# Which simple types have a unique inhabitant? 

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September 1st, 2015

## Code inference

Many programs are fun to write. Some parts can be boring, though.

We get bored when there is no choice to make.
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- Overloaded identifier disambiguation.
- Type classes, implicits.
- Proof assistants tactics.


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Some existing examples:

- Overloaded identifier disambiguation.
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- Proof assistants tactics.

We should infer any code uniquely determined by its type.

## Which types have a unique inhabitant?

Uniquely inhabited typing $(\Gamma, A)$ : inhabited $(\Gamma \vdash t: A)$ and

$$
\ulcorner\vdash t: A \wedge \Gamma \vdash u: A \quad \Longrightarrow \quad \Gamma \vdash t \simeq u: A
$$

$(\vdash)$ in a given type system (STLC with atoms, products and sums) $(\simeq)$ modulo some program equivalence (here, $\beta \eta$ )

Contribution: a decision procedure (algorithm) in this setting.

## Killer example

The Monad instance for Exception $A \stackrel{\text { def }}{=} A+E$ is canonical.

$$
\begin{aligned}
\text { return: } X & \rightarrow \\
\text { bind: } X+E & \rightarrow \quad(X+E) \\
\text { b } & \rightarrow Y+E) \quad \rightarrow \quad Y+E
\end{aligned}
$$

Functor instance also canonical.

Applicative functor, two distinct choices.

$$
\text { ap: }(X \rightarrow Y)+E \quad \rightarrow \quad X+E \quad \rightarrow \quad Y+E
$$

(Which argument to evaluate first?)

## $\beta \eta$-equivalence

Type system for pure language: enforces strong normalization.

$$
\begin{array}{ll}
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(\lambda x . t) u \rightarrow_{\beta} t[u / x] & (t: A \rightarrow B)={ }_{\eta} \lambda x . t x \\
\pi_{i}\left(t_{1}, t_{2}\right) \rightarrow_{\beta} t_{i} & (t: A * B)={ }_{\eta}\left(\pi_{1} t, \pi_{2} t\right) \\
\text { match }(\mathrm{L} t) \text { with } & \left\lvert\, \begin{array}{lll}
\mathrm{L} x_{1} \rightarrow u_{1} \\
\mathrm{R} x_{2} \rightarrow u_{2}
\end{array} \rightarrow_{\beta}\right. \\
u_{1}\left[t / x_{1}\right]
\end{array} \\
(t: A+B)={ }_{\eta} \text { match } t \text { with } \left\lvert\, \begin{array}{lll}
\mathrm{L} x_{1} \rightarrow & \mathrm{~L} x_{1} \\
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\end{array} \rightarrow_{\beta} u_{1}\left[t / x_{1}\right]
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$$

But:

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(t, u) \stackrel{?}{=} \text { match } t \text { with } \left\lvert\, \begin{aligned}
& \mathrm{L} x_{1} \rightarrow\left(\mathrm{~L} x_{1}, u\right) \\
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$\forall C[\square: A+B]$,

$$
\left.C[t: A+B]={ }_{\eta} \text { match } t \text { with } \left\lvert\, \begin{array}{l}
\mathrm{L} x_{1} \rightarrow C\left[\mathrm{~L} x_{1}\right] \\
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x_{2}
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Equivalence algorithm decidable (Neil Ghani, 1995).
Unicity?

## Unicity

A search process, enumerating distinct normal forms.

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We know about program equivalence.

Is there a proof or type system that characterizes distinct programs? No duplicates.

## the Graal of program equivalence

A type system for "normal forms" $\left(\Gamma \vdash_{n f} v: A\right)$ that is canonical: syntactically distinct $\Rightarrow$ semantically distinct complete: each STLC program is equivalent to a typable normal form

Unicity test by goal-directed search in this system.

$$
\Gamma \vdash_{\mathrm{nf}} ?: A
$$

Contribution: this, for simply-typed $\lambda$-calculus with sums.

## $\beta$-short (weak)- $\eta$-long does not cut it

$$
f:(X \rightarrow Y+Y), x: X \vdash ?: X
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$x$

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\end{array}\right. \\
& \text { match } f x \text { with }\left|\begin{array}{l|l}
\mathrm{L} y_{1} \rightarrow \text { match } f x \text { with } \\
\mathrm{R} y_{2} \rightarrow x
\end{array}\right| \begin{array}{l}
\mathrm{L} z_{1} \rightarrow x \\
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\mathrm{L} z_{1} \rightarrow x \\
\mathrm{R} z_{2} \rightarrow x \\
\mathrm{R} y_{2} \rightarrow x
\end{array}\right.
\end{array}
\end{aligned}
$$

In general: equivalent programs may differ by matching on the same subterm at different places.

Need to quotient over that.

## Intuition

Enforce sum elimination as early as possible.

During goal-directed search, we don't know yet which sums will be useful. (Type system: maximally-early introduction is a non-local criterion)

Cannot enforce early elimination of all useful subterms.

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Cannot enforce early elimination of all useful subterms.

Just eliminate all possible sums : saturation.

## Demo time

Implementation available:
https://gitlab.com/gasche/unique-inhabitant

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$\vdash$
?: X

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\text { let } z^{Y+Y}=f x \text { in ? : } X
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$\vdash$

$$
\begin{array}{l|l}
\text { let } z^{Y+Y}=f x \text { in match } z \text { with } & \begin{array}{l}
\mathrm{L} y_{1} Y \\
\mathrm{R} y_{2} Y \rightarrow ?: X
\end{array} \\
\mathrm{Y} \rightarrow: X
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f:(X \rightarrow Y+Y), x: X
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$\vdash$

| let $z^{Y+Y}=f x$ in match $z$ with | $\mathrm{L} y_{1}{ }^{Y} \rightarrow x$ <br> $\mathrm{R} y_{2}{ }^{Y} \rightarrow x$ |
| :--- | :--- |

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\end{array}
\end{array}
$$

Final result: zero, one or two (distinct) terms.

## Saturation

We alternate goal-directed (backward) search and (forward) saturation.
Saturation of $\Gamma$ : compute all possible neutral terms $\Gamma \vdash n: A+B$ and deconstruct (some of) them.

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freshness condition: neutrals typeable in a strictly smaller $\Gamma$ are old, don't deconstruct them again
$\Rightarrow$ canonicity
subformula property: the sums $(A+B)$ that appear in 「 suffice two-or-more property: at most two different neutrals of each type suffice
$\Rightarrow$ termination

## Conclusion

We build upon proof theory and logic programming - focusing (bidirectional typing, better).

Contribution: a focused saturating proof/type system, canonical and computationally complete for STLC with sums.
$\Rightarrow$ decidability of unique inhabitation
$\Rightarrow$ new insights on program equivalence (empty type?)

In the paper: other practical examples, detailed related work.

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Thanks. Any question?

