Separating Functional Computation from Relations

Ulysse Gérard and Dale Miller

Inria Saclay & LIX/École Polytechnique, Palaiseau, France

Abstract
The logical foundation of arithmetic generally starts with a quantificational logic over relations. Of course, one often wishes to have a formal treatment of functions within this setting. Both Hilbert and Church added choice operators (such as the epsilon operator) to logic in order to coerce relations that happen to encode functions into actual functions. Others have extended the term language with confluent term rewriting in order to encode functional computation as rewriting to a normal form. We take a different approach that does not extend the underlying logic with either choice principles or with an equality theory. Instead, we use the familiar two-phase construction of focused proofs and capture functional computation entirely within one of these phases. As a result, our logic remains purely relational even when it is computing functions.

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1 Introduction
The development of the logical foundations of arithmetic generally starts with the first-order logic of relations to which constructors for zero and successor have been added. Various axioms (such as Peano’s axioms) are then added to that framework in order to define the natural numbers and various relations among them. Of course, it is often natural to think of some computations, such as say, the addition and multiplication of natural numbers, as being functions instead of relations.

A common way to introduce functions into the relational setting is to enhance the equality theory. For example, Troelstra in [32, Section I.3] presents an intuitionistic theory of arithmetic in which all primitive recursive functions are treated as black boxes and every one of their instances, for example $23 + 756 = 779$, is simply added as an equation. A modern and more structured version of this approach is that of the $\lambda\Pi$-calculus modulo framework proposed by Cousineau & Dowek [10]: in that framework, the dependently typed $\lambda$-calculus (a presentation of intuitionistic predicate logic) is extended with a rich set of terms and rewriting rules on them. When rewriting is confluent, it can be given a functional programming implementation: the Dedukti proof checker [3] is based on this hybrid approach to treating functions in a relational setting.

A predicate can, of course, encode a function. For example, assume that we have a $n + 1$-ary ($n \geq 0$) predicate $R$ for which we can prove that the first $n$ arguments uniquely determine the value of its last argument. That is, assume that the following formula is provable (here, $\bar{x}$ denotes the list of variables $x_1, \ldots, x_n$):

$$\forall \bar{x}([\exists y.R(\bar{x}, y)] \land \forall y\exists z[R(\bar{x}, y) \supset R(\bar{x}, z) \supset y = z]).$$
In this situation, an $n$-ary function $f_R$ exists such that $f_R(\bar{x}) = y$ if and only if $R(\bar{x}, y)$. In order to formally describe the function $f_R$, Hilbert [23] and Church [9] evoked choice operators such as $\epsilon$ and $\iota$ which (along with appropriate axioms) are able to take a singleton set and return the unique element in that set. For example, in Church’s Simple Theory of Types [9], the expression $\lambda x_1 \ldots \lambda x_n \iota(\lambda y. R(x_1, \ldots, x_n, y))$ provides a definition of $f_R$.

In this paper, we take a different approach to separating functional computations from more general reasoning with relations. We shall not extend the equational theory beyond the minimal equality on terms and we shall not use choice principles.

Although our approach to separating functions from relations is novel, it does not need any new theoretical results: we simply make direct use of several recent results in proof theory. In particular, our paper follows the following outline.

1. We formulate a sequent calculus proof system for Heyting arithmetic where fixed points and term equality are logical connectives: that is, they are defined via their left- and right-introduction rules. This work builds on earlier work by McDowell & Miller [26] and Momigliano & Tiu [30].

2. We replace Gentzen’s sequent proofs with focused proof systems as developed by Andreoli, Baelde, and Liang & Miller [2, 5, 24]. Such inference systems structure proofs into two phases: the negative phase organizes don’t-care nondeterminism while the positive phase organizes don’t-know nondeterminism. In this way, the construction of a negative phase (reading it as a mapping from its conclusion to its premises) determines a function and the construction of the positive phase determines a more general nondeterministic relation.

3. Since $\forall x [P(x) \supset Q(x)] \equiv \exists x [P(x) \land Q(x)]$ whenever predicate $P$ denotes a singleton set, the resulting ambiguity of polarity makes it possible to position such singleton predicates always into the negative phase. As mentioned above, a suitable treatment of singleton sets allows for a direct treatment of functions.

4. We exploit focused proof systems in a second and different fashion. If we view proofs of propositional formulas as denoting typed terms, then the usual representation of terms as function-applied-to-arguments occurs when primitive types are polarized negatively. If we set the polarity of primitive types to positive, we can turn the structure of terms inside out, yielding a representation of terms similar to administrative normal form [12]. Such a term representation allows us to translate common arithmetic expressions using functions into appropriate sequences of relational expressions that compute those functions. This approach to term representation builds on the $\lambda \kappa$-term calculus of Brock-Nannestad, Guenot, & Gustafsson [7] which is closely related to the LJQ and LJQ’ proof systems of Herbelin [22] and Dyckhoff & Lengrand [11], respectively.

5. Finally, the resulting proof system provides a means to take the specification of a relation and use it directly to compute a function (something that is not available directly when applying choice operators).

These various steps lead to the systematic construction of a single, expressive proof system in which functional computation is abstracted away from quantificational logic.

## 2 The basics of focusing in quantificational intuitionistic logic

In this section, we present a proof system for an intuitionistic theory of first-order quantification in two parts: Section 2.1 presents a proof system for the propositional fragment and Section 2.2 introduces quantification and equality of terms (at all types).
Structural rules

\[ \frac{\Gamma, N \vdash N \vdash \cdot \vdash E}{\Gamma, N \vdash \cdot \vdash E} \quad \frac{C, \Gamma \vdash \Theta \vdash \Delta_1 \vdash \Delta_2}{\Gamma \vdash C, \Theta \vdash \Delta_1 \vdash \Delta_2} \quad \frac{\Gamma \vdash P \vdash \cdot \vdash E}{\Gamma \vdash P \vdash \cdot \vdash E} \quad \frac{\Gamma \vdash N \vdash \cdot \vdash}{\Gamma \vdash N \vdash \cdot \vdash} \quad \frac{\Gamma \vdash P \vdash \cdot \vdash E}{\Gamma \vdash P \vdash \cdot \vdash E} \quad \frac{R_I}{\Gamma, N \vdash \Delta_1 \vdash \Delta_2} \]

Negative phase introduction rules

\[ \frac{\Gamma \vdash \cdot \vdash P \vdash \cdot \vdash E}{\Gamma \vdash \cdot \vdash P \vdash \cdot \vdash E} \quad \frac{\Gamma \vdash \cdot \vdash E \vdash}{\Gamma \vdash \cdot \vdash E \vdash} \quad \frac{\Gamma \vdash \cdot \vdash N \vdash}{\Gamma \vdash \cdot \vdash N \vdash} \quad \frac{\Gamma \vdash \cdot \vdash E \vdash}{\Gamma \vdash \cdot \vdash E \vdash} \quad \frac{\Gamma \vdash \cdot \vdash N \vdash}{\Gamma \vdash \cdot \vdash N \vdash} \quad \frac{R_f}{\Gamma \vdash \cdot \vdash f^+, \Theta \vdash \Delta_1 \vdash \Delta_2} \]

Positive phase introduction rules

\[ \frac{\Gamma \vdash B_1 \vdash \cdot \vdash E}{\Gamma \vdash B_1 \vdash \cdot \vdash E} \quad \frac{\Gamma \vdash B_2 \vdash \cdot \vdash E}{\Gamma \vdash B_2 \vdash \cdot \vdash E} \quad \frac{\Gamma \vdash B_1 \vdash \cdot \vdash E}{\Gamma \vdash B_1 \vdash \cdot \vdash E} \quad \frac{\Gamma \vdash B_2 \vdash \cdot \vdash E}{\Gamma \vdash B_2 \vdash \cdot \vdash E} \]

Fig. 1 The propositional fragment of cut-free LJF.

2.1 Propositional intuitionistic logic

In this section, we present propositional intuitionistic logic and a focused proof system for it. Propositional intuitionistic logic formulas are given by the logical connectives \( \land, \lor, \land \lor \), and \( \top, \bot \), the logical constants \( t, f \), and atomic formulas. The focused system in Fig. 1 contains not formulas but polarized formulas. Such polarized formulas differ from unpolarized formulas in two ways. First, the conjunction is replaced with two conjunctions \( \land^+ \) and \( \land^- \) and the unit of conjunction \( t \) with \( t^+ \) and \( t^- \). Second, every atomic formula \( A \) is assigned either a positive or negative polarity in an arbitrary but fixed fashion. Thus, one can fix the polarity of atomic formulas (propositional variables) such that they are all positive or all negative or some mixture of positive and negative. A polarized formula is positive if it is a positive atomic formula or its top-level logical connective is either \( t^+ \), \( f \), \( \land^+ \), or \( \lor \). A polarized formula is negative if it is a negative atomic formula or its top-level logical connective is either \( t^- \), \( \land^- \), or \( \lor \).

Fig. 1 contains the structural and introduction rules for the propositional fragment of the LJF focused proof system [24]. That proof system uses the following two kinds of sequents: unfocused sequents have the form \( \Gamma \vdash \Theta \vdash \Delta_1 \vdash \Delta_2 \), while focused sequents have the form \( \Gamma \vdash \Delta_1 \vdash \Delta_2 \). In those inference rules, the syntactic variables \( \Delta, \Theta, \Gamma \) (possibly with subscripts) range over multisets of polarized formulas; \( P \) denotes a positive formula; \( N \) denotes a negative formula; \( C \) denotes either a positive formula or a positive atom; \( E \) denotes either a positive formula or a negative atom; and \( B \) denotes any polarized formula. Since we are working with an intuitionistic sequent system, we require that all sequents in a focused proof have exactly one formula on the right: that is, the multiset union of \( \Delta_1 \) and \( \Delta_2 \) is a singleton. Since we are considering only single-focused proof systems (as opposed to multifocused proof systems [8]), we also require that sequents of the form \( \Gamma \vdash \Theta \vdash \Delta_1 \vdash \Delta_2 \) have the property that the multiset union of \( \Theta \) and \( \Delta_1 \) be always a singleton. An invariant
in the construction of LJF proofs is that \( \Gamma \) will be a multiset that can contain only negative formulas and positive atoms. Every sequent in LJF denotes a standard sequent in LJ: simply replace \( \uparrow \) and \( \downarrow \) with commas. An unfocused sequent of the form \( \Gamma \uparrow \vdash \cdot \uparrow E \) is also called a \textit{border} sequent.

A \textit{derivation} is a tree structure of occurrences of inference rules: a derivation has one conclusion (the endsequent) and possibly several premises. A derivation with no premises is a (focused) proof. A derivation that contains only negative sequents is a \textit{negative phase}: such a phase contains introduction rules for negative connectives, and the storage rules (\( S_1 \) and \( S_r \)). A derivation that contains only positive sequents is a \textit{positive phase}: such a phase contains introduction rules for positive connectives. A \textit{bipole} is a derivation whose conclusion and premises are all border sequents: also, when reading the inference rules from the bottom up, the first inference rule is a decide rule (either \( D_l \) or \( D_r \)); the next rules are positive introduction rules; then there is a release rule (either \( R_l \) or \( R_r \)); followed by negative introduction rules and storage rules (either \( S_l \) or \( S_r \)). In other words, a bipole is the joining of a single positive phase to possibly several negative phases.

Figure 1 contains neither the initial rule nor the cut rule. Although the cut rule and the cut-elimination theorem play important roles in justifying the design of focused proof systems, they play a minor role in this paper (for example, cut-elimination is not part of our notion of computation). The initial rule will be important but not globally: we introduce it later when we need (variants of) it.

### 2.2 Quantification and term equality

In order to treat first-order quantification, sequents are extended to permit the proof-level binding mechanism of \textit{eigenvariables} [16]. To that end, we prefix all \( \uparrow \) and \( \downarrow \) sequents with \( \Sigma \cdot \), where \( \Sigma \) is a list of variables that are considered bound over the sequent. When we write a prefix as \( y : \tau, \Sigma \cdot \), we imply that \( y \) does not appear as one of the variables in \( \Sigma \).

The inference rules for term equality and quantification are displayed in Figure 2 and are taken from early papers by Schroeder-Heister [28] and Girard [18]: see also [26]. Formulas with a top-level \( \forall \) have negative polarity while formulas with a top-level \( \exists \) or equality have positive polarity. The expression \( [t/x]B \) denotes the \( \beta\eta \)-long normal form of \( (\lambda x.B)t \) and the judgment \( \Sigma \vdash t : \tau \) denotes the fact that \( t \) is a term in \( \beta\eta \)-long form and with type \( \tau \). The typing judgment will be made more precise and generalized later in Section 6.

While provability in the propositional fragment is known to be decidable [16], it has been shown in [33] that adding these rules for term equality and quantification results in an undecidable logic even if we restrict to just first-order terms and quantifiers and even without any predicate symbols (and, hence, without atomic formulas).

### 3 Inference rules for the fixed point connective

We shall now add to our collection of logical connectives a fixed point operator. There have been many treatments of fixed points and induction within proof systems such as those involving Peano’s axioms and induction schemes or those using a specially designed proof system such as Scott induction [19]. Here, we restrict our attention to the rather minimalistic setting where the fixed point operator \( \mu \) is treated as a logical connective in the sense that it has left- and right-introduction rules: these rules simply unfold \( \mu \)-expressions. While the resulting fixed point operator is self-dual and rather weak, it can still play a useful role in proving some weak theorems of arithmetic [18, 26, 28] and it can provide an interesting proof theory for aspects of model checking [4, 20, 31]. It is possible to describe a more powerful
Typed first-order quantification rules

\[
\begin{align*}
\Sigma \vdash t : \tau & \quad \Sigma, \Gamma \vdash \{t/x\}B \vdash \Downarrow E \\
\Sigma : \Gamma \Downarrow \forall x. \tau, B \vdash \Downarrow E & \quad \Sigma : \Gamma \Downarrow \forall x. \tau \vdash \Downarrow E \\
y : \tau, \Sigma : \Gamma \Downarrow \{y/x\}B \vdash \Downarrow & \quad \Sigma : \Gamma \Downarrow \forall x. \tau \vdash \Downarrow E \\
\Sigma : \Gamma \Downarrow \exists x. \tau, B \vdash \Downarrow & \quad \Sigma : \Gamma \Downarrow \exists x. \tau \vdash \Downarrow E
\end{align*}
\]

Equality rules

\[
\begin{align*}
\Sigma \theta : \Gamma \theta \vdash \theta \vdash \Delta_1 \theta \vdash \Delta_2 \theta & \\
\Sigma : \Gamma \Downarrow s = t, \Theta \vdash \Delta_1 \Downarrow \Delta_2 & \\
\Sigma : \Gamma \Downarrow t = s & \\
\Sigma : \Gamma \Downarrow \vdash t = s
\end{align*}
\]

There are two provisos: (†) \( \theta \) is the mgu of \( s \) and \( t \). (‡) \( t \) and \( s \) are not unifiable.

Figure 2 Focused proof rules for quantification and term equality.

proof system for fixed points that uses induction and co-induction rules to describe the introduction rules for the least and greatest fixed points [26,30].

The logical constant \( \mu \) is actually parameterized by a list of typed constants as follows:

\[
\mu_{\tau_1, \ldots, \tau_n} : ((\tau_1 \to \cdots \to \tau_n \to \sigma) \to \tau_1 \to \cdots \to \tau_n \to \sigma) \to \tau_1 \to \cdots \to \tau_n \to \sigma
\]

where \( n \geq 0 \) and \( \tau_1, \ldots, \tau_n \) are simple types. (Following Church [9], we use \( \sigma \) to denote the type of formulas.) Expressions of the form \( \mu_{\tau_1, \ldots, \tau_n}^{\tau_1} B_{t_1} \ldots t_n \) will be abbreviated as simply \( \mu B t \) (where \( t \) denotes the list of terms \( t_1 \ldots t_n \)). We shall also restrict fixed point expressions to use only monotonic higher-order abstraction: that is, in the expression \( \mu_{\tau_1, \ldots, \tau_n}^{\tau_1} B_{t_1} \ldots t_n \)

the expression \( B \) is equivalent (via \( \beta \eta \)-conversion) to \( \lambda P_{\tau_1} \cdots \tau_n \to \sigma \lambda x_{\tau_1} \cdots \lambda x_{\tau_n}^{\tau_1} B' \)

and where all occurrences of the variable \( P \) in \( B' \) occur to the left of an implication an even number of times. The unfolding of the fixed point expression \( \mu B t \) yields \( B(\mu B) t \) and the introduction rules for \( \mu \) establish the logical equivalence of these two expressions.

Example 1. Assume that we have a primitive type \( i \) and that there are two typed constants \( z : i \) and \( s : i \rightarrow i \). We shall abbreviate the terms \( z, (s z), (s (s z)), (s (s (s z))), \) etc by \( 0, 1, 2, 3, \) etc. The following two named fixed point expressions define the natural number predicate and the ternary relation of addition.

\[
\begin{align*}
nat & = \mu \lambda N \lambda n (n = 0 \lor \exists n' (n = s n' \land^+ N n')) \\
\text{plus} & = \mu \lambda P \lambda m \lambda p \lambda q (n = 0 \land^+ m = p) \lor \exists n' \exists p' (n = s n' \land^+ p = s p' \land^+ P n' m p')
\end{align*}
\]

The following theorem, proved using induction, states that the plus relation describes a (total) functional dependency between its first two arguments and its third.

\[
\forall m, n (\text{nat } m \supset \exists k (\text{plus } m n k)) \land \forall m, n, p, q (\text{plus } m n p \supset \text{plus } m n q \supset p = q)
\]

3.1 Focusing and unfolding

The natural rules for unfolding \( \mu \)-expressions are given as the first two inference rules of Figure 3. Here, we have assigned to such expressions the positive polarity. Since the left-introduction and right-introduction rules for \( \mu \)-expressions are the same (i.e., they are unfolded), they could have been polarized negatively as well. If we were to add an induction rule in order to have \( \mu \)-expressions capture least fixed points, the use of the positive polarity would be the most natural choice [27].
Focused sequent calculus proof systems were originally developed for quantificational logic—as opposed to arithmetic—and in that setting the bottom-up construction of the negative phase causes sequents to get strictly smaller (counting, for example, the number of occurrences of logical connectives). As a result, it was possible to design focused proof systems in which decide rules were not applied until all invertible rules were applied. We shall say that such proofs systems are strongly focused proof systems: examples of such systems can be found in [2,24].

As is obvious from the first two inference rules in Figure 3, the size of the formulas in the negative phase can increase when \( \mu \)-expressions are unfolded. Thus, a more flexible approach to building negative phases should be considered. Some focused proof systems have been designed in which a decide rule can be applied without consideration of whether all or some of the invertible rules have been applied. Following [29], such proof systems are called weakly focused proof systems: an early example of such a proof system is Girard’s LC [17]. Since we wish to use the negative phase to do functional style, determinate computation, a weakly focused system—with its possibility to stop in many different configurations—cannot provide the foundations that we need.

Instead of strongly and weakly focused proof systems, we modify the notion of strongly focusing by allowing certain explicitly described \( \mu \)-expressions appearing in the negative phase to be suspended. In that case, one can switch from a negative phase to a positive phase (using a decide rule) when the only remaining formulas in the negative phase are suspendable. In that case, those formulas are “put aside” during the processing of the positive phase and are reinstated when the positive phase switches to the negative phase (using a release rule). In more detail, let \( S \) denote a suspension predicate: this predicate is defined only on \( \mu \)-expressions and if \( S \) holds for \((\mu B\Bar{t})\) then we say that this expression is suspended. The unfold rule in Figure 3 has the proviso that \( S \) does not hold of the \( \mu \)-expression that is the subject of that inference rule. In order to accommodate suspended formulas, \( \Downarrow \)-sequents need to contain a new multiset zone, denoted by the syntactic variable \( \Omega \): in particular, they now have the structure \( \Gamma \Downarrow \Theta; \Omega \vdash \Delta_1 \Downarrow \Delta_2 \). All positive introduction rules ignore this new zone: for example, the left-introduction of \( \land \) will now be written as

\[
\begin{align*}
\frac{\Gamma \Downarrow B_1; \Theta; \Omega \vdash E \quad \Gamma \Downarrow B_2; \Theta; \Omega \vdash E}{\Gamma \Downarrow B_1 \land B_2; \Theta; \Omega \vdash E} \quad \bar{i} \in \{1,2\}.
\end{align*}
\]

The suspension property \( S \) is defined at the mathematics level and, as a result, can make use of syntactic details about \( \mu \)-expressions. For example, this property could be defined to hold for a \( \mu \)-expression that contains more than, say, 100 symbols or when the first term in the list \( \bar{t} \) is an eigenvariable. However, in order to guarantee that the negative phase is determinate, we need to require the following property:

\[(*)\] For all \( \mu \)-expressions \((\mu B\bar{t})\) and for all substitutions \( \theta \) defined on the eigenvariables free in that \( \mu \)-expression, if \( S \) holds for \((\mu B\bar{t})\theta \) then \( S \) holds for \((\mu B\bar{t})\).

That is, if an instance of a \( \mu \)-expression satisfies \( S \) after a substitution is applied, it must satisfy \( S \) before it was applied. This condition rules out the possible suspension condition “holds if it contains 100 symbols” but it allows the condition “holds if the first term in \( \bar{t} \) is an eigenvariable”. Furthermore, suspension properties should not, in general, be invariant under substitution since otherwise a suspended formula will remain suspended during the construction of a proof: it can only be used within the initial rule.

Example 2. Consider the suspension predicate that is true of \( \mu \)-expressions \( \mu B \bar{t}_1 \ldots \bar{t}_n \) if and only if \( n \geq 2 \) and \( t_1 \) and \( t_2 \) are the same variable. Clearly, property \((*)\) does not
Fixed point rules

\[ \text{Σ} : \Gamma \vdash B(µB) \Theta \vdash \Delta \vdash E \quad \text{unfoldL} \]

\[ \text{Σ} : \Gamma \vdash µB t, \Theta \vdash \Delta \vdash E \quad \text{unfoldR} \]

Modified versions of the decide and release rules

\[ \text{Σ} : \Gamma, N \Downarrow N; \Omega \vdash \cdot \Downarrow E \quad D_r \]

\[ \text{Σ} : \Gamma \Downarrow \Theta \vdash \cdot \Thickspace \vdash \cdot \Downarrow E \quad D_t \]

\[ \text{Σ} : \Gamma \Downarrow P; \Omega \vdash \cdot \Downarrow E \quad R_t \]

\[ \text{Σ} : \Gamma \Downarrow \cdot; \Theta \Downarrow P \Downarrow \cdot \quad I_r \]

Initial rule

\[ P \in \Omega \]

\[ \text{Σ} : \Gamma \Downarrow \cdot; \Omega \Downarrow P \Downarrow \cdot \quad I_r \]

The proviso † requires that µB \( \mathsf{i} \) does not satisfy \( S \). The proviso ‡ requires \( \Omega \) to be a multiset of \( \mu \)-expressions that satisfy \( S \).

\begin{figure}[h]
\centering
\includegraphics[width=\textwidth]{rules.png}
\caption{Rules governing fixed point unfoldling, suspensions, and initial sequents.}
\end{figure}

\( \downarrow \) hold and the construction of the negative phase can be non-confluent. For example, let \( A \) be \( \mu \lambda x_1 \lambda x_2 . x = a \) (where \( a \) is a constant) and consider the sequent \( \Gamma \vdash u = v, Auv \vdash \cdot \Downarrow (E u) \).

Since \( Auv \) is a \( \mu \)-expression for which \( S \) does not hold, unfolding is applicable and yields the sequent \( \Gamma \vdash u = v, u = a \vdash \cdot \Downarrow (E u) \) which then leads to the border sequent \( \Gamma \vdash \cdot \Downarrow (E a) \).

However, the first step in the negative phase of the original sequent could have been the equality introduction, which yields \( \Gamma \Downarrow Auu \vdash \cdot \Downarrow (E u) \) and this must mark the end of the negative phase since \( Auu \) is a suspended formula.

Fortunately, this non-confluent behavior is ruled out by the \((\ast)\) property above. To see this, let \( \mathcal{C} \) be an \( \Downarrow \) -sequent that and let \( \Xi \) be a negative phase that has \( \mathcal{C} \) as its endsequent and with premises that are border sequents. If we collect the premises of \( \Xi \) into a set, say, \( \mathcal{P} \), then we call \( \mathcal{P} \) an invertible decomposition of \( \mathcal{C} \).

It is easy to show, via permutations of inference rules, that if \( \mathcal{C} \) has \( P_1 \) and \( P_2 \) as invertible decompositions, then \( P_1 = P_2 \). The \((\ast)\) condition enables the permutation of the equality left-introduction rule and the \text{un}fold\text{L} rule.

\begin{definition}[Purely positive formula] A polarized formula in which all occurrences of logical connectives are polarized positively is called a purely positive formula. A \( \mu \)-expression that is also purely positive will also be called a purely positive fixed point expression.
\end{definition}

Horn clauses (Prolog) can provide immediate examples of purely positive fixed points as illustrated in Example 1. Let \( B \) be a purely positive formula. If \( \Sigma: \Gamma \Downarrow \cdot \vdash B \Downarrow \cdot \) is provable then all proofs of that sequent are built of only positive right-introduction rules for \( \mathsf{t}^+, \mathsf{\land}^+, \mathsf{\lor}^+, \mathsf{\exists}, \mu \) (unfolding) and equality. Similarly, if \( \Sigma: \Gamma \Uparrow \vdash B \vdash \cdot \) is provable then all proofs of that sequent are built of only negative left-introduction rules for \( \mathsf{t}^+, \mathsf{\land}^+, \mathsf{\lor}^+, \mathsf{\exists}, \mu \) (unfolding), and equality. Thus, focused proofs of \( B \) and \( B \supset f^+ \) are achieved by using only one phase. In particular, such proofs do not contain structural rules nor the initial rule. As a result, synthetic inference rules are not decidable since they can encode arbitrary Horn clause specifications.
3.2 Phases as abstractions

Focused proof systems make it possible to define new inference rules by abstracting away details used in the construction of phases. The positive phase allows a simple abstraction since there is exactly one formula under focus in a positive sequent. A positive phase can be seen as the (derived) inference rule with a conclusion that is a border sequent and with premises that are marked by release rules.

There are, however, at least two challenges to making abstractions of negative phases. First, the premises of a negative phase may repeat the same sequents many times since there can be many paths to compute the result of a function. We shall choose to denote as the collections of premises of the negative phase the set of border sequents (instead of as a multiset). Second, there are many ways to process the don’t-care nondeterminism that is possible when applying invertible rules. We will abstract away from those differences by simply ignoring how a phase is constructed since all constructions yield the same border sequents.

This second abstraction flows from the same motivation used in confluent rewriting systems: once a path to a normal form is found, no other paths need to be considered since all other paths must yield the same normal form.

4 The polarity ambiguity of singleton sets

As we mentioned in the introduction, singleton sets can be used to help convert relations to functions: if the n + 1-ary relation R describes a function from its first n arguments to its last argument then the expression (λy.R(x1, ..., xₙ,y)) denotes a singleton set (given fixed values for x₁, ..., xₙ). The choice operators ε or ι can then be applied to this singleton set to extract that element, resulting in a proper function λx₁...λxₙ.(λy.R(x₁, ..., xₙ,y)).

Singleton sets play a role here as well. In fact, let P be a predicate of one argument so that it is provable that P is a singleton, namely,

(∃x.P(x)) ∧ (∀x,y.P(x) ⊃ P(y) ⊃ x = y)

As a consequence, the formulas ∃x.P(x) ∧ Q(x) and ∀x,P(x) ⊃ Q(x) are equivalent. If we used the ι-operator, these formulas would also be equivalent to Q(ιP).

Note that the sequent calculus treatments of ∃x.P(x) ∧ Q(x) and ∀x,P(x) ⊃ Q(x) are strikingly different. In particular, a proof of Σ;Γ ⊢ ∃x.P(x) ∧ Q(x) proceeds by guessing a term τ and then attempting to prove Σ;Γ ⊢ P(τ) and Σ;Γ ⊢ Q(t). Of course, since P denotes a singleton, there is at most one correct guess τ and that guess is confirmed after it is inserted into the proof. On the other hand, a proof of Σ;Γ ⊢ ∀x,P(x) ⊃ Q(x) can be seen as computing the value that satisfies P. Proof construction for that sequent leads to proving y, Σ;Γ ⊢ P(y) ⊃ Q(y). As mentioned in Section 3.1, this phase will move to completion by repeatedly unfolding fixed points and if the phase completes, the eigenvariable y will be instantiated to be the unique term τ. Thus, the premises of this completed phase will have the shape Σ;Γ ⊢ · ⊢ Q(t) (assuming for the sake of argument that Q(t) is a positive formula).

Example 4. Using the definitions in Example 1, consider the construction of a negative phase of the form x,Σ;Γ ⊢ (2 = 0 ∧ x = 3) ∧ (∃x'(2 = x ∧ x = x' + 3) ⊃ Q(x) ∧ x = x'). Since plus is a µ-expression, this sequent is proved by an unfoldL inference rule (assuming that S is false for all µ-expressions, i.e., nothing should be suspended). Unfolding yields an expression with a top-level disjunction, namely, x,Σ;Γ ⊢ ((2 = 0 ∧ x = 3) ∨ ∃x'(2 = x ∧ x = x' + 3)) ⊃ Q(x) ∧ x = x'.
Following the left-introduction for that disjunction, we are left with proving two sequents: the left premises, \( x, \Sigma : \Gamma \vdash ((2 = 0 \wedge 3 = x) \vdash \top) \) is proved immediately since \( 2 = 0 \) is not unifiable (Figure 2). A proof of the second premise must proceed as follows

\[
x', \Sigma : \Gamma \vdash \top x' \vdash \top (Q (s x'))
\]

\[
x, n', x', \Sigma : \Gamma \vdash (2 = s n' \wedge x = s x' \wedge plus n' 3 x') \vdash \top (Q x)
\]

(Here, the double line between sequents denotes the application of possibly several inference rules.) After several more inference steps, the negative phase terminates with the border premise \( \Sigma : \Gamma \vdash \top \cdot \vdash (Q 5) \). By ignoring the internal structure of phases, we have just the synthetic inference rule

\[
\Sigma : \Gamma \vdash \top \vdash (Q 5)
\]

Furthermore, there were no choices involved in computing this phase. Note that the actual specification of the relation plus is used to compute the addition as a function. Later in Section 6 we shall show how we can use that synthetic inference rule to capture the more familiar looking rule

\[
\Sigma : \Gamma \vdash \top \vdash (Q (2 + 3))
\]

**Example 5.** Employing the suspension mechanism makes it possible for functional computation to be mixed with symbolic computation. For example, let multiplication be defined as the following fixed point expression.

\[
times = \mu \lambda P \lambda n \lambda m \lambda p \cdot ((n = 0 \wedge p = 0) \lor \exists n' \exists p' (n = s n' \wedge P n' m p' \wedge plus p' m p))
\]

The theorem that states that \((0 \times (x + 1)) + y = y\) can be encoded and proved in this setting by taking two steps. First we translate this expression into the following sequent (using a technique described in Section 6):

\[
y, \Sigma : \Gamma \vdash \forall u. \text{times } 0 (s x) u \supset \forall v. \text{plus } u y v \supset v = y \vdash \cdot
\]

Here, we assume the (rather typical) suspension mechanism that classifies \( \mu \)-expressions as suspendable if they are built from plus and times and their first argument is an eigenvariable. Thus, when this sequent is reduced to

\[
u, v, y, \Sigma : \Gamma \vdash \forall u. \text{times } 0 (s x) u, \text{ plus } u y v \vdash v = y \vdash \cdot
\]

only the times-expression can be unfolded. After that unfolding, the eigenvariable \( u \) will be instantiated and the plus-expression can then also be unfolded. Finally, the negative phase ends with the border sequent \( y, \Sigma : \Gamma \vdash \top \cdot \top y = y \vdash \cdot \) which is proved by a \( D_r \) rule followed by the right-introduction rule for equality.

## 5 Equivalence classes

Equivalence relations play important roles in computation and reasoning. Occasionally, we have a relation that is not functional but all the possible outcomes are equivalent, for some specific equivalence relation. For example, if two lists are considered equivalent when they
are permutations of each other, then the equivalence class of lists modulo that relation encodes multisets. Similarly, if two pairs of integers \((x, y)\) and \((w, z)\) (where \(y\) and \(z\) are not zero) are considered equivalent when \(xz = wy\) then equivalence classes encode rational numbers.

The ambiguity of singletons can be lifted to computation with equivalence classes in the following sense. Let \(\rho\) be an equivalence relation. The familiar notion \([x]_\rho\) for the \(\rho\)-equivalence class containing \(x\) is just syntactic sugar for \(\lambda y.x \rho y\). (Define logical equivalence in the usual way: \(A \equiv B\) is an abbreviation for \((A \supset B) \land (B \supset A)\).)

Assume that \(\rho\) is an equivalence relation and that the following holds for \(Q\):

\[
\forall x \forall y. x \rho y \supset Q(x) \equiv Q(y)
\]

(Note that this theorem is immediate for all \(Q : i \rightarrow o\) when \(\rho\) is equality.) The following equivalence holds.

\[
[\forall x \in [y]_\rho \supset Q(x)] \equiv [\exists x \in [y]_\rho \land Q(x)]
\]

In a more informal mathematical notation, one might replace either the above existential or universal expression with \(Q([y]_\rho)\). While we shall not use this expression (it involves a typing error), it conveys the usual mathematical sense of this ambiguity: if we show that one member of an equivalence class satisfies such a property \(Q\) then all members of that equivalence class satisfy \(Q\).

Obviously, we can generalize the notion of functional dependency to the following

\[
\forall \bar{x} (\exists y. R(\bar{x}, y) \land \forall y \forall z. R(\bar{x}, y) \supset R(\bar{x}, z) \supset y \rho z),
\]

which states that the \(n\)-ary relation is a total function up to \(\rho\). Thus, during the construction of a proof where one is asked to pick a term \(t\) that makes \(R(x_1, \ldots, x_n, t)\) true, one can instead compute just any term \(t'\) such that \(R(x_1, \ldots, x_n, t')\) (as long as the property established—\(Q\) above—is \(\rho\)-invariant). In that setting, we can also extend the phase-abstraction mechanism to exclude border premises that differ up to \(\rho\).

6 Term representation: turning formulas inside-out

6.1 Term annotations for propositional LJF

In Section 2.2 we extended the proof system in Figure 1 with quantifiers and term structures and in Section 3 with recursive definitions. Here we extend that original proof system in two different directions. First, instead of having all predicates (such as nat, plus, and times) be defined, we consider the usual approach to propositional logic where formulas can contain undefined atoms. When such atoms appear in polarized formulas, atomic formulas must be provided with an arbitrary but fixed polarity. Following the design of \(LJF\) [24], we extend the proof system in Figure 1 by adding the two variants of the initial rule displayed on the right.

Here, \(N_a\) ranges over negatively polarized atoms and \(P_a\) ranges over positively polarized atoms. Given that we are working with a propositional logic, it is possible to use a strongly focused version of \(LJF\) (as was given in [24]) and to insist that all formulas in the negative phase are processed in a left-to-right discipline. As a result, it is possible to fuse the store-left rule \((S_1)\) with other rules.

The completeness theorem for \(LJF\) can be stated as follows. Given an (unpolarized) formula \(B\), a polarization of \(B\) is a formula that results from replacing every occurrence
in B of \(\wedge\) with either \(\wedge^+\) or \(\wedge^-\) and every occurrence of t with either \(t^+\) or \(t^-\). (Also, the polarization of propositional variables can be fixed arbitrarily.) If B is an intuitionistic theorem and \(\hat{B}\) is any polarization of B, then there is an LJF proof of \(\vdash \hat{B} \vdash\) [24]. Thus, polarization does not affect provability but, as we shall illustrate, it can affect the shape of proofs.

Our second extension of the proof system in Figure 1 is meant to harness the resulting variability in proofs in order to provide a rich representation for terms and formulas. Figure 4 contains the propositional LJF inference rules annotated with the \(\lambda\)-term found in [7]. This term calculus contains three syntactic categories: Terms, Values, and Continuations. Note that it is the store-left (S\(\hat{r}\)) rule that results in bindings in term structures and that such binding can result in either a \(\lambda\)-abstraction or a \(\kappa\)-abstraction.

### 6.2 Two normal forms for simply typed terms

If all primitive types (atomic formulas) are given a negative polarity, then the terms annotating proofs in the sequents of Figure 4 provide the usual notion of \(\beta\eta\)-long normal form \(\lambda\)-terms. Recall that terms in \(\beta\eta\)-long normal form are of the form \(\lambda x_1 \ldots \lambda x_n.h\ t_1 \ldots t_m\) where \(h\) is a variable or constant, where \(t_1, \ldots, t_m\) is a list of terms in \(\beta\eta\)-long normal form, and where the term \([h\ t_1 \ldots t_m]\) has primitive type. In particular, if we use \(\llbracket \cdot \rrbracket\) to translate such \(\lambda\)-terms into terms of the first syntactic category in Figure 4, then

\[
\llbracket \lambda x_1 \ldots \lambda x_n.h\ t_1 \ldots t_m \rrbracket = \lambda x_1 \ldots \lambda x_n.h\ (\llbracket t_1 \rrbracket \ldots \llbracket t_m \rrbracket \llbracket \varepsilon \rrbracket).
\]

Note that this translation transforms the application of the function \(h\) from one argument at a time to the application of \(h\) to a list of all its arguments. Such a formal connection between \(\beta\eta\)-normal forms and this style of term representation was made by Herbelin using his LJF sequent calculus [21]. When all primitive types are given a negative bias, then no formulas are given a positive bias and, as a result, the inference rule named \(R_i/S_i\) does not appear in such proofs and terms do not contain the \(\kappa\) binding operator.

**Example 6.** Let \(i\) be a primitive type that will be considered negatively biased in the LJF proof system. The only terms \(t\) for which \(\Gamma \vdash t: (i \supset i) \supset i \supset i \vdash\) is provable are encodings of the Church numerals. In particular, the terms corresponding to the first three numerals are \(\lambda \lambda x.x \varepsilon\), \(\lambda \lambda x.f\ (\llbracket x \varepsilon \rrbracket \cdot \varepsilon)\), and \(\lambda \lambda x.f\ (\llbracket f (\llbracket x \varepsilon \rrbracket \cdot \varepsilon) \rrbracket \cdot \varepsilon)\).
If all primitive types are given a positive bias, then the terms annotating proofs in the sequents in Figure 4 provide a formal definition of a normal form similar to the one described in [12] and which is commonly called administrative normal form (ANF).

**Definition 7.** A simply typed λ-term is in administrative normal form (ANF) when written as
\[ \lambda x_1 \ldots \lambda x_n. \uparrow h, \] where \( n \geq 0 \) and \( h \) is a variable of primitive type or as
\[ \lambda x_1 \ldots \lambda x_n. h \ (p_1 :: \cdots :: p_m :: \kappa y. t), \] where \( n, m \geq 0 \), the type of \( y \) is primitive, \( t \) is a simply typed term in ANF and values \( p_1, \ldots, p_m \) are either variables of primitive type or are of the form \( \downarrow t \) where \( t \) is in ANF.

Note the following: (1) If \( p_1 \) is not a variable, then it must denote a term of arrow type and, hence, it will be a λ-abstraction: that is, immediately following the \( \downarrow \) there must be a λ-abstraction. (2) A closed term in ANF with a type of order 2 or less is of the form
\[ \lambda x_1 \ldots \lambda x_n. t \] where the types of \( x_1, \ldots, x_n \) are either primitive or first-order and where \( t \) does not contain any \( \lambda \). It can be the case, however, that \( t \) contains \( \kappa \) bindings. (3) If we ignore the requirements on certain variables being of primitive type, then this definition can be extended to untyped λ-terms.

In order to facilitate the presentation of λ-terms in ANF format, we introduce the following convention. Instead of \( \lambda x_1 \ldots \lambda x_n. \uparrow h \) we will simply drop the \( \uparrow \) and write \( \lambda x_1 \ldots \lambda x_n. h \) (remembering that \( h \) is a variable of primitive type). Also, instead of
\[ \lambda x_1 \ldots \lambda x_n. (p_1 :: \cdots :: p_m :: \kappa y. t) \] we write \( \lambda x_1 \ldots \lambda x_n. \text{name } y = h \ (p_1, \ldots, p_m) \in t \) (remember that \( y \) is a variable of primitive type) and where \( p_1, \ldots, p_m \) is a list of either variables (of primitive types) or λ-abstractions that are also in ANF.

We use the keyword “name” here instead of “let” since let-expressions are often considered to be abbreviations for β-redexes: that is, (let \( x = s \) in \( t \)) is often considered equal to \( ((\lambda x. t) s) \). Here, however, the name-expressions denote normal terms since they are annotations of cut-free sequent calculus proofs.

The figure to the right illustrates two ways of representing a labeled binary tree of height 2. Clearly, the representation on the left takes exponential space as the height increases while the representation on the right increases linearly with the height. Here we assume that \( x \) and \( f \) are two bound variables of type \( i \) and \( i \rightarrow i \rightarrow i \), respectively. Choosing between these two representation schemes involves assigning either negative or positive polarity to the atomic formula (primitive type) \( i \). For example, if \( i \) is polarized negatively, then there is an LJF proof that is annotated with the term
\[ f (\downarrow f (\downarrow x (\downarrow x \varepsilon)) (\downarrow x (\downarrow x \varepsilon)) (\downarrow f (\downarrow x (\downarrow x \varepsilon)) (\downarrow x (\downarrow x \varepsilon))) \varepsilon) \] which can be displayed, in a more friendly syntax, as
\[ f (f (x, x), f (x, x)). \] On the other hand, when \( i \) is polarized positively, the above term is no longer a proper annotation of an LJF proof while the term
\[ \text{name } y_1 = (f x \ x) \text{ in name } y_2 = (f y_1 \ y_1) \text{ in } y_2 \] does annotate an LJF proof. Since the ANF term format allows subterms to be shared, that format can allow for much smaller term structures. While sharing is a feature of ANF, we shall not require it to be particularly well behaved. For example, it is possible for a term in ANF to have vacuous naming—i.e., a named term that is never used in the name’s scope—or redundant naming—i.e., the same term can be named more than once. For example, the term
\[ \text{name } y_1 = (f x \ x) \text{ in name } y_2 = (f y_1 \ y_1) \text{ in name } y_3 = (f y_1 \ y_1) \text{ in } y_2 \]
is in ANF even though it has vacuous and redundant naming. One might imagine that multifocusing can be used to allow parallel naming, such as in the expression
\[
\text{name } y_1 = (f \ x \ x) \text{ in name } y_2 = (f \ y_1 \ y_1) \text{ and } y_3 = (f \ y_1 \ y_1) \text{ in } y_2.
\]

One might also expect that the concept of maximal multifocusing [8] could relate to insisting on “maximal sharing”. In this paper, we shall not use multifocused proofs nor insist on the absence of vacuous or redundant naming.

### 6.3 Mixed term representations

The syntax of formulas of arithmetic statements depends on two primitive types: the type of formulas $o$ and of numerals $i$. We present several examples of term representations below where $o$ is polarized negatively and $i$ is polarized positively. We also allow the binary infix term constructors $+$ and $\ast$ of type $i \to i \to i$ as well as the formula constructor $<$ (the less-than relation) of type $i \to i \to o$.

**Example 8.** When the type $i$ for numerals is polarized positively, the $\lambda\kappa$-calculus does not allow for expressions of the form $((s \cdot \cdot (sz) \cdot \cdot)$.

Instead, encoding an expression of the form $P(2 + 3)$ can be done as follows:

\[
\text{name } 1 = (s \ 0) \text{ in name } 2 = (s \ 1) \text{ in name } 3 = (s \ 2) \text{ in name } x = 2 + 3 \text{ in } P(x).
\]

Thus, numerals are really treated as pointers into a sequence of successor terms.

**Example 9.** The formula $\forall x[ (x^2 + 6) = 5x \supset (x = 2 \lor x = 3)]$ can be written as the $\lambda\kappa$-term $\forall x[\text{name } y = x \ast x \text{ in name } u = 5 \ast x \text{ in name } v = y + 6 \text{ in } (v = u \supset (x = 2 \lor x = 3))].$

The inversion of syntax that appears in ANF is familiar to those computing with relations instead of functions, as the following example illustrates.

**Example 10.** To prove that $(2 \ast (5 + 2)) < 8 + 7$ in a setting with only relations (such as, say, in Prolog) one can rewrite that inequality as the following (equivalent) formulas of arithmetic.

\[
\exists x(\text{plus } 5 2 x \land \exists y(\text{times } 2 x y \land \exists z(\text{plus } 8 7 z \land y < z))) \\
\forall x(\text{plus } 5 2 x \supset \forall y(\text{times } 2 x y \supset \exists z(\text{plus } 8 7 z \supset y < z))).
\]

Here, the binary operators $+$ and $\ast$ are interpreted by corresponding ternary predicates.

### 6.4 Interpreting term constructors

As Examples 8 and 9 illustrate, arithmetic formulas can contain a mix of uninterpreted term constructors (for example, the constructor for numerals $z$ and $s$) and interpreted term constructors (for example, $+$ and $\ast$).

The formal introduction of a new interpreted term constructor such as $f : i \to \ldots \to i \to i$ of $n$ arguments must be tied to an interpreting $\mu$-expression $R_f$ of $n + 1$-arity and a formal proof that $R_f$ encodes a function, i.e.,

$$\forall x.(\exists y. R_f(x, y)) \land \forall y \forall z. R_f(x, y) \supset R_f(x, z) \supset y = z).$$

That is, achieving a proof of this theorem permits the introduction of a new constructor $f$ where $y = f x_1 \ldots x_n$ is interpreted by $R_f x_1 \ldots x_n y$. In principle, this means that
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Name binding rules: the variable \( x \) is not bound in \( \Sigma \) nor in \( \Psi \).

\[
\begin{align*}
\Sigma : x := t, \Psi & ; \Gamma \vdash B, \Theta \vdash \Delta_1 \uparrow \Delta_2 & \quad \Sigma : x := t, \Psi ; \Gamma \vdash B \uparrow \\
\Sigma : \Psi ; \Gamma \uparrow \Delta_1 \uparrow \Delta_2 & \quad \Sigma : \Psi ; \Gamma \vdash B \downarrow \downarrow E \\
\Sigma : x := t, \Psi ; \Gamma \vdash B \downarrow \downarrow E & \quad \Sigma : x := t, \Psi ; \Gamma \vdash B \downarrow \downarrow E \\
\Sigma : \Psi ; \Gamma \vdash B \downarrow \downarrow E & \end{align*}
\]

Figure 5 Introduction rules for the constructor \( f \) and the relation \( R_f \) which interprets it.

Positive phase quantifier rules

\[
\begin{align*}
\Sigma, (\Psi) & \vdash t : \tau \uparrow \\
\Sigma, (\Psi) & \vdash [t/x]B \downarrow \downarrow E \\
\Sigma, (\Psi) & \vdash \exists x_{\tau}.B \downarrow .
\end{align*}
\]

Figure 6 The incorporation of the naming context \( \Psi \).

the formula \((\text{name } y = f x_1 \ldots x_n \text{ in } B)\) is interpreted as either \( \forall y. (R_f x_1 \ldots x_n y \in B) \) or \( \exists y. (R_f x_1 \ldots x_n y \in B) \). Clearly, the naming construction is a self-dual operator on formulas in the sense that \( \neg(\text{name } y = f x_1 \ldots x_n \text{ in } B) \) is equivalent to \((\text{name } y = f x_1 \ldots x_n \text{ in } \neg B)\). As a result, such formulas are said to have an ambiguous polarity since they can be coerced to be negative or positive. The introduction rules for interpreted term constructors are given in Figure 5.

6.5 A final extension

In order to treat the naming (sharing) of structures built using uninterpreted symbols within proofs and computations, we need to add to our sequents (both \( \uparrow \) and \( \downarrow \)) an additional zone (using the \( \Psi \) syntactic variable) that explicitly retains the naming relation. We do this by adding the \( \Psi \) context to all the previous arithmetic-related sequents and inference rules. We also add the inference rules that appear in Figure 6. In the first four of these inference rules, the formula-level binder \( \text{name } y = t \text{ in } B \) is translated to a proof-level binder by adding the pair \( y := t \) to the \( \Psi \) context.

The quantifier rules that instantiate their quantifier with a term are modified in Figure 6 so that the naming structure of sequents is respected. In particular, those rules employ the premise \( \Sigma, (\Psi) \uparrow \vdash t : \tau \uparrow \). (Here, \( (\Psi) \) is the set of (typed) variables that are bound in \( \Psi \).) Thus, the term \( t \) is, in general, a \( \lambda \kappa \)-term. The inference rules for equality must also be changed in order to account for the treatment of \( \lambda \kappa \)-terms: with only first-order constructors present (such as in our treatment of natural numbers), the treatment of unification in this setting can be based on the Martelli-Montanari algorithm [25].
7 Conclusion

We have presented a treatment of functional computation based on relations. Principles in proof theory provided both a method for moving expressions denoting embedded computation into naming-combinators of the logic (ANF normal form) and a means of organizing Gentzen-style introduction rules so that functional computations can be identified as one specific phase of computation (the negative phase). Since this view of computation is based on the construction of cut-free proofs, it is rather different from, say, the Curry-Howard correspondence.

While we have illustrated most of this mechanism using first-order term structures (such as Peano’s numerals), the proof theory behind LJF works at all finite types. As a result, this approach to functional computation is a possible avenue to explore how functional programming might be extended to treat terms containing λ-bindings.

The proof theory presented here is compatible with the proof theory for least and greatest fixed points that has been developed in a series of papers [14, 15, 26, 30] and in the Abella theorem prover [1, 6, 13]. A possible practical consequence of the design in this paper is an avenue for adding to Abella functional computations via the addition of interpreted term constructors.

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References


