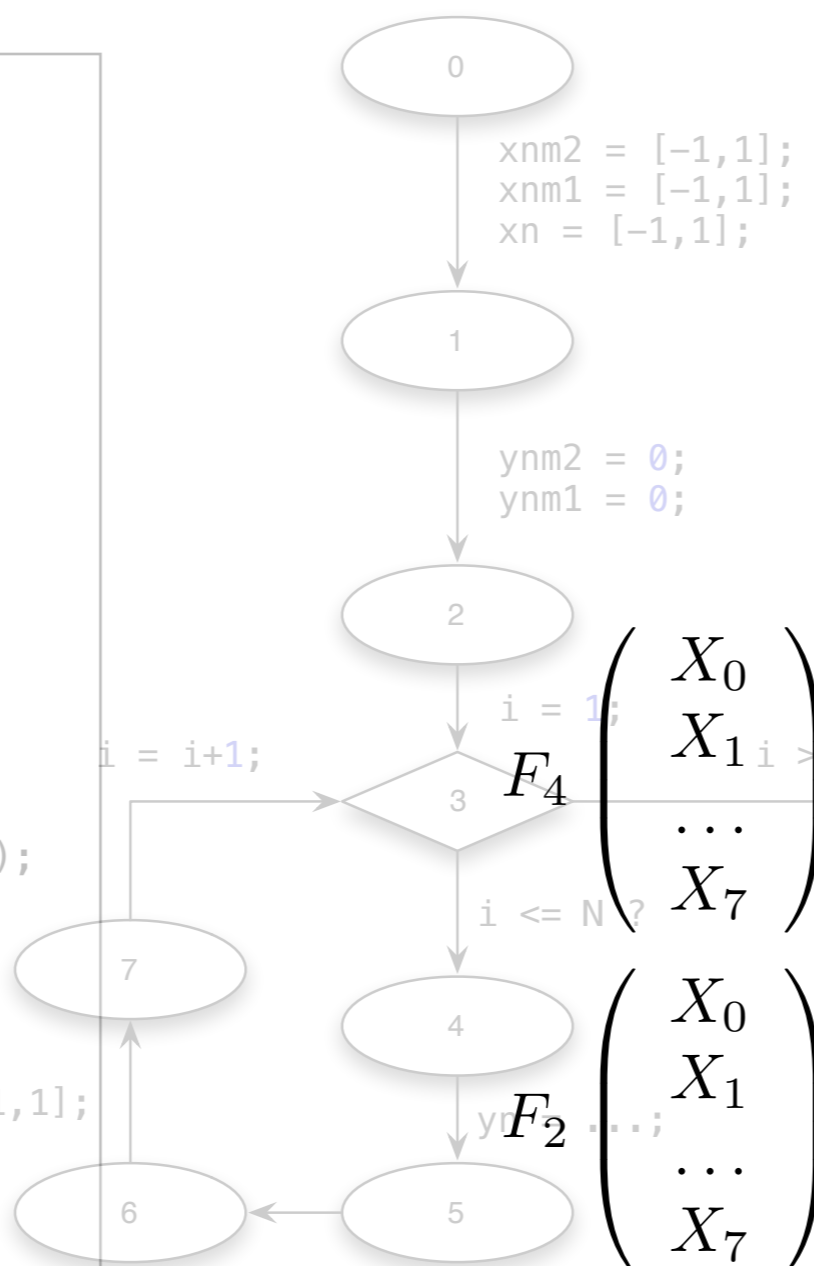
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```



$$\begin{pmatrix} X_0 \\ X_1 \\ \dots \\ X_7 \end{pmatrix} = F \begin{pmatrix} X_0 \\ X_1 \\ \dots \\ X_7 \end{pmatrix}$$

$$F_4 \begin{pmatrix} X_0 \\ X_1 \\ \dots \\ X_7 \end{pmatrix} \stackrel{N?}{=} X_4 [yn \mapsto 2 * (c * c - 1) * ynm1 \dots]$$

$$F_2 \begin{pmatrix} X_0 \\ X_1 \\ \dots \\ X_7 \end{pmatrix} = X_2 [i \mapsto 1] \cup X_7 [i \mapsto i + 1]$$

xnm2 = xnm1;
xnm1 = xn;
... Probabilistic affine forms

Static analysis in 10 (more) seconds.

- All we need to do now is solve the semantic equations.
- Classical scheme: abstract domain \rightarrow Kleene iteration \rightarrow widening.

- The abstract domain must have:

- order theoretic operations (union, intersection) to handle the control flow.

$$X_2[i \mapsto 1] \cup X_7[i \mapsto i + 1]$$

- evaluations of numerical operations to handle numerical expressions in the program.

$$X_4[yn \mapsto 2 * (c * c - 1) * ynm1 - (c * c - \sqrt{2} * c + 1) * ynm2 + c * c * xn - \dots]$$

- With soundness conditions w.r.t. the concrete semantics.

Solving the fixpoint equation: with intervals.

- We chose the interval abstract domain.

$$X_i = \left\{ x \mapsto [\underline{x}, \overline{x}], y_n \mapsto [\underline{y_n}, \overline{y_n}], \dots \right\}$$

- We unroll the loop 30 times and replace each arithmetic operation by its sound interval version.

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        xnm1 = xn;
        xn = inputsignal(i);
    }
    return 0;
}
```

$$y_n \in [-9.79528957, 9.79528957].10^9$$

Solving the fixpoint equation: with affine sets.

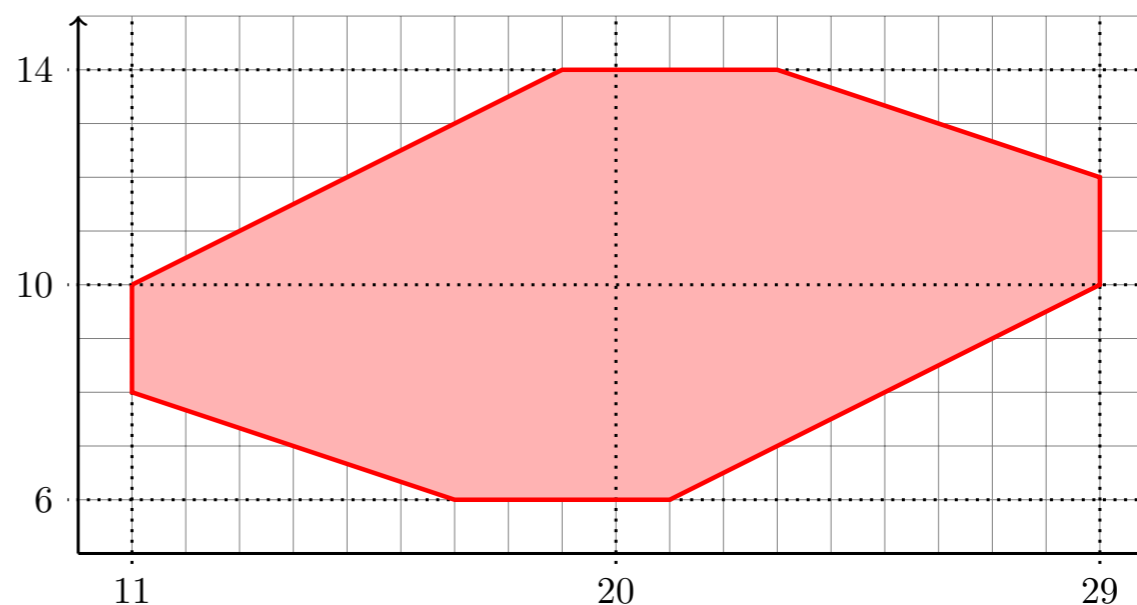
The affine set abstract domain

$$X_i = \left\{ \begin{array}{l} x \mapsto \alpha_0^x + \sum_{i=1}^m \alpha_i^x \epsilon_i \\ y \mapsto \alpha_0^y + \sum_{i=1}^m \alpha_i^y \epsilon_i \\ \dots \end{array} \middle| \alpha_i^v \in \mathbb{R}, \epsilon_i \in [-1, 1] \right\}$$

$$\gamma(X_i) = \left\{ (x, y, \dots) \in \mathbb{R}^m \middle| \exists \epsilon_1, \dots, \epsilon_n \in [-1, 1]^n, \begin{array}{l} x = \alpha_0^x + \sum_{i=1}^m \alpha_i^x \epsilon_i \\ y = \alpha_0^y + \sum_{i=1}^m \alpha_i^y \epsilon_i \\ \dots \end{array} \right\}$$

$$x = 20 - 4\epsilon_1 + 2\epsilon_3 + 3\epsilon_4$$

$$y = 10 - 2\epsilon_1 + \epsilon_2 - \epsilon_4$$



Solving the fixpoint equation: with affine sets.

The affine set arithmetic: linear operations

$$ax + by + c = (\alpha_0^x + \alpha_0^y + c) + \sum_{i=1}^m (\alpha_i^x + \alpha_i^y) \epsilon_i$$

Linear operations are exact.

Affectation creates a new noise symbol.

$$x = [a, b]; \quad \longrightarrow \quad x = \frac{a+b}{2} + \frac{b-a}{2} \epsilon_{m+1}$$

$$x = 20 - 4\epsilon_1 + 2\epsilon_3 + 3\epsilon_4$$

$$y = 10 - 2\epsilon_1 + \epsilon_2 - \epsilon_4$$

$$t = [1, 5];$$

$$z = x + 3y + t;$$



$$x = 20 - 4\epsilon_1 + 2\epsilon_3 + 3\epsilon_4$$

$$y = 10 - 2\epsilon_1 + \epsilon_2 - \epsilon_4$$

$$z = 53 - 10\epsilon_1 + 3\epsilon_2 + 2\epsilon_3 + 2\epsilon_5$$

$$t = 3 + 2\epsilon_5$$

Solving the fixpoint equation: with affine sets.

The affine set arithmetic: non-linear operations

$$x * y = (\alpha_0^x * \alpha_0^y) + \sum_{i=1}^m (\alpha_0^x \alpha_i^y + \alpha_0^y \alpha_i^x) \epsilon_i + \sum_{1 \leq i, j \leq m} \alpha_i^x \alpha_j^y \epsilon_i \epsilon_j$$

Non-linear terms are approximated in a new noise symbol.

$$\sum_{1 \leq i, j \leq m} \alpha_i^x \alpha_j^y \epsilon_i \epsilon_j \subseteq \left(\sum_{i=1}^m |\alpha_i^x| \cdot \sum_{i=1}^m |\alpha_i^y| \right) \eta_1$$

$$\begin{array}{l}
 x = 20 - 4\epsilon_1 + 2\epsilon_3 + 3\epsilon_4 \\
 y = 10 - 2\epsilon_1 + \epsilon_2 - \epsilon_4
 \end{array}
 \quad
 \begin{array}{l}
 \mathbf{t} = [1, 5]; \\
 \mathbf{z} = \mathbf{x} * \mathbf{t}; \\
 \longrightarrow
 \end{array}
 \quad
 \begin{array}{l}
 x = 20 - 4\epsilon_1 + 2\epsilon_3 + 3\epsilon_4 \\
 y = 10 - 2\epsilon_1 + \epsilon_2 - \epsilon_4 \\
 z = 60 - 12\epsilon_1 + 6\epsilon_3 + 9\epsilon_4 + 40\epsilon_5 + 18\eta_1 \\
 t = 3 + 2\epsilon_5
 \end{array}$$

Solving the fixpoint equation: with affine sets.

- We chose the affine set abstract domain.
- We unroll the loop 30 times and replace each arithmetic operation by its sound affine set version.

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```

$$y_n \in [-2.33900235, 2.33900235]$$

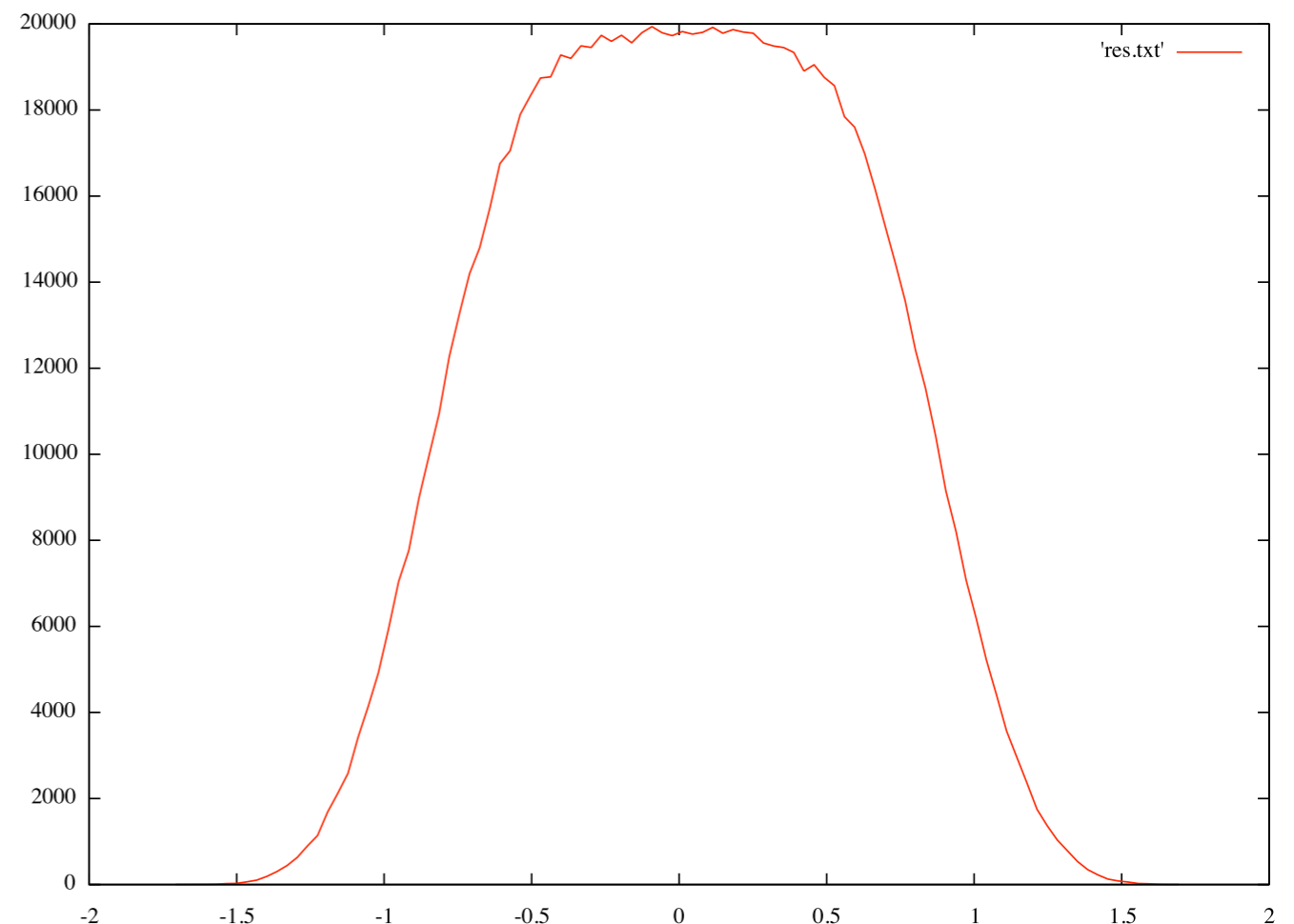
Some remarks about the inputs.

- What does it mean: $x = [-1, 1]$?
- At each loop iterate, a new value of x can be non-deterministically chosen between -1 and 1 .
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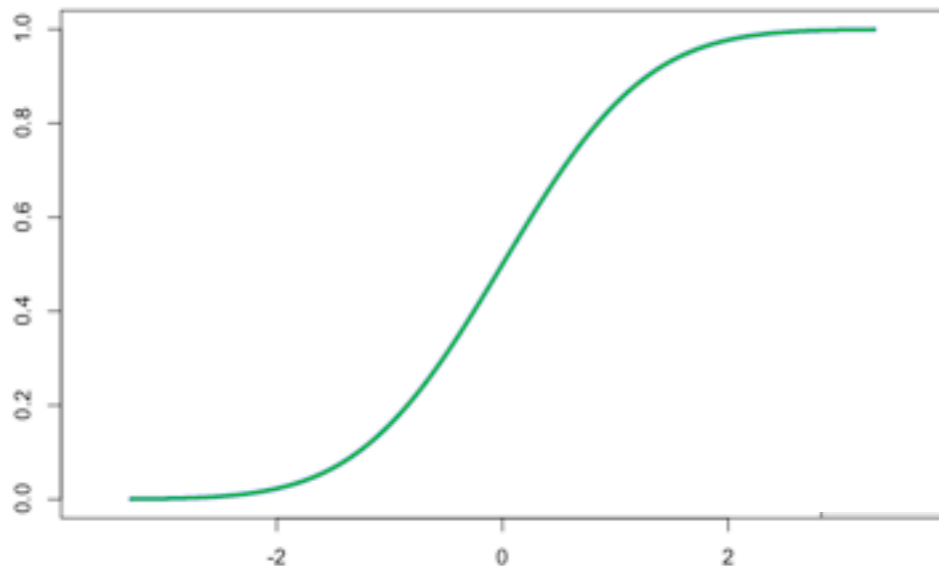
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- Simulation of the program.
- Assuming inputs are independent and uniformly distributed between -1 and 1 .



What is a realistic input ?

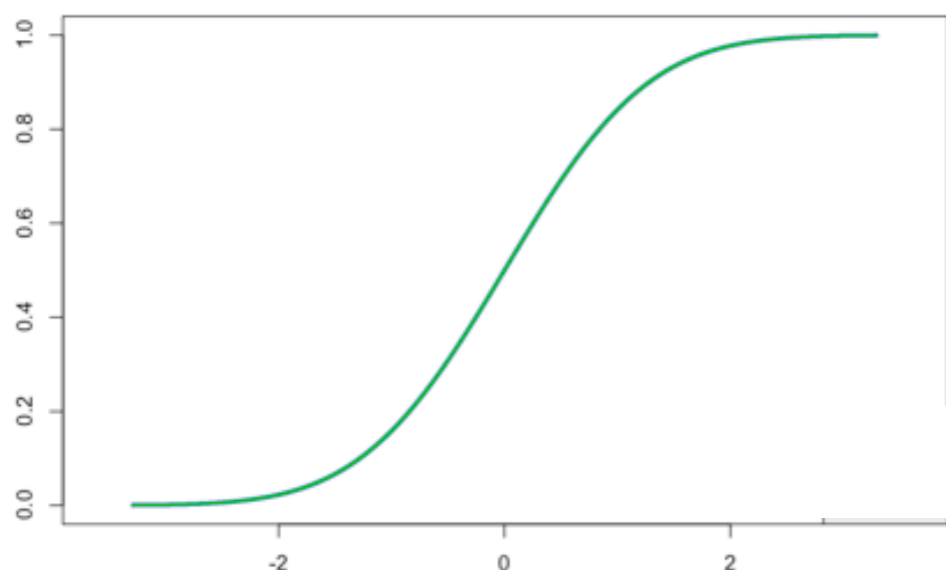
- Input values are often given by sensors that measure some physical value.
- This introduces two kinds of uncertainty:
 - non-deterministic when the evolution of the physical value is not completely determined (e.g. $\dot{y} \in [3, 3.1]$).
 - a probabilistic noise due to measurement errors.
- We need a model that can handle both kind in a uniform way.



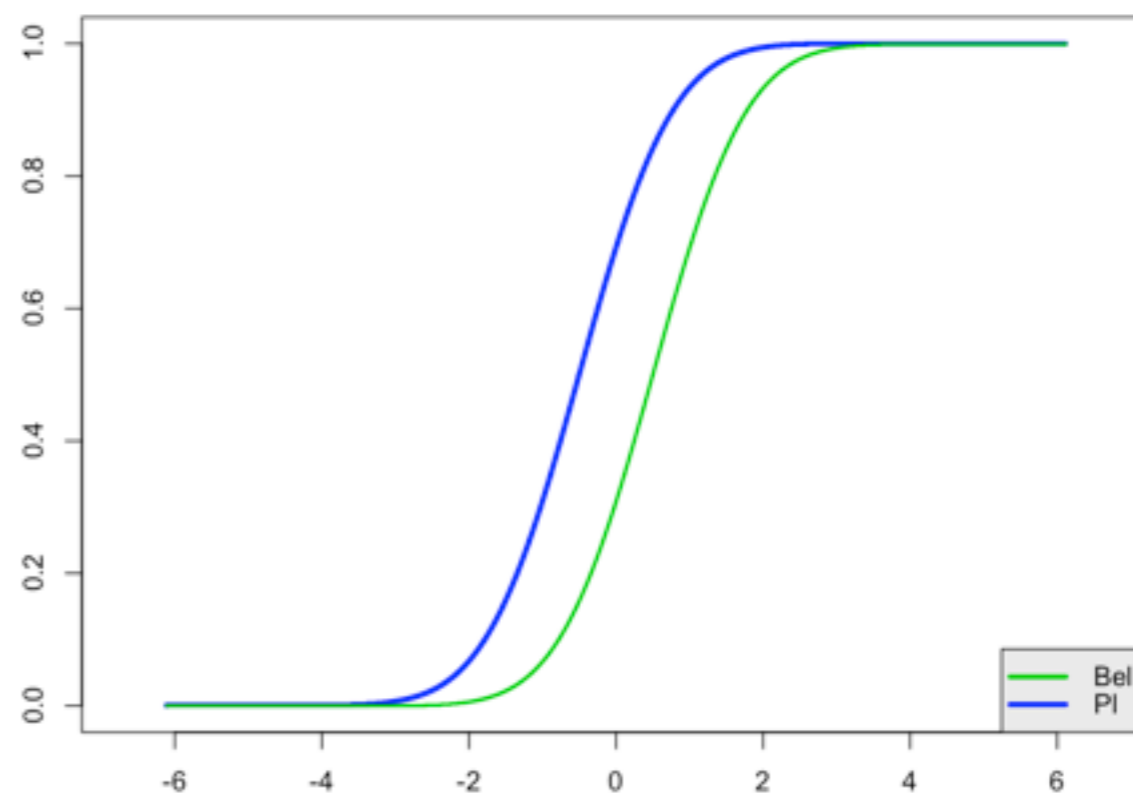
$$\text{mean} \in [-1, 1]$$

What is a realistic input ?

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mean $\in [-1, 1]$



Semantics of a program with probabilistic inputs.

Formally: we consider *deterministic* programs only.

- Semantics of the program.

$$\llbracket P \rrbracket : \mathbb{R}^n \rightarrow \mathbb{R}^n$$

- Adding non-determinism:
collecting semantics.

$$\llbracket P \rrbracket^c : \mathcal{P}(\mathbb{R}^n) \rightarrow \mathcal{P}(\mathbb{R}^n)$$

- Abstraction:
abstract semantics.

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- *Probabilistic* semantics.

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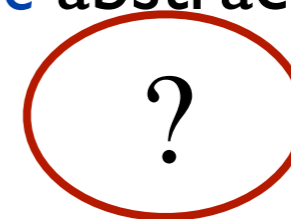
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Uncertain probabilities.

- A large community exist in the context of *uncertain probabilities*.
- It designs methods to deal with non-determinism and probability in a uniform way.
 - Mostly used in risk assessment.
 - Various terms: clouds, fuzzy sets, P-boxes, Demster-Schafer structures,
- Rules for combining such sets exist, but no real arithmetic is given.
- In the rest, I will present P-Boxes and D-S structures over \mathbb{R} .

P-Boxes: definition.

- A P-Box is given by two functions \underline{F} and \overline{F} such that:

$$\underline{F}, \overline{F} : \mathbb{R} \rightarrow [0, 1]$$

$$\forall x \in \mathbb{R}, \underline{F}(x) \leq \overline{F}(x)$$

- \underline{F} and \overline{F} represent bounds on the set of distribution functions.
- When $\underline{F} = \overline{F}$, the P-Box represent *one* distribution.

- Order: $(\underline{F}, \overline{F}) \subseteq (\underline{G}, \overline{G}) \Leftrightarrow \forall x \in \mathbb{R}, \underline{G}(x) \leq \underline{F}(x) \leq \overline{F}(x) \leq \overline{G}(x)$

- Maximal element: $\underline{F} = \lambda x.0, \overline{F} = \lambda x.1$

- Concretization: $\gamma(\underline{F}, \overline{F}) = \left\{ P \mid \forall x, \underline{F}(x) \leq P(X \leq x) \leq \overline{F}(x) \right\}$

P-Boxes: arithmetic.

- Let $(\underline{F}_X, \overline{F}_X)$ and $(\underline{F}_Y, \overline{F}_Y)$ be the P-Boxes associated to variables X et Y .
- Let $Z = X \square Y$ with $\square \in \{+, \times, -, /\}$. How to compute $(\underline{F}_Z, \overline{F}_Z)$?

- It depends on the dependency between X and Y .

- If X and Y are independent: see DS structures.

- If X and Y are not independent (unknown dependency): **Frechet bounds**

$$\forall P_X \in \gamma(\underline{F}_X, \overline{F}_X), P_Y \in \gamma(\underline{F}_Y, \overline{F}_Y),$$

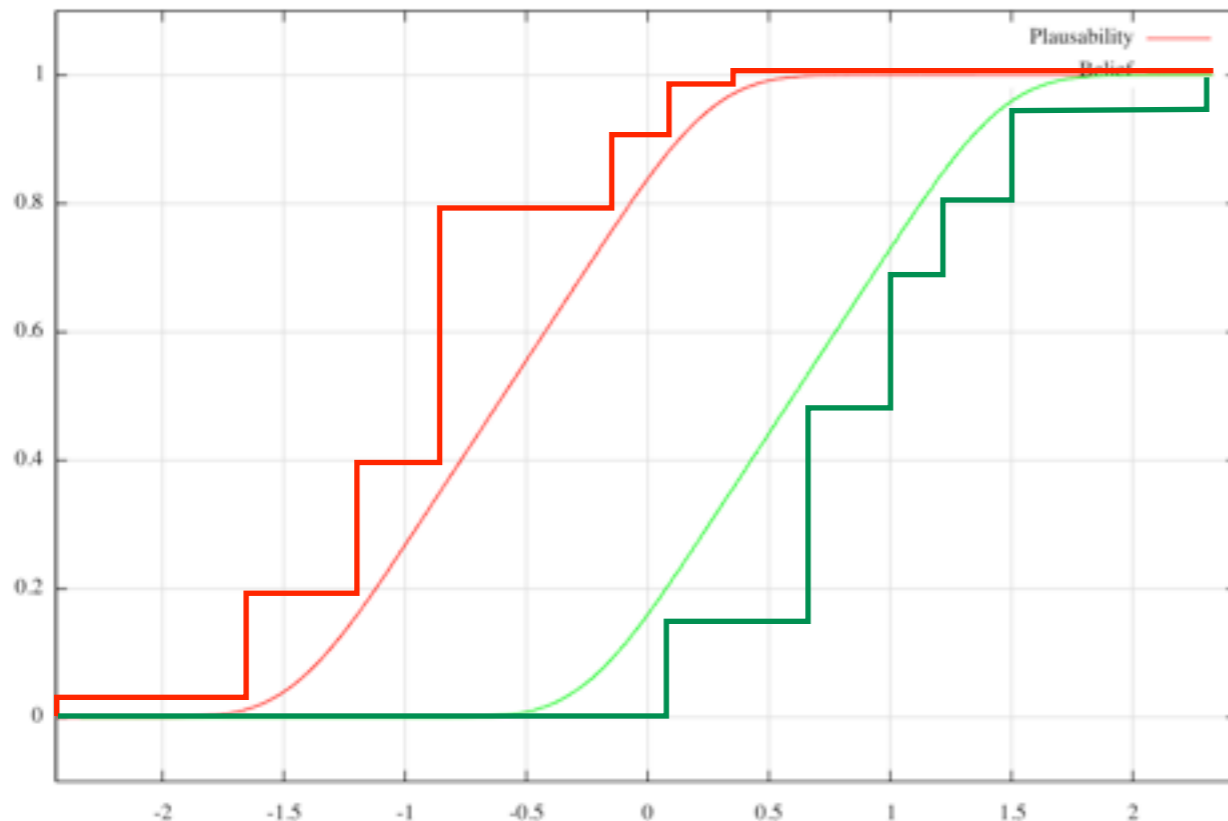
$$P(X \square Y < u) \leq \inf_{x \square y = u} \min(P_X(X < x) + P_Y(Y < y), 1)$$

$$P(X \square Y < u) \geq \sup_{x \square y = u} \max(P_X(X < x) + P_Y(Y < y) - 1, 0)$$

$$(\underline{F}_Z, \overline{F}_Z) = \lambda u. \left(\sup_{x \square y = u} \max(\underline{F}_X(x) + \underline{F}_Y(y) - 1, 0), \inf_{x \square y = u} \min(\overline{F}_X(x) + \overline{F}_Y(y), 1) \right)$$

P-Boxes: problem of representation.

- Need to represent two continuous functions for each P-Box.
- Computation of bounds for the result of any arithmetic operator requires an optimization problem.
- One solution to solve this problem: use step functions.



- Discretization of the continuous functions.
- Introduces an over-approximation.
- Equivalent to Demster-Schafer structures.

Demster-Schafer structures: definition.

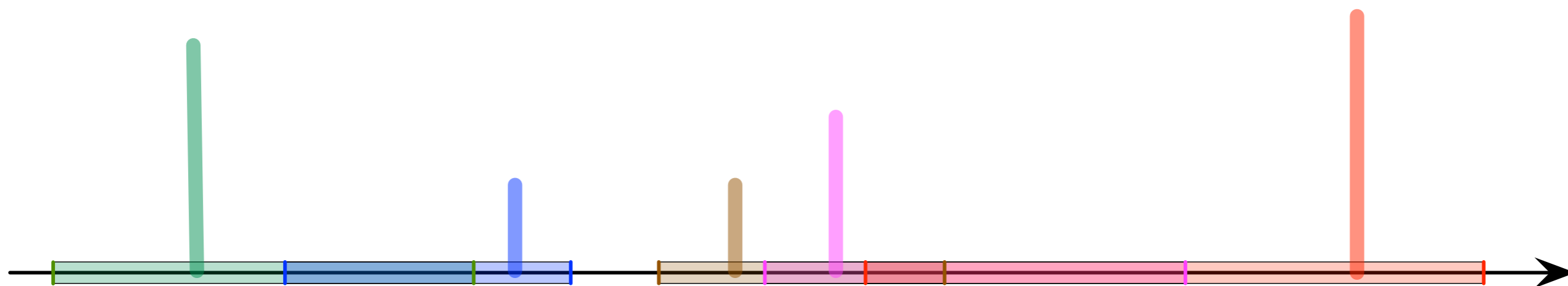
- A Dempster-Schafer structure is a set of *focal elements* associated with a probability.

$$D = \left\{ (f_i, w_i) \mid f_i \text{ is a focal element and } w_i \in [0, 1], \sum_i w_i = 1 \right\}$$

- Probabilistic choice between focal elements and then non-deterministic choice within the focal element.
- Usually, focal elements are *closed intervals*.

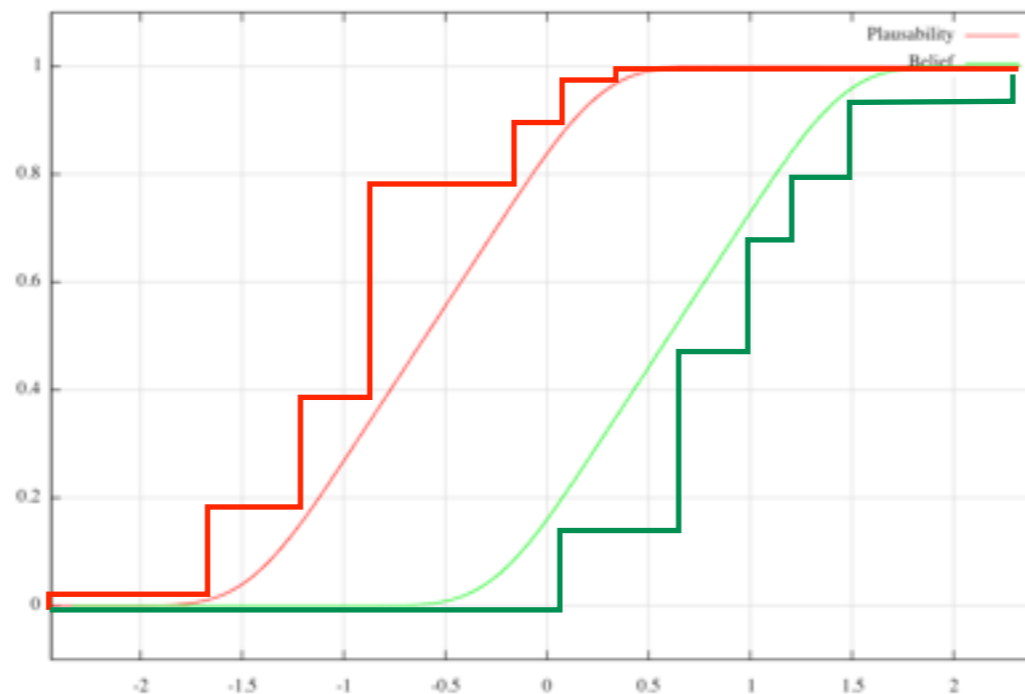
$$D = \left\{ ([a_i, b_i], w_i) \mid a_i \leq b_i \text{ and } w_i \in [0, 1], \sum_i w_i = 1 \right\}$$

- Example:

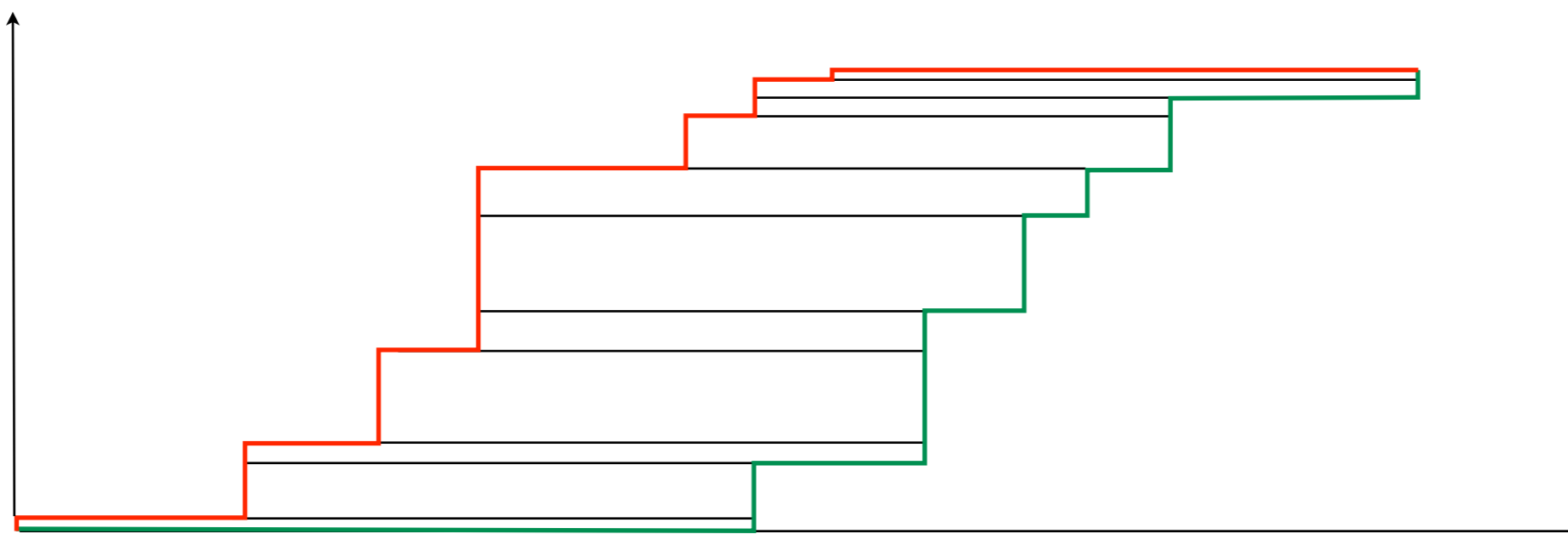


From P-Boxes to DS-structures

1. From a continuous to a discrete P-Box: discretization.



2. From a discrete P-Box to a DS-structure: Moebius inversion.



From DS-Structures to P-Boxes.

- Given a DS-Structure

$$D = \{([a_i, b_i], w_i), i \in [1, n]\}$$

- We define the two functions \underline{F} and \overline{F} by:

$$\underline{F}(x) = \sum_{i \mid b_i \leq x} w_i \quad \overline{F}(x) = \sum_{i \mid a_i < x} w_i$$

- This forms a P-Box and

$$\gamma(D) = \gamma(\underline{F}, \overline{F})$$

- A DS-structure thus represents a set of probability distributions enclosed by step functions.

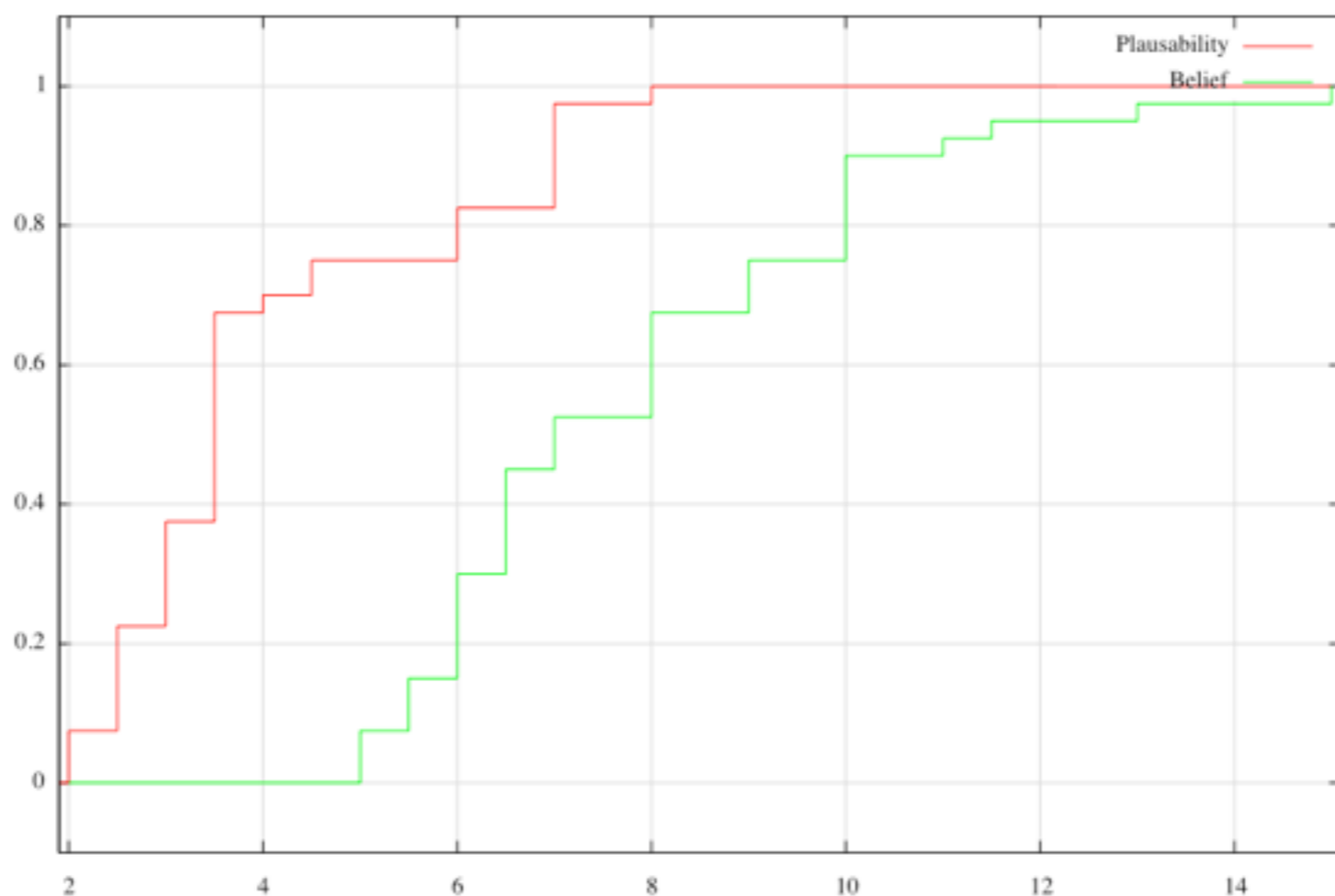
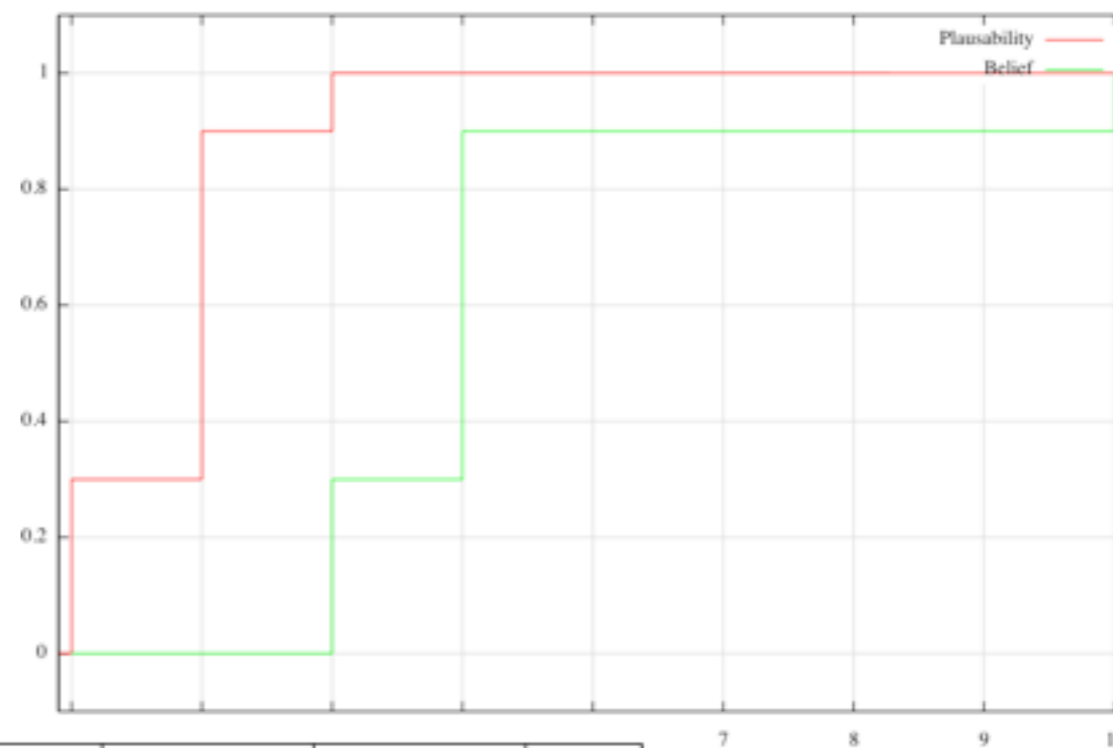
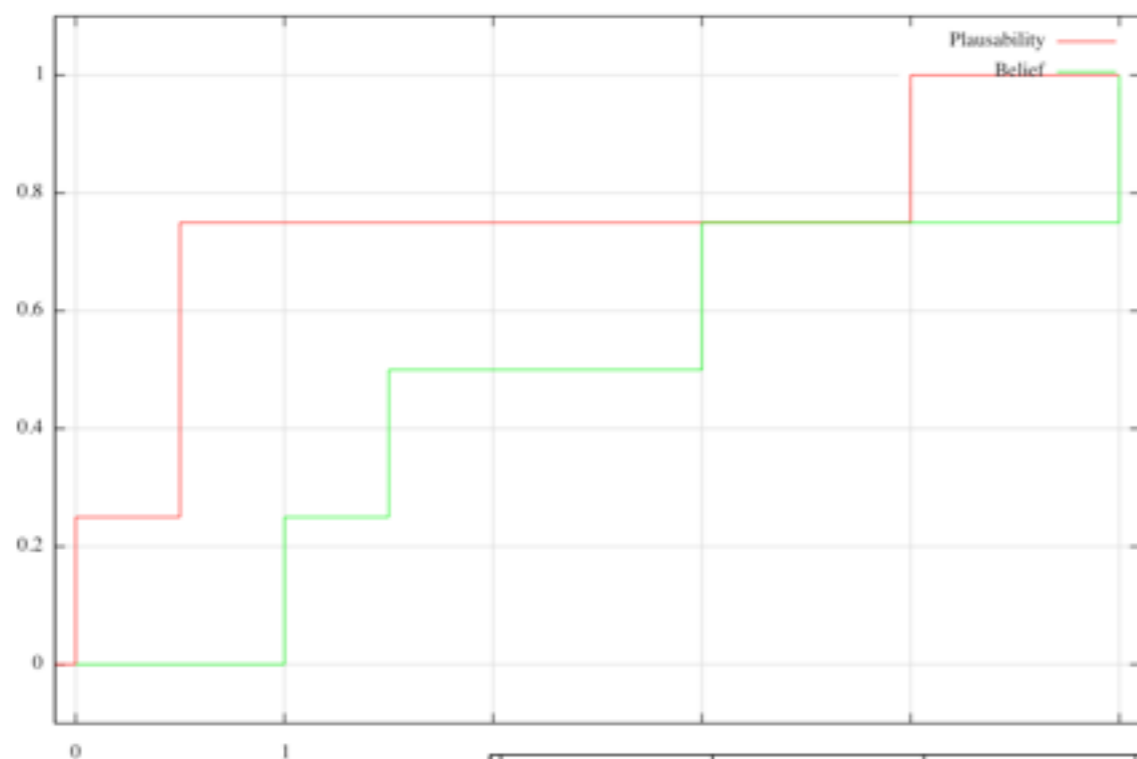
Demster-Schafer structures arithmetic.

- Case of independent inputs.

$$Z = \left\{ ([a_{ij}, b_{ij}], w_{ij}) \mid \exists i, j, [a_{ij}, b_{ij}] = [a_i, b_i] \square [a'_j, b'_j], w_{ij} = w_i \cdot w'_j \right\}$$

$Y \backslash X$	$[0, 1]$	$[0.5, 1.5]$	$[0.5, 3]$	$[4, 5]$
$[2, 4]$ 0.3	$[2, 5]$ 0.075	$[2.5, 5.5]$ 0.075	$[2.5, 7]$ 0.075	$[6, 9]$ 0.075
$[3, 5]$ 0.6	$[3, 6]$ 0.150	$[3.5, 6.5]$ 0.150	$[3.5, 8]$ 0.150	$[7, 10]$ 0.150
$[4, 10]$ 0.1	$[4, 11]$ 0.025	$[4.5, 11.5]$ 0.025	$[4.5, 13]$ 0.025	$[8, 15]$ 0.025

Demster-Schafer structures arithmetic: example.



Demster-Schafer structures arithmetic.

- Case of dependent inputs (unknown dependency).

$X \backslash Y$		[2, 4]	[3, 5]	[4, 10]
		0.3	0.6	0.1
[0, 1] 0.25		[2, 5] p_{11}	[3, 6] p_{12}	[4, 11] p_{13}
[0.5, 1.5] 0.25		[2.5, 5.5] p_{21}	[3.5, 6.5] p_{22}	[4.5, 11.5] p_{23}
[0.5, 3] 0.25		[2.5, 7] p_{31}	[3.5, 8] p_{32}	[4.5, 13] p_{33}
[4, 5] 0.25		[6, 9] p_{41}	[7, 10] p_{42}	[8, 15] p_{43}

$$p_i = \sum_{j=1}^n p_{i,j}$$

$$p'_j = \sum_{i=1}^m p_{i,j}$$

$$P(Z \leq z) \leq \sum_{a'_i \leq z} p_{i,j}$$

$$P(Z \leq z) \geq \sum_{b'_i \leq z} p_{i,j}$$

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Demster-Schafer structures arithmetic: direct method.

- Remember (P-Box arithmetic):

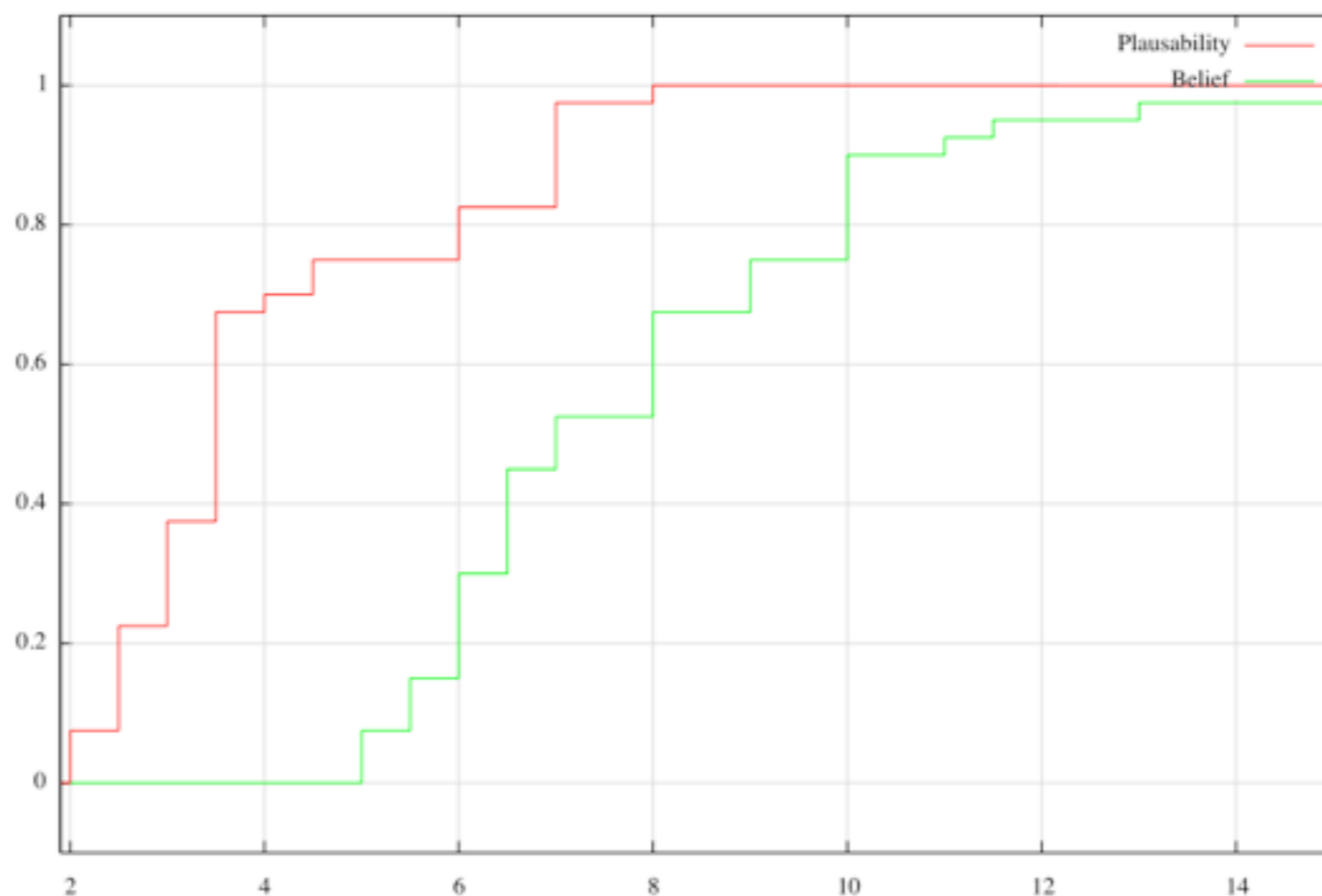
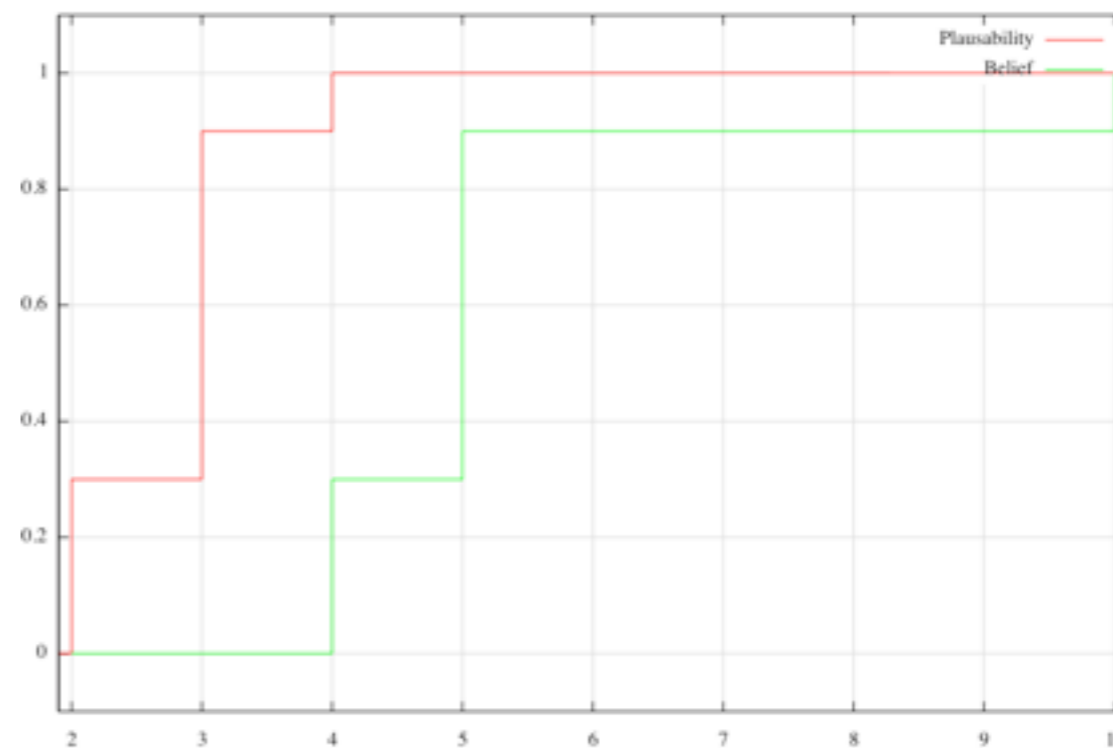
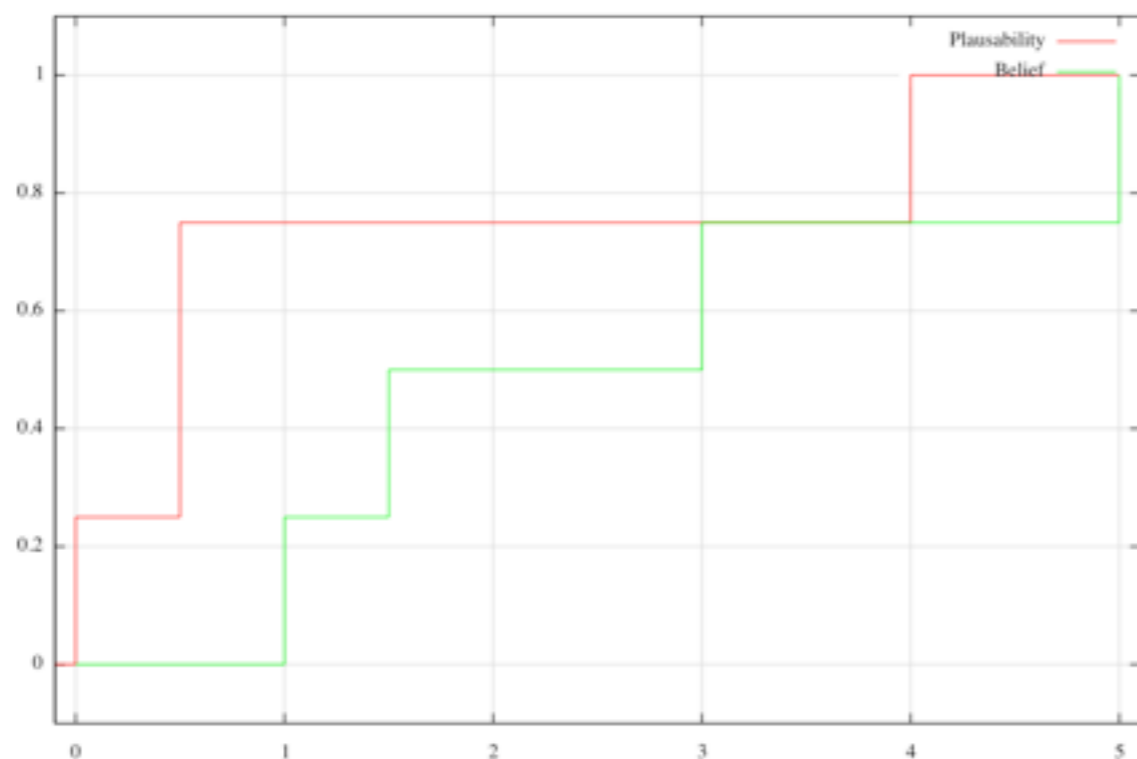
$$(\underline{F}_Z, \overline{F}_Z) = \lambda u. \left(\sup_{x \square y = u} \max(\underline{F}_X(x) + \underline{F}_Y(y) - 1, 0), \inf_{x \square y = u} \min(\overline{F}_X(x) + \overline{F}_Y(y), 1) \right)$$

- And (DS-structure to P-Box conversion):

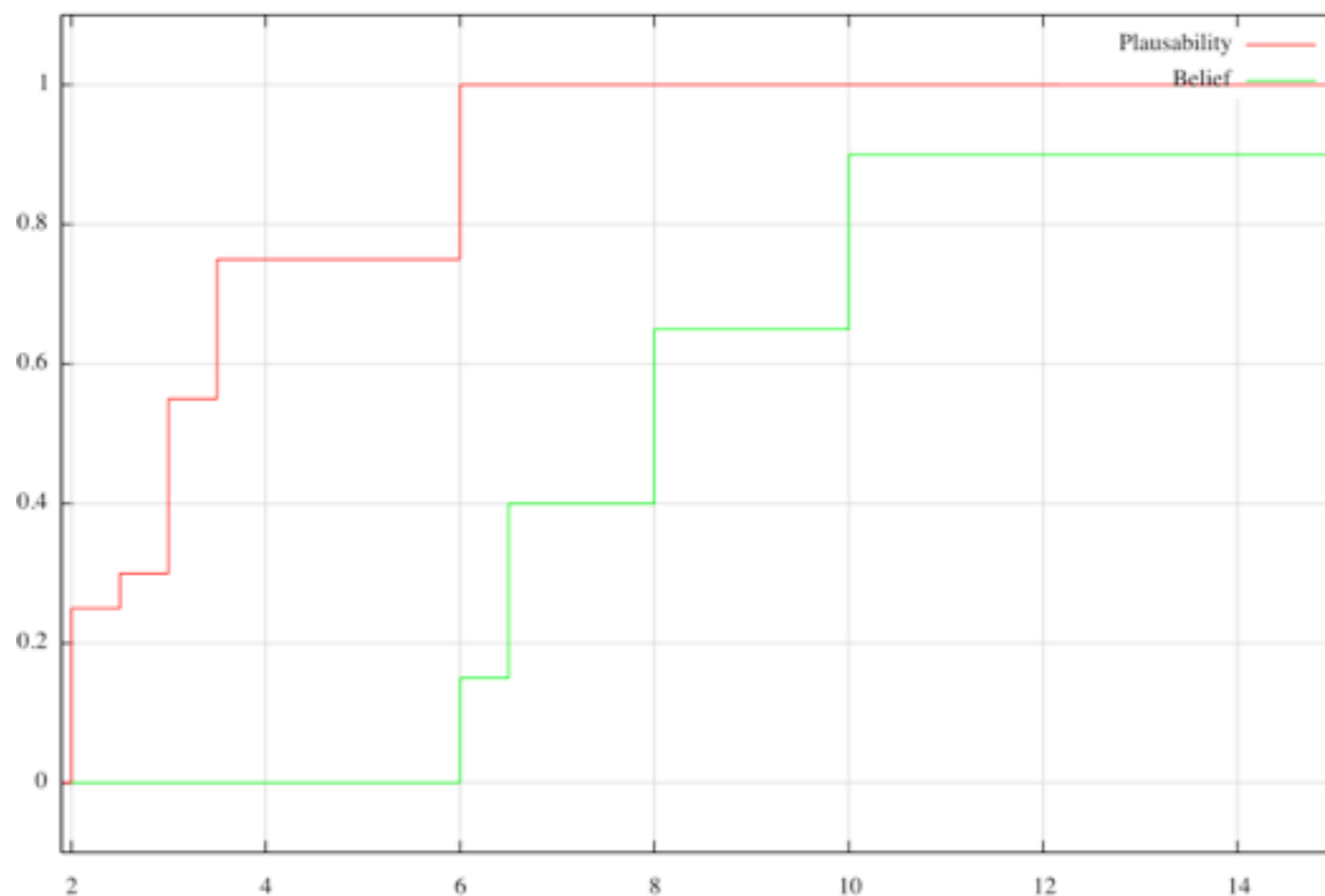
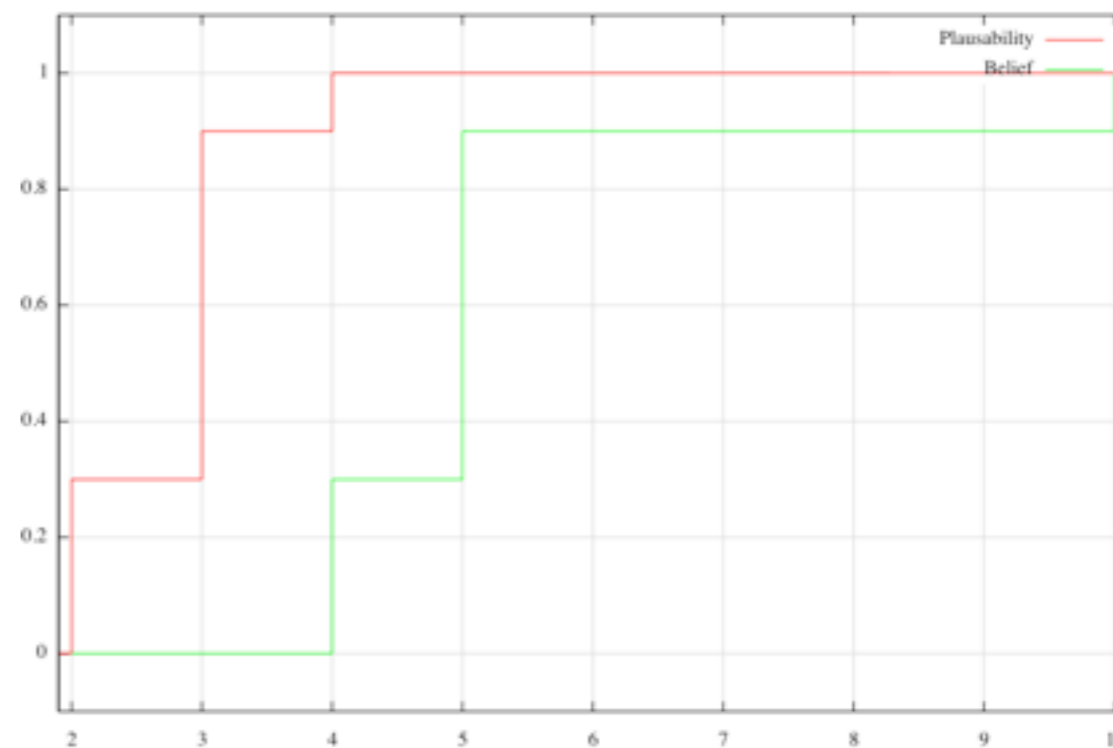
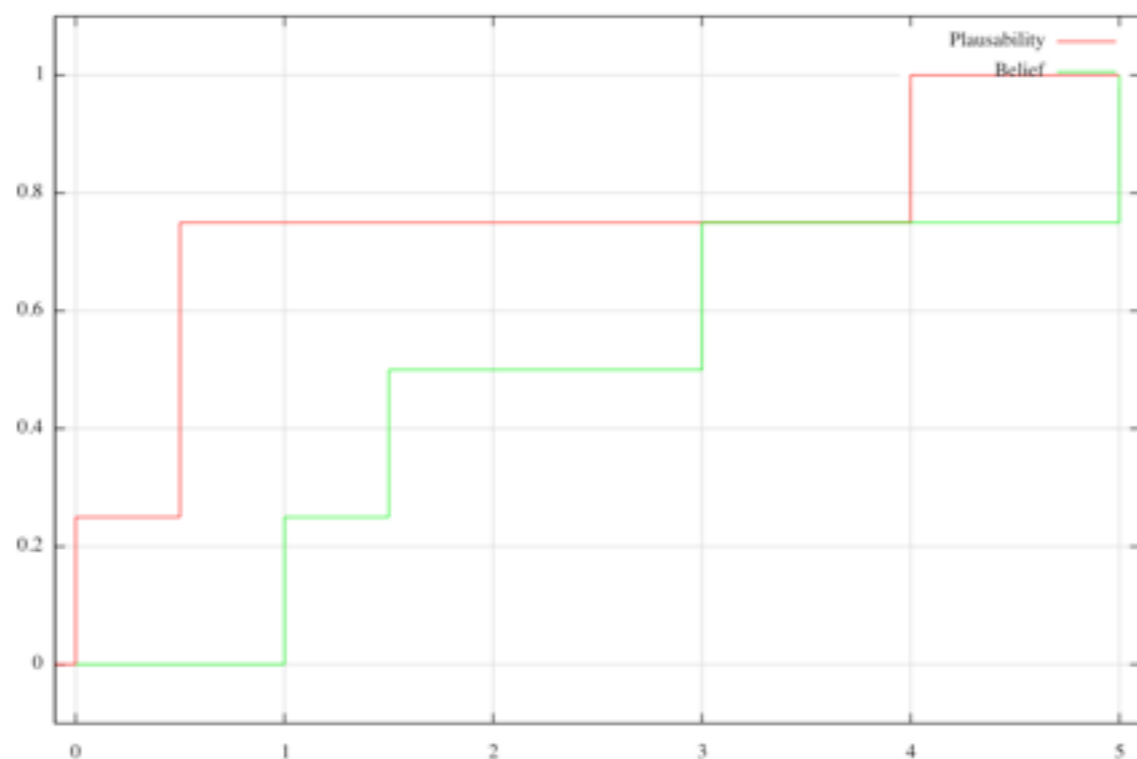
$$\underline{F}(x) = \sum_{i \mid b_i \leq x} w_i \quad \overline{F}(x) = \sum_{i \mid a_i < x} w_i$$

- Combining both we get a direct algorithm to compute the DS-structure of $Z = X \square Y$ with unknown dependency.

Demster-Schafer structures arithmetic: example.

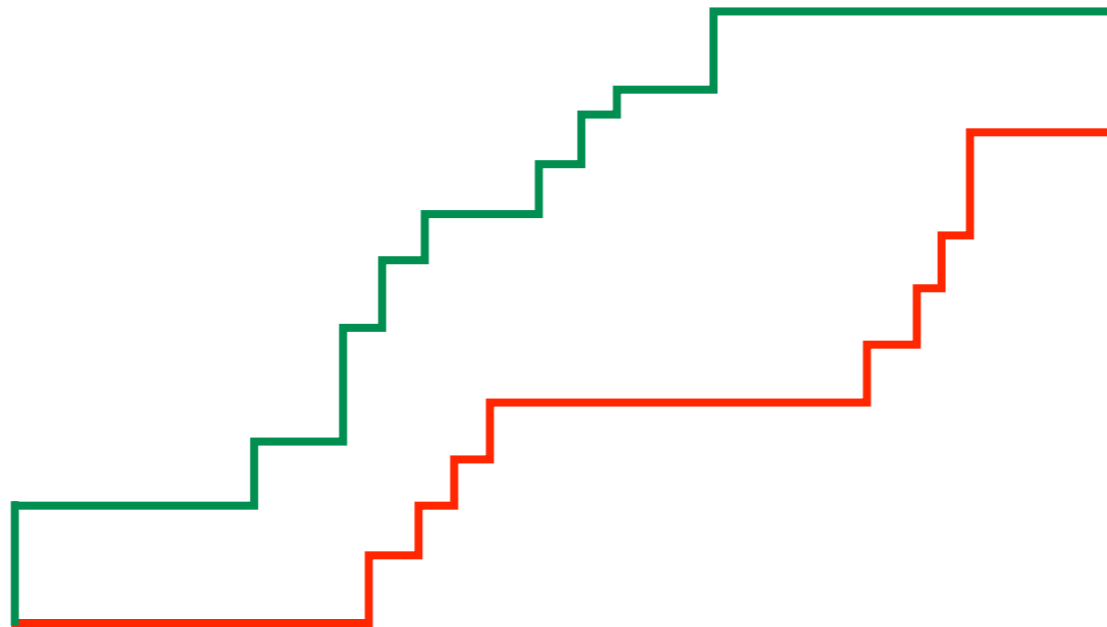


Demster-Schafer structures arithmetic: example.



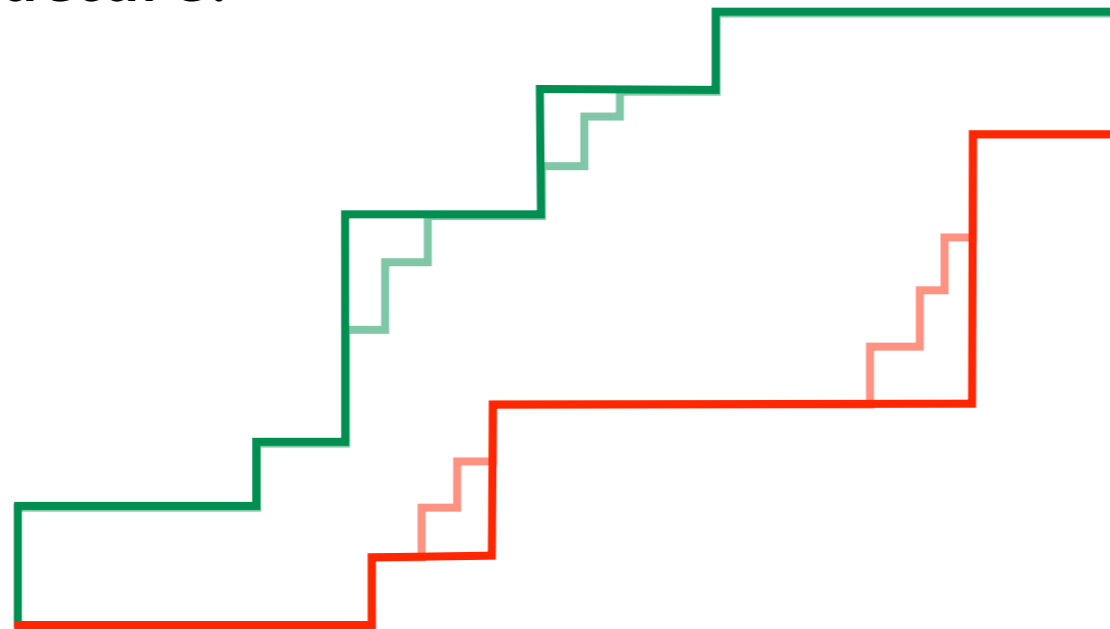
Examples of use.

- The DS-structure arithmetic has been re-implemented in C++.
- Code inspired by the Statool software.
- Implements both independent and dependent arithmetics.
- Easy to use: operator overloading.
- Efficiency: reduction operator to control the number of focal elements in the DS-structure.



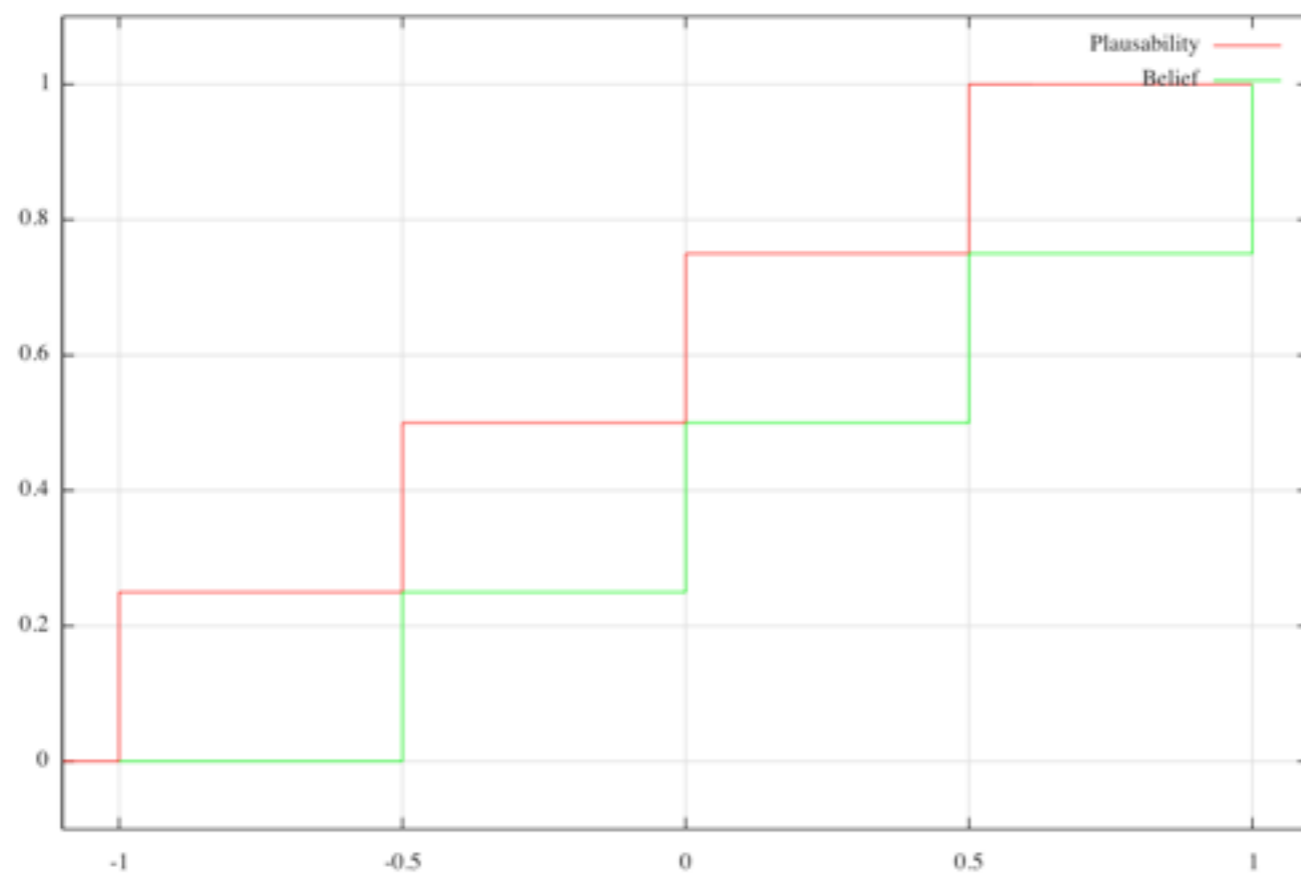
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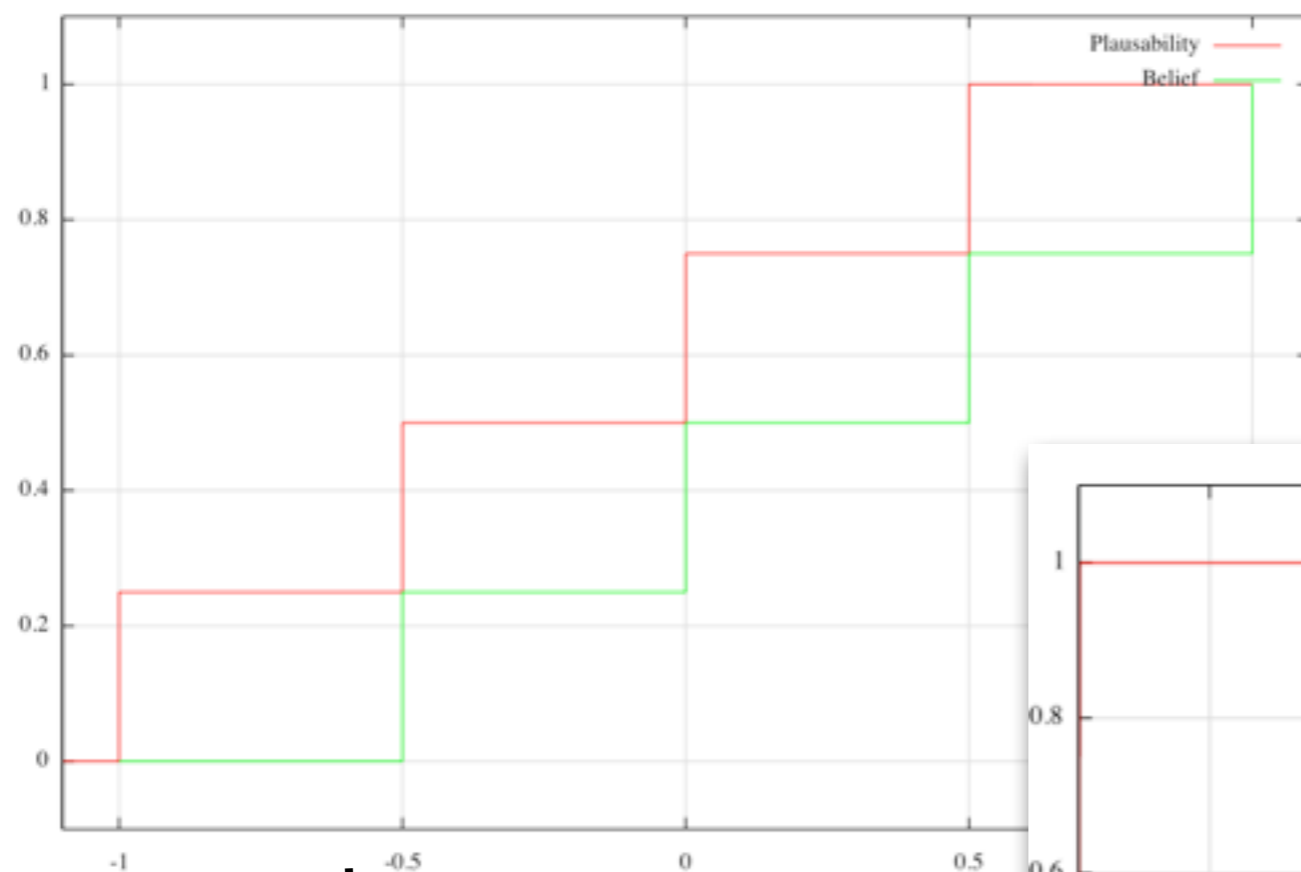
Examples of use.

- Filter with DS entries between -1 and 1 .

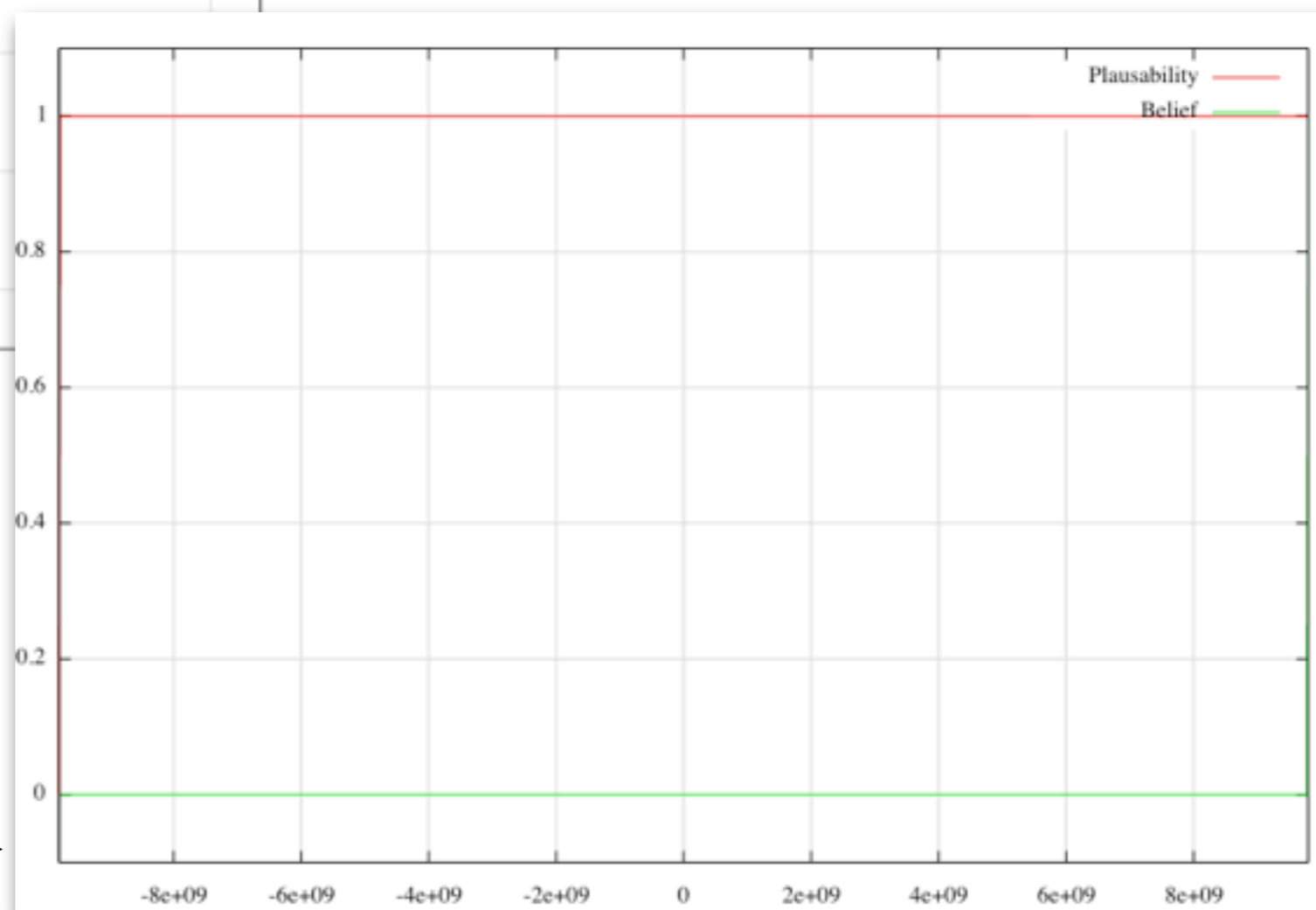


Examples of use.

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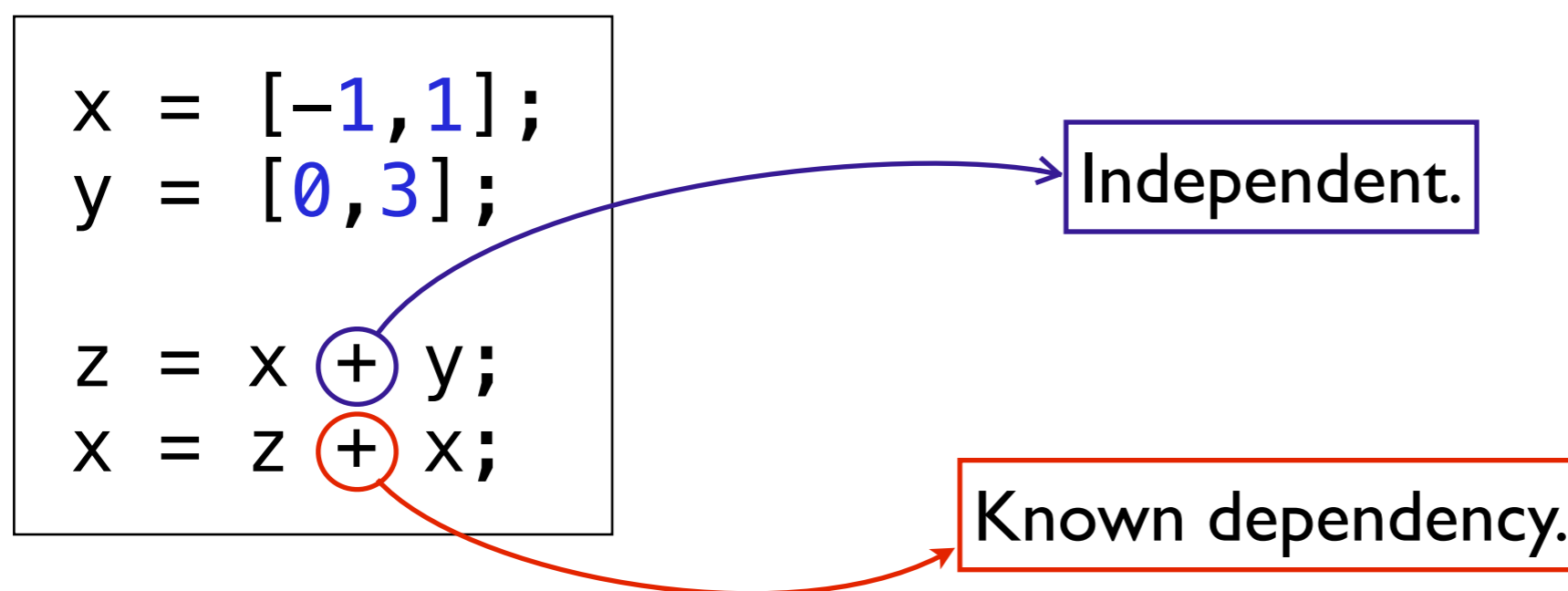


30 iterations.



Problems with the DS-Structure approach.

- When we use the «unknown dependency» arithmetics, we make huge over-approximations.
- There are cases where the dependency between variables is known.



- How can we encode this dependency ?
 - Most general way: notion of copulas.
 - Our approach: encode *linear* dependency only using affine sets.

Probabilistic affine sets.

- An affine set is the image by an affine transformation of the n -dimensional cube $[-1, 1]^n$
- A Demster-Schafer structure is given by a sequence of focal elements with associated probabilities.
- Two ways of mixing both:
 - either construct DS structures with focal elements being zonotopes.
 - either define the affine transformation of a DS structure with focal elements contained in the n -dimensional cube.
 - are both ways the same ?
- We chose the second approach and show that in this way, we introduce linear relationships between variables that help reduce the overapproximation.

Probabilistic affine sets: concept.

- A probabilistic affine set is given by:
 - an affine transformation of a set of noise symbols.
 - a function associating each noise symbol with a P-Box.
- We distinguish two kinds of noise symbols:
 - the ones representing independent inputs (ε_i). Sharing of these symbols represent linear relations between variables.
 - the ones coming from non-linear operations between variables (η_j). One such symbol is created at each non-linear operation.
- Both kinds of symbols are treated differently:
 - ε_i is supposed to be independent from $\varepsilon_{i'}$ ($i \neq i'$).
 - the dependency relation between η_j and any other noise symbol is unknown.

Probabilistic affine sets: definition.

The probabilistic affine set abstract domain

$$X_i^p = (X_i, \varphi^p)$$

$$X_i^p = \left\{ \begin{array}{l} x \mapsto \alpha_0^x + \sum_{i=1}^m \alpha_i^x \epsilon_i + \sum_{j=1}^n \beta_j^x \eta_j \\ y \mapsto \alpha_0^y + \sum_{i=1}^m \alpha_i^y \epsilon_i + \sum_{j=1}^n \beta_j^y \eta_j \\ \dots \end{array} \middle| \alpha_i^v \in \mathbb{R}, \beta_j^v \in \mathbb{R} \right\}$$

$$\varphi^p : \{ \epsilon_i, \eta_j \} \rightarrow \{ \text{P-Boxes} \}$$

We call \mathbb{AS}^p the set of all such elements.

Remark: we do not assume that the P-Boxes are bounded.

Probabilistic affine sets: concretization.

- The concretization function associates to a probabilistic affine set a set of probability distributions.

$$\gamma^p : \text{AS}^p \rightarrow \mathcal{P}(\mathcal{F}_{\mathbb{R}^n})$$

- Same as for affine sets, except that arithmetic operations are done using the P-Box domain.

$$\gamma^p(X_i, \varphi^p) = \left\{ f \in \mathcal{F}_{\mathbb{R}^V} \mid \forall v \in V, f_v \in \gamma(\underline{F}_v, \overline{F}_v) \right\}$$

$$(\underline{F}_v, \overline{F}_v) = \alpha_0^v + \sum_{i=1}^m \alpha_i^v \varphi^p(\varepsilon_i) + \sum_{j=1}^n \beta_j^v \varphi^p(\eta_j)$$

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Operations using
independency

Operations using
unknown dependency

Probabilistic affine sets: affectation.

$$x = [a, b] \quad x = \frac{a + b}{2} + \frac{b - a}{2} \varepsilon_1$$
$$\varphi^p(\varepsilon_1) = \left\{ \left\langle \left[\frac{2k - N}{N}, \frac{2(k + 1) - N}{N} \right], \right\rangle \mid k \in [0, N - 1] \right\}$$

Probabilistic affine sets: affectation.

- In case of non-deterministic inputs, we generate a new noise symbol, the associated P-Box being a uniform distribution.

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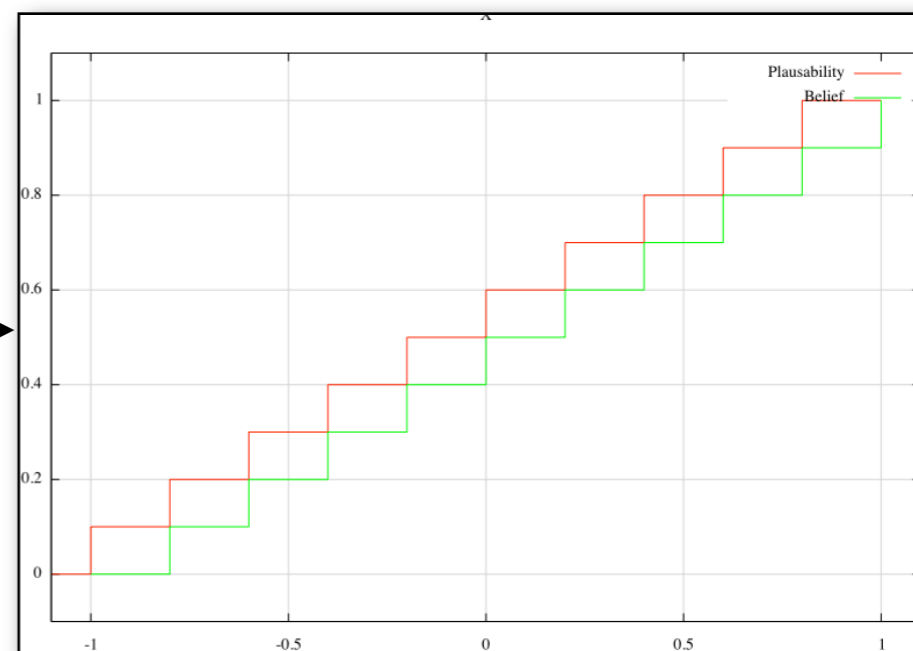
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$$x = [-1, 1], \quad N = 10$$

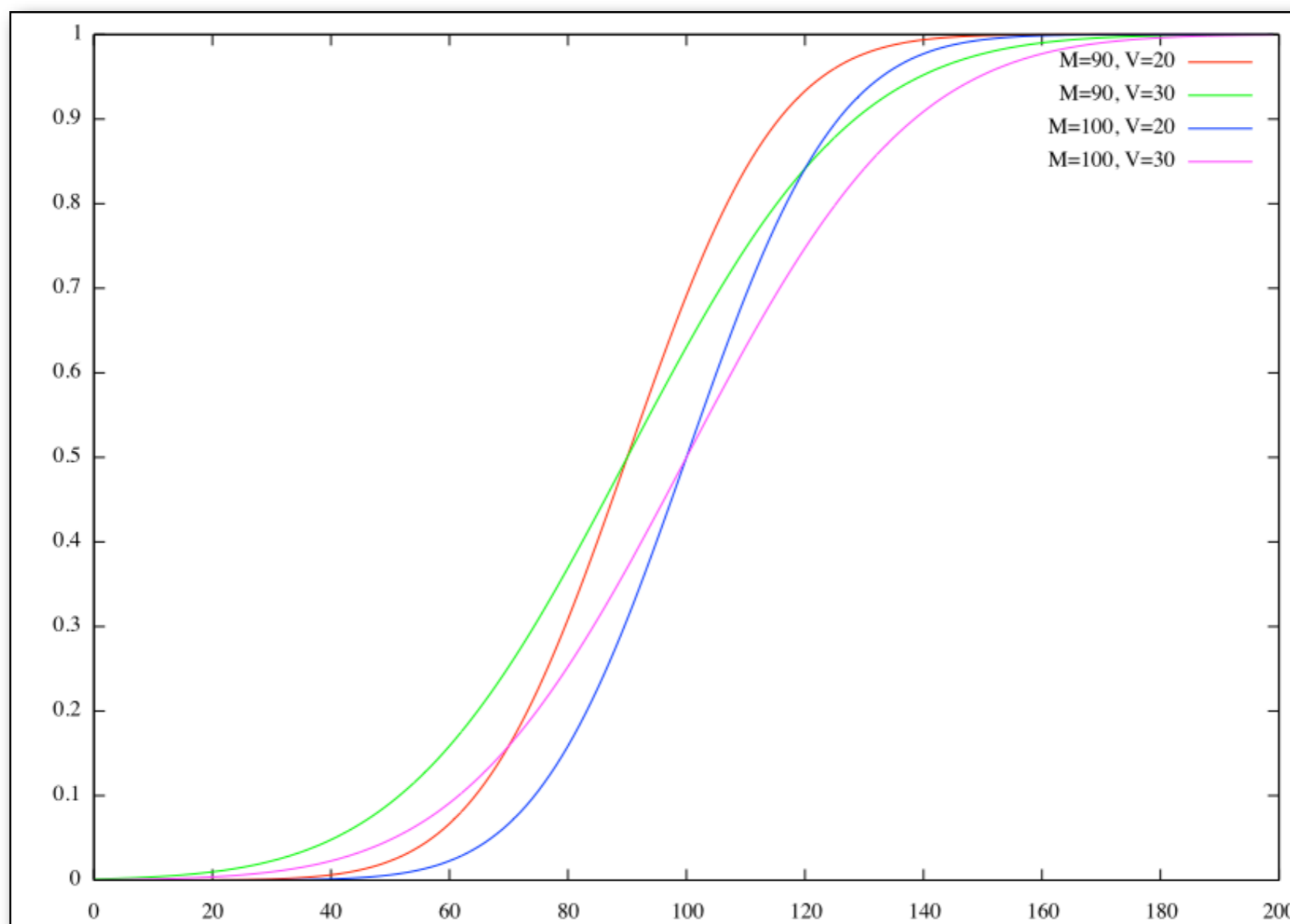


- Remark: even with this we may obtain «better» results than with standard affine forms, see the experimentations.

Probabilistic affine sets: affectation (bis).

- We need a more complicated affectation that can define some characteristics of the distributions (mean, standard deviation, ...).

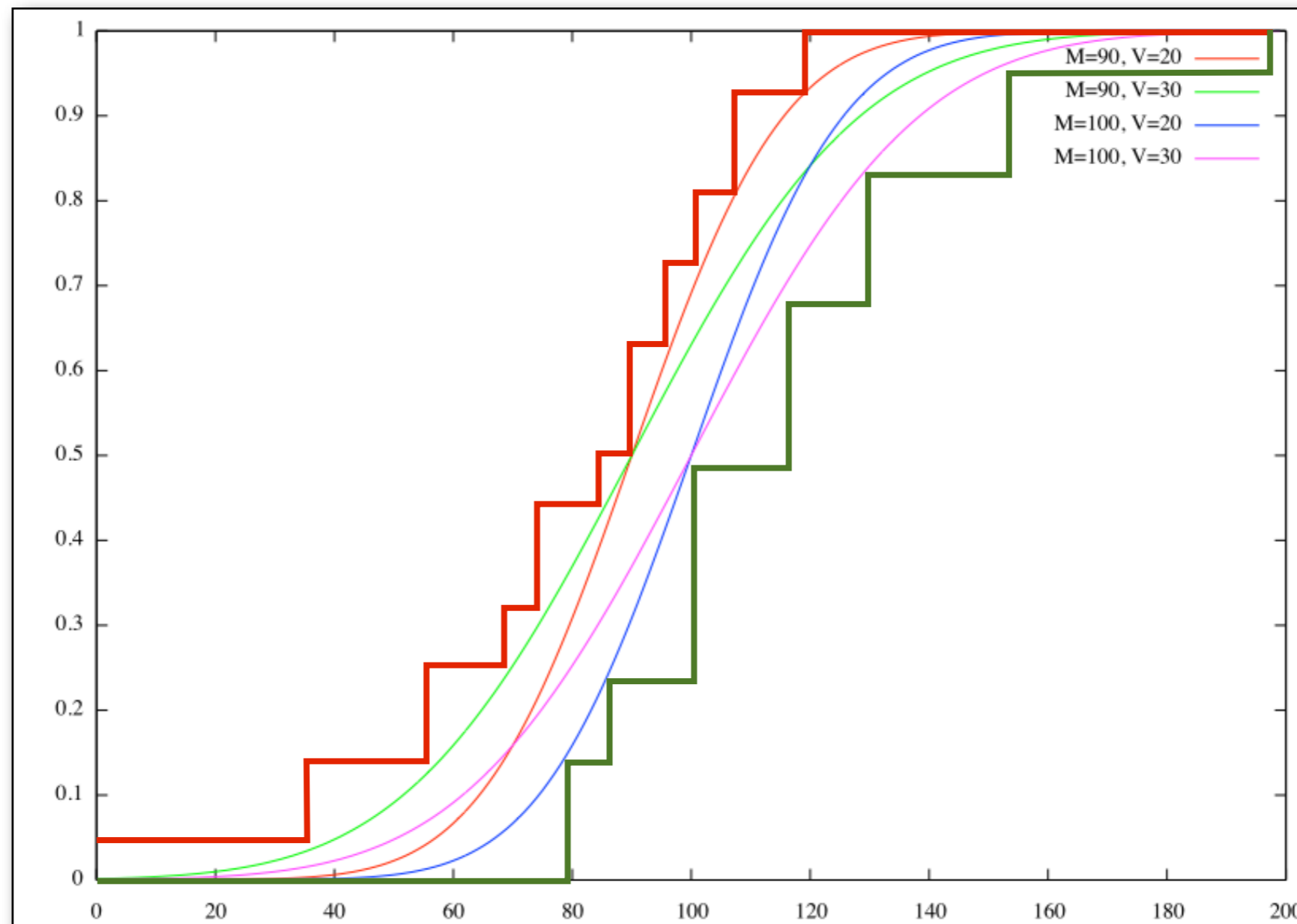
$$x = \text{normal}([90, 100], [20, 30])$$



Probabilistic affine sets: affectation (bis).

- We need a more complicated affectation that can define some characteristics of the distributions (mean, standard deviation, ...).

$$x = \text{normal}([90, 100], [20, 30])$$



Probabilistic affine sets: arithmetic.

- Linear transformation: same as for standard affine sets.

$$f_{lin}(X, \varphi^p) = (f_{lin}(X), \varphi^p)$$

- No new symbol is created, so no need to modify φ^p .
- The dependencies between variables are propagated through f_{lin} .

- Exemple:

$$\begin{array}{lcl}
 x = 20 - 4\epsilon_1 + 2\epsilon_3 & \mathbf{t = [1, 5];} & x = 20 - 4\epsilon_1 + 2\epsilon_3 \\
 y = 10 - 2\epsilon_1 + \epsilon_2 & \mathbf{z = x - 2y + t;} & y = 10 - 2\epsilon_1 + \epsilon_2 \\
 & \longrightarrow & z = 3 - 2\epsilon_2 + 2\epsilon_3 + 2\epsilon_4 \\
 & & t = 3 + 2\epsilon_4
 \end{array}$$

$$\varphi^p \longrightarrow \varphi^p \left[\epsilon_4 \mapsto \left\{ \left[\frac{2k - N}{N}, \frac{2(k + 1) - N}{N} \right], \frac{1}{N} \right\} \right]$$

Probabilistic affine sets: arithmetic.

- Multiplication: we must define the P-Box attached to the new noise symbol.

$$\begin{aligned}
 & \left(\alpha_0^x + \sum_{i=1}^m \alpha_i^x \epsilon_i + \sum_{j=1}^n \beta_j^x \eta_j \right) \times \left(\alpha_0^y + \sum_{i=1}^m \alpha_i^y \epsilon_i + \sum_{j=1}^n \beta_j^y \eta_j \right) = \\
 & \alpha_0^x * \alpha_0^y + \sum_{i=1}^m (\alpha_0^y \alpha_i^x + \alpha_0^x \alpha_i^y) \epsilon_i + \sum_{i=1}^m (\alpha_0^y \eta_i^x + \alpha_0^x \eta_i^y) \eta_i \\
 & + \sum_{1 \leq i, j \leq m} \alpha_i^x \alpha_j^y \epsilon_i \epsilon_j \\
 & + \sum_{1 \leq i \leq m, 1 \leq j \leq n} (\alpha_i^x \beta_j^y + \alpha_i^y \beta_j^x) \epsilon_i \eta_j \\
 & + \sum_{1 \leq i, j \leq n} (\beta_i^x \beta_j^y + \beta_i^y \beta_j^x) \eta_i \eta_j
 \end{aligned}$$

Probabilistic affine sets: arithmetic.

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$$\alpha_0^x * \alpha_0^y + \sum_{i=1}^m (\alpha_0^y \alpha_i^x + \alpha_0^x \alpha_i^y) \epsilon_i + \sum_{i=1}^m (\alpha_0^y \eta_i^x + \alpha_0^x \eta_i^y) \eta_i$$

Linear part

$$+ \sum_{1 \leq i, j \leq m} \alpha_i^x \alpha_j^y \epsilon_i \epsilon_j$$

$$+ \sum_{1 \leq i \leq m, 1 \leq j \leq n} (\alpha_i^x \beta_j^y + \alpha_i^y \beta_j^x) \epsilon_i \eta_j$$

$$+ \sum_{1 \leq i, j \leq n} (\beta_i^x \beta_j^y + \beta_i^y \beta_j^x) \eta_i \eta_j$$

Probabilistic affine sets: arithmetic.

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$$+ \sum_{1 \leq i, j \leq m} \alpha_i^x \alpha_j^y \epsilon_i \epsilon_j$$

$$+ \sum_{1 \leq i \leq m, 1 \leq j \leq n} (\alpha_i^x \beta_j^y + \alpha_i^y \beta_j^x) \epsilon_i \eta_j$$

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Non-linear part: must be overapproximated

Probabilistic affine sets: arithmetic.

- Overapproximation of the non-linear term.

$$\begin{aligned} \beta_{n+1}\eta_{n+1} &= \sum_{1 \leq i, j \leq m} \alpha_i^x \alpha_j^y \epsilon_i \epsilon_j \\ &+ \sum_{1 \leq i \leq m, 1 \leq j \leq n} (\alpha_i^x \beta_j^y + \alpha_i^y \beta_j^x) \epsilon_i \eta_j \\ &+ \sum_{1 \leq i, j \leq n} (\beta_i^x \beta_j^y + \beta_i^y \beta_j^x) \eta_i \eta_j \end{aligned}$$

- Remark 1: we need a normalization after that to have $\eta_{n+1} \subseteq [-1, 1]$.
- Remark 2: we treat separately the terms $\epsilon_i \epsilon_i$ as they are not independent.

Probabilistic affine sets: arithmetic.

- Overapproximation of the non-linear term.

$$\beta_{n+1}\eta_{n+1} = \sum_{1 \leq i, j \leq m} \alpha_i^x \alpha_j^y \epsilon_i \epsilon_j$$

Using independency arithmetics

$$+ \sum_{1 \leq i \leq m, 1 \leq j \leq n} (\alpha_i^x \beta_j^y + \alpha_i^y \beta_j^x) \epsilon_i \eta_j$$

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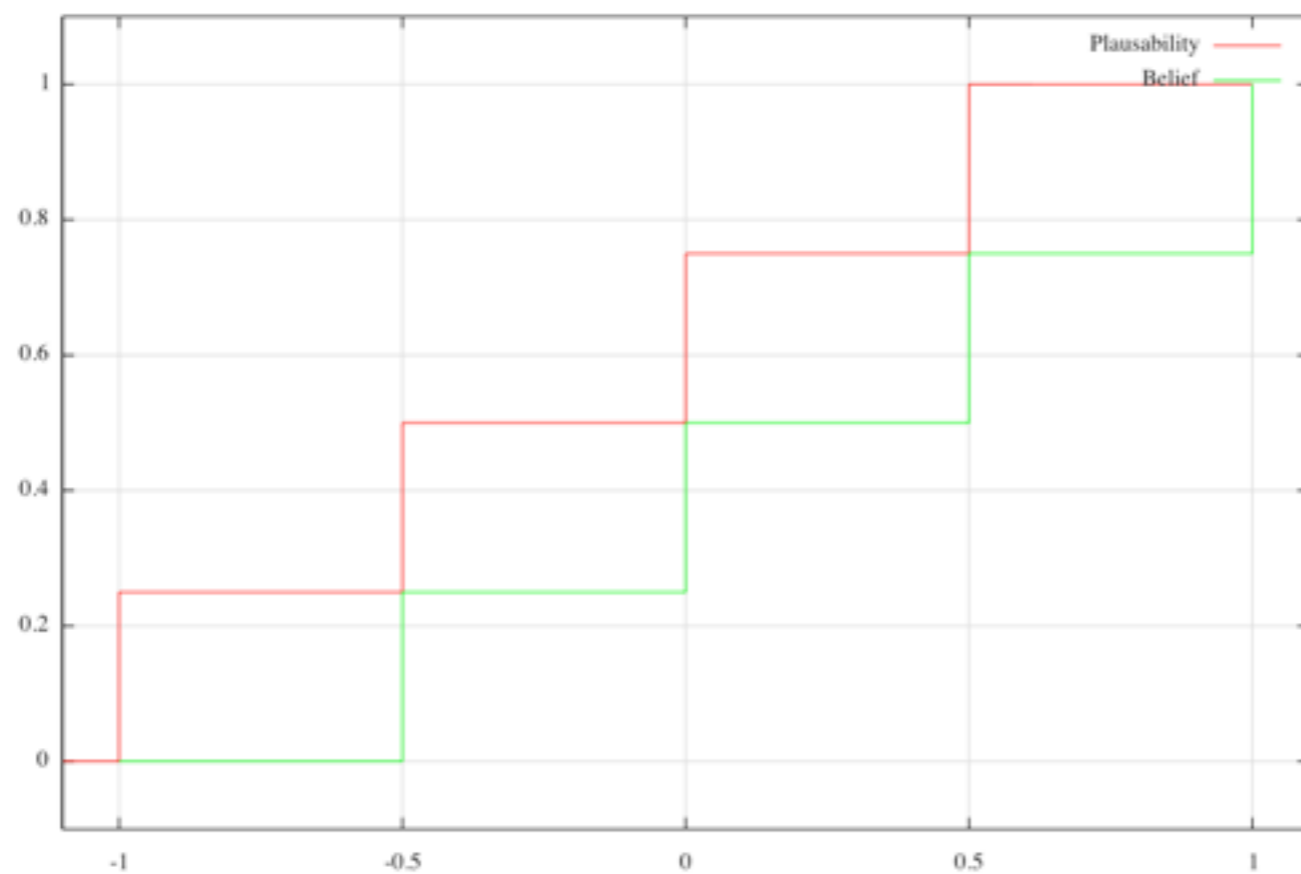
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Using unknown
dependency arithmetics

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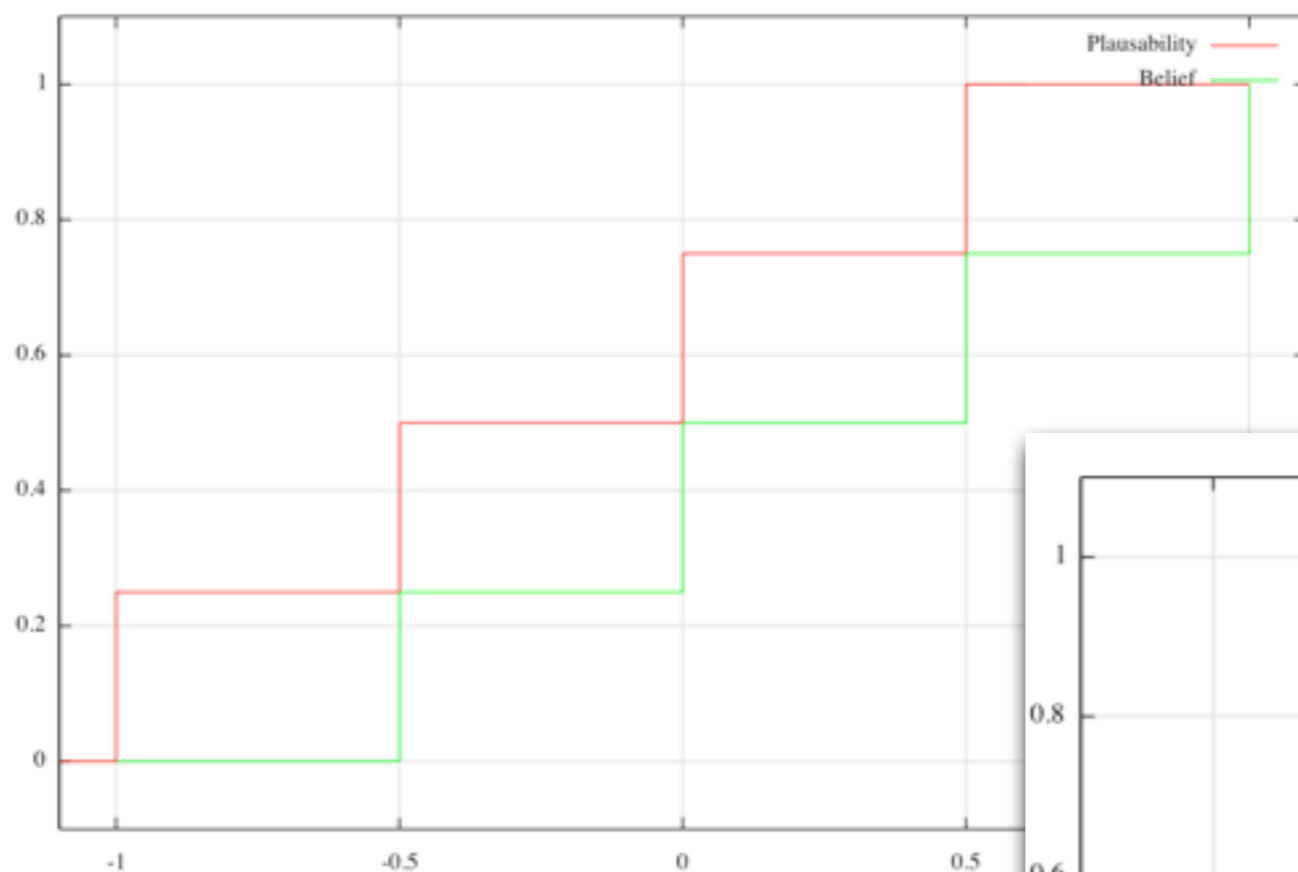
Probabilistic affine sets: example.

- Linear filter.

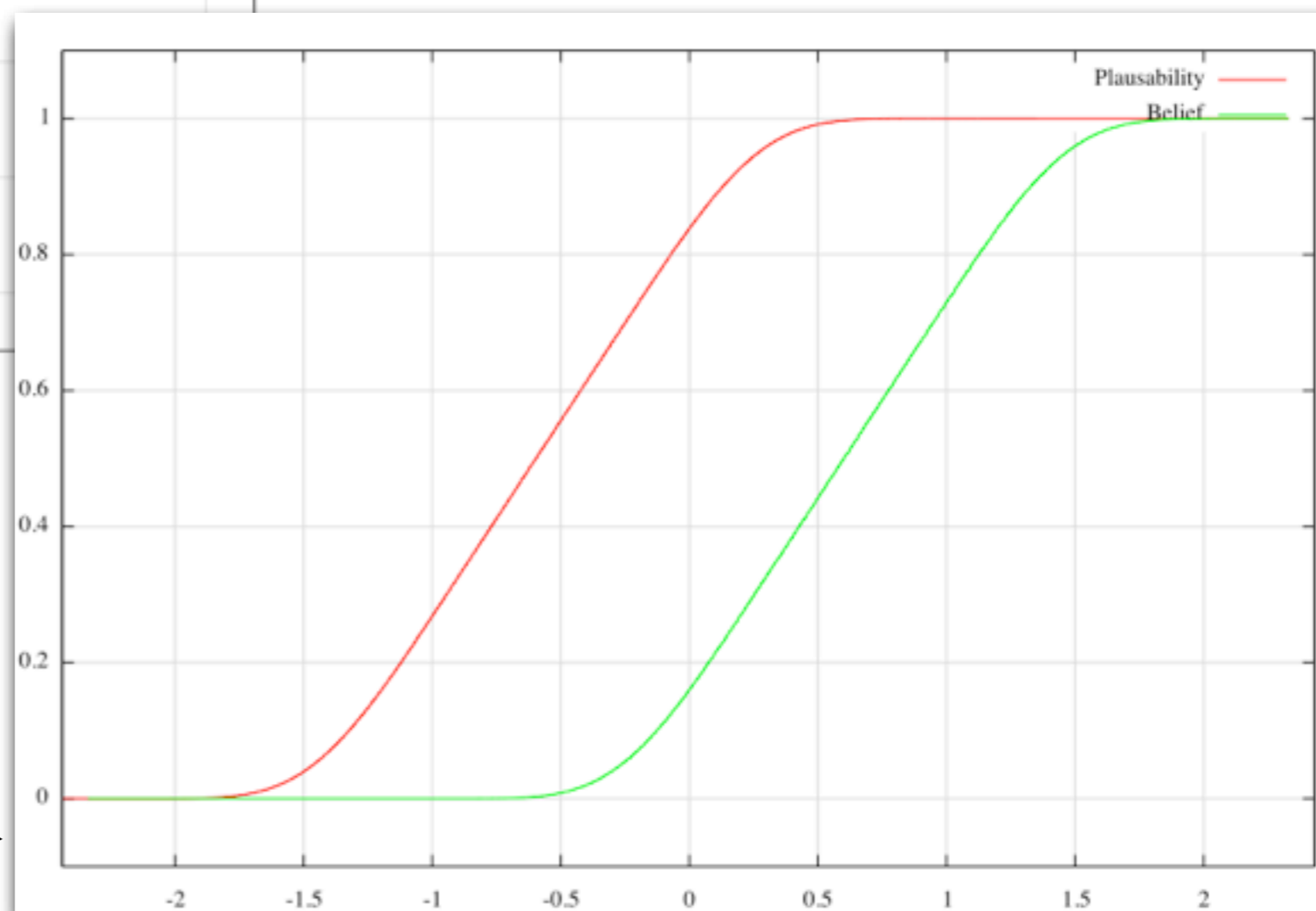


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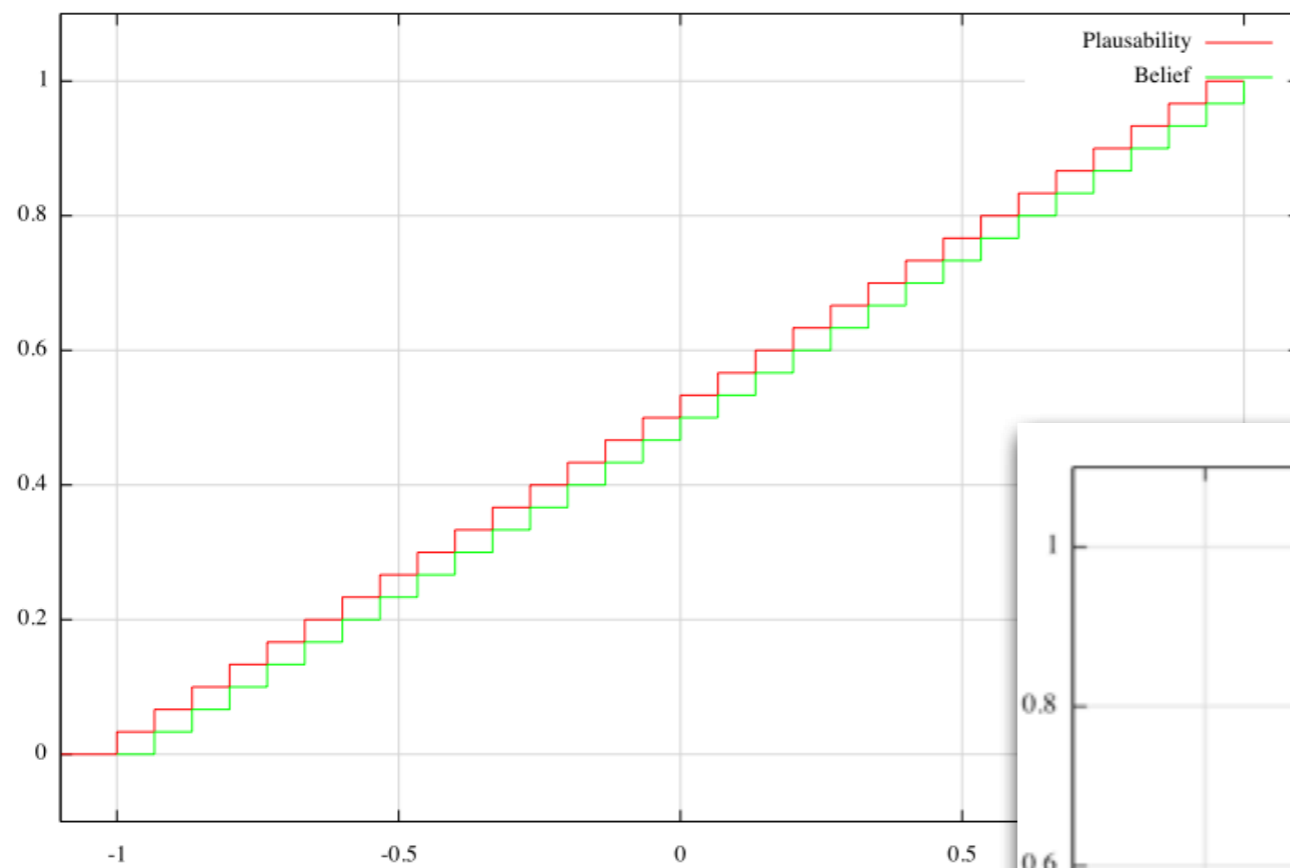


30 iterations.

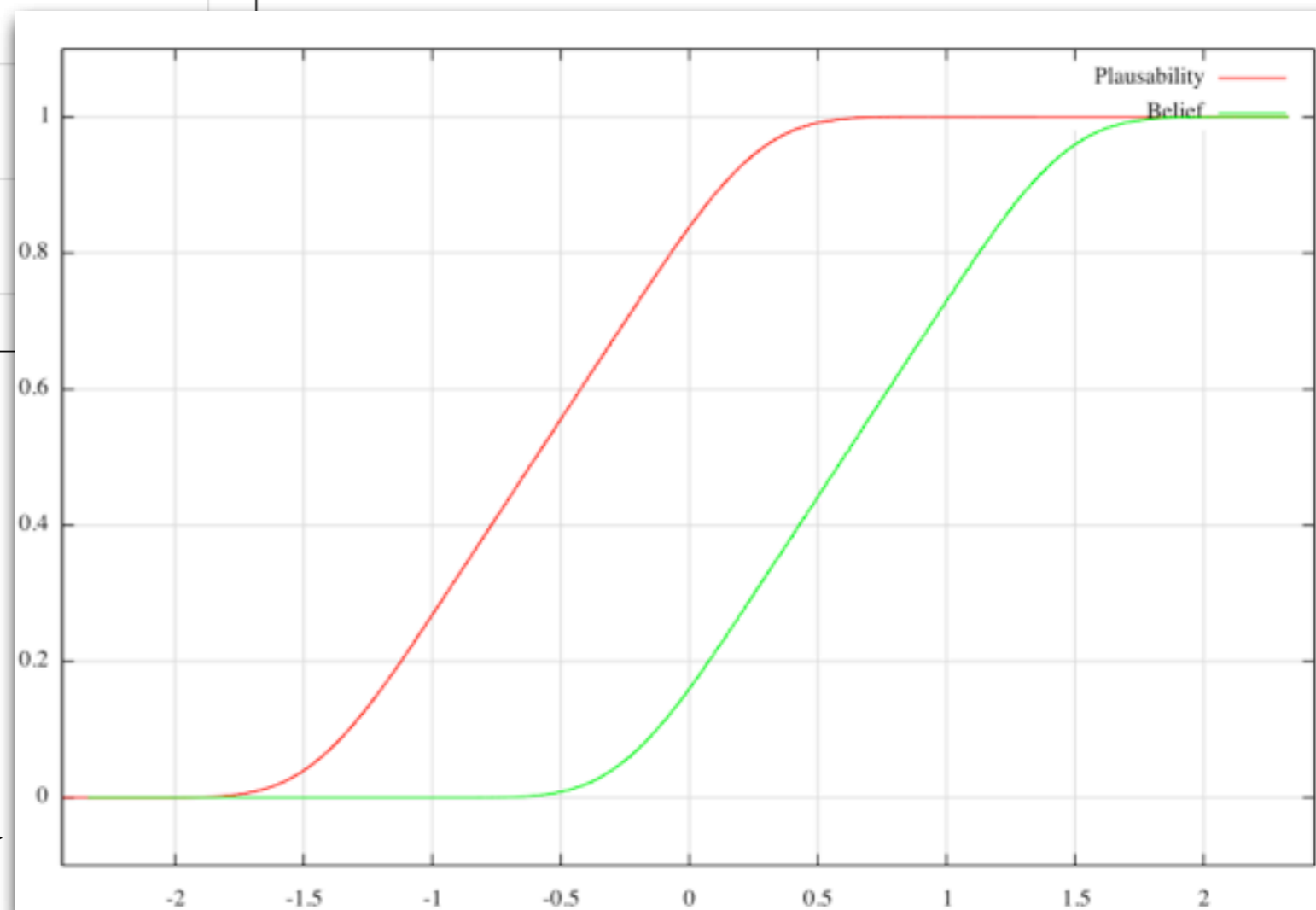


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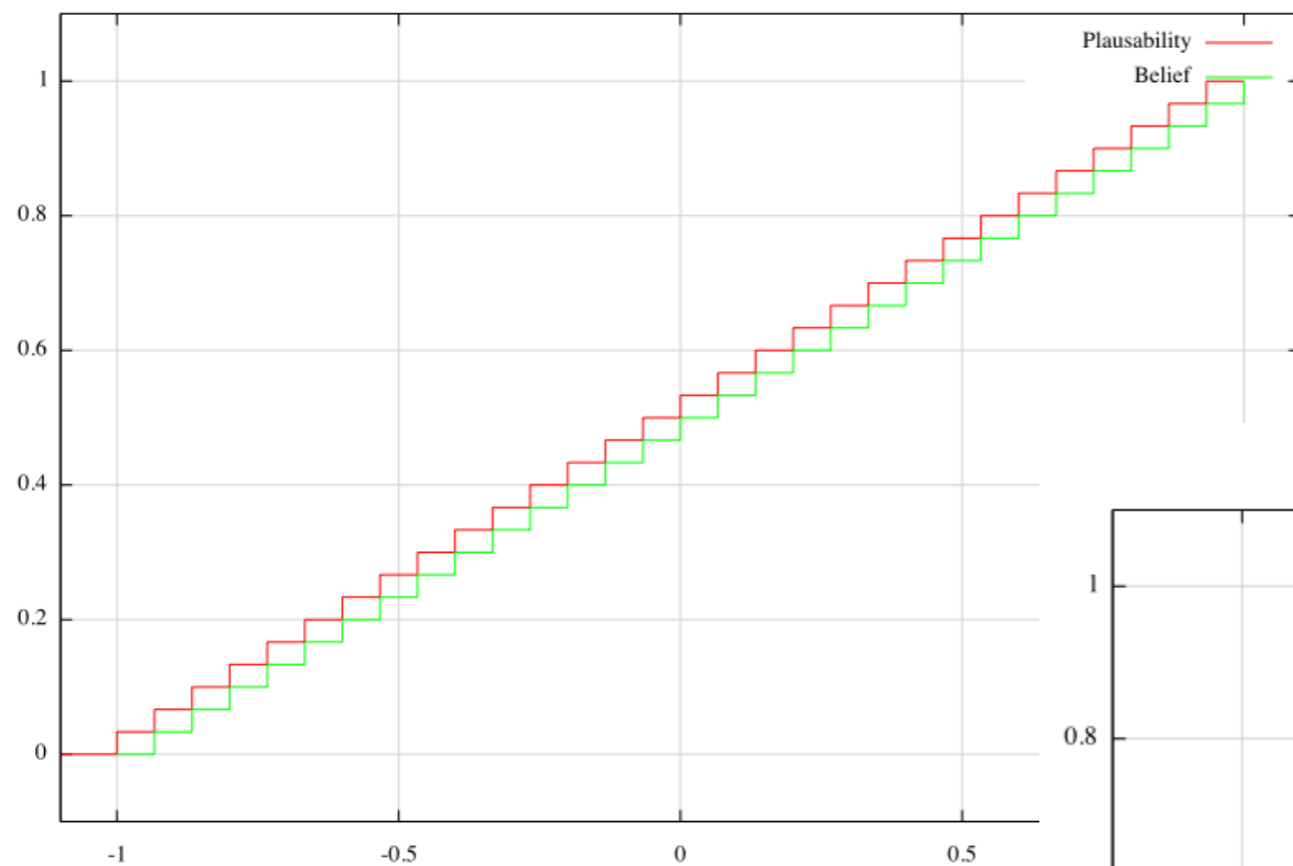


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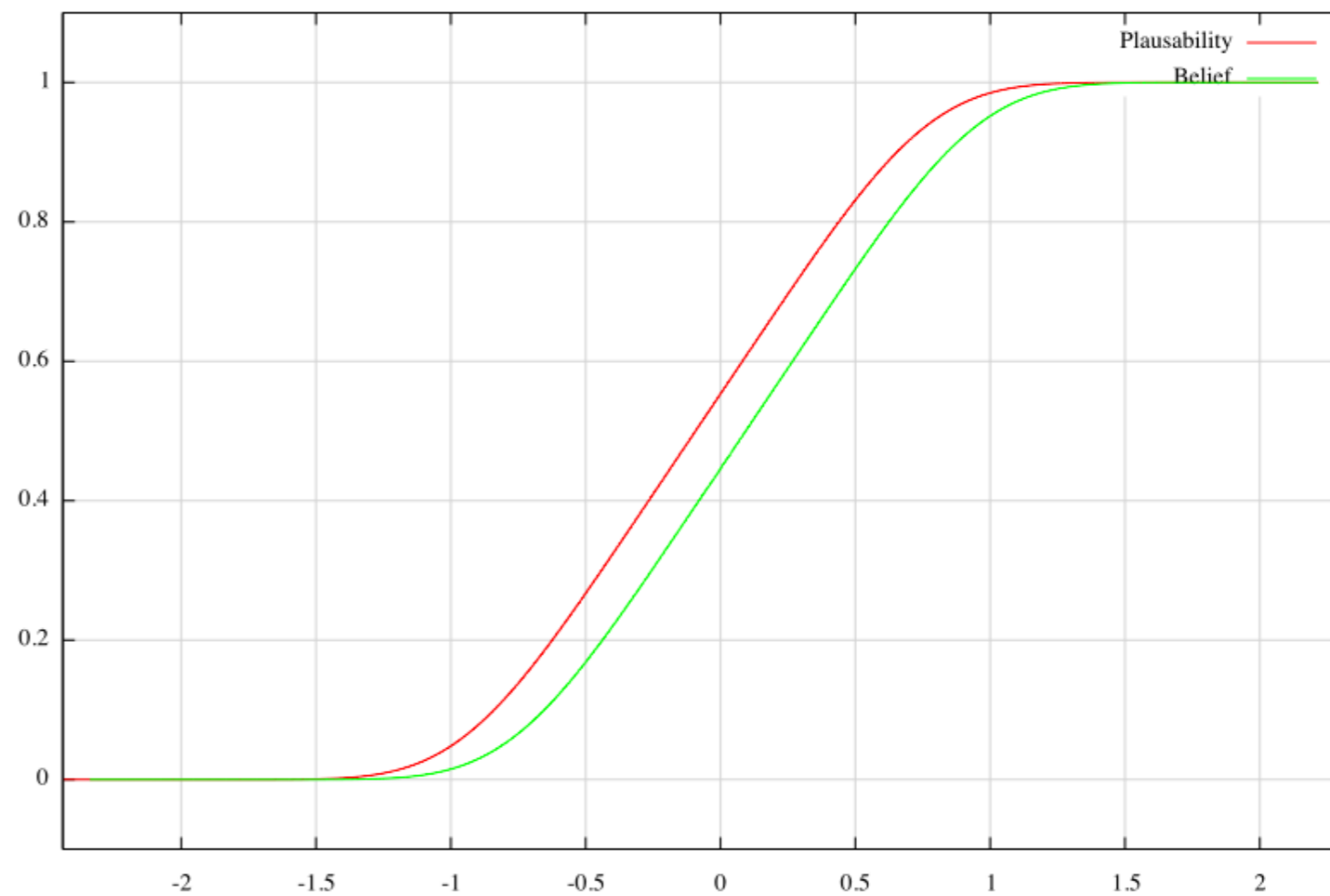
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Y_n (offset)

30 iterations.

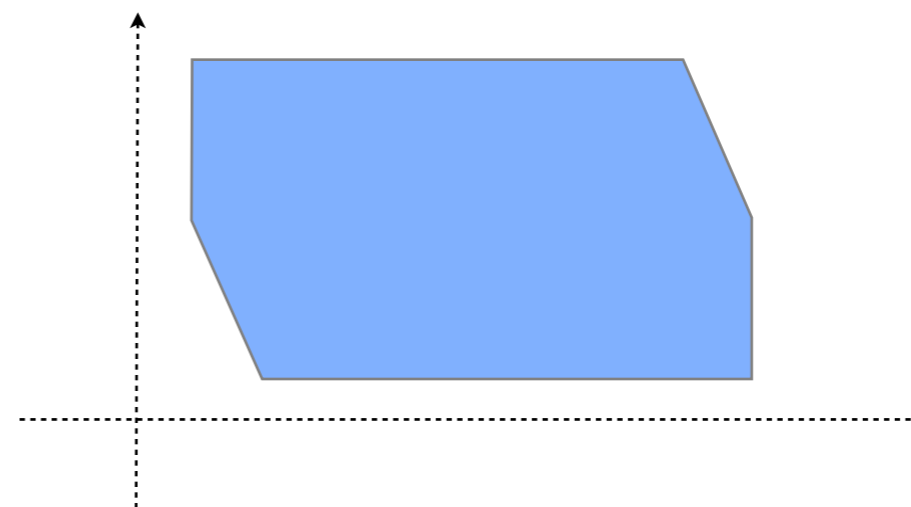
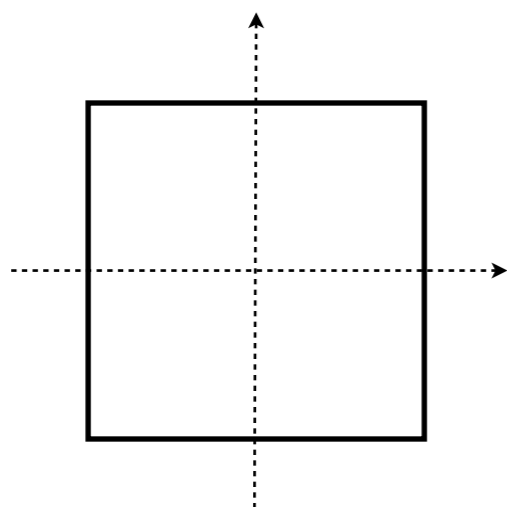


Conclusion.

Affine sets

$[-1, 1]^m$ $\xrightarrow{\text{Affine transformation.}}$ $Z(\mathbb{R}^n)$

- ✓ Arithmetic
- ✓ Order theoretic operations



$DS_{[-1, 1]^m}$ $\xrightarrow{\text{Affine transformation.}}$ $DS_{Z(\mathbb{R}^n)}$

- ✓ Arithmetic
- ⊙ Order theoretic operations

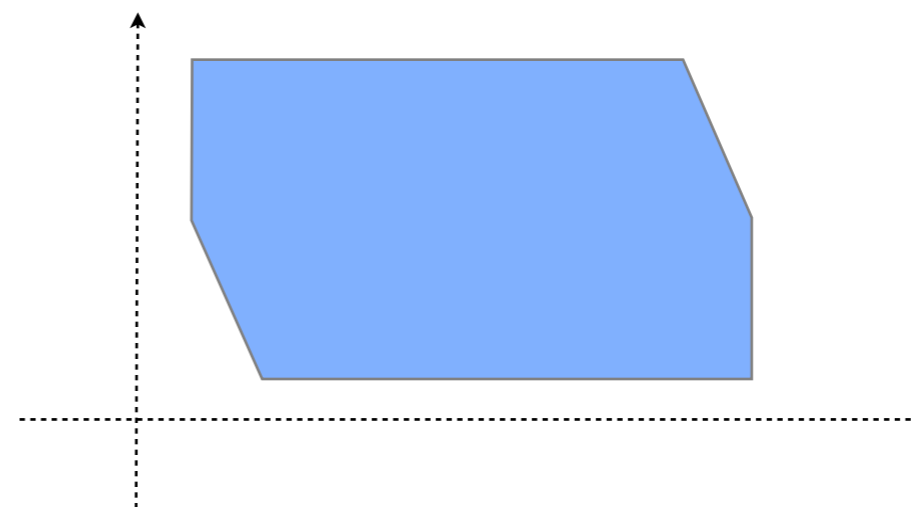
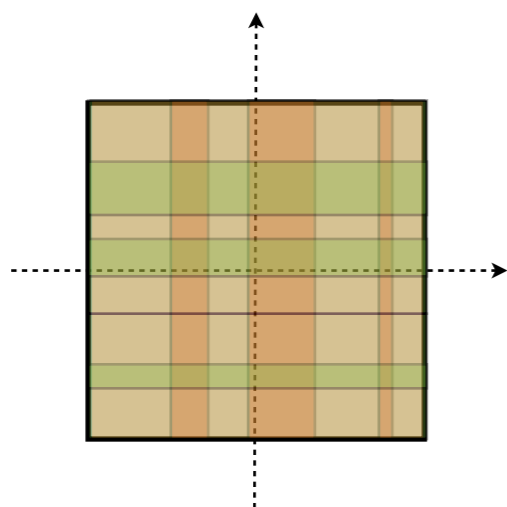
Probabilistic affine sets

Conclusion.

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- ✓ Arithmetic
- ✓ Order theoretic operations



$\text{DS}_{[-1, 1]^m}$ $\xrightarrow{\text{Affine transformation.}}$ $\text{DS}_{\mathbb{Z}(\mathbb{R}^n)}$

- ✓ Arithmetic
- ⊙ Order theoretic operations

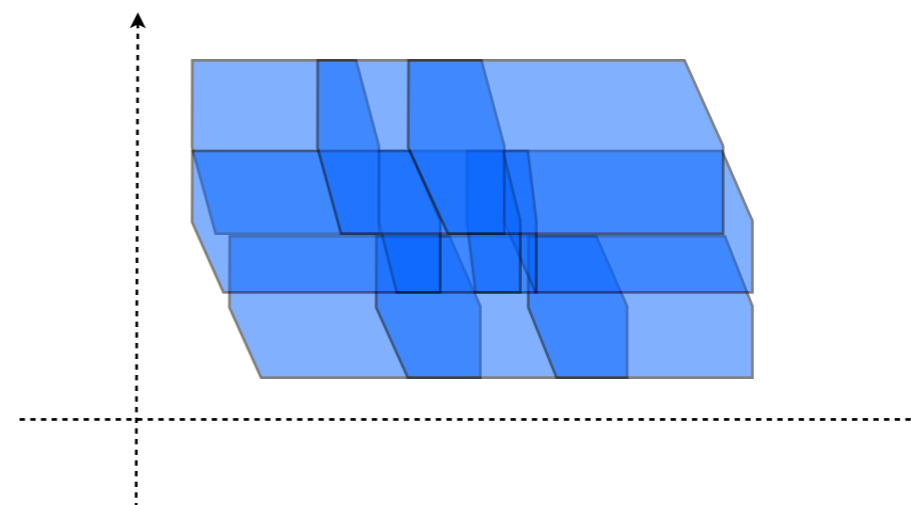
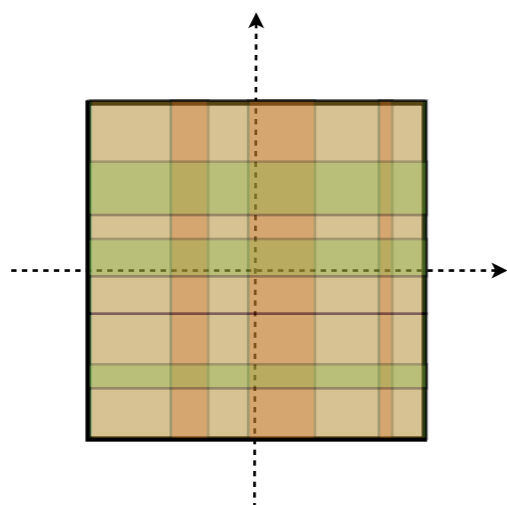
Probabilistic affine sets

Conclusion.

Affine sets

$$[-1, 1]^m \xrightarrow{\text{Affine transformation.}} \mathbb{Z}(\mathbb{R}^n)$$

- ✓ Arithmetic
- ✓ Order theoretic operations



$$\text{DS}_{[-1, 1]^m} \xrightarrow{\text{Affine transformation.}} \text{DS}_{\mathbb{Z}(\mathbb{R}^n)}$$

- ✓ Arithmetic
- ⊙ Order theoretic operations

Probabilistic affine sets

Conclusion: implementation.

- This work has been implemented in C++. See demo.