

Finding Unity in Computational Logic

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Lecture 2: Some slides about sequent calculus.

Simply typed λ -terms

The traditional approach to first-order logic is to first define *terms* and then *formulas*.

In the higher-order logic setting, formulas can appear in terms.

Thus, terms and formulas need to be defined simultaneously: types distinguish terms from formulas.

The simply typed λ -calculus [Church 1940] provides a unifying approach to terms and formulas.

The rules of α and β -conversions are used to describe equality and substitution of formulas and terms into formulas and terms.

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Various dependently type λ -calculus have been proposed to unify the notion of term, formula, and proof.

- We do not following this approach since we need a much more flexible and open notion of proof.

Inference rules: structural rules

There are exactly three sets of these: *exchange*, *contraction*, *weakening*.

$$\frac{\Sigma: \Gamma', B, C, \Gamma'' \vdash \Delta}{\Sigma: \Gamma', C, B, \Gamma'' \vdash \Delta} \text{ xL}$$

$$\frac{\Sigma: \Gamma \vdash \Delta', B, C, \Delta''}{\Sigma: \Gamma \vdash \Delta', C, B, \Delta''} \text{ xR}$$

$$\frac{\Sigma: \Gamma, B, B \vdash \Delta}{\Sigma: \Gamma, B \vdash \Delta} \text{ cL}$$

$$\frac{\Sigma: \Gamma \vdash \Delta, B, B}{\Sigma: \Gamma \vdash \Delta, B} \text{ cR}$$

$$\frac{\Sigma: \Gamma \vdash \Delta}{\Sigma: \Gamma, B \vdash \Delta} \text{ wL}$$

$$\frac{\Sigma: \Gamma \vdash \Delta}{\Sigma: \Gamma \vdash \Delta, B} \text{ wR}$$

Inference rules: identity rules

There are exactly two: *initial*, *cut*.

$$\frac{}{\Sigma : B \vdash B} \textit{init} \qquad \frac{\Sigma : \Gamma_1 \vdash \Delta_1, B \quad \Sigma : B, \Gamma_2 \vdash \Delta_2}{\Sigma : \Gamma_1, \Gamma_2 \vdash \Delta_1, \Delta_2} \textit{cut}$$

Inference rules: identity rules

There are exactly two: *initial*, *cut*.

$$\frac{}{\Sigma : B \vdash B} \textit{init} \qquad \frac{\Sigma : \Gamma_1 \vdash \Delta_1, B \quad \Sigma : B, \Gamma_2 \vdash \Delta_2}{\Sigma : \Gamma_1, \Gamma_2 \vdash \Delta_1, \Delta_2} \textit{cut}$$

Notice that if we have weakening and exchange on the left and right, then

$$\frac{}{\Sigma : B, \Gamma \vdash B, \Delta} \textit{init}$$

is *admissible*.

Inference rules: introduction rules (some examples)

$$\frac{\Sigma : B, \Gamma \vdash \Delta}{\Sigma : B \wedge C, \Gamma \vdash \Delta} \wedge L \qquad \frac{\Sigma : C, \Gamma \vdash \Delta}{\Sigma : B \wedge C, \Gamma \vdash \Delta} \wedge L$$

$$\frac{\Sigma : \Gamma \vdash \Delta, B \quad \Sigma : \Gamma \vdash \Delta, C}{\Sigma : \Gamma \vdash \Delta, B \wedge C} \wedge R$$

$$\frac{\Sigma : \Gamma_1 \vdash \Delta_1, B \quad \Sigma : C, \Gamma_2 \vdash \Delta_2}{\Sigma : B \supset C, \Gamma_1, \Gamma_2 \vdash \Delta_1, \Delta_2} \supset L \qquad \frac{\Sigma : B, \Gamma \vdash \Delta, C}{\Sigma : \Gamma \vdash \Delta, B \supset C} \supset R$$

$$\frac{\Sigma \vdash t : \tau \quad \Sigma : \Gamma, B[t/x] \vdash \Delta}{\Sigma : \Gamma, \forall_{\tau} x B \vdash \Delta} \forall L \qquad \frac{\Sigma, y : \tau : \Gamma \vdash \Delta, B[y/x]}{\Sigma : \Gamma \vdash \Delta, \forall_{\tau} x B} \forall R$$

Permutations of inference rules

$$\frac{\frac{\Sigma: \Gamma, p, r \vdash s, \Delta \quad \Sigma: \Gamma, q, r \vdash s, \Delta}{\Sigma: \Gamma, p \vee q, r \vdash s, \Delta} \vee L}{\Sigma: \Gamma, p \vee q \vdash r \supset s, \Delta} \supset R$$

$$\frac{\frac{\Sigma: \Gamma, p, r \vdash s, \Delta}{\Sigma: \Gamma, p \vdash r \supset s, \Delta} \supset R \quad \frac{\Sigma: \Gamma, q, r \vdash s, \Delta}{\Sigma: \Gamma, q \vdash r \supset s, \Delta} \supset R}{\Sigma: \Gamma, p \vee q \vdash r \supset s, \Delta} \vee L$$

Permutations of inference rules (continued)

$$\frac{\frac{\Sigma: \Gamma_1, r \vdash \Delta_1, p \quad \Sigma: \Gamma_2, q \vdash \Delta_2, s}{\Sigma: \Gamma_1, \Gamma_2, p \supset q, r \vdash \Delta_1, \Delta_2, s} \supset L}{\Sigma: \Gamma_1, \Gamma_2, p \supset q \vdash \Delta_1, \Delta_2, r \supset s} \supset R$$

To switch the order of these two inference rules requires introduction some weakenings and a contraction.

$$\frac{\frac{\frac{\Sigma: \Gamma_1, r \vdash \Delta_1, p}{\Sigma: \Gamma_1, r \vdash \Delta_1, p, s} wR}{\Sigma: \Gamma_1 \vdash \Delta_1, p, r \supset s} \supset R \quad \frac{\frac{\Sigma: \Gamma_2, q \vdash \Delta_2, s}{\Sigma: \Gamma_2, q, r \vdash \Delta_2, s} wL}{\Sigma: \Gamma_2, q \vdash \Delta_2, r \supset s} \supset R}{\frac{\Sigma: \Gamma_1, \Gamma_2, p \supset q \vdash \Delta_1, \Delta_2, r \supset s, r \supset s}{\Sigma: \Gamma_1, \Gamma_2, p \supset q \vdash \Delta_1, \Delta_2, r \supset s} cR} \supset L$$