Convex relaxations for quadrilinear terms

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Outline

Background and Motivations Motivations Existing convex envelopes

Convex relaxations for $x_1x_2x_3x_4$

Investigated convex relaxations Computational assessment Computational results

Applications to known problems

MDGP and HFP problems A bound evaluation algorithm Computational results



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Motivations

- The convex envelopes of graphs of all monomials of degree 2 and 3 on an arbitrary box are explicitly known.
- Such a description is unknown, in general, for degree at least 4.
- Branch-and-Bound based global optimization methods, applied to formulations involving multivariate polynomials, rely on such convex envelopes.



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► The bilinear term x_jx_k is replaced by a new variable x_i, and the following linear inequalities are added to the problem relaxation:

$$\begin{array}{rcl} x_i & \geq & x_j^L x_k + x_k^L x_j - x_j^L x_k^L \\ x_i & \geq & x_j^U x_k + x_k^U x_j - x_j^U x_k^U \\ x_i & \leq & x_j^L x_k + x_k^U x_j - x_j^L x_k^U \\ x_i & \leq & x_j^U x_k + x_k^L x_j - x_j^U x_k^L \end{array}$$

(McCormick's envelope)



▶ The trilinear term $x_j x_k x_h$ is replaced by a variable x_i , and linear inequalities are added to the problem relaxation depending on the signs of the bounds on variables (Meyer & Floudas, 2004).

e.g. case
$$x^L \ge 0, y^L \ge 0, z^L \le 0, z^U \ge 0$$
: $(x, y, z \text{ permutation of } x_j, x_k, x_h)$

$$\begin{array}{lll} x_i & \leq & y^U \varepsilon^U x + x^U \varepsilon^U y + x^U y^U \varepsilon - 2x^U y^U \varepsilon^U \\ x_i & \leq & y^U \varepsilon^L x + x^L \varepsilon^U y + x^L y^U \varepsilon - x^L y^U \varepsilon^L - x^L y^U \varepsilon^U \\ x_i & \leq & y^U \varepsilon^L x + x^L \varepsilon^L y + x^U y^L \varepsilon - x^L y^U \varepsilon^L - x^L y^L \varepsilon^L \\ x_i & \leq & y^L \varepsilon^U x + x^U \varepsilon^L y + x^U y^L \varepsilon - x^U y^L \varepsilon^L - x^L y^L \varepsilon^L \\ x_i & \leq & y^L \varepsilon^L x + x^U \varepsilon^L y + x^L y^L \varepsilon - x^U y^L \varepsilon^L - x^L y^L \varepsilon^L \\ x_i & \leq & y^L \varepsilon^U x + x^L \varepsilon^U y + (\theta/(\varepsilon^U - \varepsilon^L)) \varepsilon + (-(\theta\varepsilon^L)/(\varepsilon^U - \varepsilon^L) - x^L y^U \varepsilon^U - x^U y^L \varepsilon^L + x^U y^U \varepsilon^L) \\ x_i & \geq & y^U \varepsilon^L x + x^U \varepsilon^U y + x^U y^U \varepsilon - 2x^U y^U \varepsilon^L \\ x_i & \geq & y^U \varepsilon^L x + x^U \varepsilon^U y + x^U y^U \varepsilon - 2x^U y^U \varepsilon^L \\ x_i & \geq & y^U \varepsilon^L x + x^U \varepsilon^U y - x^U y^U \varepsilon^U - x^U y^L \varepsilon^U - x^U y^L \varepsilon^L \\ x_i & \geq & y^U \varepsilon^U x + x^L \varepsilon^U y + x^L y^U \varepsilon - x^L y^U \varepsilon^U - x^L y^U \varepsilon^L \\ x_i & \geq & y^U \varepsilon^U x + x^L \varepsilon^U y + x^L y^U \varepsilon - x^L y^U \varepsilon^U - x^L y^U \varepsilon^L \\ x_i & \geq & y^U \varepsilon^U x + x^L \varepsilon^U y + x^L y^U \varepsilon - x^L y^U \varepsilon^U - x^L y^U \varepsilon^L \\ x_i & \geq & y^L \varepsilon^U x + x^U \varepsilon^U y + x^L y^L \varepsilon - x^L y^U \varepsilon^U - x^L y^U \varepsilon^L \\ x_i & \geq & y^L \varepsilon^U x + x^U \varepsilon^U y + x^L y^L \varepsilon - x^U y^L \varepsilon^U - x^L y^U \varepsilon^U \\ x_i & \geq & y^L \varepsilon^U x + x^U \varepsilon^U y + x^L y^U \varepsilon - x^U y^L \varepsilon^U - x^L y^U \varepsilon^U \\ x_i & \geq & y^L \varepsilon^U x + x^U \varepsilon^U y + x^L y^U \varepsilon - x^U y^U \varepsilon^U - x^L y^U \varepsilon^U \\ x_i & \geq & y^L \varepsilon^L x + x^U \varepsilon^U y + (\bar{\theta}/(\varepsilon^L - \varepsilon^U)) \varepsilon + (-(\bar{\theta}\varepsilon^U)/(\varepsilon^L - \varepsilon^U) - x^U y^L \varepsilon^L - x^L y^U \varepsilon^L + x^U y^U \varepsilon^U), \end{aligned}$$



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Existing convex envelopes

• The concave univariate function $f(x_i)$ is replaced by a variable x_i and two inequalities are added to the problem relaxation:

$$\begin{array}{rcl} x_i & \leq & f(x_j) \\ x_i & \geq & f(x_j^L) + \frac{f(x_j^U) - f(x_j^L)}{x_j^U - x_j^L} (x_j - x_j^L). \end{array}$$

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For concave (convex) $f(x_j)$, the first (second) constraint is a nonlinear over (under)-estimator which is usually replaced by a pre-determined number of tangents to *f* at various given points.



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For concave (convex) $f(x_j)$, the first (second) constraint is a nonlinear over (under)-estimator which is usually replaced by a pre-determined number of tangents to f at various given points.



- ▶ The term x_j^{2k} for any $k \in \mathbb{N}$ is replaced by a variable x_i and treated as a convex univariate function.
- ▶ The term x_j^{2k+1} for any $k \in \mathbb{N}$ is replaced by a variable x_i . If the range of x_j does not include 0, the function is convex or concave. Otherwise, the convex/concave envelope is given in (Liberti & Pantelides, 2003) a tight linear relaxation is:

$$\begin{aligned} & (x_j^L)^{2k+1} \left(1 + R_k \left(\frac{x_j}{x_j^L} - 1 \right) \right) & \leq x_i \leq (x_j^U)^{2k+1} \left(1 + R_k \left(\frac{x_j}{x_j^U} - 1 \right) \right) \\ & (2k+1)(x_j^U)^{2k} x_j - 2k(x_j^U)^{2k+1} & \leq x_j \leq (2k+1)(x_j^L)^{2k} x_j - 2k(x_j^L)^{2k+1}, \end{aligned}$$

$$R_k = rac{r_k^{2k+1}-1}{r_k-1}$$



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$$\begin{aligned} & (x_j^L)^{2k+1} \left(1 + R_k \left(\frac{x_j}{x_j^L} - 1 \right) \right) & \leq x_i \leq (x_j^U)^{2k+1} \left(1 + R_k \left(\frac{x_j}{x_j^U} - 1 \right) \right) \\ & (2k+1)(x_j^U)^{2k} x_j - 2k(x_j^U)^{2k+1} & \leq x_j \leq (2k+1)(x_j^L)^{2k} x_j - 2k(x_j^L)^{2k+1}, \end{aligned}$$

$$R_k = \frac{r_k^{2k+1} - 1}{r_k - 1} \qquad \begin{array}{c|c} k & r_k \\ 1 & -0.50000000 \\ 2 & -0.608295862 \\ -0.608295862 \\ 3 & -0.6703320476 \\ -0.7145577272 \\ 5 & -0.74705407749 \end{array}$$

-0.8340533676

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Obtaining convex relaxations

Basic idea: given a sufficiently rich set of "elementary" convex envelopes, compose convex relaxations (albeit not envelopes) of complex functions relatively easily.

Example: given f(x), g(x) with known convex/concave envelopes, in order to obtain a convex relaxation for f(x)g(x):

- apply the bilinear convex envelope to the product w_1w_2 ,
- replace the necessary "defining constraints":

 $w_1 = f(x)$ $w_2 = g(x)$

by the convex/concave envelopes of f, g.

Note: this strategy may yields non-unique ways of combining terms (due to the associativity of the product).



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Given a quadrilinear term

 $x_1 x_2 x_3 x_4$

we consider the following three types of term grouping:

 $((x_1x_2)x_3)x_4$ $(x_1x_2)(x_3x_4)$ $(x_1x_2x_3)x_4$

and derive three corresponding linear convex relaxations for $x_1x_2x_3x_4$.



Let us consider:

$$S_{1} = \{(x, w) \in \mathbb{R}^{4} \times \mathbb{R}^{3} | x_{i} \in [x_{i}^{L}, x_{i}^{U}], w_{1} = x_{1}x_{2}, w_{2} = w_{1}x_{3}, w_{3} = w_{2}x_{4}\}$$

$$S_{2} = \{(x, w) \in \mathbb{R}^{4} \times \mathbb{R}^{3} | x_{i} \in [x_{i}^{L}, x_{i}^{U}], w_{1} = x_{1}x_{2}, w_{2} = x_{3}x_{4}, w_{3} = w_{1}w_{2}\}$$

$$S_{3} = \{(x, w) \in \mathbb{R}^{4} \times \mathbb{R}^{2} | x_{i} \in [x_{i}^{L}, x_{i}^{U}], w_{1} = x_{1}x_{2}x_{3}, w_{2} = w_{1}x_{4}\}$$

S₁: bilinear envelope exploited thrice
 S₂: bilinear envelope exploited thrice
 S₃: bilinear envelope + trilinear envelope

Which one yields the tightest bounds?



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Test instances

- ► 80 test instances generated varying signs of the bounds/bound interval widths.
- 20 combinations by varying the signs of bounds on the 4 variables (missing cases are equivalent to covered cases by simple symmetry considerations).
- ► same initial width of the bound intervals for all variables. Then progressively, for *i* = 1, 2, 3, the width of the bound interval of *x_i* is reduced.

This simulates the exploration of a single branch of a typical sBB search tree, whose nodes have decreasing range widths.

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Comparison of relaxations

The comparison among the considered relaxations is made in terms of the **volume** of the corresponding enveloping polytopes.

Exploiting envelopes for bilinear and trilinear terms leads to an increased number of variables \implies the obtained polytopes belong to \mathbb{R}^7 and \mathbb{R}^6 .

 \implies **Projection** of the polytopes onto the space of $(x, f(x) := x_1x_2x_3x_4) \in \mathbb{R}^5$.

- Computation of the projections: cdd software (Fukuda, 2008).
- Computation of the volume of the projected polytopes: lrs software (Avis, 2006).

All the results are computed in exact arithmetic.



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Results

Inst.		<i>x</i> ₁		<i>x</i> 2		<i>x</i> 3		<i>x</i> ₄	$((x_1x_2)x_3)x_4$	$(x_1x_2)(x_3x_4)$	$(x_1x_2x_3)x_4$
	$ \cdot $	sign	$ \cdot $	sign	·	sign	$ \cdot $	sign			
instl	2	+, +	2	+, +	2	-,+	2	-, +	8282/45	1474/15	1508117/8640
inst2	2	+, +	2	+, +	2	-, +	2	-, -	10922/45	298793/1215	1928777/8640
inst3	2	+, +	2	-, +	2	-, +	2	-, +	2080/27	2080/27	3136/45
inst4	2	+, +	2	-,+	2	-, +	2	-, -	3424/27	3056/15	4576/45
inst5	2	-, +	2	-,+	2	-, +	2	-, +	416/15	416/15	416/15
inst6	2	-, +	2	-,+	2	-, +	2	-, -	736/15	2080/27	736/15
inst7	2	+, +	2	-,+	2	-, -	2	-, +	1664/9	3056/15	4736/27
inst8	2	+, +	2	-,+	2	_, _	2	-, -	736/3	298793/1215	6032/27
inst9	2	-,+	2	-, -	2	— , —	2	-, +	1664/9	3056/15	4736/27
inst10	2	-,+	2	-, -	2	— , —	2	-, -	736/3	298793/1215	6032/27
inst11	2	-,+	2	-, +	2	— , —	2	-, +	3136/45	2080/27	3728/45
inst12	2	-,+	2	-, +	2	— , —	2	-, -	4576/45	1474/15	6608/45
inst13	2	+, +	2	+, +	2	+, +	2	-, +	40166/195	298793/1215	38288/195
inst14	2	+, +	2	+, +	2	+, +	2	-, -	53686/195	359936/1215	48688/195
inst15	2	+, +	2	+, +	2	— , —	2	-, +	40166/195	298793/1215	38288/195
inst16	2	+, +	2	+, +	2	— , —	2	-, -	53686/195	359936/1215	48688/195
inst17	2	+, +	2	-, -	2	_, _	2	-, +	40166/195	298793/1215	38288/195
inst18	2	+, +	2	-, -	2	_, _	2	_ , _	53686/195	359936/1215	48688/195
inst19	2	_, _	2	-, -	2	_, _	2	-, +	40166/195	298793/1215	4983841/44928
inst20	2	-, -	2	-, -	2	_ , _	2	-, -	53686/195	359936/1215	48688/195



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Results

Inst.		<i>x</i> ₁		<i>x</i> 2		<i>x</i> 3		<i>x</i> ₄	$((x_1x_2)x_3)x_4$	$(x_1x_2)(x_3x_4)$	$(x_1x_2x_3)x_4$
	$ \cdot $	sign	$ \cdot $	sign	$ \cdot $	sign	$ \cdot $	sign			
inst21	1	+, +	2	+, +	2	-,+	2	-, +	48958/675	1886/45	47746613/691200
inst22	1	+, +	2	+, +	2	-, +	2	— , —	63358/675	21847/225	59852213/691200
inst23	1	+, +	2	-, +	2	-, +	2	-, +	11368/375	11368/375	2128/75
inst24	1	+, +	2	-, +	2	-, +	2	-, -	6056/125	781148/10125	3128/75
inst25	1	-, +	2	-, +	2	-, +	2	-, +	104/15	104/15	104/15
inst26	1	-, +	2	-, +	2	-, +	2	-, -	184/15	520/27	184/15
inst27	1	+, +	2	-, +	2	-, -	2	-, +	81008/1125	781148/10125	15584/225
inst28	1	+, +	2	-, +	2	_, _	2	_ , _	104408/1125	7503097/81000	19484/225
inst29	1	-, +	2	-, -	2	-, -	2	-, +	416/9	764/15	1184/27
inst30	1	-, +	2	-, -	2	-, -	2	— , —	184/3	298793/4860	1508/27
inst31	1	-, +	2	-, +	2	-, -	2	-, +	784/45	520/27	932/45
inst32	1	-, +	2	-, +	2	-, -	2	— , —	1144/45	737/30	1652/45
inst33	1	+, +	2	+, +	2	+, +	2	-, +	8842/105	21847/225	30404/315
inst34	1	+, +	2	+, +	2	+, +	2	— , —	11362/105	695674/6075	50144/315
inst35	1	+, +	2	+, +	2	-, -	2	-, +	8842/105	21847/225	25364/315
inst36	1	+, +	2	+, +	2	-, -	2	— , —	11362/105	695674/6075	31244/315
inst37	1	+, +	2	_, _	2	—, —	2	-, +	8842/105	21847/225	25364/315
inst38	1	+, +	2	_, _	2	—, —	2	_ , _	11362/105	695674/6075	31244/315
inst39	1	_, _	2	_, _	2	—, —	2	-, +	8842/105	21847/225	458469/5600
inst40	1	-, -	2	_, _	2	_, _	2	_, _	11362/105	695674/6075	50144/315

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Results

Inst.		<i>x</i> ₁		<i>x</i> 2		<i>x</i> 3		<i>x</i> ₄	$((x_1x_2)x_3)x_4$	$(x_1x_2)(x_3x_4)$	$(x_1x_2x_3)x_4$
	$ \cdot $	sign	$ \cdot $	sign	$ \cdot $	sign	$ \cdot $	sign			
inst41	1	+, +	1	+, +	2	-, +	2	-, +	335651/12000	8453/480	161590649/6144000
inst42	1	+, +	1	+, +	2	-, +	2	— , —	421651/12000	874021/24000	196456649/6144000
inst43	1	+, +	1	-, +	2	-, +	2	-, +	2842/375	2842/375	532/75
inst44	1	+, +	1	-, +	2	-, +	2	— , —	1514/125	195287/10125	782/75
inst45	1	-, +	1	-, +	2	-, +	2	-, +	26/15	26/15	26/15
inst46	1	-, +	1	-, +	2	-, +	2	— , —	46/15	130/27	46/15
inst47	1	+, +	1	-, +	2	—, —	2	-, +	20252/1125	195287/10125	3896/225
inst48	1	+, +	1	-,+	2	-, -	2	-, -	26102/1125	7503097/324000	4871/225
inst49	1	-, +	1	-, -	2	-, -	2	-, +	20252/1125	195287/10125	3896/225
inst50	1	-, +	1	-, -	2	—, —	2	— , —	26102/1125	7503097/324000	4871/225
inst51	1	-, +	1	-, +	2	—, —	2	-, +	196/45	130/27	233/45
inst52	1	-, +	1	-, +	2	—, —	2	— , —	286/45	737/120	413/45
inst53	1	+, +	1	+, +	2	+, +	2	-, +	47921/1440	874021/24000	3961/99
inst54	1	+, +	1	+, +	2	+, +	2	— , —	59201/1440	56957/1350	6568/99
inst55	1	+, +	1	+, +	2	—, —	2	-, +	47921/1440	874021/24000	15757/495
inst56	1	+, +	1	+, +	2	-, -	2	— , —	59201/1440	56957/1350	18727/495
inst57	1	+, +	1	_, _	2	-, -	2	-, +	47921/1440	874021/24000	969001783/35371875
inst58	1	+, +	1	_, _	2	-, -	2	— , —	59201/1440	56957/1350	368725761/11790625
inst59	1	— , —	1	_, _	2	-, -	2	-, +	47921/1440	874021/24000	3307195027/243302400
inst60	1	_, _	1	-, -	2	-, -	2	_, _	59201/1440	56957/1350	6568/99



(□) (圖) (E) (E) (E)

Results

	n										
INSI.		<i>x</i> ₁		x2		x3		x4	$((x_1x_2)x_3)x_4$	$(x_1x_2)(x_3x_4)$	$(x_1x_2x_3)x_4$
	$ \cdot $	sign	$ \cdot $	sign	$ \cdot $	sign	$ \cdot $	sign			
inst61	1	+, +	1	+, +	1	-,+	2	-, +	335651/48000	8453/1920	161590649/24576000
inst62	1	+, +	1	+, +	1	-, +	2	_, _	421651/48000	874021/96000	196456649/24576000
inst63	1	+, +	1	-, +	1	-,+	2	-, +	1421/750	1421/750	133/75
inst64	1	+, +	1	-, +	1	-,+	2	-, -	757/250	195287/40500	391/150
inst65	1	-,+	1	-, +	1	-,+	2	-, +	13/30	13/30	13/30
inst66	1	-,+	1	-, +	1	-,+	2	-, -	23/30	65/54	23/30
inst67	1	+, +	1	-, +	1	-, -	2	-, +	12851/1875	1733/240	20/3
inst68	1	+, +	1	-, +	1	-, -	2	_, _	10609/1250	3203327/360000	97/12
inst69	1	-, +	1	-, -	1	-, -	2	-, +	12851/1875	1733/240	20/3
inst70	1	-,+	1	-, -	1	-, -	2	_, _	10609/1250	3203327/360000	97/12
inst71	1	-,+	1	-, +	1	-, -	2	-, +	133/75	1421/750	641/300
inst72	1	-,+	1	-, +	1	-, -	2	-, -	391/150	943/360	1141/300
inst73	1	+, +	1	+, +	1	+, +	2	-, +	1162283/94080	1673383477/129600000	34879/2940
inst74	1	+, +	1	+, +	1	+, +	2	-, -	1377883/94080	24832097/1620000	39779/2940
inst75	1	+, +	1	+, +	1	-, -	2	-, +	1162283/94080	1673383477/129600000	34879/2940
inst76	1	+, +	1	+, +	1	-, -	2	-, -	1377883/94080	24832097/1620000	39779/2940
inst77	1	+, +	1	-, -	1	-, -	2	-, +	1162283/94080	1673383477/129600000	34879/2940
inst78	1	+, +	1	—, —	1	_, _	2	_, _	1377883/94080	24832097/1620000	39779/2940
inst79	1	_ , _	1	—, —	1	_, _	2	-, +	1162283/94080	1673383477/129600000	45232093/516096000
inst80	1	-, -	1	-, -	1	-, -	2	-, -	1377883/94080	24832097/1620000	39779/2940



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Molecular Distance Geometry Problem

▶ The MDGP is the problem of finding an embedding in \mathbb{R}^3 of a weighted graph G = (V, E) such that all Euclidean distances between points in the embedding are the same as the corresponding edge weights in the graph.

The *main application* is to find the 3-dimensional structure of a molecule given a subset of the atomic distances.

▶ Given a set *V* of *n* atoms, a set *E* of inter-atomic distances $d_{ij} = d(\{i, j\})$ for $\{i, j\} \in E$, a NLP formulation of the MDGP is:

 $\min_x f(x)$

$$f(x) = \sum_{\{i,j\} \in E} (||x_i - x_j||^2 - d_{ij}^2)^2.$$



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Molecular Distance Geometry Problem

A typical term $(||x_i - x_j||^2 - d_{ij}^2)^2$ expanded is: (each 3-vector x_i has components (x_{i1}, x_{i2}, x_{i3}))

$$\begin{aligned} (||x_i - x_j||^2 - d_{ij}^2)^2 &= - 4x_{i2}x_{j2}x_{i3}^2 - 4x_{i1}x_{j1}x_{i2}^2 - 4x_{i1}x_{j1}x_{j2}^2 - 4x_{i1}x_{j1}x_{i3}^2 + 4x_{i1}x_{j1}d_{ij}^2 \\ &- 4x_{i1}^2x_{i2}x_{j2} - 4x_{j1}^2x_{i2}x_{j2} - 4x_{i2}^2x_{i3}x_{j3} - 4x_{i1}x_{j1}x_{j3}^2 - 4x_{j1}^2x_{i3}x_{j3} \\ &+ 4x_{i2}x_{j2}d_{ij}^2 - 4x_{i2}x_{j2}x_{j3}^2 + 4x_{i3}x_{j3}d_{ij}^2 - 4x_{j2}^2x_{i3}x_{j3} - 4x_{i1}^2x_{i3}x_{j3} \\ &+ 8x_{i1}x_{j1}x_{i2}x_{j2} + 8x_{i1}x_{j1}x_{i3}x_{j3} + 8x_{i2}x_{j2}x_{i3}x_{j3} + x_{i1}^4 + x_{j1}^4 + x_{i2}^4 \\ &+ x_{j2}^4 + x_{i3}^4 + x_{j3}^4 - 4x_{i1}^3x_{j1} + 6x_{i1}^2x_{j1}^2 + 2x_{i1}^2x_{i2}^2 + 2x_{i1}^2x_{j2}^2 \\ &+ 2x_{i1}^2x_{i3}^2 + 2x_{i1}^2x_{j3}^2 - 2x_{i1}^2d_{ij}^2 - 4x_{i1}x_{j1}x_{j1} + 2x_{j2}^2 + 2x_{j1}^2x_{j2}^2 \\ &+ 2x_{j1}^2x_{i3}^2 + 2x_{j1}^2x_{j3}^2 - 2x_{j1}^2d_{ij}^2 - 4x_{i1}x_{j1}x_{j1} + 2x_{j2}^2 + 2x_{j2}^2x_{j3}^2 - 2x_{j2}^2d_{ij}^2 \\ &+ 2x_{i2}^2x_{i3}^2 - 2x_{i2}^2d_{ij}^2 - 4x_{i2}x_{j2}^2 + 2x_{i2}x_{j2}^2 + 2x_{i2}^2x_{j3}^2 \\ &+ 2x_{i1}^2x_{i3}^2 + 2x_{i1}^2x_{j3}^2 - 2x_{i1}^2d_{ij}^2 - 4x_{i2}x_{i3}x_{j3} - 2x_{j2}^2d_{ij}^2 + d_{ij}^2. \end{aligned}$$

many quartic terms!



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It is a known problem in quantum chemistry: finding spatial orbitals of electrons in a closed-shell atomic system.

- Non-relativistic time-independent Schrödinger equation: $H\Psi_n = E\Psi_n$ (*H* = Hamiltonian operator of the system, representing the total energy).
- ► HF model: the electrons in atoms and molecules move independently of each other, the motion of each one of the electrons being determined by the attractive electrostatic potential of the nuclei and by a repulsive average field due to all the other electrons of the system.
- The approximate solutions Φ_n of the Schrödinger equation are products of *orbitals* {φ_i}, which are solutions of the HF equations.
- Orbitals approximated by suitable bases $\{\chi_s \mid s \leq b\}$:

$$\bar{\varphi}_i := \sum_{s \le b} c_{si} \chi_s$$

 $\bar{\varphi}_i$ approximations of φ_i .



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- ► HFP: finding a set of coefficients c_{si} such that the $\overline{\varphi}_i$ are the best possible approximations of the spatial orbitals.
- ► NLP problem: minimize a suitable energy function (quality of the approximation) s.t. {\$\overline{\varphi}\$}\$ is an orthonormal set:

$$\begin{array}{ll} \min & E(c) \\ \text{s.t.} & \left\langle \sum_{s \leq b} c_{si} \chi_s \;,\; \sum_{s \leq b} c_{sj} \chi_s \right\rangle = \delta_{ij} \quad \forall i \leq j \leq n \\ & c^L \leq c \leq c^U \;. \end{array}$$

orthonormality constraints are quadratic in the decision variables c.



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min
$$E(c)$$

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 $c^L \le c \le c^U$.

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Convex relaxations for quadrilinear terms
Applications to known problems
A bound evaluation algorithm

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Bound evaluation algorithm

• The natural application of tight lower bounds computed through a convex relaxation is within the sBB algorithm.

Our alternative: a simplified *partial sBB* algorithm. At each branching step, the algorithm only records the most promising node and discards the other, thus *exploring a single branch up to a leaf*.

• A very simple branching strategy (the variable index *i* maximizing $|x_i^* - \bar{x}_i|$); termination: either on iteration limit or on reaching a node that is infeasible or that contains the global optimum.



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Constructing the convex relaxation

solver_RQuarticConvex within ROSE

- Step1: replace each nonlinear term by an added variable
- **Step2:** add a defining constraint "added variable = nonlinear term" to the problem
- Step 3: replace each defining constraint by a convex relaxation.

Note: The 3 different convex relaxations yielded by the different defining constraints due to the different associativity precedences in

```
((x_1x_2)x_3)x_4 (x_1x_2)(x_3x_4) (x_1x_2x_3)x_4
```

are implemented.



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Computational results

Instance	$((x_1x_2)x_3)x_4$	$(x_1x_2)(x_3x_4)$	$(x_1x_2x_3)x_4$
lavor5	-1580.81	-1758.4	-683.82
lavor6	-2652.05	-2746.92	-1117.05
lavor7	-3427.96	-3411.96	-2378.53
beryllium	-22.6887	-21.8208	-17.988
neon	-1292.64	-1306.4	-1342.71



Conclusions

- ► We proposed a computational approach to determine the best among three convex relaxations for quadrilinear terms.
- The results suggest that a strategy taking into account widths and signs of the input bounds could be used in a sBB solver in order to automatically select the best relaxation procedure.

Future work

- Computational experiences on large scale instances.
- ▶ Implementation of a full sBB.
- ► Theoretical study on the relaxation strenght of quadrilinear terms.



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