

Proof theory for indexed nested sequents

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Abstract. Fitting’s indexed nested sequents can be used to give deductive systems to modal logics which cannot be captured by pure nested sequents. In this paper we show how the standard cut-elimination procedure for nested sequents can be extended to indexed nested sequents, and we discuss how indexed nested sequents can be used for intuitionistic modal logics.

1 Introduction

Modal logics were originally defined in terms of axioms in a Hilbert system, and later in terms of their semantics in relational structures. Structural proof theory for modal logics, however, was considered a difficult topic as traditional (Gentzen) sequents did not provide fully satisfactory (i.e. analytic and modular) proof systems even for some common modal logics. Nonetheless, the proof theory of modal logics has received more attention in the last decades, and some extensions of traditional sequents were successfully proposed to handle modalities. Two approaches can be distinguished: (1) systems that incorporate relational semantics in the formalism itself like *labelled sequent systems* (e.g., [24, 27, 18]) which use sequents that explicitly refer to the relational semantics: formulas are labelled with states and relational atoms describe the accessibility relation, and (2) systems that use syntactical devices to handle the modalities like *nested sequents*, which are an extension of ordinary sequents to a structure of tree, first introduced by Kashima [12], and then independently rediscovered by Brünnler [3] and Poggiolesi [21]. They can be translated into a subclass of labelled sequents called in [11] labelled tree sequents, if the relational structure is made explicit. However, compared to labelled deductive systems, the tree structure restricts the expressivity of nested sequents. In particular, it seems that nested sequents cannot give cut-free deductive systems for logics obeying the Scott-Lemmon axioms, which correspond to a “confluence” condition on the relational structure [14].

Fitting recently introduced *indexed nested sequents* [7], an extension of nested sequents which goes beyond the tree structure to give a cut-free system for the classical modal logic K extended with an arbitrary set of Scott-Lemmon axioms. In some sense indexed nested sequents are more similar to labelled systems than pure nested sequents—in fact, the translation between nested sequents and labelled tree sequents mentioned above is naturally extended in [23] to a translation between indexed nested sequents and labelled tree sequents with equality, where some nodes of the underlying tree can be identified.

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In this paper we investigate some proof-theoretical properties of indexed nested sequents. The first and foremost one is the cut-elimination theorem. As Fitting’s original system does not use a cut rule, this result is actually entailed by his (semantical) completeness theorem. Using the translation mentioned above, one could also use the cut-elimination result for labelled tree sequents with equality, yielding an indirect proof [23]. However, only an internal cut-elimination proof makes a proof formalism a first-class citizen for structural proof theory. For this reason we give in this paper a syntactic proof of cut-elimination carried out within indexed nested sequents. We achieve this by making some subtle but crucial adjustments to the standard cut-elimination proof for pure nested sequents.

One of the main advantages is that this proof can be exported to the intuitionistic framework with basically no effort. We achieve this by using the techniques that had already been successfully used for ordinary nested sequents [8, 26, 15]. This allows us to present the cut-free indexed nested sequents systems in a uniform manner for classical and intuitionistic modal logic. The deductive systems are almost identical, the main difference being that an intuitionistic sequent has only one “output” formula, in the same way as in ordinary sequent calculus an intuitionistic sequent has only one formula on the right.

As there is no straightforward definition of the extension of intuitionistic modal logic with Scott-Lemmon axioms, the indexed nested sequents system can be seen as one way to define it. This point is examined in the last section with a discussion on the various alternatives that exist in the literature and how they relate to the proposed system.

2 Indexed nested sequents and the Scott-Lemmon axioms

We start by working with formulas in negation normal form, generated by the following grammar, which extends the language of propositional classical logic with the two modalities \Box and \Diamond

$$A ::= a \mid \bar{a} \mid A \wedge B \mid A \vee B \mid \Box A \mid \Diamond A \quad (1)$$

where a is taken from a countable set of propositional atoms, \bar{a} is its negation, and $\bar{\bar{a}}$ is equivalent to a . For every formula A , its negation \bar{A} , is defined as usual via the De Morgan laws. For now, we use $A \multimap B$ as abbreviation for $\bar{A} \vee B$.

Classical modal logic \mathbf{K} is obtained from classical propositional logic by adding the axiom \mathbf{k} : $\Box(A \multimap B) \multimap (\Box A \multimap \Box B)$ and the *necessitation rule* that allows to derive the formula $\Box A$ from any theorem A .

Stronger modal logics can be obtained by adding to \mathbf{K} other axioms. We are interested here specifically in the family of *Scott-Lemmon axioms* of the form

$$\mathbf{g}_{k,l,m,n} : \Diamond^k \Box^l A \multimap \Box^m \Diamond^n A \quad (2)$$

for a tuple $\langle k, l, m, n \rangle$ of natural numbers, where \Box^m stands for m boxes and \Diamond^n for n diamonds. Fitting [7] introduced indexed nested sequents exactly to provide a structural proof system for classical modal logic \mathbf{K} , that could be extended with rules for the Scott-Lemmon axioms.

A (*pure*) *nested sequent* is a multiset of formulas and *boxed sequents*, according to the following grammar $\Gamma ::= ; j A, \Gamma \mid j [\Gamma], \Gamma$ where A is a modal formula. We understand such a nested sequent through its interpretation as a modal formula, written $fm(\cdot)$, given inductively by $fm(\cdot) = ?$; $fm(A, \Gamma) = A _ fm(\Gamma)$; and $fm([\Gamma_1], \Gamma_2) = \Box fm(\Gamma_1) _ fm(\Gamma_2)$. A nested sequent can therefore be seen as a tree of ordinary *one-sided* sequents, with each node representing the scope of a modal $_$. It therefore is of the general form

$$A_1, \dots, A_k, [\Gamma_1], \dots, [\Gamma_n] \quad (3)$$

An *indexed nested sequent*, as defined in [7], is a nested sequent where each sequent node (either the root or any interior node) carries an *index*, denoted by lowercase letters like u, v, w, x, \dots , and taken from a countable set (e.g., for simplicity, the set of natural numbers), so we write an indexed sequent by extending (3) in the following way

$$A_1, \dots, A_k, [{}^{w_1}\Gamma_1], \dots, [{}^{w_n}\Gamma_n] \quad (4)$$

where $\Gamma_1, \dots, \Gamma_n$ are now indexed sequents, and where the index of the root is not explicitly shown (e.g., we can assume that it is 0). For an indexed nested sequent Σ , we write I_Σ to denote the set of indexes occurring in Σ .

Intuitively, indexed nested sequents are no longer trees, but any kind of *rooted* directed graphs, by identifying nodes carrying the same index.

In nested sequent calculi, a rule can be applied at any depth in the structure, that is, inside a certain nested sequent context. We write $\Gamma^{i_1} f g \dots^{i_n} f g$ for an n -ary context (i.e. one with n occurrences of the $f g$) where i_1, \dots, i_n are the indexes of the sequent nodes that contain the $f g$, in the order of their appearance in the sequent. A hole in a context can be replaced by a formula or sequent. More precisely, we write $\Gamma^{i_1} f \Delta_1 g \dots^{i_n} f \Delta_n g$ for the sequent that is obtained from $\Gamma^{i_1} f g \dots^{i_n} f g$ by replacing the k -th hole by Δ_k , for each $k \geq 1, \dots, n$ (if $\Delta_k = ;$ it simply amounts to removing the $f g$). We might omit the index at the context-braces when this information is clear or not relevant.

Example 2.1 For example, $A, [{}^1 B, [{}^2 C, f g]], [{}^3 D, [{}^1 f g, A]], [{}^2 D, f g]$ is a ternary context that we can write as $\Gamma^{2f} g^1 f g^2 f g$. If we substitute the sequents $\Delta_1 = D, [{}^4 E]$; $\Delta_2 = F$; and $\Delta_3 = [{}^5 G]$ into its holes, we get: $\Gamma^{2f} \Delta_1 g^1 f \Delta_2 g^2 f \Delta_3 g = A, [{}^1 B, [{}^2 C, D, [{}^4 E]]], [{}^3 D, [{}^1 F, A]], [{}^2 D, [{}^5 G]]$

In Figure 1, the classical system that we call iNK is an adaptation of the system described by Fitting in [7] to our notations and to the one-sided setting. It can also be seen as Brännler's system [3] extended with indexes.

What is different from the pure nested sequent system is the addition of the two structural rules **tp** and **bc**, called *teleportation* and *bracket-copy*, respectively, which are variants of the formula-contraction **FC** and the sequent-contraction **SC** of [7]. We need two versions of **bc** to take care of every possible context where the rule may be applied. Another peculiarity is that in the rules for \Box we demand that the index of the new bracket in the premiss does not occur in the conclusion.

$$\begin{array}{c}
\text{id} \frac{}{\Gamma\{a, \bar{a}\}} \quad \vee \frac{\Gamma\{A, B\}}{\Gamma\{A \vee B\}} \quad \wedge \frac{\Gamma\{A\} \quad \Gamma\{B\}}{\Gamma\{A \wedge B\}} \quad \diamond \frac{\Gamma\{\diamond A, [^u A, \Delta]\}}{\Gamma\{\diamond A, [^u \Delta]\}} \quad \square \frac{\Gamma\{[^\vee A]\}}{\Gamma\{\square A\}} \quad v \text{ is fresh} \\
\text{tp} \frac{\Gamma^{w\{ \emptyset \}} \quad w\{A\}}{\Gamma^{w\{A\}} \quad w\{ \emptyset \}} \quad \text{bc}_1 \frac{\Gamma^{w\{ [^u \Delta] \}} \quad w\{ [^u \emptyset \] \}}{\Gamma^{w\{ [^u \Delta] \}} \quad w\{ \emptyset \}} \quad \text{bc}_2 \frac{\Gamma^{w\{ [^u \Delta \ w\{ [^u \emptyset] \} \}}}{\Gamma^{w\{ [^u \Delta \ w\{ \emptyset \} \}}}
\end{array}$$

Fig. 1. System iNK

$$\mathfrak{g}_{k,l,m,n} \frac{\Gamma^{u_0\{ [^{u_1} \Delta_1, \dots [^{u_k} \Delta_k, [^{v_1} \dots [^{v_l} \dots] \dots] \dots] \dots \}, [^{w_1} \Sigma_1, \dots [^{w_m} \Sigma_m, [^{x_1} \dots [^{x_n} \dots] \dots] \dots \}}}{\Gamma^{u_0\{ [^{u_1} \Delta_1, \dots [^{u_k} \Delta_k] \dots \}, [^{w_1} \Sigma_1, \dots [^{w_m} \Sigma_m] \dots \}}}$$

Fig. 2. Inference rule $\mathfrak{g}_{k,l,m,n}$ (where $l + n \neq 0$, $v_1 \dots v_k$ and $x_1 \dots x_n$ are fresh, and $v_l = x_n$)

$$\mathfrak{g}_{k,0,m,0} \frac{\sigma \Gamma^{u_0\{ [^{u_1} \Delta_1, \dots [^{(u_k)} \Delta_k], \dots \}, [^{w_1} \Sigma_1, \dots [^{(w_m)} \Sigma_m], \dots \}}}{\Gamma^{u_0\{ [^{u_1} \Delta_1, \dots [^{u_k} \Delta_k], \dots \}, [^{w_1} \Sigma_1, \dots [^{w_m} \Sigma_m], \dots \}}}$$

Fig. 3. Special case for $\mathfrak{g}_{k,0,m,0}$

Finally, for a tuple hk, l, m, ni with $l + n \neq 0$, the rule $\mathfrak{g}_{k,l,m,n}$ in Figure 2 is defined as in [7]. It must satisfy that $v_1 \dots v_k$ and $x_1 \dots x_n$ are fresh indexes which are pairwise distinct, except for the *confluence condition*: we always have $v_l = x_n$. When one or more elements of the tuple hk, l, m, ni are equal to 0, then we have the following special cases:

- if $k = 0$ (or $m = 0$) then u_1 to u_k (resp. w_1 to w_m) all collapse to u_0 .
- if $l = 0$ then w_1 to w_l all collapse to u_k , and similarly, if $n = 0$ then x_1 to x_n all collapse to v_m . In particular, if $k = 0$ and $l = 0$, we must have $x_n = u_0$, and similarly, if $m = 0$ and $n = 0$, we demand that $v_l = u_0$.

An example of how this rule can be used to derive an instance of the Scott-Lemmon axioms can be found in the proof of Theorem 4.2.

The case where $l = 0$ and $n = 0$ was not handled by Fitting in [7]; we give a corresponding rule in Figure 3. In that case, not only do we identify u_k and w_m , but it is also necessary to apply a substitution $\sigma: I_\Gamma \dashv I_\Gamma$ to the indexes in the context $\Gamma^{u_0} f g$, giving the new context $\sigma \Gamma^{u_0} f g$, such that $\sigma(u_k) = \sigma(w_m)$ in the whole sequent (and $\sigma(y) = y$ for any other $y \geq I_\Gamma$).

For a given set $\mathbf{G} \subseteq \mathbb{N}^4$, write $\text{iNK} + \mathbf{G}$ for the system obtained from iNK by adding the corresponding rules given in Figures 2 and 3. System $\text{iNK} + \mathbf{G}$ is sound and complete wrt. the logic corresponding $\mathbf{K} + \mathbf{G}$ (which is obtained from \mathbf{K} by adding the corresponding axioms (2)). Soundness is proven by Fitting [7] wrt. relational frames; and completeness via a translation to *set-prefixed tableaux system* for which in turn he gives a semantic completeness proof.

$$\text{cut} \frac{\Gamma\{A\} \quad \Gamma\{\bar{A}\}}{\Gamma\{\emptyset\}} \quad \Bigg| \quad \text{w} \frac{\Gamma\{\emptyset\}}{\Gamma\{\Delta\}} \quad \text{c} \frac{\Gamma\{\Delta, \Delta\}}{\Gamma\{\Delta\}} \quad \text{nec} \frac{\Gamma}{[\Gamma]} \quad \text{isub} \frac{\Gamma}{\sigma\Gamma}$$

Fig. 4. Left: The one-sided cut-rule – **Right:** Additional structural rules

3 Cut-elimination

In this section, we present a cut-elimination proof for the indexed nested sequent system $\text{iNK} + \mathbf{G}$ that relies on a standard double-induction on the height of the derivation above a given cut-rule (left of Figure 4), and the cut rank.

Definition 3.1 The *height of a derivation tree* π , denoted by $\text{ht}(\pi)$, is the length of the longest path in the tree from its root to one of its leaves. The *rank* of an instance of cut is the depth of the formula introduced by the cut. We also write cut_r to denote an instance of cut with rank at most r . The *cut-rank* of a derivation π , denoted by $\text{rk}(\pi)$, is the maximal rank of a cut in π .

To facilitate the overall argument, we consider a variant of system iNK , that we call *system* $\text{i}\ddot{\text{N}}\text{K}$, that is obtained from iNK by removing the teleportation rule tp (but keeping the bc -rules), and by replacing the id - and \diamond -rules by

$$\text{id} \frac{}{\Gamma^{u\{a\}} \quad u\{\bar{a}\}} \quad \text{and} \quad \ddot{\diamond} \frac{\Gamma^{u\{\diamond A\}} \quad u\{[A, \Delta]\}}{\Gamma^{u\{\diamond A\}} \quad u\{[\Delta]\}} \quad (5)$$

respectively. The reason behind this is that iNK and $\text{i}\ddot{\text{N}}\text{K}$ are equivalent (with and without cut, as shown below in Lemma 3.4), but the tp -rule is admissible in the new system. We will also need some additional structural rules called *weakening*, *contraction*, *necessitation*, and *index substitution* respectively, which are shown on the right in Figure 4. The rules for weakening and contraction are similar to the standard sequent rules except that they can apply deeply inside a context. The rules nec and isub on the other hand cannot be applied deep inside a context; they always work on the whole sequent. In isub , the sequent $\sigma\Gamma$ is obtained from Γ by applying the substitution $\sigma: I_\Gamma \dashv I_\Gamma$ on the indexes occurring in Γ , where σ can be an arbitrary renaming.

Lemma 3.2 *The rules nec , w , isub and c are cut-rank and height preserving admissible for $\text{i}\ddot{\text{N}}\text{K} + \mathbf{G}$, and all rules of $\text{i}\ddot{\text{N}}\text{K} + \mathbf{G}$ (except for the axiom id) are cut-rank and height-preserving invertible.*

Proof This proof is analogous to that for the pure nested sequent systems in [3]. For bc and $\mathbf{g}_{k,l,m,n}$, note that their inverses are just weakenings. \dashv

Lemma 3.3 *The rule tp is admissible for $\text{i}\ddot{\text{N}}\text{K} + \mathbf{G}$ (and for $\text{i}\ddot{\text{N}}\text{K} + \mathbf{G} + \text{cut}$).*

Proof The proof uses an induction on the number of instances of tp in a proof, eliminating topmost instances first, by an induction on the height of the proof

above it and a case analysis of the rule r applied just before tp . The only nontrivial case is when $r = \square$:

$$\text{tp} \frac{\square \frac{\Gamma^u\{\ulcorner A\urcorner\}^u\}}{\Gamma^u\{\ulcorner \square A\urcorner\}^u}}{\Gamma^u\{\ulcorner \square A\urcorner\}^u} \rightsquigarrow \begin{array}{l} \text{w} \frac{\Gamma^u\{\ulcorner A\urcorner\}^u\}}{\Gamma^u\{\ulcorner \ulcorner A\urcorner\urcorner\}^u\}} \\ \text{tp} \frac{\Gamma^u\{\ulcorner \ulcorner A\urcorner\urcorner\}^u\}}{\Gamma^u\{\ulcorner \ulcorner A\urcorner\urcorner\}^u\}} \\ \text{bc} \frac{\Gamma^u\{\ulcorner \ulcorner A\urcorner\urcorner\}^u\}}{\Gamma^u\{\ulcorner \ulcorner A\urcorner\urcorner\}^u\}} \\ \square \frac{\Gamma^u\{\ulcorner \ulcorner A\urcorner\urcorner\}^u\}}{\Gamma^u\{\ulcorner \ulcorner A\urcorner\urcorner\}^u\}} \end{array}$$

we transform the derivation as follows and then use the admissibility of weakening (Lemma 3.2) and the induction hypothesis to conclude. \dashv

Lemma 3.4 *A sequent Δ is provable in $\text{iNK} + \mathbf{G}$ (or in $\text{iNK} + \mathbf{G} + \text{cut}$) if and only if it is provable in $\text{i}\ddot{\text{N}}\text{K} + \mathbf{G}$ (resp. in $\text{i}\ddot{\text{N}}\text{K} + \mathbf{G} + \text{cut}$).*

Proof Given a proof of Δ in $\text{iNK} + \mathbf{G}$, we can observe that the rules id and \diamond are just special cases of the rules id and $\ddot{\diamond}$, respectively. Thus, we obtain a proof of Δ in $\text{i}\ddot{\text{N}}\text{K} + \mathbf{G}$ from admissibility of tp (Lemma 3.3). Conversely, if we have a proof of Δ in $\text{i}\ddot{\text{N}}\text{K} + \mathbf{G}$, we can obtain a proof of Δ in $\text{iNK} + \mathbf{G}$ by replacing all instance of id and \diamond by the following derivations:

$$\text{tp} \frac{\text{id} \frac{\Gamma^u\{\emptyset\}^u\{a, \bar{a}\}}{\Gamma^u\{a\}^u\{\bar{a}\}}}{\Gamma^u\{a\}^u\{\bar{a}\}} \quad \text{and} \quad \begin{array}{l} \text{tp} \frac{\Gamma^u\{\diamond A\}^u\{[A, \Delta]\}}{\Gamma^u\{\emptyset\}^u\{\diamond A, [A, \Delta]\}} \\ \diamond \frac{\Gamma^u\{\emptyset\}^u\{\diamond A, [A, \Delta]\}}{\Gamma^u\{\emptyset\}^u\{\diamond A, [A, \Delta]\}} \\ \text{tp} \frac{\Gamma^u\{\emptyset\}^u\{\diamond A, [A, \Delta]\}}{\Gamma^u\{\diamond A\}^u\{[\Delta]\}} \end{array}$$

respectively. The same proof goes for the system with cut . \dashv

Finally we can prove the reduction lemma.

Lemma 3.5 (Reduction Lemma) *If there is a proof π of shape*

$$\text{cut}_{r+1} \frac{\begin{array}{c} \pi_1 \\ \Gamma fAg \end{array} \quad \begin{array}{c} \pi_2 \\ \Gamma f\bar{A}g \end{array}}{\Gamma f; g}$$

in $\text{i}\ddot{\text{N}}\text{K} + \mathbf{G}$ such that $\text{rk}(\pi_1) = r$ and $\text{rk}(\pi_2) = r$, then there is proof π' of $\Gamma f; g$ in $\text{i}\ddot{\text{N}}\text{K} + \mathbf{G}$ such that $\text{rk}(\pi') = r$.

Proof We proceed by induction on $\text{ht}(\pi_1) + \text{ht}(\pi_2)$, making a case analysis on the bottommost rules in π_1 and π_2 . The cases are almost identical to [3]; we only show the ones that are new or different. Details can be found in [16]. As an example of commutative case, we consider when the bottommost rule r of π_1 (or π_2) is $\mathfrak{g}_{k,0,m,0}$. Then we have

$$\text{cut} \frac{\begin{array}{c} \mathfrak{g}_{k,0,m,0} \\ \sigma_{w \rightarrow u} \frac{\Gamma\{\Gamma_{k-1}\{\ulcorner \Delta\urcorner\}^u, \Gamma_{m-1}\{\ulcorner \Sigma\urcorner\}^u\}\{A\}}{\Gamma\{\Gamma_{k-1}\{\ulcorner \Delta\urcorner\}^u, \Gamma_{m-1}\{\ulcorner \Sigma\urcorner\}^u\}\{A\}} \end{array} \quad \begin{array}{c} \Gamma\{\Gamma_{k-1}\{\ulcorner \Delta\urcorner\}^u, \Gamma_{m-1}\{\ulcorner \Sigma\urcorner\}^u\}\{\bar{A}\} \\ \Gamma\{\Gamma_{k-1}\{\ulcorner \Delta\urcorner\}^u, \Gamma_{m-1}\{\ulcorner \Sigma\urcorner\}^u\}\{\emptyset\} \end{array}}{\Gamma\{\Gamma_{k-1}\{\ulcorner \Delta\urcorner\}^u, \Gamma_{m-1}\{\ulcorner \Sigma\urcorner\}^u\}\{\emptyset\}}$$

which can be replaced by

$$\text{cut} \frac{\frac{\frac{\sigma_{w \rightarrow u} \Gamma\{\Gamma_{k-1}\{[\overset{1}{\Delta}]\}, \Gamma_{m-1}\{[\overset{w}{\Sigma}]\}\}\{A\}}{\Gamma\{\Gamma_{k-1}\{[\overset{1}{\Delta}]\}, \Gamma_{m-1}\{[\overset{w}{\Sigma}]\}\}\{\emptyset\}}}{\Gamma\{\Gamma_{k-1}\{[\overset{1}{\Delta}]\}, \Gamma_{m-1}\{[\overset{w}{\Sigma}]\}\}\{\emptyset\}}} \quad \text{isub} \frac{\Gamma\{\Gamma_{k-1}\{[\overset{2}{\Delta}]\}, \Gamma_{m-1}\{[\overset{w}{\Sigma}]\}\}\{\bar{A}\}}{\sigma_{w \rightarrow u} \Gamma\{\Gamma_{k-1}\{[\overset{2}{\Delta}]\}, \Gamma_{m-1}\{[\overset{w}{\Sigma}]\}\}\{\bar{A}\}}}{\sigma_{w \rightarrow u} \Gamma\{\Gamma_{k-1}\{[\overset{2}{\Delta}]\}, \Gamma_{m-1}\{[\overset{w}{\Sigma}]\}\}\{\emptyset\}}}{\Gamma\{\Gamma_{k-1}\{[\overset{1}{\Delta}]\}, \Gamma_{m-1}\{[\overset{w}{\Sigma}]\}\}\{\emptyset\}}$$

where $\Gamma_{k-1} f g$ and $\Gamma_{m-1} f g$ correspond to contexts which are of the form $[^{u_1} \Delta_1, \dots, [^{u_{k-1}} \Delta_{k-1}, f g]]$ and $[^{w_1} \Sigma_1, \dots, [^{w_m} \Sigma_m, f g]]$ respectively, and we can proceed by induction hypothesis.

The most interesting key case is when the cut-formula $A = \diamond B$, that is, when the bottommost rule r of π_1 is \diamond :

$$\text{cut}_{r+1} \frac{\frac{\frac{\diamond}{\Gamma\{\diamond B\}} \frac{\Gamma^w\{\diamond B\} \{[\overset{1}{B}, \Delta]\}}{\Gamma^w\{\diamond B\} \{[\overset{1}{\Delta}]\}}}{\Gamma^w\{\emptyset\} \{[\overset{1}{\Delta}]\}} \quad \frac{\frac{\square}{\Gamma\{\square \bar{B}\}} \frac{\Gamma^w\{[\overset{2}{\bar{B}}]\} \{[\overset{1}{\Delta}]\}}{\Gamma^w\{\square \bar{B}\} \{[\overset{1}{\Delta}]\}}}{\Gamma^w\{\emptyset\} \{[\overset{1}{\Delta}]\}}}{\Gamma^w\{\emptyset\} \{[\overset{1}{\Delta}]\}}$$

which can be reduced to

$$\text{cut}_{r+1} \frac{\frac{\frac{\frac{\diamond}{\Gamma\{\diamond B\}} \frac{\Gamma^w\{\diamond B\} \{[\overset{1}{B}, \Delta]\}}{\Gamma^w\{\diamond B\} \{[\overset{1}{\Delta}]\}}}{\Gamma^w\{\emptyset\} \{[\overset{1}{B}, \Delta]\}} \quad \frac{\frac{\frac{\square}{\Gamma\{\square \bar{B}\}} \frac{\Gamma^w\{[\overset{2}{\bar{B}}]\} \{[\overset{1}{\Delta}]\}}{\Gamma^w\{\square \bar{B}\} \{[\overset{1}{\Delta}]\}}}{\Gamma^w\{\emptyset\} \{[\overset{1}{B}, \Delta]\}} \quad \frac{\frac{\text{isub} \frac{\Gamma^w\{[\overset{2}{\bar{B}}]\} \{[\overset{1}{\Delta}]\}}{\Gamma^w\{[\overset{2}{\bar{B}}]\} \{[\overset{1}{\Delta}]\}}}{\Gamma^w\{\emptyset\} \{[\overset{1}{\Delta}]\}}}{\Gamma^w\{\emptyset\} \{[\overset{1}{B}, \Delta]\}}}{\Gamma^w\{\emptyset\} \{[\overset{1}{B}, \Delta]\}} \quad \frac{\frac{\text{tp} \frac{\Gamma^w\{[\overset{2}{\bar{B}}]\} \{[\overset{1}{\Delta}]\}}{\Gamma^w\{[\overset{2}{\bar{B}}]\} \{[\overset{1}{\Delta}]\}}}{\Gamma^w\{\emptyset\} \{[\overset{1}{B}, \Delta]\}}}{\Gamma^w\{\emptyset\} \{[\overset{1}{B}, \Delta]\}}}{\Gamma^w\{\emptyset\} \{[\overset{1}{\Delta}]\}} \quad \frac{\frac{\text{bc} \frac{\Gamma^w\{[\overset{2}{\bar{B}}]\} \{[\overset{1}{\Delta}]\}}{\Gamma^w\{[\overset{2}{\bar{B}}]\} \{[\overset{1}{\Delta}]\}}}{\Gamma^w\{\emptyset\} \{[\overset{1}{B}, \Delta]\}}}{\Gamma^w\{\emptyset\} \{[\overset{1}{B}, \Delta]\}}}{\Gamma^w\{\emptyset\} \{[\overset{1}{\Delta}]\}}$$

where on the left branch we use height-preserving admissibility of weakening and proceed by induction hypothesis, and on the right branch we use admissibility of the isub- and tp-rules (Lemmas 3.2 and 3.3). \dashv

Theorem 3.6 *If a sequent Γ is derivable in $\text{i}\ddot{\text{N}}\text{K} + \text{G} + \text{cut}$ then it is also derivable in $\text{i}\ddot{\text{N}}\text{K} + \text{G}$.*

Proof The proof goes by induction on the cut rank of π ; the induction step uses also an induction on the number of occurrences of cut with the maximal rank and Lemma 3.5 to eliminate each time the topmost occurrence in the proof. \dashv

Theorem 3.7 *If a sequent Γ is derivable in $\text{i}\text{N}\text{K} + \text{G} + \text{cut}$ then it is also derivable in $\text{i}\text{N}\text{K} + \text{G}$.*

Proof Following Theorem 3.6 and Lemma 3.4. \dashv

4 From classical to intuitionistic

Starting from the proof system for classical modal logic discussed in the previous section, we will show now how to obtain an intuitionistic variant. This will be done in a similar way as Gentzen did in his original work for the ordinary sequent calculus [9].

The first step is to enrich the language of formulas with implication and disallow negation on atoms, i.e., we no longer restrict formulas to negative normal form:

$$A ::= a \mid j \mid ? \mid A \wedge A \mid A _ A \mid A \sqsupset A \mid A \sqsubset A \mid \Box A \mid \Diamond A \quad (6)$$

We can define $\vdash A = A \sqsupset ?$ and $\succ = \vdash ?$. Intuitionistic modal logic IK is obtained from intuitionistic propositional logic by adding the axioms

$$\begin{array}{ll} \mathbf{k}_1: \Box(A _ B) _ (\Box A _ \Box B) & \mathbf{k}_3: \Diamond(A _ B) _ (\Diamond A _ \Diamond B) \\ \mathbf{k}_2: \Box(A _ B) _ (\Diamond A _ \Diamond B) & \mathbf{k}_4: (\Diamond A _ \Box B) _ \Box(A _ B) \\ & \mathbf{k}_5: \Diamond ? _ ? \end{array} \quad (7)$$

and the rule *nec*, similarly to Section 2. The axioms in (7) are logical consequences of \mathbf{k} in the classical case but not in the intuitionistic case.¹

We will consider the following schema as the intuitionistic equivalent to Scott-Lemmon axioms:

$$\mathbf{g}_{k,l,m,n}: (\Diamond^k \Box^l A _ \Box^m \Diamond^n A) \wedge (\Diamond^m \Box^n A _ \Box^k \Diamond^l A) \quad (8)$$

The two conjuncts correspond to the classical $\mathbf{g}_{k,l,m,n}$ and $\mathbf{g}_{m,n,k,l}$ which are equivalent via De Morgan in classical logic, but not in intuitionistic modal logic.

In the following, we will first present a *two-sided* version of the classical one-sided system iNK that was given in Figure 1. For this, the first step is to include the distinction between input and output formulas into the data structure. To that purpose we use here the notion of *polarity*, as studied by Lamarche in [13]. We assign to every formula in the nested sequent a unique polarity: either *input*, denoted by a $_$ -superscript, or *output*, denoted by a \bullet -superscript. A two-sided indexed nested sequent therefore is of the following form, denoted by Γ° if it contains at least one input formula and by A^\bullet otherwise:

$$\begin{array}{l} \Gamma^\circ ::= A^\bullet \mid j \mid \Gamma^\circ, A^\circ \mid j \mid \Gamma^\circ, [^w \Gamma^\circ] \\ A^\bullet ::= ; \mid j \mid A^\bullet, B^\bullet \mid j \mid A^\bullet, [^u A^\bullet] \end{array} \quad (9)$$

We are now ready to see the inference rules. The two-sided version of iNK₂ is shown in Figure 5. As expected, the rules for output formulas are the same as in the one-sided case, and the rules for input formulas show dual behavior.

¹ This is the variant of IK first mentioned in [5] and [20] and studied in detail in [25]. There are many more variants of intuitionistic modal logic, e.g. [6, 22, 2, 19]. Another popular variant is *constructive modal logic* (e.g. [17]), which rejects axioms \mathbf{k}_3 - \mathbf{k}_5 in (7) and only allows \mathbf{k}_1 and \mathbf{k}_2 . It has a different cut-elimination proof in nested sequents [1]. For this reason we work in this paper with IK which allows all of \mathbf{k}_1 - \mathbf{k}_5 .

$$\begin{array}{cccc}
 \perp^\bullet \frac{}{\Gamma\{\perp^\bullet\}} & \text{id} \frac{}{\Gamma\{a^\bullet, a^\circ\}} & \supset_c^\bullet \frac{\Gamma\{A^\circ\} \quad \Gamma\{B^\bullet\}}{\Gamma\{A \supset B^\bullet\}} & \supset^\circ \frac{\Gamma\{A^\bullet, B^\circ\}}{\Gamma\{A \supset B^\circ\}} \\
 \wedge^\bullet \frac{\Gamma\{A^\bullet, B^\bullet\}}{\Gamma\{A \wedge B^\bullet\}} & \wedge^\circ \frac{\Gamma\{A^\circ\} \quad \Gamma\{B^\circ\}}{\Gamma\{A \wedge B^\circ\}} & \vee^\bullet \frac{\Gamma\{A^\bullet\} \quad \Gamma\{B^\bullet\}}{\Gamma\{A \vee B^\bullet\}} & \vee_c^\circ \frac{\Gamma\{A^\circ, B^\circ\}}{\Gamma\{A \vee B^\circ\}} \\
 \square^\bullet \frac{\Gamma\{\square A^\bullet, [\overset{w}{A}^\bullet, \Delta]\}}{\Gamma\{\square A^\bullet, [\overset{w}{\Delta}]\}} & \square^\circ \frac{\Gamma\{[\overset{v}{A}^\circ]\}}{\Gamma\{\square A^\circ\}} & \diamond^\bullet \frac{\Gamma\{[\overset{v}{A}^\bullet]\}}{\Gamma\{\diamond A^\bullet\}} & \diamond_c^\circ \frac{\Gamma\{\diamond A^\circ, [\overset{w}{A}^\circ, \Delta]\}}{\Gamma\{\diamond A^\circ, [\overset{w}{\Delta}]\}} \\
 \text{tp} \frac{\Gamma^w\{\emptyset\} \quad \overset{w}{\Gamma}\{A\}}{\Gamma^w\{A\} \quad \overset{w}{\Gamma}\{\emptyset\}} & \text{bc}_1 \frac{\Gamma^w\{[\overset{u}{\Delta}]\} \quad \overset{w}{\Gamma}\{[\overset{u}{\emptyset}]\}}{\Gamma^w\{[\overset{u}{\Delta}]\} \quad \overset{w}{\Gamma}\{\emptyset\}} & \text{bc}_2 \frac{\Gamma^w\{[\overset{u}{\Delta} \overset{w}{\Gamma}\{[\overset{u}{\emptyset}]\}]\}}{\Gamma^w\{[\overset{u}{\Delta} \overset{w}{\Gamma}\{\emptyset}\]}\}}
 \end{array}$$

Fig. 5. Two-sided classical system iNK_2

$$\supset_i^\bullet \frac{\Gamma^\downarrow\{A \supset B^\bullet, A^\circ\} \quad \Gamma\{B^\bullet\}}{\Gamma\{A \supset B^\bullet\}} \quad \vee_1^\circ \frac{\Gamma\{A^\circ\}}{\Gamma\{A \vee B^\circ\}} \quad \vee_2^\circ \frac{\Gamma\{B^\circ\}}{\Gamma\{A \vee B^\circ\}} \quad \diamond_i^\circ \frac{\Gamma\{[\overset{w}{A}^\circ, \Delta]\}}{\Gamma\{\diamond A^\circ, [\overset{w}{\Delta}]\}}$$

Fig. 6. Intuitionistic variants of some rules for system iNIK

Finally, the step from classical to intuitionistic simply consists in restricting the number of output formulas in the sequent to one, but it is crucial to observe that we count the whole sequent, and not every bracket separately [26]. So an intuitionistic indexed nested sequent is of the form:

$$\Gamma^\circ ::= A^\bullet, A^\circ \text{ j } A^\bullet, [\overset{v}{\Gamma^\circ}] \quad (10)$$

where A^\bullet is defined as in (9). Moreover, since we do not have an explicit contraction rule, but have it incorporated into inference rules (e.g., \square^\bullet), the inference rules $_^\circ$, \bullet° and \diamond° have to be adapted, as shown on Figure 6, in order to maintain the property that each sequent in a proof contains exactly one output formula. In particular, to ensure that both premisses of the \bullet° -rule are intuitionistic sequents, the notation $\Gamma^\downarrow f \ g$ stands for the context obtained from $\Gamma f \ g$ by removing the output formula. We define $\text{iNIK} = \text{iNK}_2 \text{ nf } \bullet^\circ, _^\circ, \diamond_c^\circ g [f \ \bullet_i^\circ, _1^\circ, _2^\circ, \diamond_i^\circ g$. Observe that the structural rules tp , bc_1 , and bc_2 are identical for all three systems (one-sided classical, two-sided classical, and two-sided intuitionistic).

It is also the case that each system can be extended with the rules presented in Figures 2 and 3. In the classical case, it will give the system $\text{iNK}_2 + \text{G}$ equivalent to $\text{iNK} + \text{G}$ and basically identical to Fitting's system [7]. In the intuitionistic case, it gives us a system $\text{iNIK} + \text{G}$, and the rest of the paper is dedicated to the study of this system. This modular way of adding structural rules for the Scott-Lemmon axioms to the basic deductive system corresponding to K or IK is similar to the way labelled sequent systems handle the Scott-Lemmon axioms.²

² Indeed, like iNK_2 and iNIK , Negri's [18] system for classical logic K can be seen as the classical variant of Simpson's system [25] for intuitionistic logic IK . Then the same structural rules can be added to each system to extend it to geometric axioms, so in particular to Scott-Lemmon axioms.

Finally, the cut-elimination proof conducted in $\text{iNK} + \text{G}$ can be reproduced in a similar fashion in $\text{iNK}_2 + \text{G}$ and $\text{iNIK} + \text{G}$, the two-sided cut-rule being of the form $\text{cut}_c \frac{\Gamma\{A^\circ\} \quad \Gamma\{A^\bullet\}}{\Gamma\{\emptyset\}}$ in the classical case, and $\text{cut}_i \frac{\Gamma^\perp\{A^\circ\} \quad \Gamma\{A^\bullet\}}{\Gamma\{\emptyset\}}$ in the intuitionistic case, where a unique output needs to be maintained in the left branch.

Theorem 4.1 *If a sequent Γ is derivable in $\text{iNK}_2 + \text{G} + \text{cut}_c$ (resp. $\text{iNIK} + \text{G} + \text{cut}_i$) then it is also derivable in $\text{iNK}_2 + \text{G}$ (resp. $\text{iNIK} + \text{G}$).*

Proof The proof works similarly to the one of Theorem 3.7. For the intuitionistic system, the cases are similar to [26], except for the specific indexed ones. Details can be found in [16]. \square

The cut-elimination theorem can be used to show completeness: every theorem of $\text{K} + \text{G}$ (resp. $\text{IK} + \text{G}$) is a theorem of $\text{iNK}_2 + \text{G}$ (resp. $\text{iNIK} + \text{G}$).

Theorem 4.2 *If a formula A is provable in the Hilbert system $\text{IK} + \text{G}$, then the sequent A° is provable in the indexed nested sequent system $\text{iNIK} + \text{G}$.*

Proof The axioms of intuitionistic propositional logic as well as the axioms k_1 - k_5 can be derived in iNIK , in the same way as in [26]. The inference rule nec can be simulated by the structural rule nec , which is admissible in $\text{iNIK} + \text{G}$ (Lemma 3.2), and *modus ponens* mp can be simulated by the cut-rule, which is also admissible (Theorem 4.1). Thus, it remains to show that any $\mathfrak{g}_{k,l,m,n}$ axiom can be derived, using the corresponding $\mathfrak{g}_{k,l,m,n}$ -rule (which is the same as $\mathfrak{g}_{m,n,k,l}$):

$$\begin{array}{c}
\text{id} \frac{}{[U_1 \dots [U_k \Box^l p^\bullet, [V_1 \Box^{l-1} p^\bullet, \dots [V_{l-1} \Box p^\bullet, [V_l]] \dots]] \dots],} \\
\text{tp} \frac{[W_1 \dots [W_m [X_1 \dots [X_{n-1} [X_n p^\bullet, p^\circ]] \dots]] \dots]}{[U_1 \dots [U_k \Box^l p^\bullet, [V_1 \Box^{l-1} p^\bullet, \dots [V_{l-1} \Box p^\bullet, [V_l p^\bullet]] \dots]] \dots],} \quad c_l = d_n \\
\mathfrak{g}_{k,l,m,n} \frac{[U_1 \dots [U_k \Box^l p^\bullet, [V_1 \dots [V_l]] \dots]] \dots, [W_1 \dots [W_m \Diamond^n p^\circ, [X_1 \dots [X_n]] \dots]] \dots]}{[U_1 \dots [U_k \Box^l p^\bullet, [V_1 \dots [V_l]] \dots]] \dots, [W_1 \dots [W_m \Diamond^n p^\circ, [X_1 \dots [X_n]] \dots]] \dots]} \\
\frac{}{k \cdot \Diamond^\bullet, m \cdot \Box^\circ} \frac{}{\Diamond^k \Box^l p^\bullet, \Box^m \Diamond^n p^\circ} \\
\supset^\circ \frac{}{\Diamond^k \Box^l p \supset \Box^m \Diamond^n p^\circ}
\end{array}$$

And similarly for the other conjunct. \square

The same proof can be done in the classical case, and provides an alternative to the completeness of indexed nested sequents wrt. set prefixed tableaux in [7].

However, there are examples of theorems of $\text{iNIK} + \text{G}$ that are not theorems of $\text{IK} + \text{G}$, that is, the indexed nested sequent system is not sound with respect to the Hilbert axiomatisation using what we gave above as the intuitionistic alternative to Scott-Lemmon axioms. There is already a simple counter-example when one considers G to be composed with only the axiom $\mathfrak{g}_{1,1,1,1} : \Diamond \Box A \quad \Box \Diamond A$. Then

$$F = (\Diamond(\Box(a _ b) \wedge \Diamond a) \wedge \Diamond(\Box(a _ b) \wedge \Diamond b)) \quad \Diamond(\Diamond a \wedge \Diamond b) \quad (11)$$

is derivable in $\text{iNIK} + \mathfrak{g}_{1,1,1,1}$, but is not a theorem of $\text{IK} + \mathfrak{g}_{1,1,1,1}$ (as mentioned in [25]). Thus, the logic given by the Hilbert axiomatisation $\text{IK} + \text{G}$ and the one given by the indexed nested sequent system $\text{iNIK} + \text{G}$ actually differ in the intuitionistic case. We will address this issue in more detail in the next section.

5 Semantics of the Scott-Lemmon axioms

In the classical case, the indexed nested sequent system is not only equivalent to the Hilbert axiomatisation using Scott-Lemmon axioms, it is actually sound and complete wrt. the corresponding Kripke semantics. In this section, we investigate the behavior of the indexed nested sequents system $iNIK + G$ with respect to Kripke semantics. For this, we briefly recall the standard Kripke semantics of classical and intuitionistic modal logics. The classical semantics is standard, but the intuitionistic might be less well-known. We use here the birelational models, as they are discussed in [4, 20, 25].

A *classical frame* $\langle W, R \rangle$ is a non-empty set W of *worlds* and a binary relation $R \subseteq W \times W$, called the *accessibility relation*. An *intuitionistic frame* $\langle W, R, \preceq \rangle$ is additionally equipped with a preorder \preceq on W , such that:

- (F1) For all $u, v, v' \preceq W$, if uRv and $v \preceq v'$, there exists $u' \preceq W$ such that $u \preceq u'$ and $u'Rv'$.
- (F2) For all $u', u, v \preceq W$, if $u \preceq u'$ and uRv , there exists $v' \preceq W$ such that $u'Rv'$ and $v \preceq v'$.

A *classical model* $\mathcal{M} = \langle W, R, V \rangle$ is a classical frame together with a *valuation* function $V: W \rightarrow 2^A$ mapping each world w to the set of propositional variables which are true in w . In an *intuitionistic model* $\langle W, R, \preceq, V \rangle$, the function V must be monotone with respect to \preceq , i.e. $w \preceq v$ implies $V(w) \subseteq V(v)$.

We write $w \Vdash a$ if $a \preceq V(w)$. From there, the relation \Vdash is extended to all formulas in a parallel way in the classical and intuitionistic case, that is, considering a classical model to be a special case of an intuitionistic model, where $w \preceq v$ iff $w = v$, we give below the definition for both at the same time:

$w \Vdash A \wedge B$	iff	$w \Vdash A$ and $w \Vdash B$
$w \Vdash A \vee B$	iff	$w \Vdash A$ or $w \Vdash B$
$w \Vdash A \rightarrow B$	iff	for all w' with $w \preceq w'$, if $w' \Vdash A$ then also $w' \Vdash B$
$w \Vdash \Box A$	iff	for all w' and u with $w \preceq w'$ and $w'Ru$, we have $u \Vdash A$
$w \Vdash \Diamond A$	iff	there is a $u \preceq W$ such that wRu and $u \Vdash A$

If $w \Vdash A$ we say that w *forces* A . We write $w \not\Vdash A$ if w does not force A , i.e. it is not the case that $w \Vdash A$. It follows that \Vdash also satisfies monotonicity, i.e. if $w \preceq v$ and $w \Vdash A$ then $v \Vdash A$. (In the classical case we also have $w \not\Vdash A$ iff $w \Vdash \neg A$ which implies the de Morgan dualities, in particular, $w \Vdash \Box(\neg A)$ iff $w \not\Vdash (\Diamond A)$.) We say that a formula A is *valid in a model* \mathcal{M} , if for all $w \preceq W$ we have $w \Vdash A$. Finally, we say a formula is *classically (or intuitionistically) valid*, if it is valid in all classical (resp. intuitionistic) models.

The Hilbert systems for K and IK , introduced in Sections 2 and 4 respectively, are sound and complete with respect to arbitrary classical and intuitionistic models respectively. We are now going to adapt the method of Fitting [7] for proving the soundness of the classical system $iNK_2 + G$ to study the soundness of our proposed intuitionistic system $iNIK + G$ with respect to a subclass of intuitionistic models. The first step is to put intuitionistic indexed nested sequent in correspondence with intuitionistic models in order to define the *validity of a sequent* in a model.

Definition 5.1 Let Σ be an indexed nested sequent. We write I_Σ to denote the set of indexes occurring in Σ , and we write R_Σ for the accessibility relation induced by Σ , that is, the binary relation $R_\Sigma \subseteq I_\Sigma \times I_\Sigma$ defined as: $wR_\Sigma v$ iff $\Sigma = \Gamma \overline{f} \overline{v} \Delta]g$ for some $\Gamma \overline{f} g$ and Δ , i.e. v is the index of a child of w .

Example 5.2 If we consider the sequent Σ obtained in the Example 2.1, we have that $I_\Sigma = \overline{f}0, 1, 2, 3, 4, 5g$ with 0 being the index of the root, so $R_\Sigma = \overline{f}(0, 1), (0, 2), (0, 3), (1, 2), (2, 4), (2, 5), (3, 1)g$

Definition 5.3 Let Σ be an indexed nested sequent and let $\mathcal{M} = \langle W, R, \cdot, V \rangle$ be an intuitionistic Kripke model. A *homomorphism* $h: \Sigma \rightarrow \mathcal{M}$ is a mapping $h: I_\Sigma \rightarrow W$, such that $wR_\Sigma v$ implies $h(w)Rh(v)$ for all $w, v \in I_\Sigma$.

A preorder relation between homomorphisms can be obtained from the preorder in an intuitionistic model: For $h, h': \Sigma \rightarrow \mathcal{M}$ two homomorphisms, we write $h \leq h'$ if $h(w) \leq h'(w)$ in \mathcal{M} for all $w \in I_\Sigma$. The notion of validity can then be defined by induction on the subsequents of a given sequent.

Definition 5.4 Let Σ and Δ be indexed nested sequents, and $w \in I_\Sigma$. We say that $h\Delta, wi$ is an *exhaustive subsequent* of Σ if either $\Delta = \Sigma$ and $w = 0$, or $\Sigma = \Gamma \overline{f} \overline{w} \Delta]g$ for some context $\Gamma \overline{f} g$.

Note that for a given index v of Σ , there might be more than one Δ such that $h\Delta, vi$ is an exhaustive subsequent of Σ , simply because v occurs more than once in Σ . For this reason we will write \dot{v} to denote a particular occurrence of v in Σ and Σ/\dot{v} for the subsequent of Σ rooted at the node \dot{v} . $h\Sigma/\dot{v}, vi$ stands then for a uniquely defined exhaustive subsequent of Σ .

Definition 5.5 Let $h: \Sigma \rightarrow \mathcal{M}$ be a homomorphism from a sequent Σ to a model \mathcal{M} . Let $w \in I_\Sigma$ and let $h\Delta, wi$ be an exhaustive subsequent of Σ . From (9) and (10), Δ has one of the following forms:

- $\Delta = B_1^\bullet, \dots, B_l^\bullet, [{}^{v_1}A_1^\bullet], \dots, [{}^{v_n}A_n^\bullet]$. Then we define $hh, wi \in \Delta$ if $h(w) \not\leq B_i$ for some $i \leq l$ or $hh, v_j i \in A_j^\bullet$ for some $j \leq n$
- $\Delta = B_1^\bullet, \dots, B_l^\bullet, [{}^{v_1}A_1^\bullet], \dots, [{}^{v_n}A_n^\bullet], A^\circ$. Then we define $hh, wi \in \Delta$ if either $h(w) \not\leq B_i$ for some $i \leq l$ or $hh, v_j i \in A_j^\bullet$ for some $j \leq n$ or $h(w) \leq A$.
- $\Delta = B_1^\bullet, \dots, B_l^\bullet, [{}^{v_1}A_1^\bullet], \dots, [{}^{v_n}A_n^\bullet], [{}^u\Pi^\circ]$. Then we define $hh, wi \in \Delta$ if either $h(w) \not\leq B_i$ for some $i \leq l$ or $hh, v_j i \in A_j^\bullet$ for some $j \leq n$ or for all homomorphisms $h' \leq h$, we have that $hh', ui \in \Pi^\circ$.

If, for all $h' \leq h$, $hh', wi \in \Delta$, we say that $h\Delta, wi$ is *intuitionistically valid* in \mathcal{M} under h . Then, a sequent Σ is *valid* in a model \mathcal{M} , if $h\Sigma, 0i$ is valid in \mathcal{M} under every $h: \Sigma \rightarrow \mathcal{M}$.

Informally, an indexed nested sequent is valid if it contains anywhere in the sequent tree a valid output formula or an invalid input formula. More formally:

Lemma 5.6 Let Σ be an indexed nested sequent. Let $h\Delta, vi$ be an exhaustive subsequent of Σ . Suppose $\Delta = \Gamma \overline{w} \overline{f} A]g$ for some context $\Gamma \overline{w} \overline{f} g$ and some formula A . Let \mathcal{M} be a Kripke model and $h: \Sigma \rightarrow \mathcal{M}$ a homomorphism.

- If $A = A^\circ$ and $h(w) \Vdash A$, then $\Vdash h, vi \vdash \Delta$.
- If $A = A^\bullet$ and $h(w) \not\Vdash A$, then $\Vdash h, vi \vdash \Delta$.

Proof By induction on the height of the tree rooted at the considered occurrence of v . The base case occurs when A° (or A^\bullet) is at the root of that tree. \square

We now make explicit the class of model that we are going to consider in order to interpret system $\text{iNIK} + \mathbf{G}$. We adapt the notion of graph-consistency introduced by Simpson [25] to the indexed nested sequents framework.

Definition 5.7 A intuitionistic model \mathcal{M} is called *graph-consistent* if for any indexed nested sequent Γ , given any homomorphism $h: \Gamma \Vdash \mathcal{M}$, any $w \geq I_\Gamma$, and any $w' \Vdash h(w)$, there exists $h' \Vdash h$ such that $h'(w) = w'$.³

Definition 5.8 Let $\mathcal{M} = \langle W, R, \Vdash, Vi \rangle$ be an intuitionistic model and let $\langle k, l, m, n \rangle \in \mathbb{N}^4$. We say that \mathcal{M} is a $\mathbf{g}(k, l, m, n)$ -*model* if for all $w, u, v \geq W$ with $wR^k u$ and $wR^m v$ there is a $z \geq W$ such that $uR^l z$ and $vR^n z$.⁴ For a set \mathbf{G} of \mathbb{N}^4 -tuples, we say that \mathcal{M} is a \mathbf{G} -*model*, if for all $\langle k, l, m, n \rangle \in \mathbf{G}$ we have that \mathcal{M} is a $\mathbf{g}(k, l, m, n)$ -model.

We finally prove that any theorem of $\text{iNIK} + \mathbf{G}$ is valid in every graph-consistent \mathbf{G} -model by showing that each rule of $\text{iNIK} + \mathbf{G}$ is sound when interpreted in these models.

Lemma 5.9 Let $\mathbf{G} \subseteq \mathbb{N}^4$, and let $r \frac{\Sigma_1 \cdots \Sigma_n}{\Sigma}$ be an instance of an inference rule in $\text{iNIK} + \mathbf{G}$ for $n = 0, 1, 2$. If all of $\Sigma_1, \dots, \Sigma_n$ are valid in every graph-consistent \mathbf{G} -model, then so is Σ .

Proof First, assume that r is $\mathbf{g}_{k,l,m,n} \frac{\Phi}{\Psi}$, for some $\langle k, l, m, n \rangle \in \mathbf{G}$ such that $k, l, m, n > 0$ (similar proof when one parameter is 0). By way of contradiction, suppose that Φ is valid in every graph-consistent \mathbf{G} -model and that there is a \mathbf{G} -model $\mathcal{M} = \langle W, R, \Vdash, Vi \rangle$, a homomorphism $h: \Psi \Vdash \mathcal{M}$ such that $\Vdash h, 0i$ is not valid in \mathcal{M} under h . Recall that Ψ is of form

$$\Psi = \Gamma^{u_0} \Vdash^{u_1} \Delta_1, \dots, \Vdash^{u_k} \Delta_k \dots, \Vdash^{w_1} \Sigma_1, \dots, \Vdash^{w_m} \Sigma_m \dots \Vdash g$$

Therefore, there exist u_0, u_k, w_m in W such that $u_0 = h(u_0)$, $u_k = h(u_k)$, $w_m = h(w_m)$, and $u_0 R^k u_k$, and $u_0 R^m w_m$ (Definitions 5.1 and 5.3). Hence, as \mathcal{M} is in particular a $\mathbf{g}(k, l, m, n)$ -model, there exists $y \geq W$ with $u_k R^l y$ and $w_m R^n y$ (Definition 5.8). Namely, there are worlds $v_1, \dots, v_l, x_1, \dots, x_n$ in W such that $u_k R v_1 \dots v_{l-1} R v_l$, $w_m R x_1 \dots x_{n-1} R x_n$, and $v_l = y = x_n$. By noting that

$$\Phi = \Gamma^{u_0} \Vdash^{u_1} \Delta_1, \dots, \Vdash^{u_k} \Delta_k, \Vdash^{v_1} \dots \Vdash^{v_l} \dots, \Vdash^{w_1} \Sigma_1, \dots, \Vdash^{w_m} \Sigma_m, \Vdash^{x_1} \dots \Vdash^{x_n} \dots \Vdash g$$

³ One might consider this definition unsatisfactory as it is not a pure frame condition, but we have to leave a detailed study of this issue to future research. \square \exists $\{$

⁴ We define the composition of two relations R, S on a set W as usual: $($

we can define a homomorphism $h': \Phi \dashv \dashv \mathcal{M}$ with $h'(z) = h(z)$ for all $z \geq I_\Psi$, $h'(v_i) = v_i$ for $1 \leq i \leq l$ and $h'(x_j) = x_j$ for $1 \leq j \leq n$.

We are now going to show that for every $h: \Psi \dashv \dashv \mathcal{M}$, and every occurrence \dot{z} of an index $z \geq I_\Psi$, we have $hh, zi \dashv \dashv \Psi j_z$ iff $hh', zi \dashv \dashv \Phi j_z$. We proceed by induction on the height of the tree rooted at \dot{z} .

1. The node of \dot{z} is a leaf node of Ψ , and $z \notin u_k$ and $z \notin w_m$. Then we have $\Psi j_z = \Phi j_z$ and the claim holds trivially.
2. The node of \dot{z} is an inner node of Ψ , and $z \notin u_k$ and $z \notin w_m$. By the induction hypothesis, for every $t \geq I_\Psi$ with $zR_\Psi t$, every occurrence \dot{t} of t in Ψj_z , and every $h: \Psi \dashv \dashv \mathcal{M}$, $hh, ti \dashv \dashv \Psi j_t$ iff $hh', ti \dashv \dashv \Phi j_t$. The statement follows then by unravelling the definition of $\dashv \dashv$ (Definition 5.5).
3. $z = u_k$. For any occurrence \dot{z} in the context $\Gamma^{z_0} f g$, the proof is similar to one of the previous cases. Otherwise, we know that $\Psi j_z = \Delta_k$ and $\Phi j_z = \Delta_k, [^{v_1} \dots [^{v_l}] \dots]$. Furthermore, for all $i \leq l$ and $h'' \dashv \dashv h$ we have $hh'', v_i i \dashv \dashv [^{v_{i+1}} \dots [^{v_l}] \dots]$, and therefore $hh, zi \dashv \dashv \Psi j_z$ iff $hh', zi \dashv \dashv \Phi j_z$.
4. $v = w_m$. This case is similar to the previous one.

Since we assumed that $h\Psi, 0i$ is not valid in \mathcal{M} under h , we can conclude that $h\Phi, 0i$ is not valid in \mathcal{M} under h' , contradicting the validity of Φ .

The proof for **bc**, **tp**, and the other cases of $\mathfrak{g}_{k,l,m,n}$ is similar.

For the logical rules, we will only consider in detail the case for \Box° , the others being similar. Suppose that $\Phi = \Gamma^w f [^v A^\circ] g$ is valid in every graph-consistent \mathbf{G} -model. For $\Psi = \Gamma^w f \Box A^\circ g$, suppose that there exists a graph-consistent \mathbf{G} -model $\mathcal{M} = \langle W, R, \cdot, V \rangle$ and a homomorphism $h: \Psi \dashv \dashv \mathcal{M}$ such that $h\Psi, 0i$ is not valid in \mathcal{M} under h . Therefore, there exists $h' \dashv \dashv h$ such that $hh', 0i \dashv \dashv \Psi$, in particular by Lemma 5.6, $h'(w) \dashv \dashv \Box A$. So there exists w and v such that wRv , $h'(w) \dashv \dashv w$ and $v \dashv \dashv A$. As \mathcal{M} is graph-consistent, there exists h'' such that $w = h''(w)$. Thus, we can extend h'' by setting $h''(v) = v$ to obtain a homomorphism $h'': \Phi \dashv \dashv \mathcal{M}$, indeed Φ and Ψ have the same set of indexes related by the same underlying structure, but for the fresh index v that does not appear in Ψ . Finally, as $h''(v) \dashv \dashv A$, we have by Lemma 5.6 that $h\Phi, 0i$ is not valid in \mathcal{M} under h'' which contradicts the assumption of validity of Φ . \dashv

Theorem 5.10 *Let \mathbf{G} be given. If a sequent Σ is provable in $\text{iNIK} + \mathbf{G}$ then it is valid in every graph-consistent intuitionistic \mathbf{G} -model.*

Proof By induction on the height of the derivation, using Lemma 5.9. \dashv

The soundness result in [7] can be obtained as a corollary of this theorem, as our proof method extends Fitting's technique to the intuitionistic framework.

Corollary 5.11 *Let \mathbf{G} be given. If a sequent Σ is provable in $\text{iNK}_2 + \mathbf{G}$ then it is valid in every classical \mathbf{G} -model.*

6 Discussion

It has long been known that there is a close correspondence between the logic $\mathbf{K} + \mathbf{G}$ and the Kripke semantics:

Theorem 6.1 (Lemmon and Scott [14]) *Let $\mathbf{G} \subseteq \mathbf{N}^4$. A formula is derivable in $\mathbf{K} + \mathbf{G}$, iff it is valid in all classical \mathbf{G} -models.*

This means that in the classical case, we have a complete triangle between Kripke models, Hilbert axiomatisation and nested sequents systems via Theorems 4.2, 5.11 and 6.1.

In the intuitionistic case, the correspondence is less clear, and a lot of questions are still open. We do have Theorems 4.2 giving that every theorem of $\mathbf{IK} + \mathbf{G}$ is a theorem of $\mathbf{iNIK} + \mathbf{G}$, and Theorem 5.10 giving that every theorem of $\mathbf{iNIK} + \mathbf{G}$ is valid in all graph-consistent \mathbf{G} -models, but there is no proper equivalent to Theorem 6.1 to “link” the two theorems into an actual soundness and completeness result for $\mathbf{iNIK} + \mathbf{G}$. As we have seen in Section 4, the first inclusion is strict, since the formula in (11) is provable in $\mathbf{iNIK} + \mathbf{G}$, but not in $\mathbf{IK} + \mathbf{G}$. However, the strictness of the second inclusion is open. The question is: Is there a certain set $\mathbf{G} \subseteq \mathbf{N}^4$, such that there exists a formula that is valid in every directed graph-consistent \mathbf{G} -models, but that is not a theorem of $\mathbf{iNIK} + \mathbf{G}$?

On the other hand, Theorems 6.2.1 and 8.1.4 of [25] entail a parallel result to Theorem 6.1 for a restricted family of the intuitionistic Scott-Lemmon axioms, those for which $l = 1$ and $n = 0$ (or equivalently $l = 0$ and $n = 1$), that is, of the form: $(\diamond^k \Box A \quad \Box^m A) \wedge (\diamond^k A \quad \Box^m \diamond A)$. Therefore, in this restricted case, the inclusions collapse too. The reason why this result holds seems to be that in a derivation of a theorem of such a logic, the steps referring to non-tree graphs can be eliminated via appealing to the closure of the accessibility relation (see [25]). This is similar to what happens when going from indexed to pure nested sequents calculi, and suggests that a pure nested sequent calculus could be provided for these logics in the intuitionistic case too. Indeed, these axioms are the intuitionistic variants of some of the *path axioms* of [10], for which a pure nested sequent calculus is given; but for the general case, [10] only provides a display calculus.

To conclude, we can say that for intuitionistic modal logics the accurate definition might actually come from structural proof-theoretical studies rather than Hilbert axiomatisations or semantical considerations. For Simpson [25] there are two different (but equivalent) ways to define intuitionistic modal logics, either the natural deduction systems he proposes, or the extension of the standard translation for intuitionistic modal logics into first-order intuitionistic logic. Equivalence between the natural deduction systems and the Hilbert axiomatisations, or direct interpretation of the natural deduction systems in intuitionistic (birelational) structures are just side-results. He therefore sees their failure for the majority of logics not as a problem, but rather as another justification of the validity of the proof-theoretic approach.

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