Finding Unity in Computational Logic

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Lecture 1: Some introductory material.

Computation-as-model: Computations happens, *i.e.*, states change, communications occur, *etc.* Logic is used to make statements *about* computation. *E.g.*, Hoare triples, modal logics.

Computation-as-deduction: Elements of logic are used to model elements of computation directly.

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Computation-as-deduction: Elements of logic are used to model elements of computation directly.

Proof normalization. Programs are proofs and computation is proof normalization (λ -conversion, cut-elimination). A foundations for functional programming.

Proof search. Programs are theories and computation is the search for sequent proofs. A foundations for logic programming.

There are great many "logics" used practice and in research. Implemented computational logic systems demand selecting one of two logics: *Classical Logic* and *Intuitionistic Logic*.

These two choices covers a large percentage of existing computational systems based on logic.

[Linear logic lies behind these other two logics.]

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The *propositional vs first-order vs higher-order* logic divide is not a problem of unity: HO logic can directly support both propositional logic and first-order logic.

We shall use proof search paradigm (and sequent calculus) to model

- computation (a la logic programming)
- model checking
- theorem prover

The first two unfold recursive definitions and explore a space by finite unfoldings.

Theorem proving (with induction and co-induction) attempt to prove things hold for a possibly infinite domains.

Being part of a common framework allows, for example, mixing

- computation and deduction, and
- model checking and theorem proving.

There are many proof systems

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- natural deduction
- sequent calculus

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- tableaux
- resolution refutations

Other useful proof systems with simple connections to the sequent calculus.

Lecture 1: introduction, sequent calculus

Lecture 2: classical and intuitionistic logic

Lecture 3: abstract logic programming

Lecture 4: focused proof systems

Lecture 5: inductive definitions

Lecture 6: model checking and inductive theorem proving