

Directed Algebraic Topology and Concurrency

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Theorem

Two **weakly dihomotopic** paths on the **geometric model** of a conservative program induce the same **action on valuations**. Moreover, if one of them is an **execution trace**, then so is the other.

Proof

By a standard result from general topology and the [Curryfication](#) of h , namely

$$\hat{h} : s \in [0, q] \mapsto (t \in [0, r] \mapsto h(t, s) \in X)$$

is a [continuous](#) path on $dX^{[0,r]}(p, p')$.

The image of \hat{h} is thus compact, so we cover it with open balls given by the main theorem of geometric models.

By the Lebesgue number theorem there exists a real number $\varepsilon > 0$ such that $|s - s'| \leq \varepsilon$ implies that $\hat{h}(s)$ and $\hat{h}(s')$ belong to the same open ball from the covering.

The conclusion follows considering the sequence

$$\hat{h}(0), \hat{h}(\varepsilon), \hat{h}(2\varepsilon), \hat{h}(3\varepsilon), \dots, \hat{h}(n\varepsilon), \hat{h}(q)$$

where n is the greatest natural number such that $n\varepsilon \leq q$.

Concatenation of homotopies

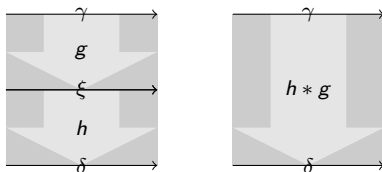
vertical composition

Let $g : [0, r] \times [0, q'] \rightarrow X$ and $h : [0, r] \times [0, q] \rightarrow X$ be homotopies from γ to ξ and from ξ to δ .

The mapping $h * g : [0, r] \times [0, q + q'] \rightarrow X$ defined by

$$h * g(t, s) = \begin{cases} g(t, s) & \text{if } 0 \leq s \leq q \\ h(t, s - q) & \text{if } q \leq s \leq q + q' \end{cases}$$

is a homotopy from γ to δ .



If g and h are (weakly) directed homotopies, then so is their concatenation $h * g$.

Homotopy and dihomotopy relations

An **anti-directed homotopy** from γ to δ is a homotopy of paths $h : [0, r] \times [0, q] \rightarrow X$ such that $(t, s) \mapsto h(t, q - s)$ is a directed homotopy from δ to γ .

An **elementary homotopy** between γ to δ is a homotopy of paths $h : [0, r] \times [0, q] \rightarrow X$ obtained as a finite concatenation of directed homotopies and anti-directed homotopies.

Two paths γ and γ' are said to be **homotopic** when there exists a **homotopy** between them. We have the equivalence relation \sim_h between paths on a topological space.

They are said to be **dihomotopic** when there exists an **elementary homotopy** between them. We have the equivalence relation \sim_d between directed paths on a locally ordered space.

They are said to be **weakly dihomotopic** when there exists a weakly directed homotopy between them. We have the equivalence relation \sim_w between directed paths on a locally ordered space.

An important remark

If h is a **homotopy** from γ to γ' on the topological space X and $f : X \rightarrow Y$ is a **continuous map**, then $f \circ h$ is a **homotopy** from $f \circ \gamma$ to $f \circ \gamma'$ on the topological space Y .

If h is a **(weakly) directed homotopy** from γ to γ' on the local pospace space X and $f : X \rightarrow Y$ is a **local pospace morphism**, then $f \circ h$ is a **(weakly) directed homotopy** from $f \circ \gamma$ to $f \circ \gamma'$ on the local pospace space Y .

If $\gamma, \gamma' : [0, r] \rightarrow X$ are ((weakly) di)homotopic, then so are $f \circ \gamma, f \circ \gamma' : [0, r] \rightarrow Y$.

Reparametrization

An increasing and surjective map $\theta : [0, r] \rightarrow [0, r]$ is called a **reparametrization**.

The mapping

$$h : (t, s) \in [0, r] \times [0, 1] \mapsto \theta(t) + s \cdot (\max(t, \theta(t)) - \theta(t)) \in [0, r]$$

is a directed homotopy from θ to $\max(\text{id}_{[0, r]}, \theta)$.

If $\gamma : [0, r] \rightarrow X$ is a directed path on the local pospace X , then $\gamma \circ h$ is a directed homotopy from $\gamma \circ \theta$ to $\gamma \circ \max(\text{id}_{[0, r]}, \theta)$

Therefore γ and $\gamma \circ \theta$ are dihomotopic.

Images of directed paths on a pospace

Theorem

The image of a nonconstant directed path on a pospace is isomorphic to $[0, 1]$.

Corollary

Two directed paths on a pospace having the same image are dihomotopic.

proof:

Suppose that $\text{im}(\gamma) = \text{im}(\gamma')$.

$\phi : [0, r] \rightarrow \text{im}(\gamma)$ a pospace isomorphism.

$\phi^{-1} \circ \gamma$ and $\phi^{-1} \circ \gamma'$ are reparametrization.

We have h an elementary homotopy from $\phi^{-1} \circ \gamma$ to $\phi^{-1} \circ \gamma'$.

Hence $\phi \circ h$ is an elementary homotopy from γ and γ' .

Programs with mutex only

a result by É. Goubault and S. Mimram

Let X be the geometric model of a conservative program whose semaphores have arity 1 (mutex), then two directed paths on X are dihomotopic **if and only if** they are homotopic.

Compatible programs

Two programs P and Q are said to be **compatible** when their initial valuations and their arity maps coincide on the intersection of their domains of definition. In that case we define the **parallel composition** $P|Q$.

By extension we define the parallel composition of P_1, \dots, P_N when the programs are **pairwise compatible**.

Two programs are said to be **syntactically independent** when the set of resources they use are disjoint:

- they have no variables in common,
- they have no semaphores in common, and
- they have no barriers in common.

Syntactically independent programs are compatible.

Syntactical independence can be decided **statically** but it is too **restrictive**.

Model Independence

Suppose the programs P_1, \dots, P_N are **conservative**.

The programs P_1, \dots, P_N are said to be **model independent** when

$$\llbracket P_1 | \dots | P_N \rrbracket = \llbracket P_1 \rrbracket \times \dots \times \llbracket P_N \rrbracket$$

Model independence can be decided **statically**.

The class of geometric models satisfies a **unique decomposition property**.

Compatible permutations

Suppose that the programs P_1, \dots, P_N are compatible and that P_j has n_j running processes.

The identifiers of the running processes of $P_1 | \dots | P_N$ are the elements of $\{1, \dots, n\}$ with

$$n = \sum_{j=1}^N n_j$$

Assume we have a partition

$$\{1, \dots, n\} = S_1 \sqcup \dots \sqcup S_N$$

Two multi-instructions μ and μ' ($\text{dom}(\mu), \text{dom}(\mu') \subseteq \{1, \dots, n\}$) can be **swapped** when

$$\{j \in \{1, \dots, N\} \mid S_j \cap \text{dom}(\mu) \neq \emptyset\} \cap \{j \in \{1, \dots, N\} \mid S_j \cap \text{dom}(\mu') \neq \emptyset\} = \emptyset$$

A permutation π of the set $\{0, \dots, q-1\}$ is said to be **compatible** with the sequence of multi-instructions μ_0, \dots, μ_{q-1} when it is order preserving on all pairs $\{k, k'\}$ such that μ_k and $\mu_{k'}$ cannot be swapped.

The permutation π is said to be **compatible** with the directed path γ when it is compatible with its associated sequence of multi-instructions.

Observational independence

related to partial order reduction (?)

The programs P_1, \dots, P_N are said to be **observationally independent** when:

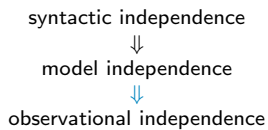
- for all execution traces γ
- for all permutations π compatible with the sequence of multi-instructions $(\mu_0 \cdots \mu_{q-1})$ associated with γ ,

the sequence $\pi \cdot (\mu_0 \cdots \mu_{q-1})$ is associated with an execution trace γ' having the same action on the system state than γ , that is to say

$$\sigma \cdot (\mu_0 \cdots \mu_{q-1}) = \sigma \cdot (\mu_{\pi^{-1}(0)} \cdots \mu_{\pi^{-1}(q-1)}) .$$

Observational independence cannot be decided **statically**, moreover it is too **loose**.

Main theorem



One-dimensional regions

Let G be a **finite** graph, the collection $\mathcal{R}_1 G$ of all **finite unions of connected subsets** of $|G|$ forms a **Boolean subalgebra** of $\text{Pow}(|G|)$.

Moreover

$$\mathcal{R}_1 G \cong \text{Pow}(V) \times (\mathcal{R}_1]0, 1[)^{\text{card}A}$$

with A (resp. V) being the set of arrows (resp. vertices) of G , and $\mathcal{R}_1]0, 1[$ being the Boolean algebra of finite unions of subintervals of $]0, 1[$.

The elements of $\mathcal{R}_1 G$ are seen as **one-dimensional blocks**.

Proof: If X is a connected subset of $|G|$ then for all arrows $\alpha \in G$, $X \cap (\{\alpha\} \times]0, 1[)$ has at most two connected components.

The finiteness condition is not necessary e.g.

$$\cdots \rightarrow \cdot \rightarrow \cdot \rightarrow \cdot \rightarrow \cdot \rightarrow \cdot \rightarrow \cdot \rightarrow \cdot \rightarrow \cdot \rightarrow \cdot \rightarrow \cdots$$

Yet some infinite graphs may not enjoy the property e.g. when G is a graph with a single vertex and infinitely many arrows.

Higher dimensional blocks

- A **block** of dimension $n \in \mathbb{N}$, or **n -block**, is the product of n connected subsets of the metric graph $|G|$.
- A collection of blocks is called a **block covering** of $X \subseteq |G|^n$ when the union of its elements is X .
- The collection of n -dimensional block coverings is denoted by $\text{Cov}_n G$, it is preordered by

$$C \preceq C' \quad \equiv \quad \forall b \in C \exists b' \in C', b \subseteq b'$$

Maximal blocks

- A block contained in X is said to be a block of X . Such a block is said to be **maximal** when no block of X strictly contains it.
- The **maximal block covering** of $X \subseteq |G|^n$ is the set of all its maximal blocks, it is denoted by $\alpha_n(X)$.
- $\alpha_n(X) = \emptyset$ if and only if $X = \emptyset$.

A Galois connection

We have a Galois connection (γ_n, α_n) between $\text{Cov}_n G$ and $\text{Pow}(|G|^n)$ with $\gamma_n(D) = \bigcup D$ for all $D \in \text{Cov}_n G$.

$$\text{Cov}_n G \begin{array}{c} \xrightarrow{\gamma_n} \\ \xleftarrow{\alpha_n} \end{array} \text{Pow}(|G|^n)$$

In particular $\gamma_n \circ \alpha_n = id$ and $id \preceq \alpha_n \circ \gamma_n$. That Galois connection induces an **isomorphism of Boolean algebras** between $\text{Pow}(|G|^n)$ and the image of α_n i.e. the collection of maximal block coverings.

Proof: any block is contained in a maximal block (by the Hausdorff maximal principle).

$$\bigcup_i \uparrow (B_1^{(i)} \times \dots \times B_n^{(i)}) = \left(\bigcup_i \uparrow B_1^{(i)} \right) \times \dots \times \left(\bigcup_i \uparrow B_n^{(i)} \right)$$

Isothetic regions

- An **isothetic region** of dimension n is a subset of $|G|^n$ that admits a **finite** block covering.
- **The geometric model of a conservative program is an isothetic region.**
- The collection of isothetic regions of dimension n is denoted by $\mathcal{R}_n G$.
- The collection of **finite** block covering of dimension n is denoted by $\text{Cov}_{nf} G$.

The previous Galois connection

restricted to isothetic regions

Suppose that the graph G is finite. The collection of n -dimensional isothetic regions $\mathcal{R}_n G$ forms a Boolean subalgebra of $\text{Pow}(|G|^n)$ and the previous Galois connection restricts to a Galois connection between $\text{Cov}_{nf} G$ and $\mathcal{R}_n G$, which induces an **isomorphism of Boolean algebras** between $\mathcal{R}_n G$ and the image of α_n i.e. the collection of finite maximal block coverings.

$$\text{Cov}_{nf} G \begin{array}{c} \xrightarrow{\gamma_n} \\ \xleftarrow{\alpha_n} \end{array} \mathcal{R}_n G$$

A subset $X \subseteq |G|^n$ is an isothetic region iff the collection of maximal subblocks of X is finite and covers X .

The complement of a block is an isothetic region

If X is 1-dimensional then its maximal blocks are its connected components. The complement of a block $B = B_1 \times \cdots \times B_n$ can be written as

$$B^c = \bigcup_{k=1}^n |G| \times \cdots \times B_k^c \times \cdots \times |G|$$

Its maximal blocks are found among that of B^c therefore they have the form

$$D_1 \times \cdots \times D_{k-1} \times C_k \times D_{k+1} \times \cdots \times D_n$$

with $k \in \{1, \dots, n\}$, C_k ranging through the connected components of B_k^c and D_j , for $j \neq k$, ranging through the connected components of $|G|$.

Intersection of two isothetic regions

The intersection of the blocks B and B' is given by

$$B \cap B' = (B_1 \cap B'_1) \times \cdots \times (B_n \cap B'_n)$$

The maximal blocks of $B \cap B'$ are therefore of the form

$$C_1 \times \cdots \times C_n$$

with each C_k ranging through the connected components of $(B_k \cap B'_k)$.

It follows from De Morgan's laws that the intersection of two regions is still a region.

Moreover if \mathcal{B} and \mathcal{B}' are block coverings of X and X' **containing all their maximal blocks**, then the union of the collections of maximal blocks of $B \cap B'$ for $B \in \mathcal{B}$ and $B' \in \mathcal{B}'$ is a block covering of $X \cap X'$ **containing all its maximal blocks**.

Concluding the proof

If \mathcal{F} is any finite block covering of X , then

$$X^c = \bigcap_{B \in \mathcal{F}} B^c$$

- The collection of maximal blocks of B^c is finite and covers B^c .
- The maximal blocks of X^c are obtained as certain finite intersection of the form

$$\bigcap \{M_B \mid B \in \mathcal{F}\}$$

where M_B is a maximal block of B^c .

- The maximal blocks of X^c thus form a finite block covering of X^c .

A result from directed topology

For all directed paths γ on $\downarrow G \downarrow^n$ and all $X \in \mathcal{R}_n G$, the inverse image of X by γ has **finitely** many connected components.

Closure, interior, and boundary of an isothetic region

The closure operator preserves finite products, therefore it preserves blocks.

The **closure operator** preserves finite unions hence it **preserves isothetic regions**.

The **boundary** of a set is the intersection of its closure and the closure of its complement, hence it also **preserves isothetic regions**.

The **interior** of a set is the difference between its closure and its boundary. It follows that the interior operator also **preserves isothetic regions**.

The forward and the backward operators

Let A, B be subsets of a local pospace X .

- The **forward** and the **backward** operators are defined as

$$\text{frw}(A, B) = \{\partial^+ \delta \mid \delta \text{ directed path on } X; \partial \delta \in A; \text{im}(\delta) \subseteq A \cup B\}$$

$$\text{bck}(A, B) = \{\partial \delta \mid \delta \text{ directed path on } X; \partial^+ \delta \in A; \text{im}(\delta) \subseteq A \cup B\}$$

- The **future cone** of A in X is $\text{cone}^f A := \text{frw}(A, X)$ and the **past cone** of A in X is $\text{cone}^p A := \text{bck}(A, X)$.
- The **future closure** of A in X is $\overline{A}^f := \text{frw}(A, \overline{A})$ and the **past closure** of A in X is $\overline{A}^p := \text{bck}(A, \overline{A})$.
The closure \overline{A} being understood in X .

Theorem: if A, B , and X are isothetic regions, then so are $\text{frw}(A, B)$, $\text{cone}^f A$, \overline{A}^f , and their duals.

Future/past stable subsets of X

let A be a subset of a local pospace X .

- $\text{cone}^f \text{cone}^f A = \text{cone}^f A$ and $\text{cone}^p \text{cone}^p A = \text{cone}^p A$
- A is said to be future (resp. past) stable (in X) when $\text{cone}^f A = A$ (resp. $\text{cone}^p A = A$)
- A is future stable iff $X \setminus A$ is past stable
- The collection of future stable subsets of X is a complete lattice, the greatest lower (resp. least upper) bound of a family being given by its intersection (resp. union).
- The same holds for past stable subsets.

Past/future attractors

Let A be a subset of a local pospace X .

$$\text{cone}^p A = \{p \in X \text{ from which } A \text{ can be reached}\} = \text{bck}(A, X)$$

$$\text{escape}^f A = \{p \in X \text{ from which } A \text{ cannot be reached}\}$$

$$\text{escape}^f A = (\text{cone}^p A)^c$$

$$\text{att}^p A = \{p \in X \text{ from which } A \text{ cannot be avoided}\}$$

$$\text{att}^p A = \text{escape}^f(\text{escape}^f A)$$

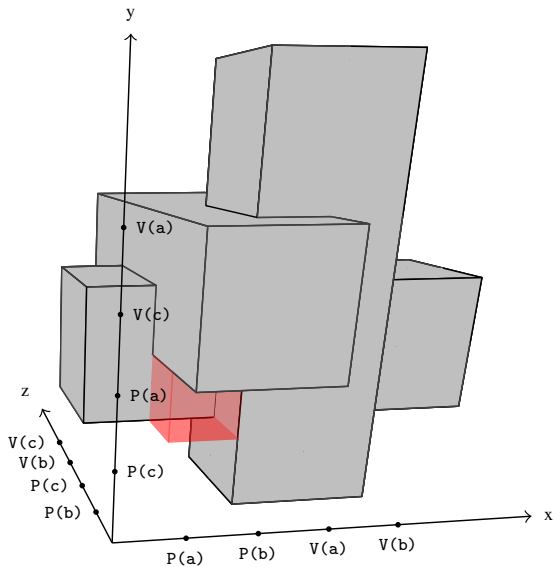
The deadlock attractor of a conservative program

Let G_1, \dots, G_n be the running processes of a conservative program P .

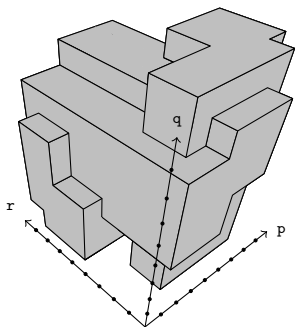
Let $\llbracket P \rrbracket$ be the geometric model of the program.

- The **reachable** space of $\llbracket P \rrbracket$ is the future cone of the initial point
- A point $p \in \llbracket G_i \rrbracket$ is said to be **terminal** when $\llbracket \gamma \rrbracket$ is empty for all directed paths on $\llbracket G_i \rrbracket$ starting at p .
- A point $p \in \llbracket P \rrbracket$ is said to be **terminal** when so are all its projections
- The terminal points form a future stable isothetic region of $\llbracket P \rrbracket$
- A point $p \in \llbracket P \rrbracket$ is said to be **deadlock** when its future cone neither contains directed loops (i.e. it is **loop-free**) nor terminal points.
- The deadlock points form a future stable isothetic region of $\llbracket P \rrbracket$
- The **deadlock attractor** of the program is the past attractor of its deadlock region.

Three dining philosophers



The Lipski algorithm



```
sem 1:  u v w x y z
```

```
proc:
```

```
  p = P(x);P(y);P(z);V(x);P(w);V(z);V(y);V(w)
```

```
  q = P(u);P(v);P(x);V(u);P(z);V(v);V(x);V(z)
```

```
  r = P(y);P(w);V(y);P(u);V(w);P(v);V(u);V(v)
```

```
init:  p q r
```


Commutative monoids

- $(M, *, \varepsilon)$ such that for all $a, b, c \in M$,
 - $(ab)c = a(bc)$
 - $\varepsilon a = a = a\varepsilon$
 - $ab = ba$
- For all set X the collection MX of **multisets** over X
 i.e. maps $\phi : X \rightarrow \mathbb{N}$ s.t. $\{x \in X \mid \phi(x) \neq 0\}$ is finite
 forms a commutative monoid with pointwise addition
- A commutative monoid is said to be **free** when
 it is isomorphic with some MX
- Functor $M : Set \rightarrow Cmon$

- A multiset ϕ can be written as

$$\sum_{x \in X} \phi(x)x$$

- In particular, if $f : X \rightarrow Y$ is a set map, then

$$M(f)(\phi) = \sum_{x \in X} \phi(x)f(x)$$

Prime vs irreducible

- d divides x , denoted by $d|x$, when there exists x' such that $x = dx'$
- u unit: exists u' s.t. $uu' = \varepsilon$ then write $x \sim y$ when $y = ux$ for some unit u
- i irreducible: i nonunit and $x|i$ implies $x \sim i$ or x unit
- p prime: p nonunit and $p|ab$ implies $p|a$ or $p|b$
- If M contains nontrivial units, then one can consider the quotient monoid M/\sim where $x \sim y$ stands for: there exists a unit u s.t. $y = ux$

Examples

monoid	irreducibles	primes	units
$\mathbb{N} \setminus \{0\}, \times, 1$	{prime numbers}		{1}
$\mathbb{N}, +, 0$	{1}		{0}
$\mathbb{R}_+, +, 0$	\emptyset		{0}
$\mathbb{R}_+, \vee, 0$	\emptyset	$\mathbb{R}_+ \setminus \{0\}$	{0}
$\mathbb{Z}_6, \times, 1$	\emptyset	{0, 2, 3, 4}	{1, 5}

Graded commutative monoid

- $(M, *, \varepsilon)$ **graded**: there is a morphism $g : (M, *, \varepsilon) \rightarrow (\mathbb{N}, +, 0)$
s.t. $g^{-1}(\{0\}) = \{\text{units of } M\}$
- If M is graded then
 - $\{\text{irreducibles of } M\}$ generates M
 - $\{\text{primes of } M\} \subseteq \{\text{irreducibles of } M\}$

Irreducible that are not prime

$$M = (\{a + b\sqrt{10} \mid a, b \in \mathbb{Z}; a \neq 0 \text{ or } b \neq 0\}, \times, 1)$$

- $N : M \rightarrow (\mathbb{Z} \setminus \{0\}, \times, 1)$; $N(a + b\sqrt{10}) = a^2 - 10b^2$
 $N(uv) = N(u)N(v)$
 u unit iff $N(u) \in \{\pm 1\}$
 $N(a + b\sqrt{10}) \bmod 10 \in \{1, 4, 5, 6, 9\}$
 therefore $N(a + b\sqrt{10}) \notin \{\pm 2, \pm 3\}$

uv	$N(uv)$	$N(u)$
2	4	$\pm 1, \pm 2, \pm 4$
3	9	$\pm 1, \pm 3, \pm 9$
$4 \pm \sqrt{10}$	6	$\pm 1, \pm 2, \pm 3, \pm 6$

- 2, 3, and $4 \pm \sqrt{10}$ are irreducible but not prime
 since $2 \cdot 3 = (4 + \sqrt{10}) \cdot (4 - \sqrt{10})$
- $\{a + b\sqrt{10} \mid a, b \in \mathbb{Z}\} \setminus \{0\}$ is graded by the number of prime factors of $N(u)$

$\mathbb{N}[X]$ polynomials with coefficients in \mathbb{N}

On Direct Product Decomposition of Partially Ordered Sets. Junji Hashimoto

Annals of Mathematics 2(54), pp 315-318 (1951)

$$X^5 + X^4 + X^3 + X^2 + X + 1 =$$

$$\begin{cases} (X + 1)(X^4 + X^2 + 1) = (X^3 + 1)(X^2 + X + 1) & \text{in } \mathbb{N}[X] \\ (X + 1)(X^2 + X + 1)(X^2 - X + 1) & \text{in } \mathbb{Z}[X] \end{cases}$$

- therefore $X + 1$, $X^2 + X + 1$, $X^3 + 1$, and $X^4 + X^2 + 1$ are **irreducible** but **not prime**
- $\mathbb{N}[X] \setminus \{0\}$ is graded by the degree

Characterization of the free commutative monoids

Unique factorization

- The following are equivalent:
 - M is free commutative
 - any element of M can be written as a product of irreducibles in a unique way up to reordering
 - $\{\text{primes of } M\} = \{\text{irreducibles of } M\}$ and generates M
 - M is graded and $\{\text{irreducibles of } M\} \subseteq \{\text{primes of } M\}$
- Standard examples:
 - $(\mathbb{N} \setminus \{0\}, \times, 1)$
 - $(\mathbb{N}, +, 0)$ and its finite products in the category of commutative monoids.
Indeed $(\mathbb{N}, +, 0)^n \cong M(\{1, \dots, n\})$
 - $(\mathbb{Z}[X] \setminus \{0\}, \times, 1)$ (if F is a factorial ring, then so is $F[X]$)
Algebra, Serge Lang. Springer (2002)
 - Note that two free commutative monoids are isomorphic in $\mathcal{C}mon$ iff their set of prime elements have the same cardinality
e.g. $(\mathbb{N} \setminus \{0\}, \times, 1) \cong (\mathbb{Z}[X] \setminus \{0\}, \times, 1)$ in $\mathcal{C}mon$

Connected sum of manifolds

A less common example

In differential geometry, the compact, connected, oriented, smooth n -dimensional manifolds without boundary equipped with the connected sum $\#$ form a commutative monoid \mathcal{M}_n whose neutral element is the n -sphere.

tom Dieck, T. Algebraic Topology. European Mathematical Society 2008. p.390

\mathcal{M}_2 is freely generated by the torus T^2 .

Massey, W.S. A Basic Course in Algebraic Topology. Springer 1991. Chapter 1.

\mathcal{M}_3 is freely generated by countably many elements.

Hempel, J. 3-Manifolds. American Mathematical Society 1976. Chapter 3.

Jaco, W. Lectures on Three-Manifold Topology. American Mathematical Society 1980. Chapter 2.

- existence of the decomposition is due to Hellmuth Kneser (1929)
Kneser, H. Geschlossene Flächen in dreidimensionalen Mannigfaltigkeiten.
Jahresbericht der Deutschen Mathematiker-Vereinigung 38:248259 1929.
- uniqueness of the decomposition is due to John W. Milnor (1962)
Milnor, J. A Unique Decomposition Theorem for 3-Manifolds.
American Journal of Mathematics 84(1):17 1962.

In particular $\mathcal{M}_2 \cong (\mathbb{N}, +, 0)$ and $\mathcal{M}_3 \cong (\mathbb{N} \setminus \{0\}, \times, 1)$

The noncommutative monoid of languages

- \mathbb{A}^* (non commutative) monoid of words on the alphabet \mathbb{A} .
Let ε denotes the empty word
- A language is a set of words on \mathbb{A} . Let D and D' be languages
 - define $D \cdot D' := \{w \cdot w' \mid w \in D; w' \in D'\}$
 - one has $\emptyset \cdot D = D \cdot \emptyset = \emptyset$ and $\{\varepsilon\} \cdot D = D \cdot \{\varepsilon\} = D$
 - The monoid of **nonempty** languages is $\mathcal{D}(\mathbb{A})$
 - $\mathcal{D}(\mathbb{A})$ is commutative iff $\text{Card}(\mathbb{A}) \leq 1$. Note that $\mathcal{D}(\emptyset) \cong \{0\}$
 - however $\mathcal{D}(\{a\})$ is not free commutative

The noncommutative monoid of homogeneous languages

- $H \in \mathcal{D}(\mathbb{A})$ is homogeneous when all the words in H have the same length
- Define $\dim(H)$ as the length common to all the words of H .
It is well defined since H is nonempty.
- $H \cdot H' = \{w \cdot w' \mid w \in H ; w' \in H'\}$ is homogeneous iff so are H and H'
- $\mathcal{D}_h(\mathbb{A}) \subseteq \mathcal{D}(\mathbb{A})$ the submonoid of homogeneous languages.
- $H \in \mathcal{D}_h(\mathbb{A}) \mapsto \dim(H) \in (\mathbb{N}, +, 0)$ is a morphism of monoid
- $\dim(H) = 0$ iff $H = \{\varepsilon\}$
- $\mathcal{D}_h(\mathbb{A})$ is commutative iff $\text{Card}(\mathbb{A}) \leq 1$
- $\mathcal{D}_h(\{a\}) \cong (\mathbb{N}, +, 0)$

Action of the symmetric groups

on the left of the homogeneous languages

- The n^{th} symmetric group \mathfrak{S}_n acts on the left of the set of words of length n i.e. mappings from $\{1, \dots, n\}$ to \mathbb{A} , by $\sigma \cdot \omega := \omega \circ \sigma^{-1}$
- Then \mathfrak{S}_n acts on the left of the homogeneous languages of dimension n
- Write $H \sim H'$ when $\dim(H) = \dim(H')$ and $H' = \sigma \cdot H$ for some $\sigma \in \mathfrak{S}_{\dim(H)}$
- If $\sigma \in \mathfrak{S}_n$ and $\sigma' \in \mathfrak{S}_{n'}$ then define $\sigma \otimes \sigma' \in \mathfrak{S}_{n+n'}$ as:

$$\sigma \otimes \sigma'(k) := \begin{cases} \sigma(k) & \text{if } 1 \leq k \leq n \\ (\sigma'(k-n)) + n & \text{if } n+1 \leq k \leq n+n' \end{cases}$$

- A Godement exchange law is satisfied, which ensures that \sim is actually a congruence:

$$(\sigma \cdot H) \cdot (\sigma' \cdot H') = (\sigma \otimes \sigma') \cdot (H \cdot H')$$

i.e. $H \sim K$ and $H' \sim K'$ implies $HH' \sim KK'$

The commutative monoid of homogeneous languages

- The commutative monoid of homogeneous languages is $\mathcal{H}(\mathbb{A}) = (\mathcal{D}_h(\mathbb{A}), \cdot, \{\varepsilon\}) / \sim$
- The monoid $\mathcal{H}(\mathbb{A})$ is graded by $H \in \mathcal{H}(\mathbb{A}) \mapsto \dim(H) \in (\mathbb{N}, +, 0)$

The commutative monoid $\mathcal{H}(\mathbb{A})$ is free

- For any homogeneous language H and $\sigma \in \mathfrak{S}_{\dim(H)}$, $\text{card}(H) = \text{card}(\sigma \cdot H)$ so we can define the cardinality of any element of $\mathcal{H}(\mathbb{A})$

The commutative monoid of finite homogeneous languages

- $M' \subseteq M$ is said to be **pure** when for all $x, y \in M$, $xy \in M'$ implies $x, y \in M'$
- A pure submonoid of a free commutative monoid is free
- The submonoid $\mathcal{H}_f(\mathbb{A}) \subseteq \mathcal{H}(\mathbb{A})$ of finite languages is pure, therefore it is free
- $H \in \mathcal{H}_f(\mathbb{A}) \mapsto \text{Card}(H) \in (\mathbb{N} \setminus \{0\}, \times, 1)$ is a morphism of monoid
- The primality of $\text{Card}(H)$ does not imply that of H
e.g. $H = \{ab, ac\} = \{a\} \cdot \{b, c\}$ though $\text{card}(H) = 2$
- The primality of H does not imply that of $\text{Card}(H)$
e.g. $H = \{a, b, c, d\}$ is prime though $\text{card}(H) = 4$

The brute force algorithm for factoring in $\mathcal{H}_f(\mathbb{A})$

Theory

Given $w \in \mathbb{A}^n$ and $I \subseteq \{1, \dots, n\}$, we write $w|_I$ for the subword of w consisting of letters with indices in I .

Given a homogeneous language H of dimension n , we write

$$H|_I = \{w|_I \mid w \in H\}$$

Denoting I^c for $\{1, \dots, n\} \setminus I$, we have

$$[H] = [H|_I] \cdot [H|_{I^c}]$$

in $\mathcal{H}_f(\mathbb{A})$ **if and only if** for all words $u, v \in H$ there exists a word $w \in H$ such that

$$w|_I = u|_I \quad \text{and} \quad w|_{I^c} = v|_{I^c}$$

The brute force algorithm for factoring in $\mathcal{H}_f(\mathbb{A})$

Practice

For $I \subseteq \{1, \dots, n\}$ let $\pi_{|I}$ be the “projection” that sends $w \in H$ to $w_{|I} \in \mathbb{A}^{\text{card}(I)}$.

1. choose $I \subseteq \{1, \dots, n\}$ of cardinality $k \leq n/2$
2. if $\pi_{|I^c}(\pi_{|I}^{-1}(u))$ does not depend on $u \in H_{|I}$, then we have the factorization

$$[H] = [H_{|I}] \cdot [H_{|I^c}]$$

and we are done

3. otherwise check whether there are still subsets of $\{1, \dots, n\}$ to check:
 - 3.1. yes: go to step 1
 - 3.2. no: $[H]$ is prime

The preorder \preceq over $\mathcal{H}(\mathbb{A})$

inherited from a preorder \preceq over \mathbb{A}

- Let \preceq^n by the product preorder on the words of length n
- Given $H, H' \in \mathcal{D}_h(\mathbb{A})$ of the same dimension n , write $H \preceq H'$ when for all $\omega \in H$ there exists $\omega' \in H'$ such that $\omega \preceq^n \omega'$
- Given $X, X' \in \mathcal{H}(\mathbb{A})$ of the same dimension n write $X \preceq X'$ when there exist $H \in X$ and $H' \in X'$ such that $H \preceq H'$
- $X \preceq Y$ and $X' \preceq Y'$ implies $X \cdot X' \preceq Y \cdot Y'$
i.e. $(\mathcal{H}(\mathbb{A}), \preceq)$ is a preordered commutative monoid
- If \preceq is actually a partial order on \mathbb{A} , then so is \preceq on $\mathcal{H}(\mathbb{A})$
- If \preceq is the equality relation, then $X \preceq Y$ amounts to $H_X \subseteq H_Y$ for some representatives H_X and H_Y of X and Y .

Homogeneous dictionaries

over the alphabets $|G|$ and $\mathcal{R}_1 G \setminus \{\emptyset\}$ with G being a finite graph

- $\mathbb{A} = |G|$ is the geometric realization of a finite graph:
 - a point of $|G|^n$ can be seen as a word of length n on \mathbb{A}
 - a nonempty subset of $|G|^n$ is thus a homogeneous dictionary on \mathbb{A}
 - the product of the monoid $\mathcal{D}_h(\mathbb{A})$ corresponds to the cartesian product of isothetic regions
- $\mathbb{A} = \mathcal{R}_1 G \setminus \{\emptyset\}$ is the collection of **nonempty** finite unions of connected subsets of $|G|$:
 - an n -block is an n -fold product of nonempty elements of $\mathcal{R}_1 G$
i.e. a word of length n on \mathbb{A}
 - a nonempty family of n -blocks is thus an homogeneous dictionary on \mathbb{A} (of dimension n)
 - the concatenation of words on \mathbb{A} corresponds to the cartesian product of blocks

The canonical morphism of monoids

$$\gamma : \mathcal{H}(\mathcal{R}_1 G \setminus \{\emptyset\}) \rightarrow \mathcal{H}(\lfloor G \rfloor)$$

- Let γ be the map sending an homogeneous dictionary on $\mathcal{R}_1 G \setminus \{\emptyset\}$ to the union of its elements
 - γ is a morphism of monoids from $\mathcal{D}_h(\mathcal{R}_1 G \setminus \{\emptyset\})$ to $\mathcal{D}_h(\lfloor G \rfloor)$
 - γ is compatible with the action of the symmetric groups in the sense that

$$H' = \sigma \cdot H \Rightarrow \bigcup H' = \sigma \cdot (\bigcup H)$$
 - γ induces a morphism of monoids from $\mathcal{H}(\mathcal{R}_1 G \setminus \{\emptyset\})$ to $\mathcal{H}(\lfloor G \rfloor)$
- The induced morphism γ does not preserve the prime elements e.g. consider a covering of $[0, 1]^2$ with 3 distinct rectangles

The canonical morphism of monoids

$$\alpha : \mathcal{H}(\downarrow G \downarrow) \rightarrow \mathcal{H}(\mathcal{R}_1 G \setminus \{\emptyset\})$$

- Define $\alpha(X)$ as the collection of maximal blocks of X :
 - given $X, Y \subseteq \downarrow G \downarrow^n$, the collection of maximal blocks of $X \times Y$ is $\{C \times D \mid C \text{ and } D \text{ are maximal blocks of } X \text{ and } Y\}$
 - the unique maximal block of the unique nonempty subset of $\downarrow G \downarrow^0$ is ε
 - α is a morphism of monoids from $\mathcal{D}_h(\downarrow G \downarrow)$ to $\mathcal{D}_h(\mathcal{R}_1 G \setminus \{\emptyset\})$
 - if C is a maximal block of $X \subseteq \downarrow G \downarrow^n$ then $\sigma \cdot C$ is a maximal block of $\sigma \cdot X$.
 - α induces a morphism of monoids from $\mathcal{H}(\downarrow G \downarrow)$ to $\mathcal{H}(\mathcal{R}_1 G \setminus \{\emptyset\})$
 - $\text{im}(\alpha)$ is a submonoid of $\mathcal{H}(\mathcal{R}_1 G \setminus \{\emptyset\})$
- the morphisms γ and α induce isomorphisms of ordered monoids between $\text{im}(\alpha)$ and $\mathcal{H}(\downarrow G \downarrow)$, the order relation being inherited from inclusion over $\mathcal{R}_1 G \setminus \{\emptyset\}$ and equality over $\downarrow G \downarrow$.
- therefore $\text{im}(\alpha)$ is commutative free

The free commutative monoids of isothetic regions

- By definition, an isothetic region is a finite union of blocks of $X \subseteq \downarrow G \downarrow^n$.
- We have seen that an isothetic region has finitely many maximal blocks .
- For $X, Y \in \mathcal{H}(\downarrow G \downarrow)$, $\alpha(X \cdot Y)$ is finite iff $\alpha(X)$ and $\alpha(Y)$ are so:
 - then $\{X \in \text{im}(\alpha) \mid \text{card}(X) \text{ is finite}\}$ is a pure submonoid of $\text{im}(\alpha)$
 - this commutative monoid is thus free and isomorphic to the monoid of isothetic regions, the latter being defined as

$$\gamma(\{X \in \text{im}(\alpha) \mid \text{card}(X) \text{ is finite}\})$$

- The monoid of isothetic regions is thus free commutative.

A better factoring algorithm

by Nicolas Ninin

Let $X \subseteq |G|^n$ be an isothetic region and \mathcal{F} be a finite block covering of X^c

- For each $(\omega_1, \dots, \omega_n) \in \mathcal{F}$ define the word $(\beta_1, \dots, \beta_n)$ over $\{0, 1\}$ as follows:
for all $k \in \{1, \dots, n\}$
 - $\beta_k = 0$ if $\omega_k = |G|$;
 - $\beta_k = 1$ otherwise.
- Denote by \sim the equivalence relation generated by $\beta \sim \beta'$ when $\beta \wedge \beta'$ is not identically null.
- For each \sim -equivalence class \mathcal{E} denotes $\bigvee \mathcal{E}$ by $\beta_{\mathcal{E}}$
- Then the subsets $\beta_{\mathcal{E}}^{-1}(\{1\})$ with \mathcal{E} ranging through the \sim -classes provides a partition of $\{1, \dots, n\}$ which is a factorization of X .

if $\mathcal{F} = \alpha(X^c)$ then we obtain the prime factorization of X