

Reformulations in Mathematical Programming

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Mathematical Programming

- Mathematical programs consist of sets of parameters, variables, objective functions, constraints
- The objective functions are mathematical expressions in terms of parameters and variables, together with an optimization direction
- The constraints are relations between mathematical expressions in terms of parameters and variables
- All such entities can also be expressed in terms of indices, which must be *quantified* over specified sets



The Language

Consider an alphabet L including numbers, mathematical operators (+, -, ×, ÷, ↑, ∑, ∏, log, exp, ∀), brackets, and symbols denoting parameters and variables

Given a sequence of elements of L, is it a well-formed statement of a mathematical program?

- I.e., we treat Mathematical Programming (MP) as a language, whose semantic purpose is to describe a set of points in a Euclidean space (the *optima*)
- One possible grammar of the MP language is specified in the appendix of the AMPL book



Main motivation

- Given an optimization problem, many different MP formulations can describe its solution set
- The performances of solution algorithms depend on the MP formulation

Given an optimization problem and a solution algorithm, what is the MP formulation yielding the best performance?

How do we pass from one formulation to another that keeps some (all) of the mathematical properties of the old formulation?



Reformulations: Existing definitions

- "Q is a reformulation of P": what does it mean?
- Definition in Mathematical Programming Glossary :

Obtaining a new formulation Q of a problem P that is in some sense better, but equivalent to a given formulation. Trouble: Vague.

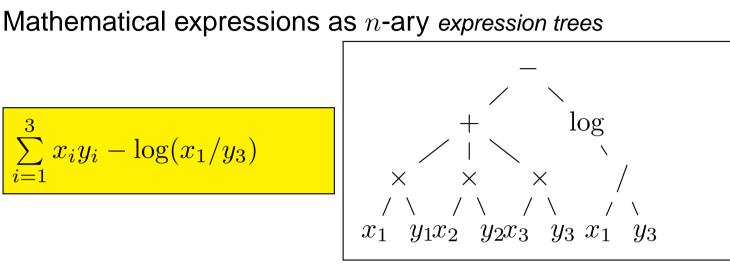
Definition by H. Sherali [private communication] :

bijection between feasible sets, objective function of Q is a monotonic univariate function of that of P. Trouble: feasible sets bijection: condition is too restrictive

• Definition by P. Hansen [Audet et al., JOTA 1997] : P, Q

opt. problems; given an instance p of P and q of Q and an optimal solution y^* of q, Q is a reformulation of P if an optimal solution x^* of p can be computed from y^* within a polynomial amount of time. **Trouble:** only maintains optimality, requires polynomial-time transformation

Storing MP formulations



- A formulation P is a 7-tuple (P, V, E, O, C, B, T) =(parameters, variables, expression trees, objective functions, constraints, bounds on variables, variable types)
- Objectives are encoded as pairs (d, f) where $d \in \{-1, 1\}$ is the optimization direction and f is the function being optimized
- Constraints are encoded as triplets $c \equiv (e, s, b)$ (e ∈ E, s ∈ {≤, ≥, =}, b ∈ ℝ)
 - $\mathcal{F}(P) = \text{feasible set}, \mathcal{L}(P) = \text{local optima}, \mathcal{G}(P) = \text{global optima}$



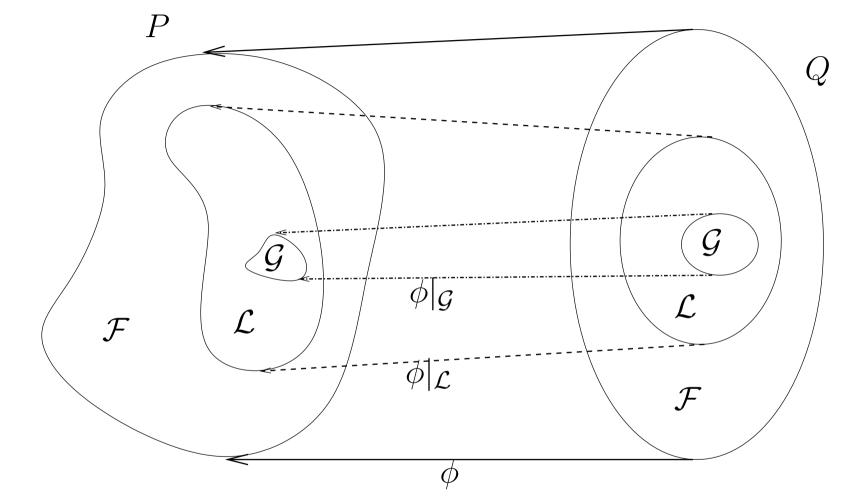
Auxiliary problems

If problems P, Q are related by a computable function f through the relation f(P, Q) = 0, Q is an *auxiliary problem* with respect to P.

- Opt-reformulations (Or exact reformulations): preserve all optimality properties
- Narrowings: preserve some optimality properties
- Relaxations: provide bounds to an objective function value towards its optimization direction
- Approximations: formulation Q depending on a parameter k such that " $\lim_{k\to\infty} Q(k)$ " is an opt-reformulation, narrowing or relaxation

Opt-reformulations

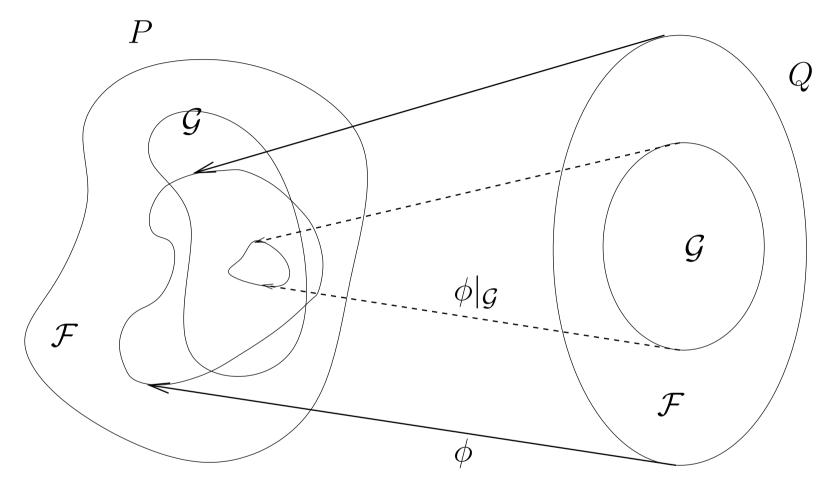




Main idea: if we find an optimum of Q, we can map it back to the same type of optimum of P, and for all optima of P, there is a corresponding optimum in Q.







Main idea: if we find a global optimum of Q, we can map it back to a global optimum of P. There may be optima of P without a corresponding optimum in Q.



Relaxations

- A problem Q is a relaxation of P if: (a) $\mathcal{F}(P) \subseteq \mathcal{F}(Q)$ and (b) for all $(f, d) \in \mathcal{O}(P)$, $(\bar{f}, \bar{d}) \in \mathcal{O}(Q)$ and $x \in \mathcal{F}(P)$ we have $\bar{d}\bar{f}(x) \ge df(x)$
- Relaxations guarantee the bound of all objectives over all the feasible region



Approximations

Q is an *approximation* of *P* if there exist: (a) an auxiliary problem Q^* of *P*; (b) a sequence $\{Q_k\}$ of problems; (c) an integer k' > 0; such that:

1.
$$Q = Q_{k'}$$

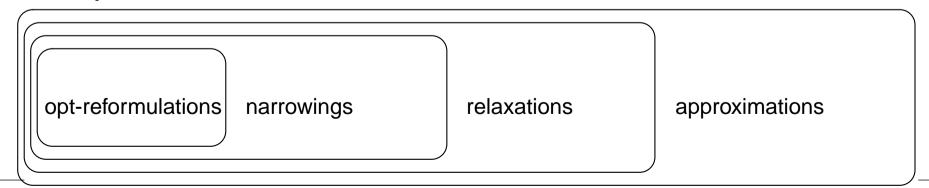
- 2. $\forall f^* \in \mathcal{O}(Q^*)$ there is a sequence of functions $f_k \in \mathcal{O}(Q_k)$ converging uniformly to f^* ;
- 3. $\forall c^* = (e^*, s^*, b^*) \in C(Q^*)$ there is a sequence of constraints $c_k = (e_k, s_k, b_k) \in C(Q_k)$ such that e_k converges uniformly to e^* , $s_k = s^*$ for all k, and b_k converges to b^* .

There can be approximations to opt-reformulations, narrowings, relaxations



Composition laws

- Opt-reformulation, narrowing, relaxation, approximation are all transitive relations, so they can be chained
- An approximation of any reformulation chain is an approximation
- A reformulation chain involving opt-reformulations, narrowings, relaxations is a relaxation
- A reformulation chain involving opt-reformulations and narrowings is a narrowing
- A reformulation chain involving opt-reformulations only is an opt-reformulation





Research programme

- Identify a library of reformulations that can be carried out *automatically* (by a computer) — under way
- Implement data structures for holding MP formulations as well as algorithms for changing their structures under way
- Create a language for combining elementary reformulations into complex (possibly conditional) reformulations, according to the composition laws above — to do
- Create a heuristic method for finding out the *best* reformulation given an optimization problem and a solution algorithm to do